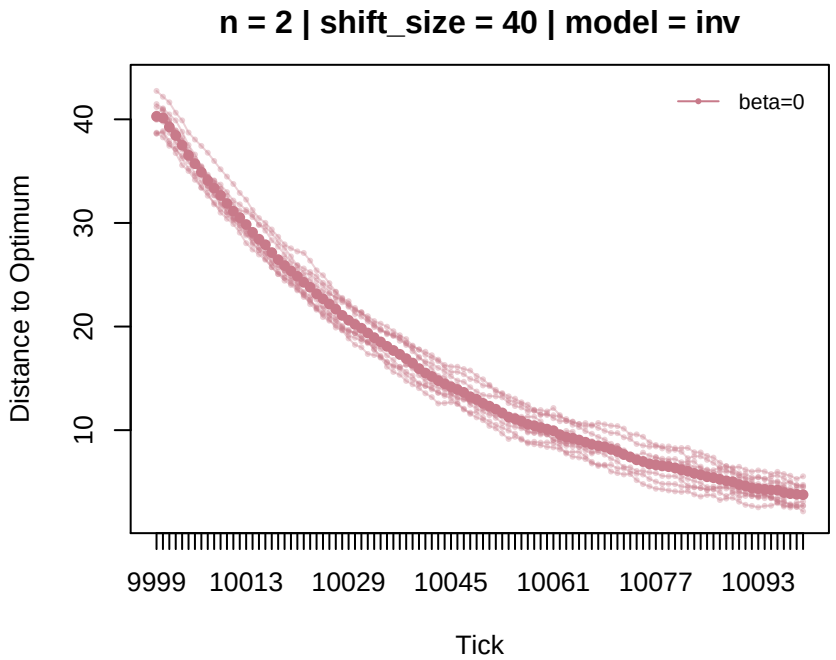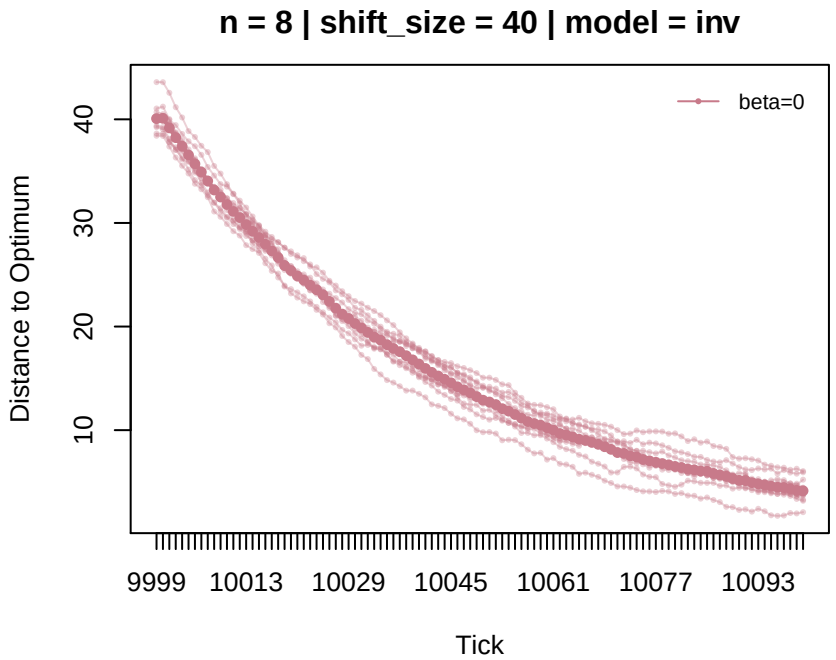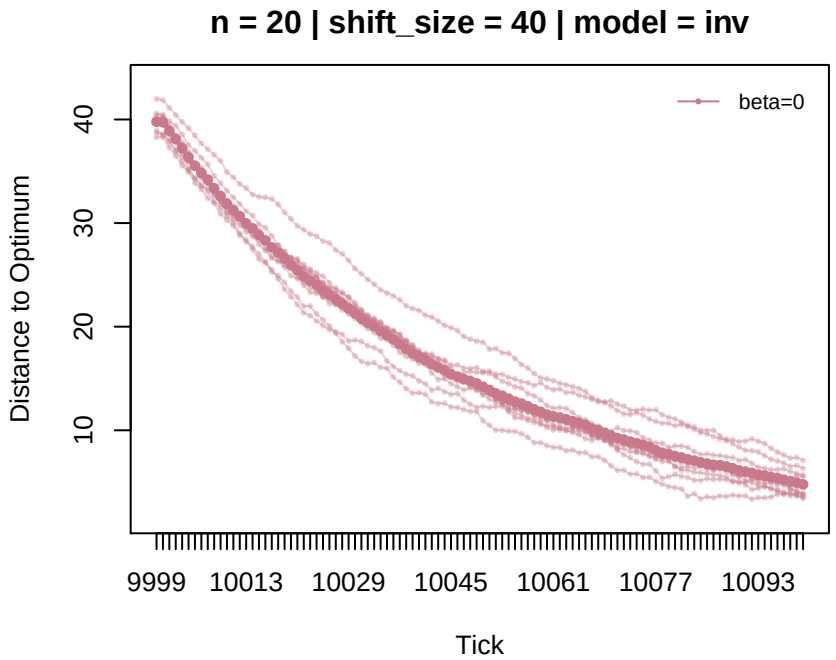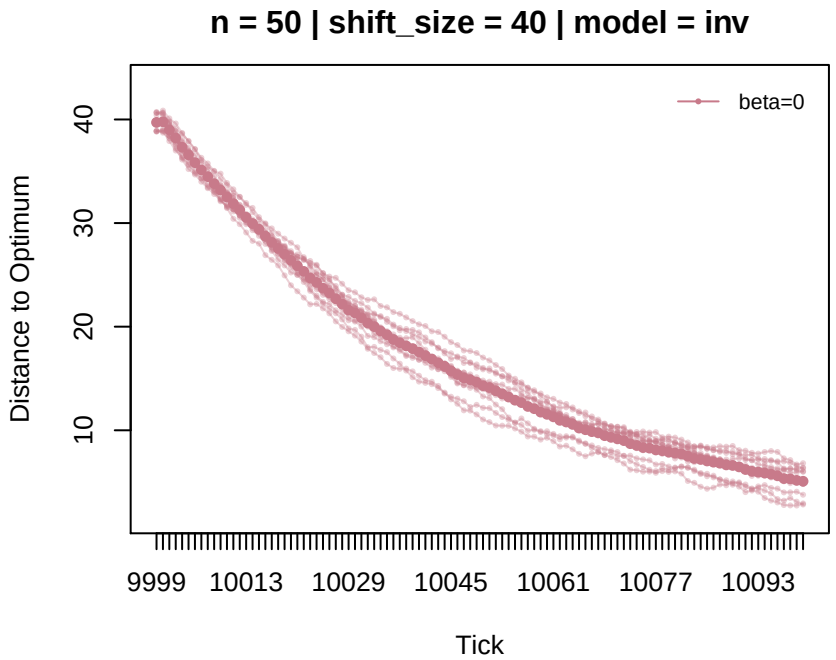Trajectory over ticks | model = inv | shift_size = 40