



PennState
College of Engineering

ME 563: Nonlinear Finite Elements

Application and Exploration of Nonlinear Finite Elements

Hyperelasticity, Part 2



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1. Introduction

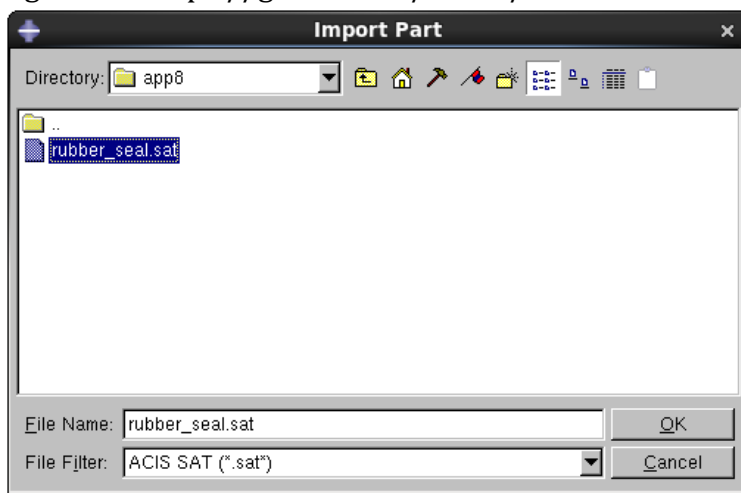
In this application, we will learn about and apply the follow concepts:

- Contact
- Rigid body
- Hyperelasticity
- PBS job scripts?

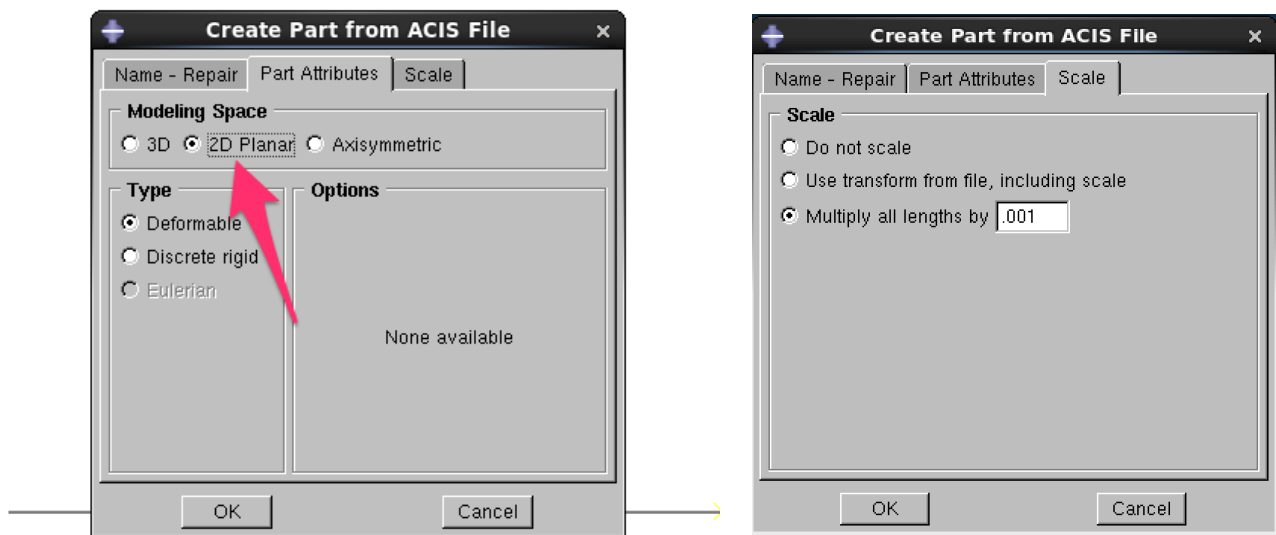
2. Define Geometry

Clone github directory and import rubber_seal.sat into Abaqus:

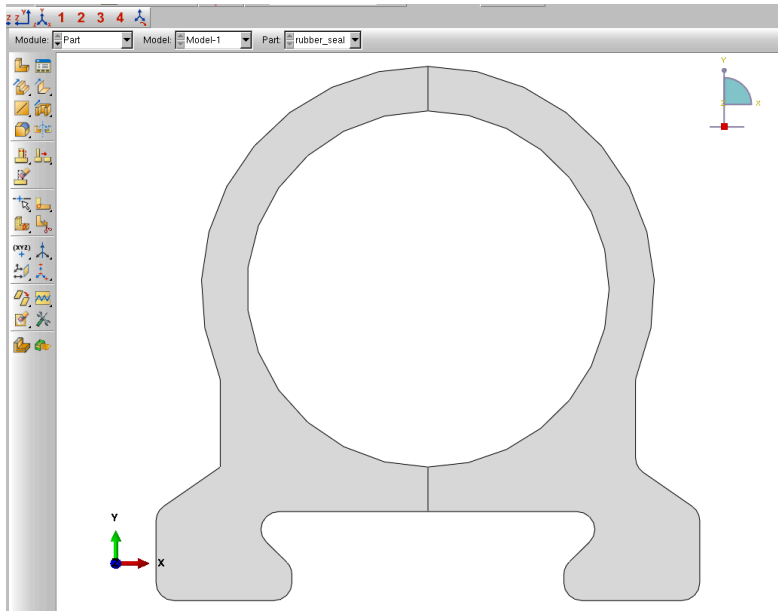
```
> git clone https://github.com/rhk12/RubberSeal
```



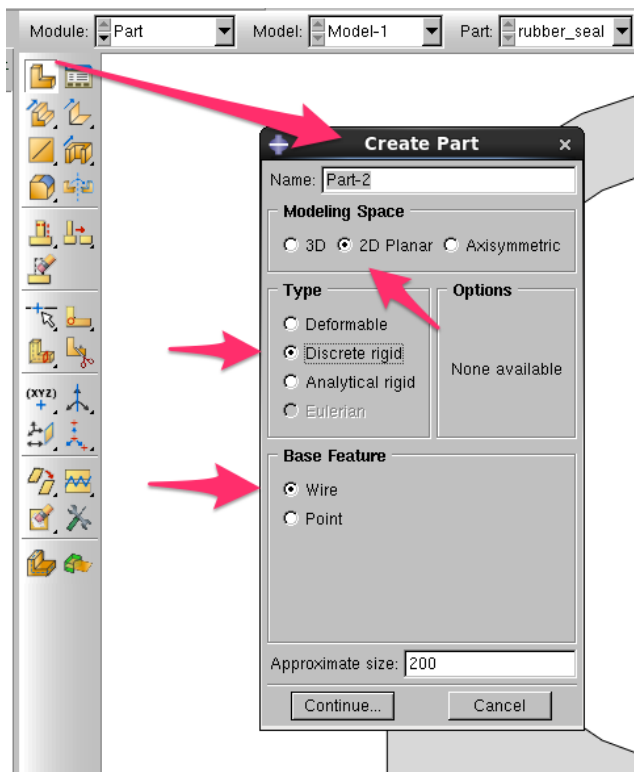
Be sure to import it into 2D planar Modeling Space:



