



# Computer Science and Computer Engineering (CS)

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## Characterization of Objects in Indoor Spaces of Human Occupation Using Knowledge Graphs

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# Object Detection

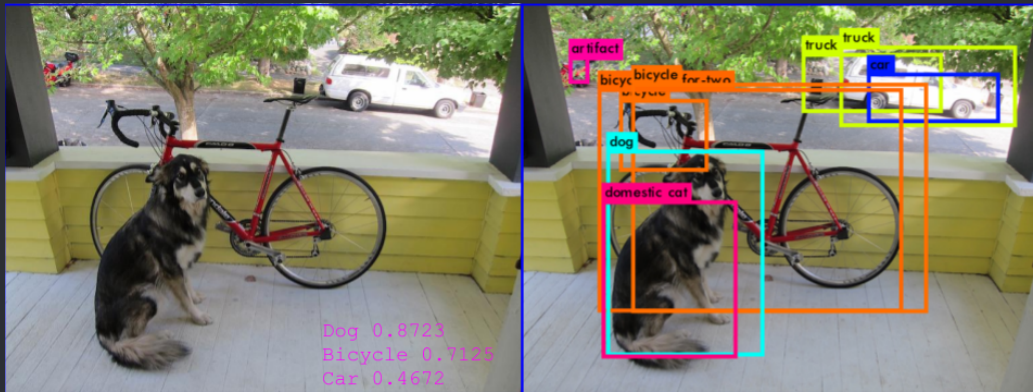
## *Characteristics*

Object detection has *two* main tasks:

- Image classification.
- Object localization.

# Object Detection

## *Object localization*



# Object detection

\*-CNN

## R-CNN: *Regions with CNN features*

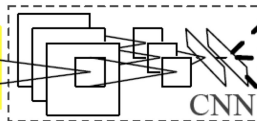


1. Input image



2. Extract region proposals (~2k)

warped region



3. Compute CNN features

aeroplane? no.

⋮

person? yes.

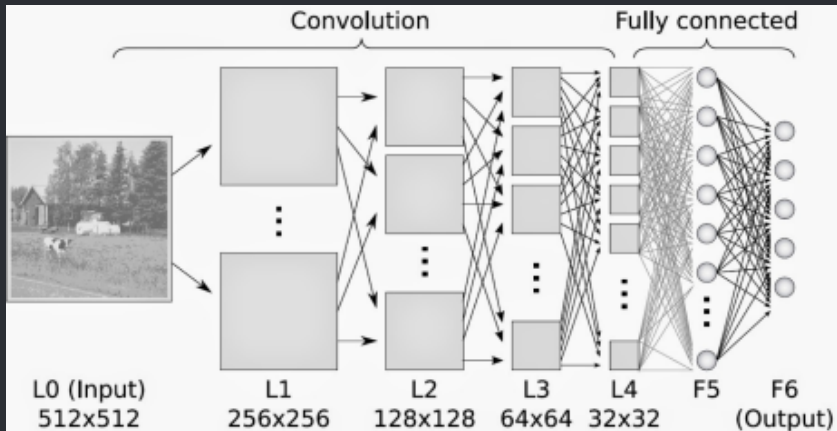
⋮

tvmonitor? no.

4. Classify regions

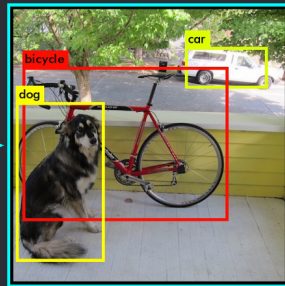
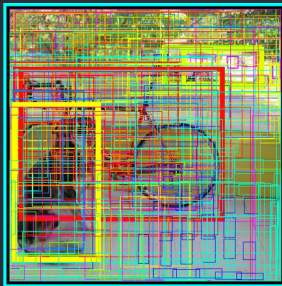
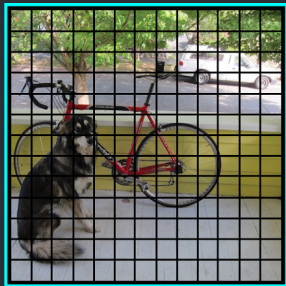
# Object detection

