$$M = \begin{bmatrix} M_x \\ M_y \\ M_z \end{bmatrix} \sim M$$

$$\sum_{n=1}^{\infty} \begin{bmatrix} M_x \\ M_z \end{bmatrix} \sim M$$

Suppose we're in camera 30 coords

F(), S)
BROF

bidirectronal radrance distribution functions