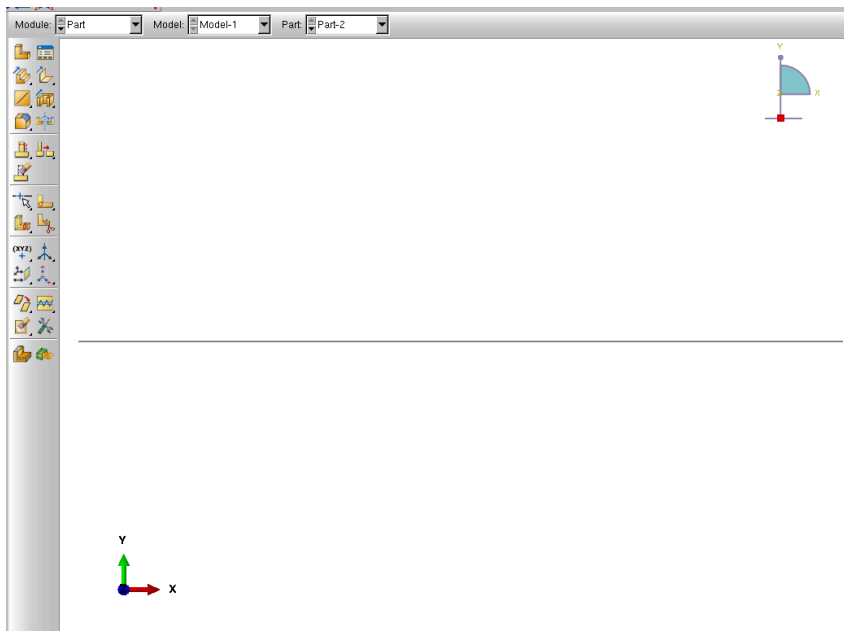
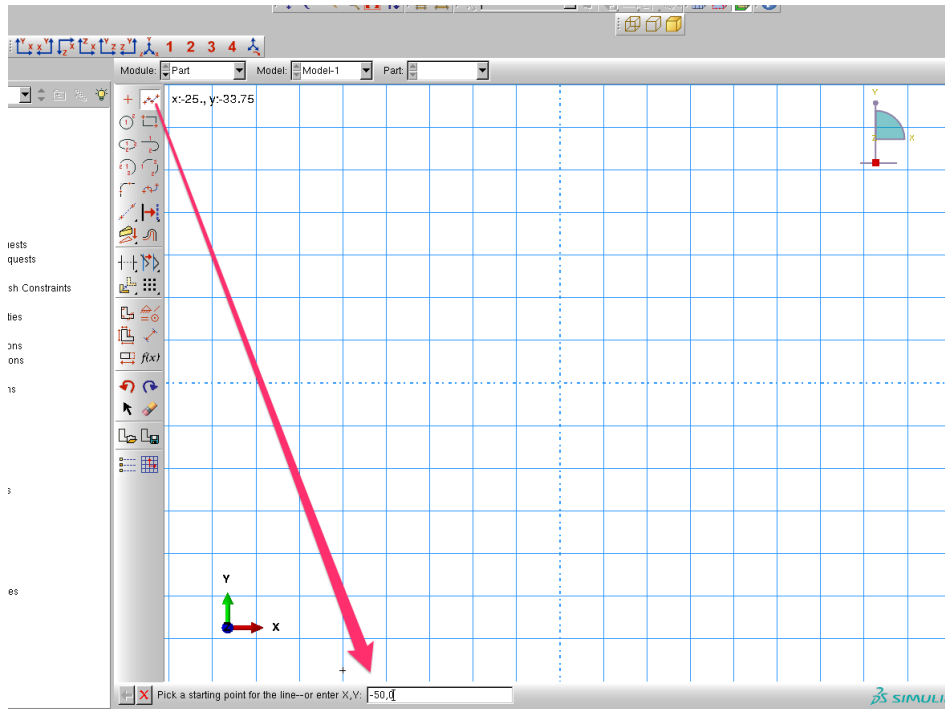
You should have this:



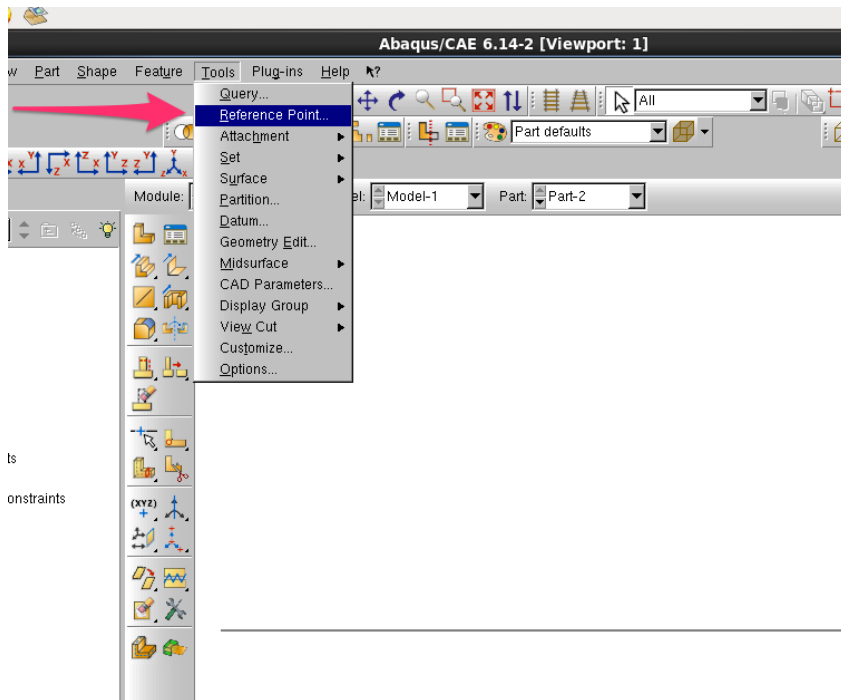
Create another part, choose 2d planar, discrete rigid:



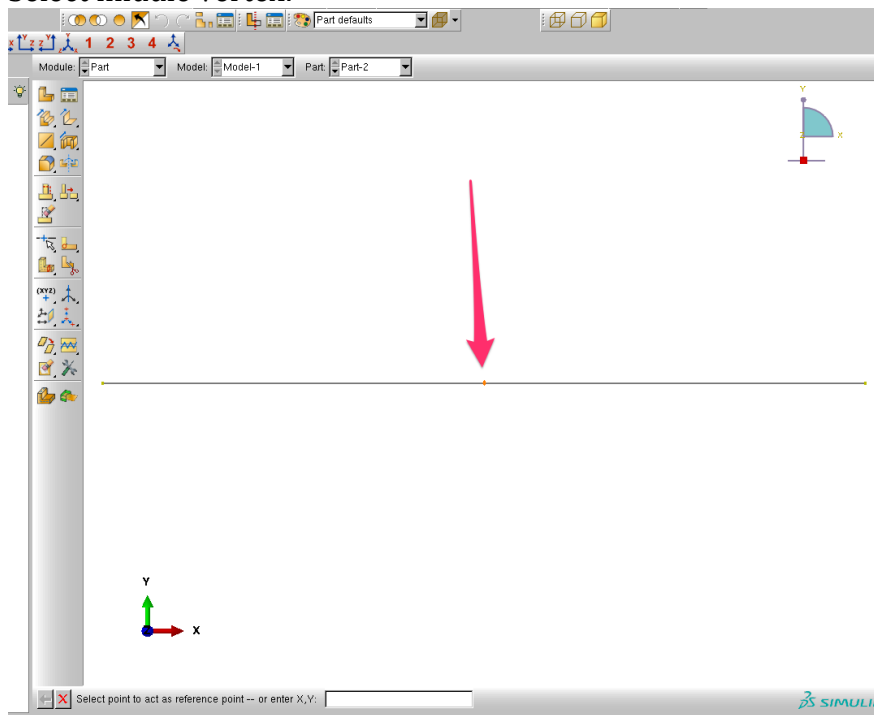
Create a wire part at the top and bottom: $(-0.050, 0)$ to $(0.050, 0)$



Use Tools->Reference Point to assign a ref. point to the rigid body:



Select middle vertex:



Do this another time so we have two wire parts.

3. Define Materials

Create material using the Arruda Boyce constants we obtained last time.

Hyperelastic

Material type: ☒ Isotropic ☐ Anisotropic

Strain energy potential: **Arruda-Boyce**

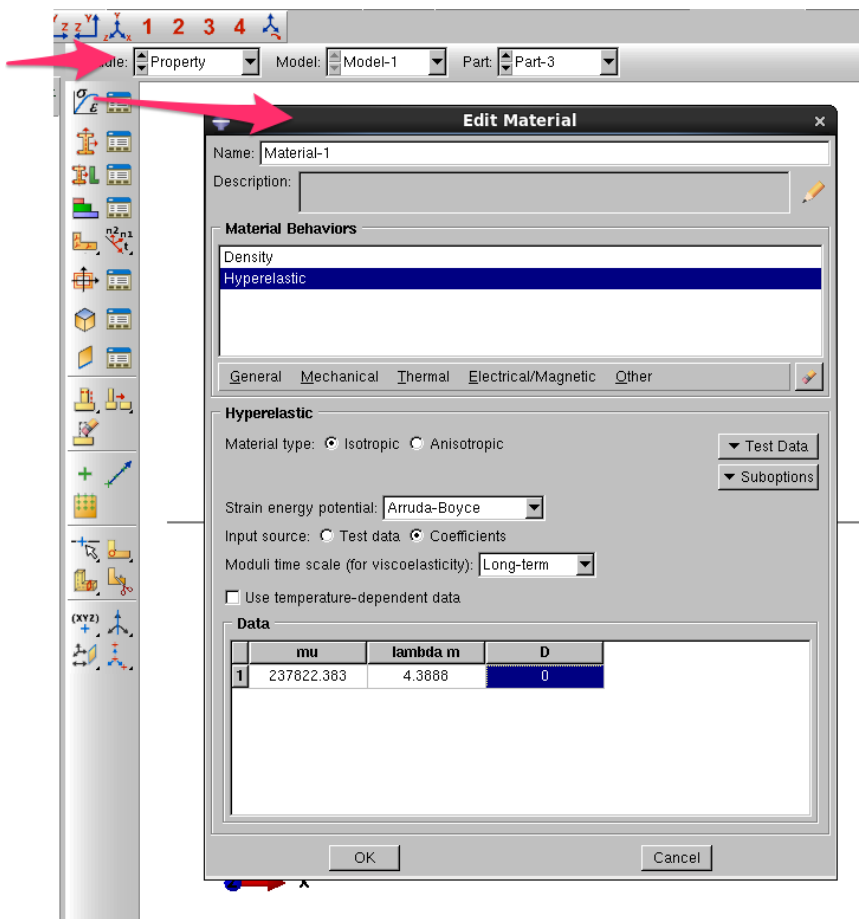
Input source: ☐ Test data ☒ Coefficients

