

Richard Hu

☎ (647) 995-9055 | ✉ richie.hu@mail.utoronto.ca | 📱 rhklite

Education

University of Toronto

Master of Applied Science, Mechanical Engineering

Specialization Mechatronics, Mobile Robotics, Machine Learning

Toronto, Canada

Sep. 2019 - Expected Sep 2020

University of Toronto

Bachelor of Applied Science, Mechanical Engineering

Specialization Robotics and Mechatronics Minor; GPA (3.81/4.00)

Toronto, Canada

Sep. 2013 - Apr. 2018

Experience

Autonomous System and Biomechatronics Lab

Researcher, Master Thesis

Toronto, Ontario

Sep. 2018 - Present

- **Autonomy** Designed a mobile robot platform for urban search and rescue in ROS and C++
- **Machine Learning** Developed a deep reinforcement learning network and virtual-to-real transfer pipeline
- **Localization** Implemented lidar and vision based SLAM for real time pose estimation
- **Control** Optimized a robust motion controller for rough terrain navigation
- **Deployment** In house experimental testing with autonomous point to point navigation

aUToronto - SAE AutoDrive Challenge (2018, 2019 Winner)

Planning and Control Team

Toronto, Ontario

Sept. 2018 - Present

- **Autonomy** Aim to develop a level 4 autonomous vehicle using ROS and C++; team of 30+ students
- **Localization** Implemented real-time kinematics GPS for precision localization
- **Planning** Optimize trajectory planner for real time performance
- **Simulation** Evaluation of planning and control system using kinematics and dynamics model

Toward Smart Cities: Road Accident Prevention

Course Project

Toronto, Ontario

Sep. 2018 - Dec. 2018

- **Smart City** Data-driven accident prediction using scikit-learn in Python; team of 5 students
- **Data Engineering** Data collection, visualization, feature engineering, and negative sampling
- **Machine Learning** Trained and benchmarked 3 supervised learning models: Random Forest, SVM, and Deep Neural Network

Autonomous Turtlebot

Course Project

Toronto, Ontario

Jan. 2018 - Sep. 2018

- **Mapping** Developed robot coverage and exploration algorithm using ROS and C++
- **Computer Vision** Object detection and identification using OpenCV library
- **Social** Implemented person-following and emotional model for human-robot interaction

Autonomous Maze Navigation Rover Design

Course Project

Toronto, Ontario

Sep. 2017 - Dec. 2017

- **Autonomy** Implemented localization, collision avoidance, and path planning algorithm in MATLAB and Arduino
- **Control** Designed architecture for autonomous payload pick-up and delivery in a maze

Conavi Medical - Novasight Hybrid System

Mechanical Engineer Intern

Toronto, Ontario

May. 2016 - Aug. 2017

- **Research** Investigated potential design hazards and risks of catheter rotary assembly
- **Manufacturing** Streamlined an efficient assembly and calibration work instruction
- **Organisation** Established a inventory system with full traceability for FDA 510k submission validation
- **Project Management** Directed technical design reviews with senior leadership; accelerated the exit of the project phase

Honors & Awards

All Terms **Dean's Honour list**, University of Toronto

Toronto, Ontario

2018 **Best Undergraduate Poster Presentation**, CFD Society of Canada

Winnipeg, Manitoba

2015 **University of Toronto Excellence Award**, University of Toronto

Toronto, Ontario

2015 **Shell Canada Limited Engineering Scholarship**, University of Toronto

Toronto, Ontario

2015 **Best Innovation Award and Best Prototype Award**, U of T Engineering Competition Junior Design

Toronto, Ontario