## Convolutional Layer



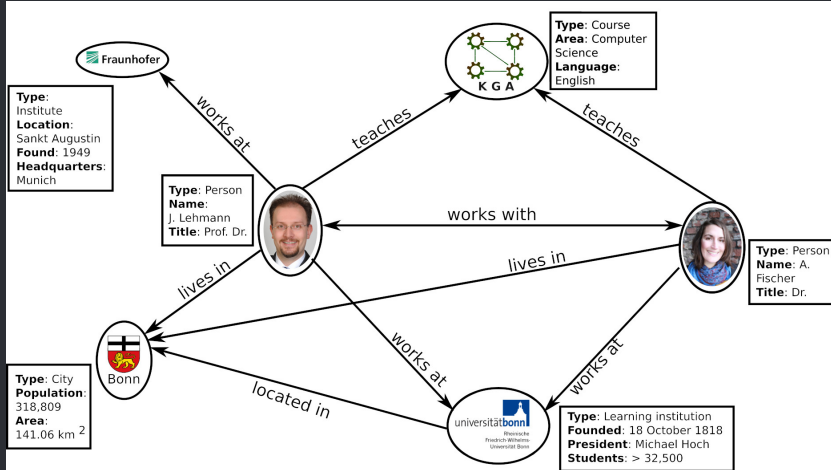
# Object detection

*YOLOv2 model*



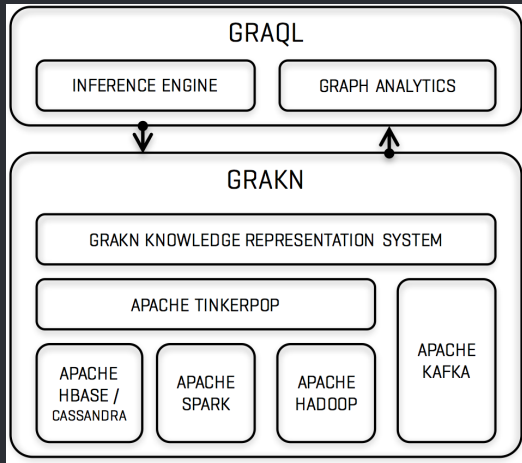
# Knowledge graph

## Example case



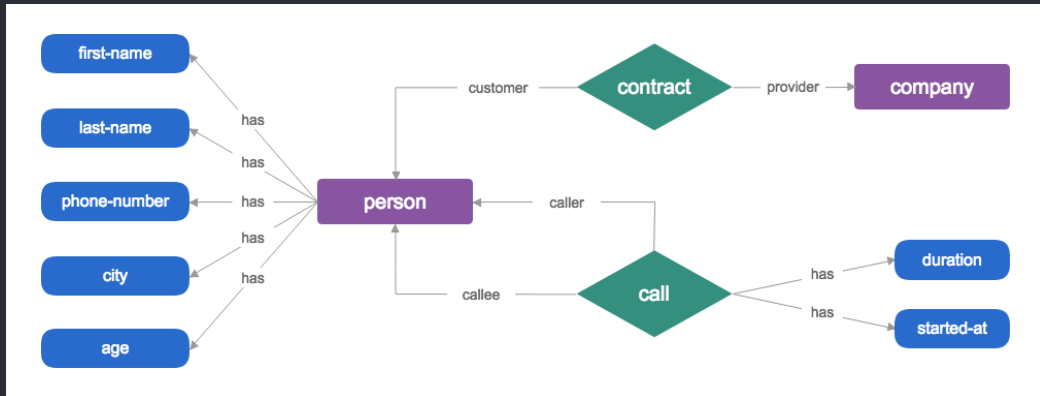
# Grakn

## Architecture





# Grakn Schema



# Grakn

## DDL & DML

### DATA DEFINITION

DEFINE	<code>define schema_statement+;</code>
UNDEFINE	<code>undefine schema_statement+;</code>

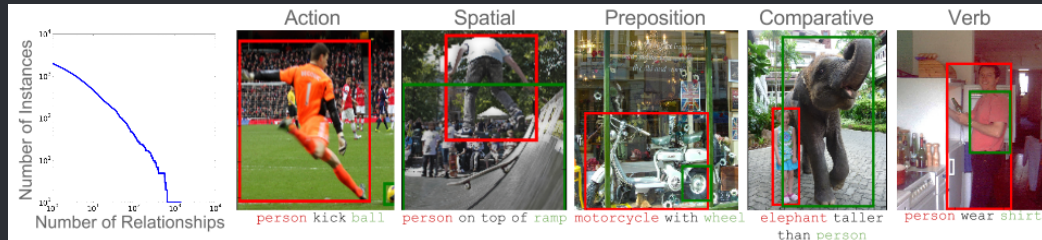
### DATA MANIPULATION

GET	<code>match pattern+; get variable*; modifiers*;</code>
DELETE	<code>match pattern+; delete variable*; modifiers*;</code>
INSERT	<code>[match pattern+;] insert instance_statement+;</code>
GROUP	<code>match pattern+; get variable*; group variable; [count;]</code>
AGGREGATE VALUES	<code>match pattern+; get variable*; aggregate_function variable;</code>
COMPUTE ANALYTICS	<code>compute condition+;</code>