Moduli time scale (for viscoelasticity): **Long-term**

☐ Use temperature-dependent data

Data

	μ	λ	D
1	237822.383	4.38887181	0



Property Model: Model-1 Part: Part-3

Edit Material

Name: Material-1

Description:

Material Behaviors

Density

Hyperelastic

General Mechanical Thermal Electrical/Magnetic Other

Hyperelastic

Material type: ☒ Isotropic ☐ Anisotropic

Strain energy potential: **Arruda-Boyce**

Input source: ☐ Test data ☒ Coefficients

Moduli time scale (for viscoelasticity): **Long-term**

☐ Use temperature-dependent data

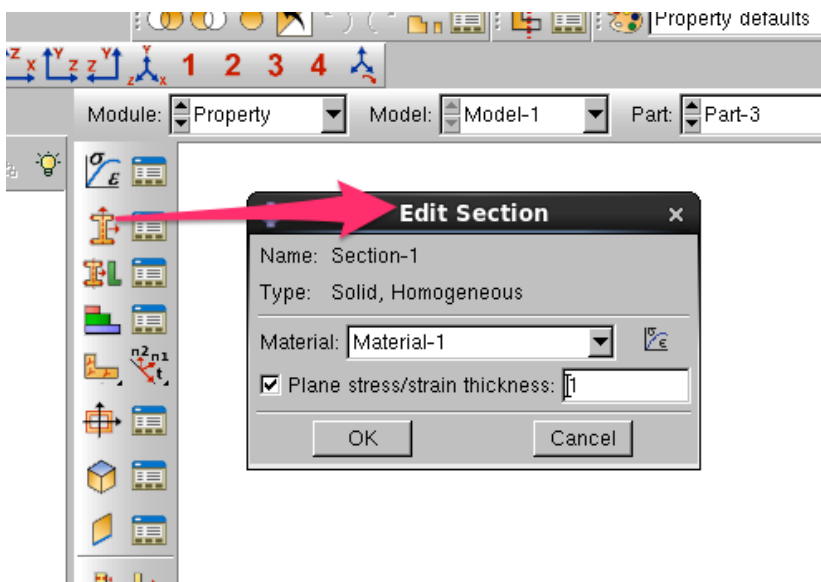
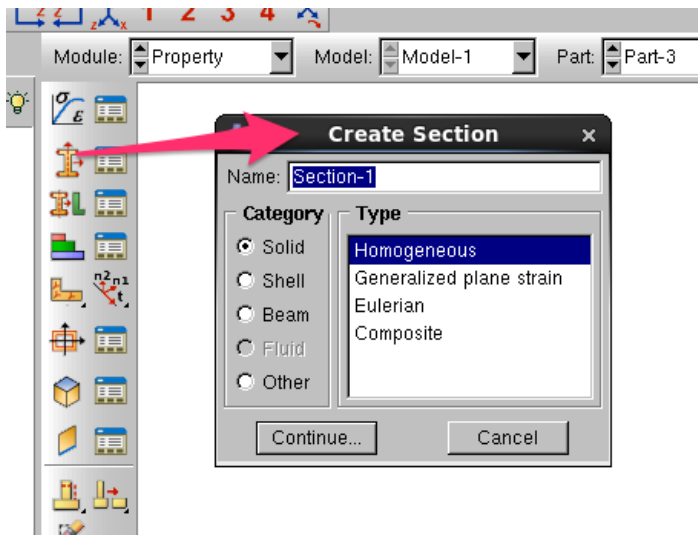
Data

	μ	λ	D
1	237822.383	4.3888	0

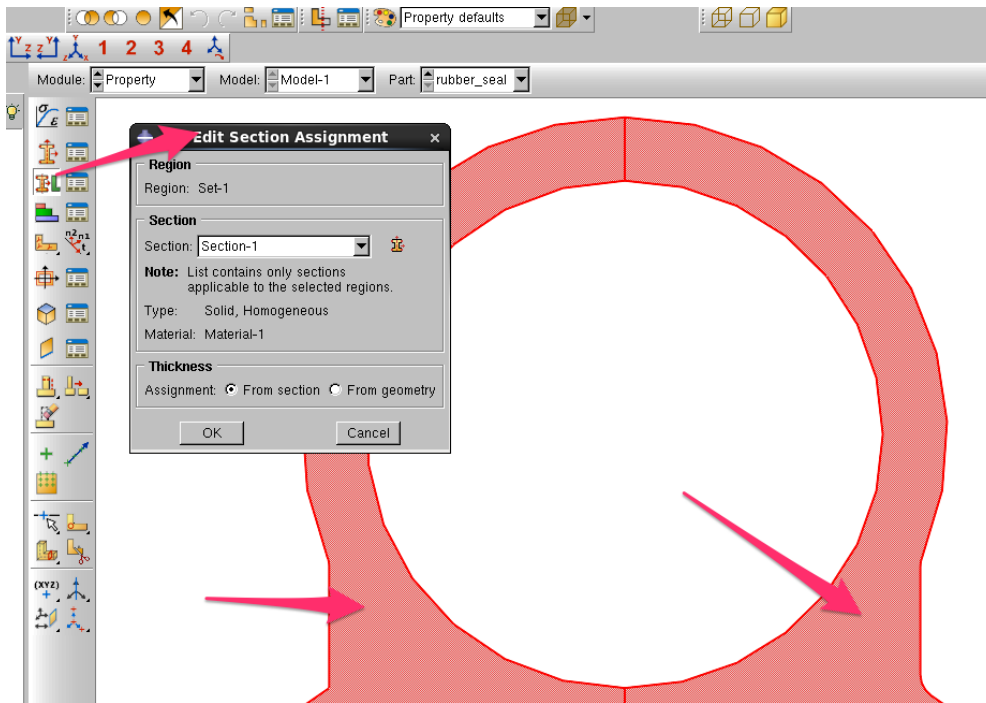
OK Cancel

4. Create and Assign Sections

Create a solid homogeneous section

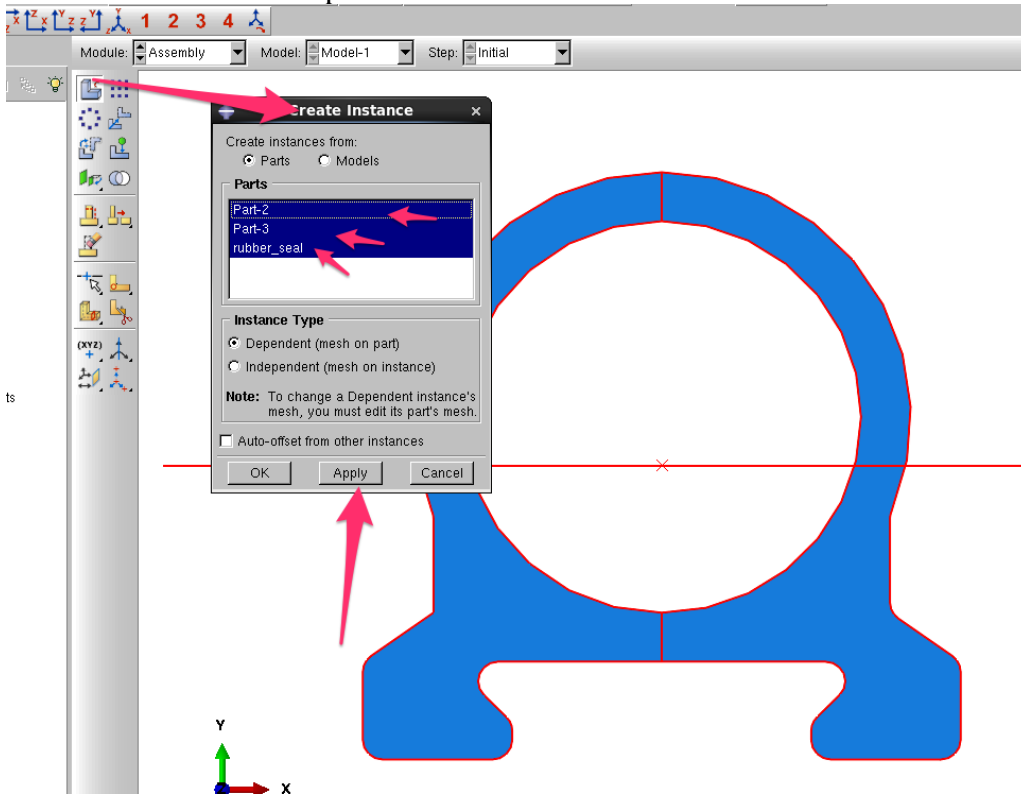


Assign section:

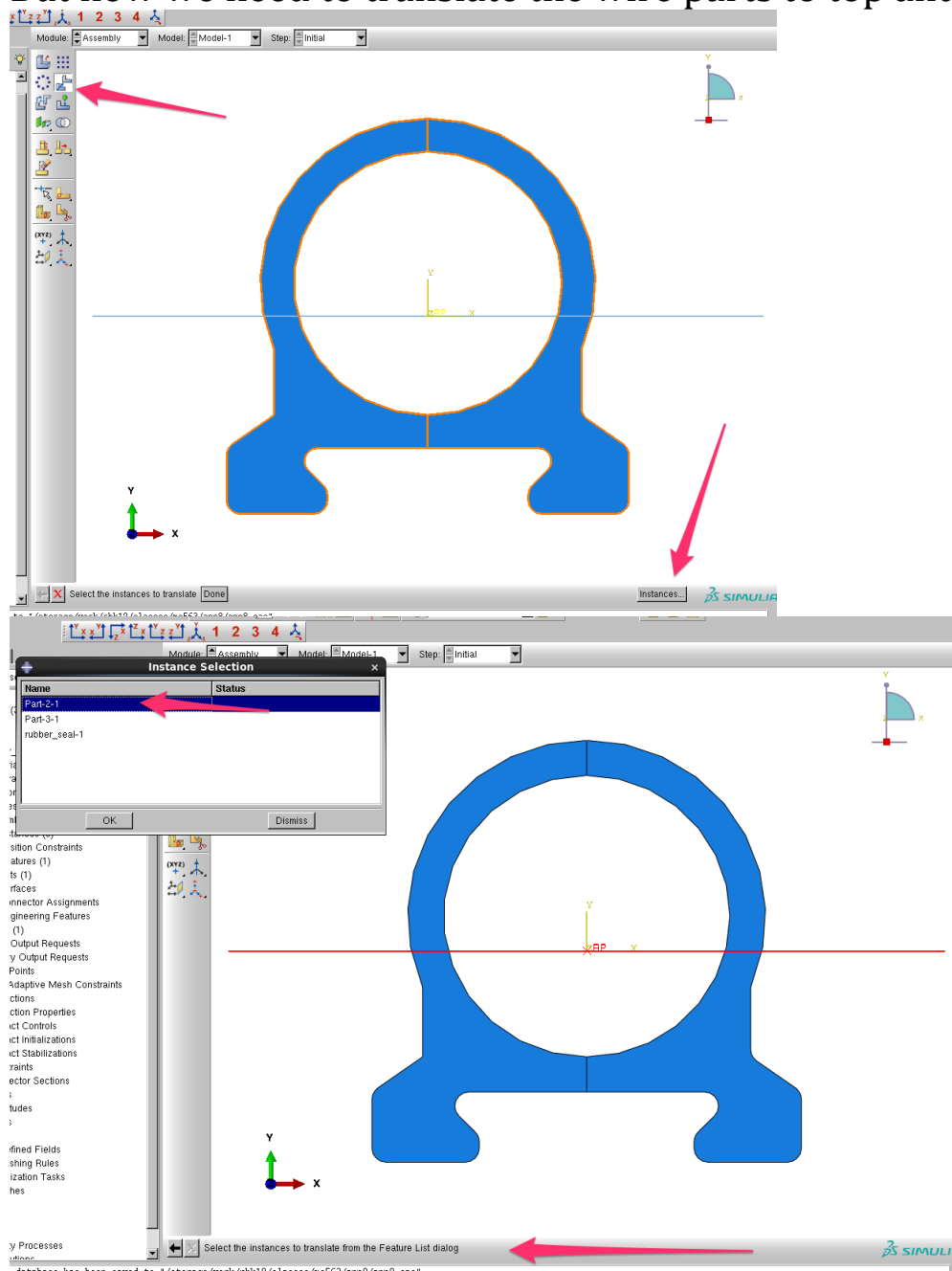


5. Assembly

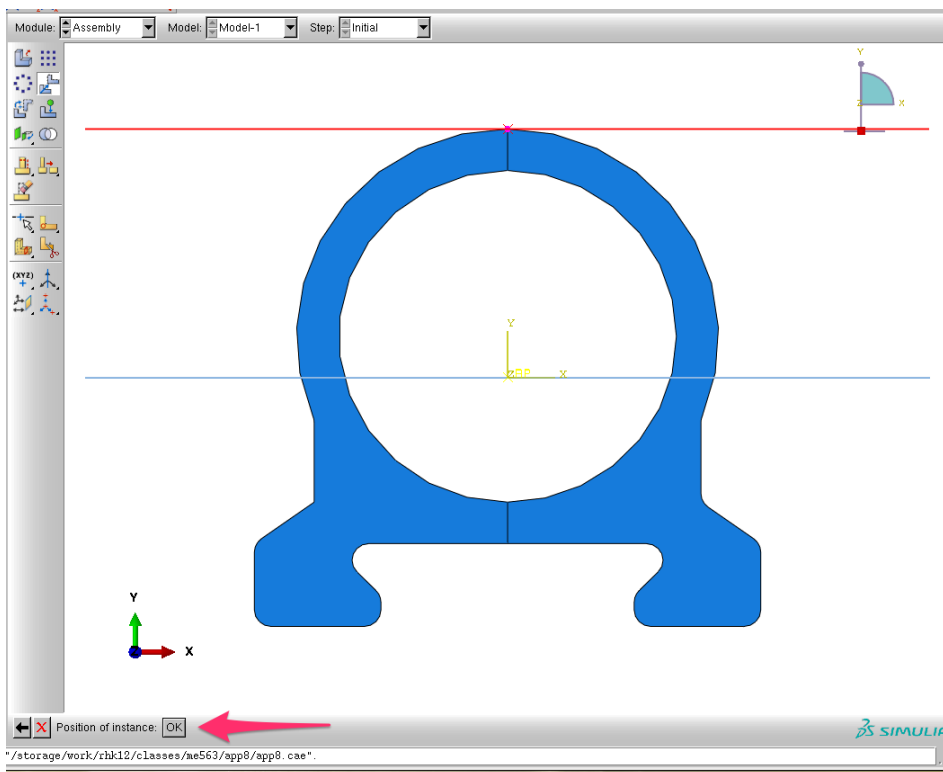
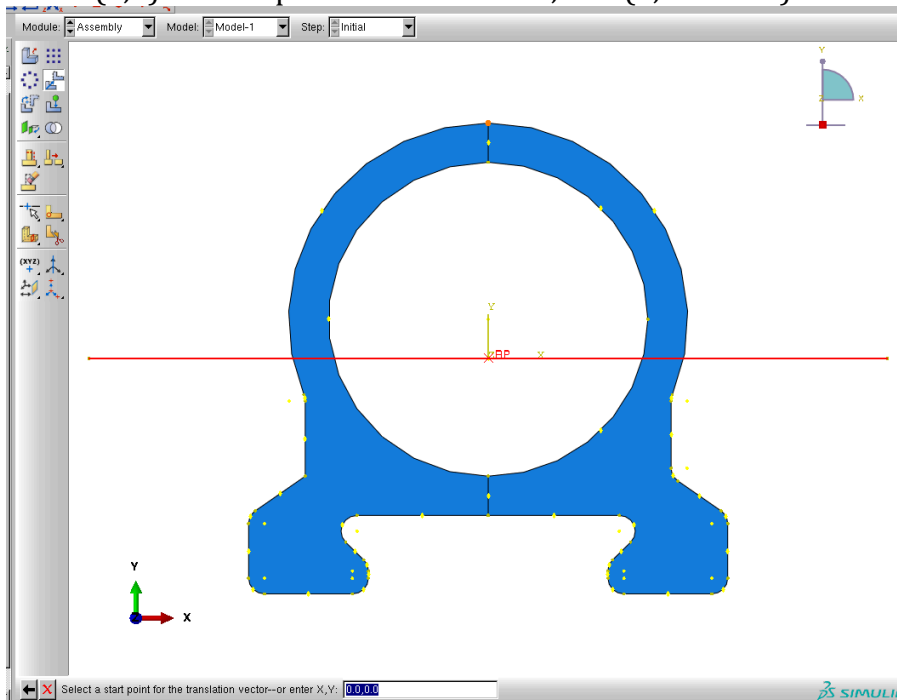
Create instances for all parts:



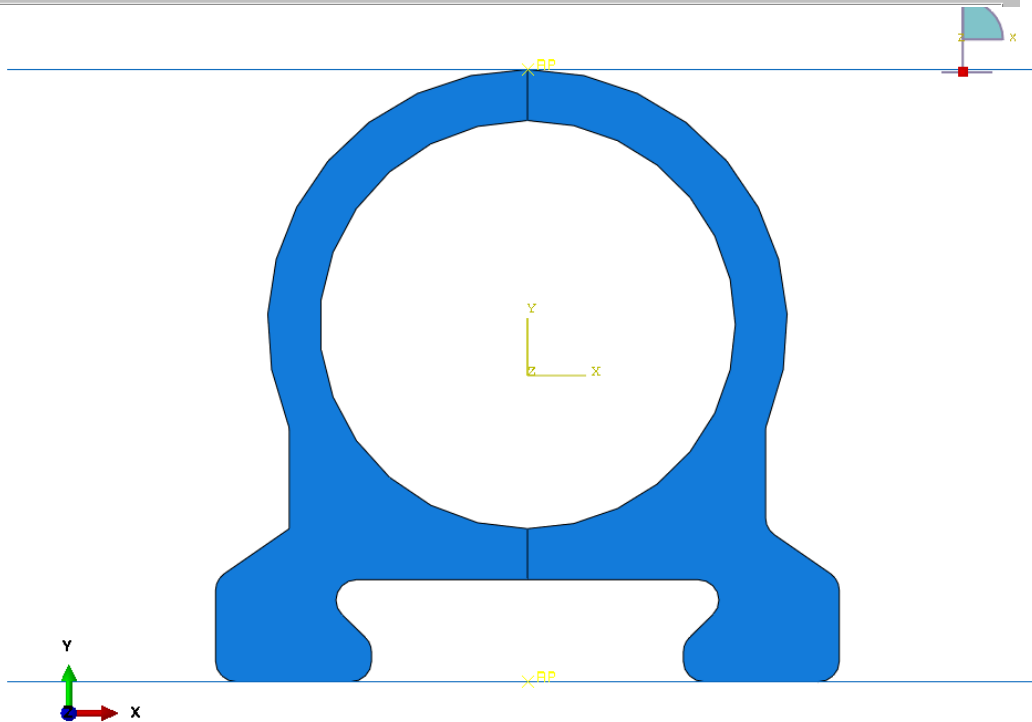
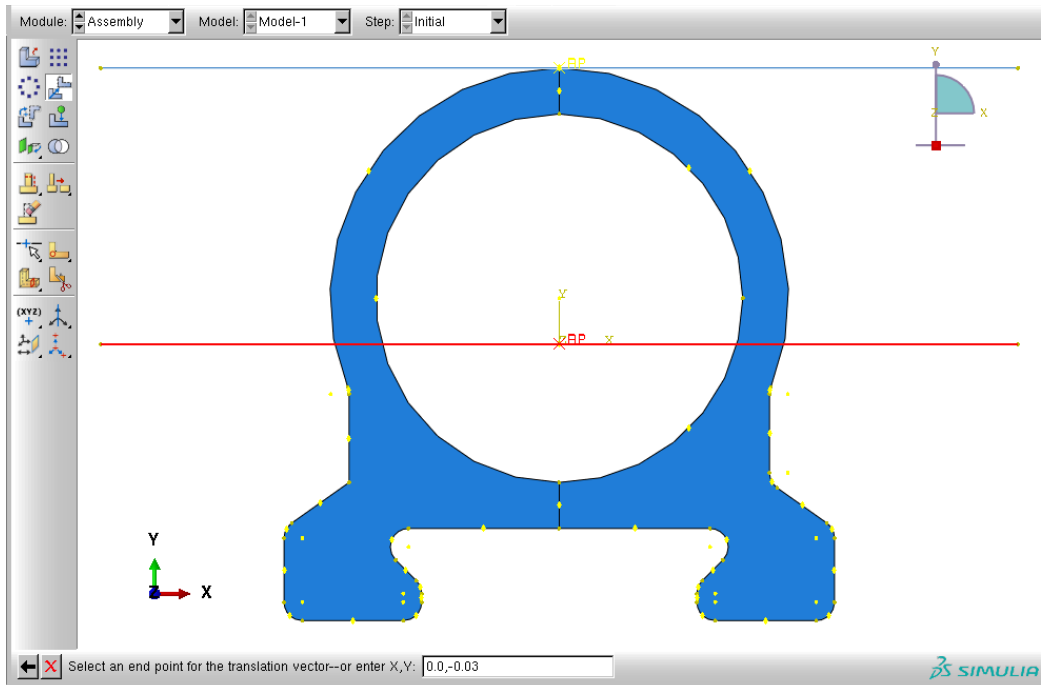
But now we need to translate the wire parts to top and bottom:



Select (0,0) as start point for translation, and (0, 0.03001) as the end point.

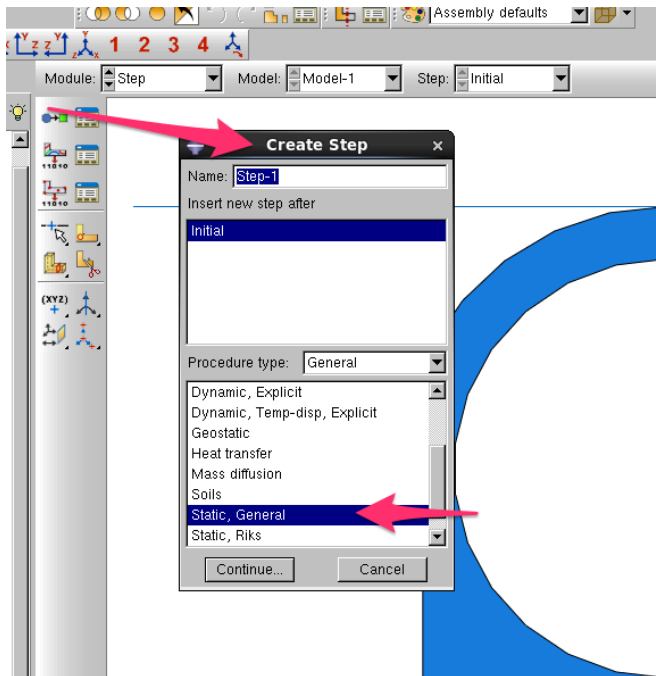


now do similar procedure to move the other wire to the bottom. You will want to translate the part -0.030 in y-direction:

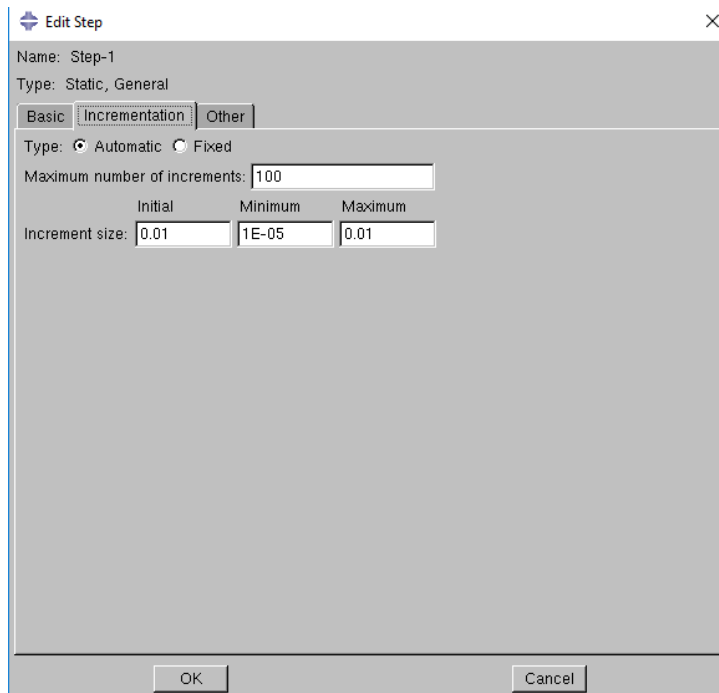


6. Create Step

Make a static step with nlgeom on.

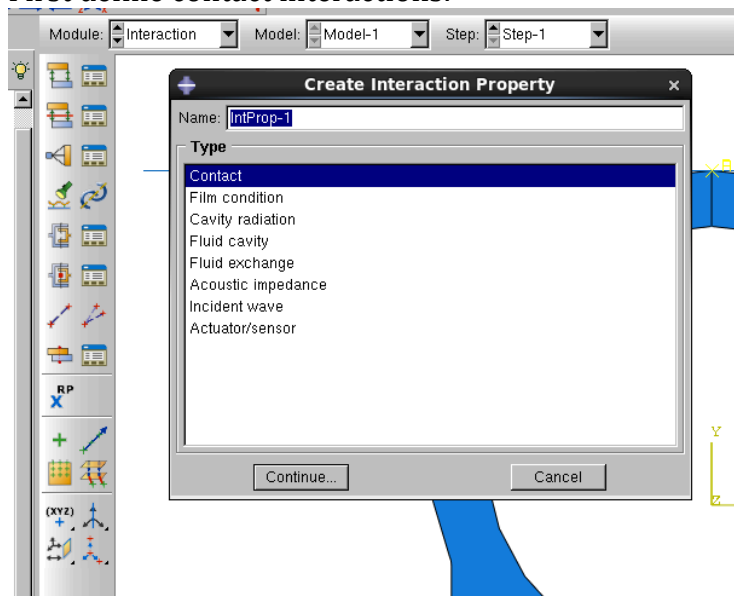


Adjust increment size to increase our number of plot steps and help with the NR convergence:

