Richard Hu

(647) 995-9055 | richie.hu@mail.utoronto.ca | rhklite

Experience

Autonomous System and Biomechatronics Lab *Toronto, Ontario*

Research *Sept. 2018 - Present*

- **System** Designed an entire autonmous mobile robot system architecture using ROS and C++
- **SLAM** Implemented Lidar based and vision based SLAM for autonomous navigation
- **Control** Developed position controller and velocity controller for skid steer control
- **Reinforcement Learning** Sim to real transfer of learned policy onto the autonomous mobile platform for rough terrain navigation

Conavi Medical *Toronto, Ontario*

Mechanical Design Intern - Novasight Hybrid System *May. 2016 - Aug. 2017*

- **Design** Designed components that were critical to patient safety using MATLAB and SolidWorks
- **Research** Investigated potential design hazards and risks for ensuring patient safety
- **Manufacturing** Fabricated catheter manufacturing jigs and drafted assembly work instructions
- **Reviews** Directed major technical design reviews with senior leadership. Led to accelerated progress and exit of project phase
- **Management** Established a management system with full traceability, gaureeted validity of 510k submission to FDA

Projects

aUToronto - AutoDrive Challenge *Toronto, Ontario*

Mapping and Localization Team *Sept. 2018 - July. 2019*

- **Mapping** Processed semantic map using python, QGIS and Open Street Map
- **Localization** Implemented real-time kinematics GPS system for localzation

Toward Smart Cities: Data-driven Road Accident Prevention *Toronto, Ontario*

Data Scientist *Sept. 2018 - Dec. 2018*

- **Machine Learning** Implemented SVM, Random Forest, and Deep Neural Network model for road accident prediction using Sklearn
- **Data Engineering** Processed weather, traffic, and geography data; performed feature-engineering and negative sampling

Pico-Scale Hydro Turbine Design *Toronto, Ontario*

Mechanical Design *Jan. 2018 - Sept. 2018*

- **Design** Designed and tested a variable guide vane for pico-scale hydro turbine using Solidworks and ANSYS CFX
- **Prototype** Built the pico-scale turbine and pressurized pipeline test rig

Autonomous Maze Navigation Rover Design *Toronto, Ontario*

Software Development & System Design *Sept. 2017 - Dec. 2017*

- **Autonomy** Implemented localization, obstacle detection, and path planning in MATLAB and Arduino
- **System** Designed architecture for autonomous payload pick-up and delivery in a maze

Honors & Awards

2018	**Best Undergraduate Poster Presentation**, CFD Society of Canada	*Winnipeg, Ontario*
All Terms	**Dean's Honour list**, University of Toronto	*Toronto, Ontario*
2015	**University of Toronto Excellence Award**, University of Toronto	*Toronto, Ontario*
2015	**Shell Canada Limited Engineering Scholarship**, University of Toronto	*Toronto, Ontario*
2015	**Best Innovation Award and Best Prototype Award**, U of T Engineering Competition Junior Design	*Toronto, Ontario*

Education

University of Toronto *Toronto, Canada*

Master of Applied Science, Mechanical Engineering *Sept. 2019 - April Present*

Research Learning based rough terrain navigation for mobile robots research at Autonomous Systems and Biomechatronics Lab

University of Toronto *Toronto, Canada*

Bachelor of Applied Science, Mechanical Engineering, With Distinction - Dean's Honours List *Sept. 2013 - April 2018*

Specialization Mechatronics Stream and Bioengineering Stream, Robotics and Mechatronics Minor. GPA (3.81/4.00)