`one_or_more*` `zero_or_more*` `[optional]`

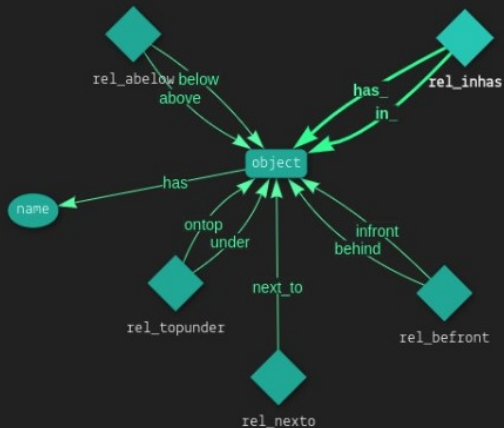
# Solution

## *Types of semantic relationships*



## Solution

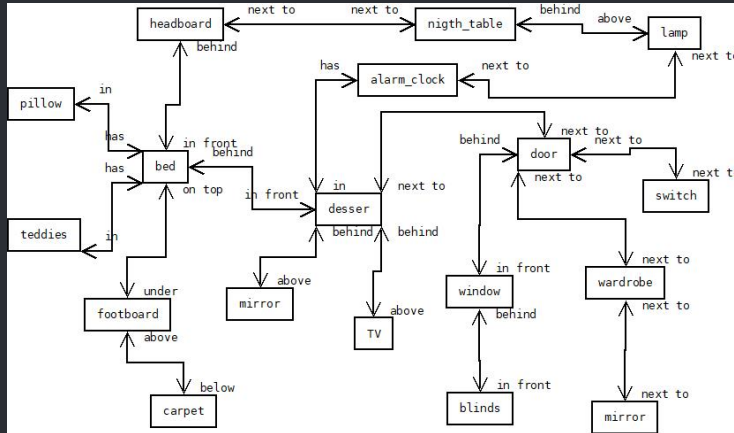
*Predicates of the semantic relationships types*



# Solution

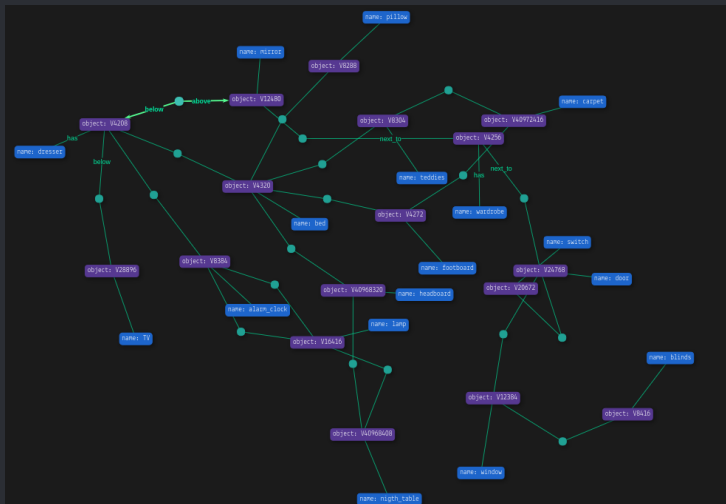
## Relationships draft

The following figure shows a draft of all the relationships recover from our study object.



# Solution

Graph generate with Grakn



## Solution

*Graph generate with Grakn*



## Conclusions

- We show that it is possible to create a knowledge graph from the semantic relationships that occur in an indoor space of human occupation
- The most accurate predicate, in our scenario for binding two objects is the *spatial* relationship.
  - Indeed, in most localization scenarios this predicate is the most accurate because the other produces so many combinations.
- Grakn is a very outstanding tool to create knowledge graph with a given list of predicates.
  - Grakn even offers the possibility of making *machine reasoning* from the data input.
- We seek to create complementary datasets that will help convolutional layer neural network to reduce processing time.