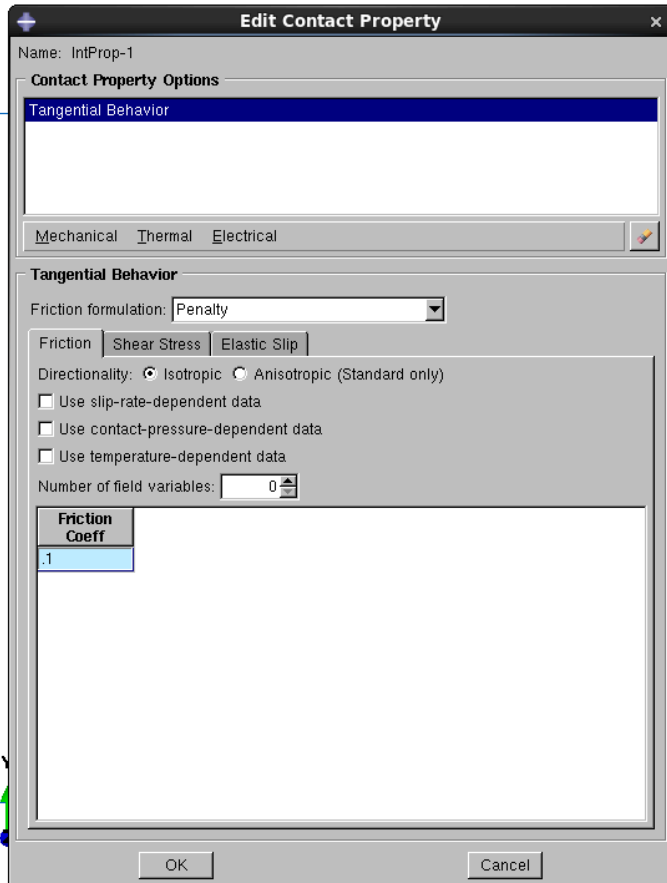


7. Define Contact Interactions

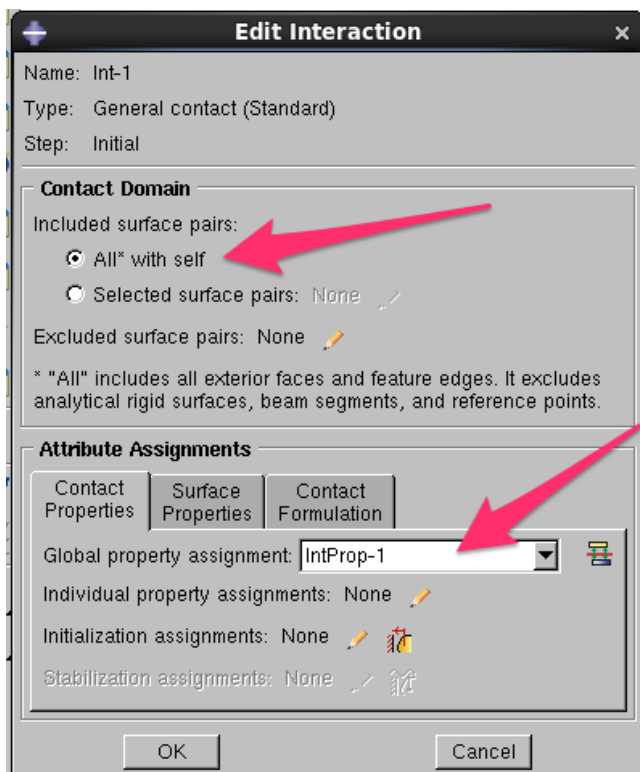
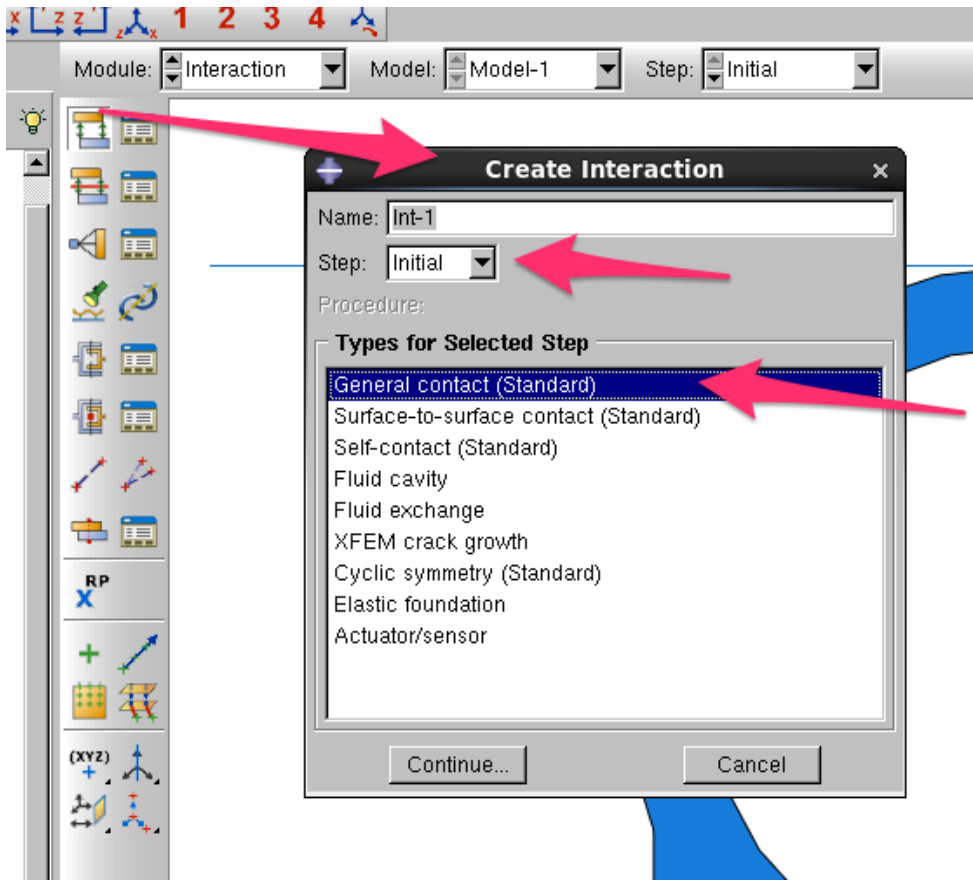
First define contact interactions:



Define a tangential friction behavior using a penalty formulation:

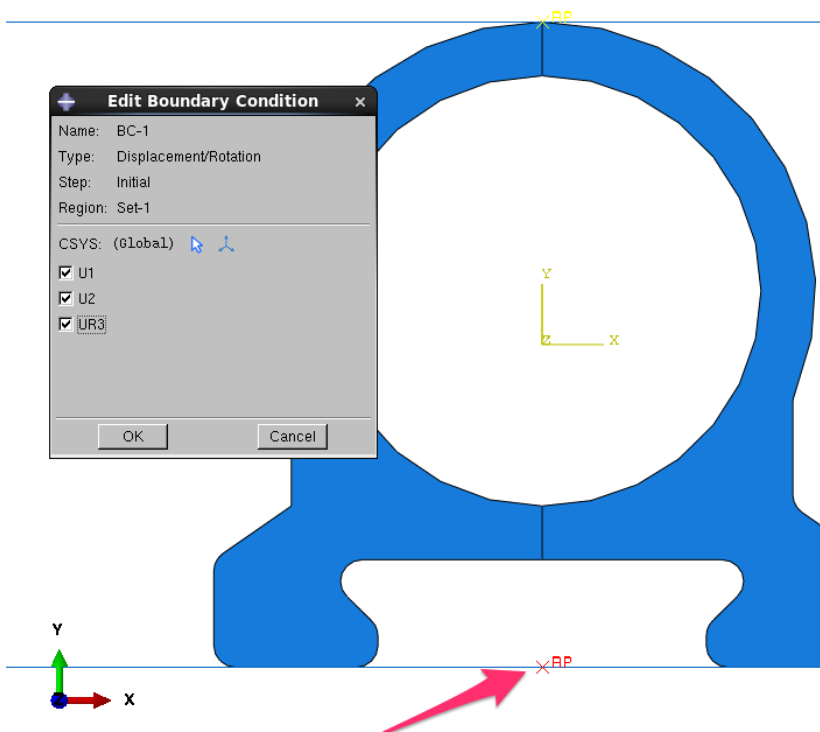
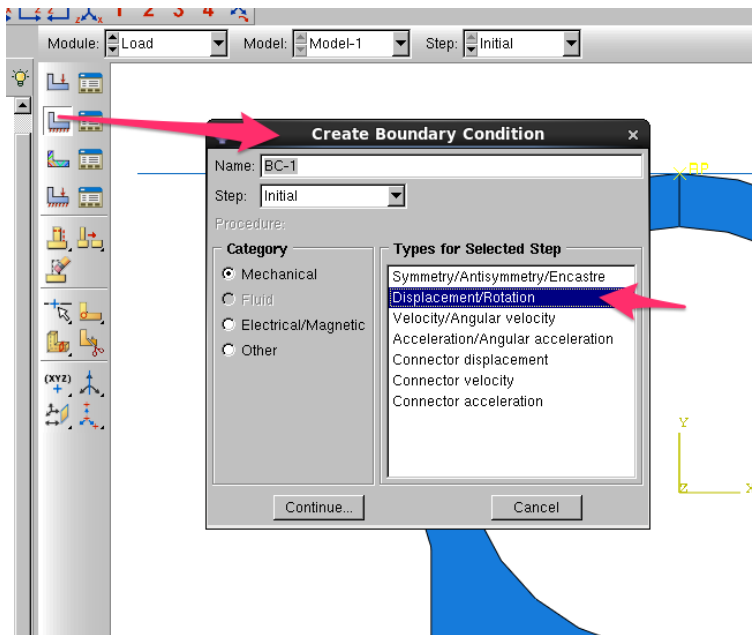


Create the interaction:

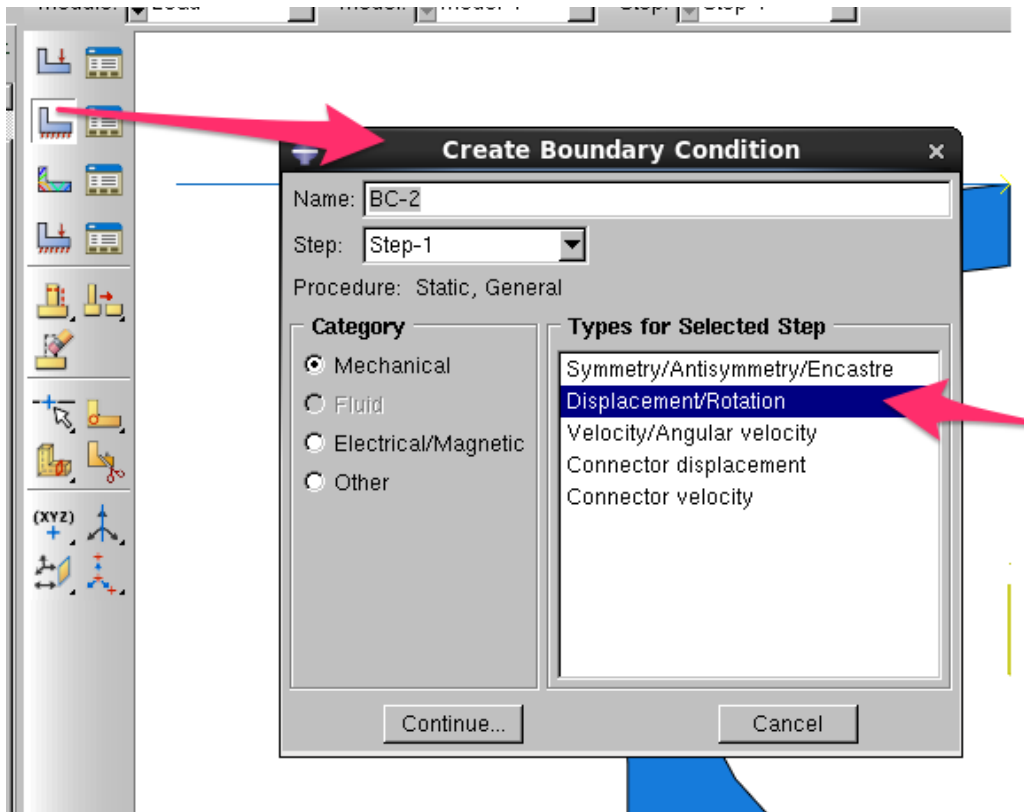


8. Define Loads and BCs

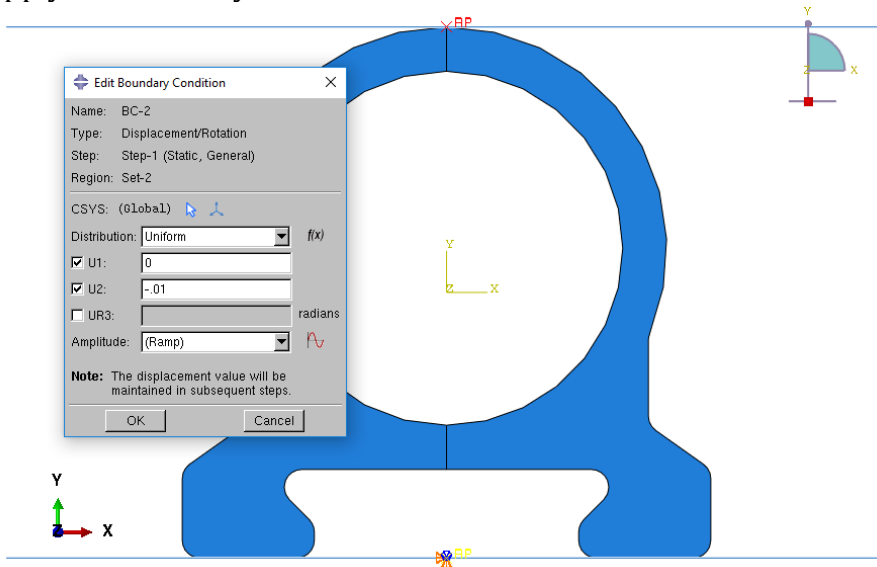
Create a boundary condition fixed on bottom wire:



Apply negative displacement and **constrain in the x-direction** to top wire:

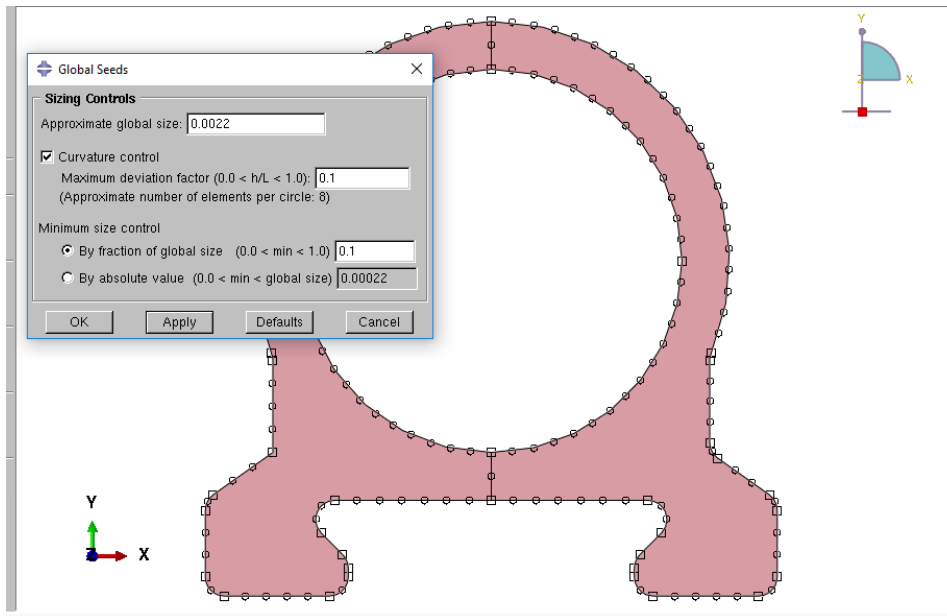


Apply -0.01 in the y-direction:

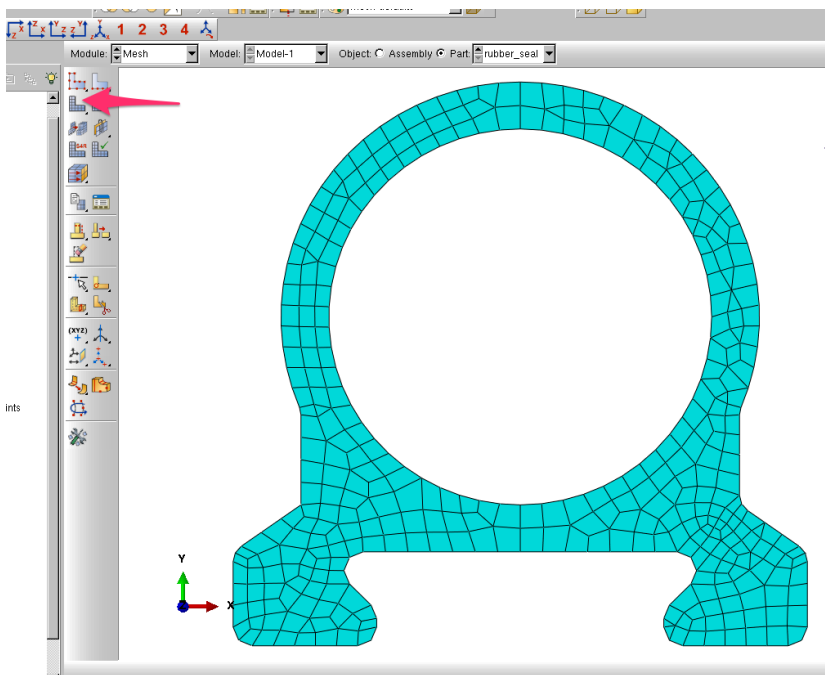


9. Mesh the Parts

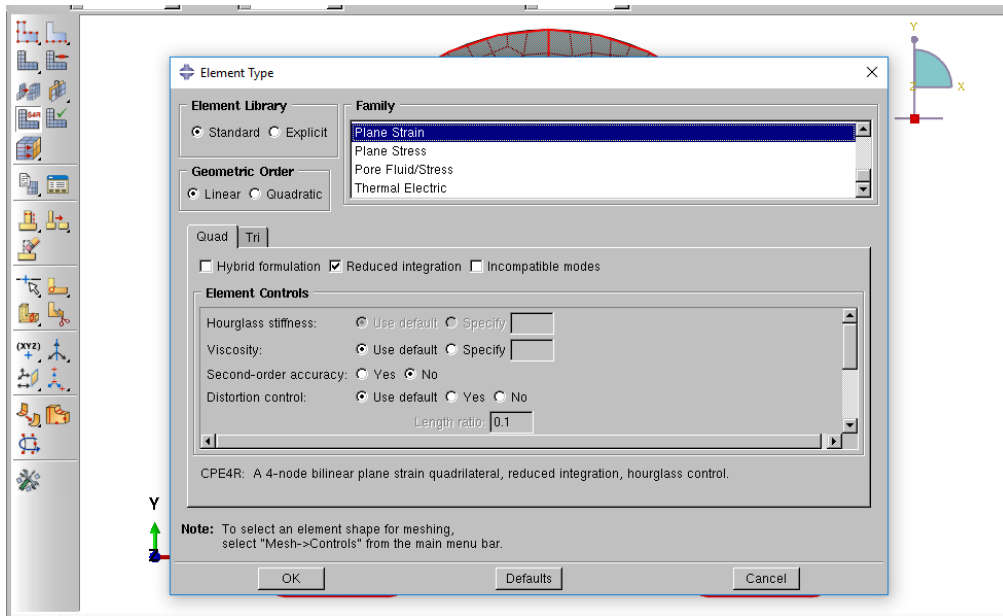
Take the defaults for the mesh:



And mesh:

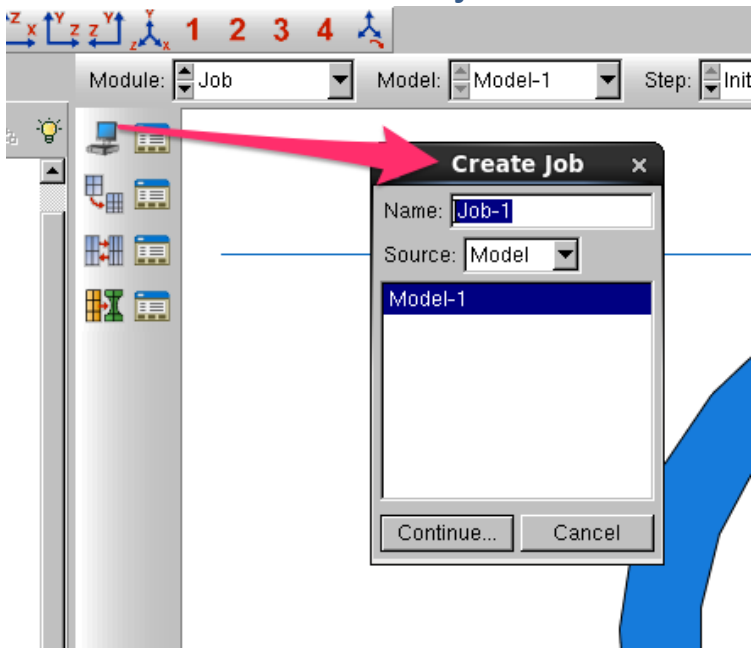


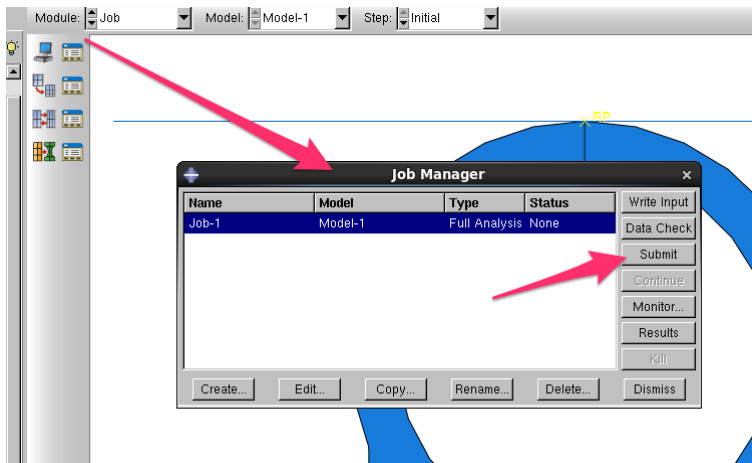
Be sure to select plane strain elements at element type:



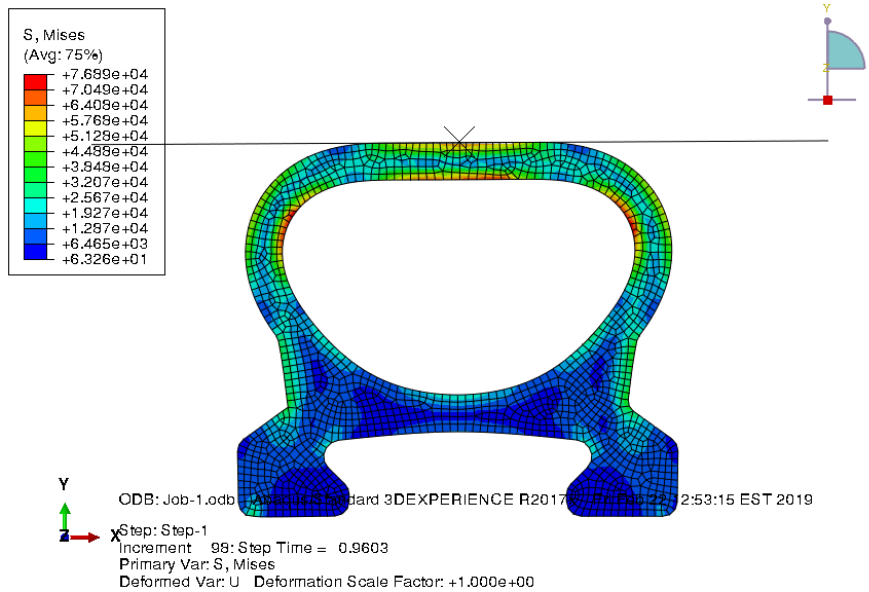
Mesh the wires with the defaults as well.

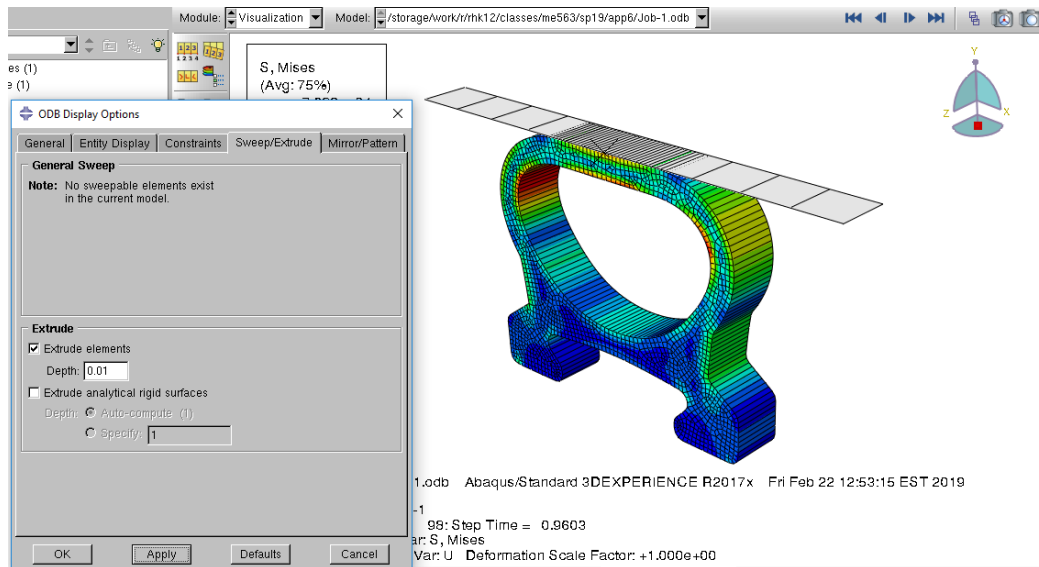
10. Create a simulation job





11. Visualize Results





12. Other items to consider:

- **Energy of system**
 - Can you plot it and show that energy is conserved?
- **Modify mesh density**
 - Do we have a converged solution?
 - Are there certain element types that exhibit locking or hourglassing in this problem?