Devin T. Schwab

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Objective: Push the boundaries of robot software and artificial intelligence

Education: Aug 2009 – Aug 2014

Case Western Reserve University

Cleveland, OH

- BSE in Electrical Engineering, Summa Cum Laude
- BS in Computer Science, Summa Cum Laude
- Minor in Japanese with multiple study abroad programs in Tokyo for Japanese language
- GPA: 4.0
- Accepted into the B.S./M.S. program

Aug 2014 – Aug 2015

Case Western Reserve University

Cleveland, OH

- Masters in Computer Science
- GPA: 4.0
- Thesis: Hierarchical Sampling for Least-Squares Policy Iteration
- Adviser: Soumya Ray

Aug 2015 – Present Robotics Institute – Carnegie Mellon University Cleveland, OH

- Pursuing a PhD in Robotics
- GPA: 4.0
- Adviser: Manuela Veloso
- NDSEG Fellowship Recipient

Work Experience

Digidevin LLC – Cleveland, OH

Aug 2014 – Present – Created Business to Perform Software Development as a Service

• Contract to write end-user graphical user interface that interfaces with the customer's custom hardware device (under NDA, so specifics cannot be discussed)

The University of Hong Kong – Hong Kong

Feb. 2013 - Dec. 2013 - Research Associate with DARPA Robotics Challenge (DRC) Team

- Wrote software to complete the 8 DRC Trials tasks which included: walking, manipulation and driving using a humanoid robot named Atlas
- Developed software to provide robot interactions using devices such as the Kinect, the PC Move, Wiimote and the Leap Motion
- Wrote software to process data from the Carnegie Robotics Multisense Head
- Wrote software to control the Sandia National Laboratories' robotic hand
- Worked on team's software architecture for the competition.

NASA Glenn Research Center – Cleveland, OH

May 2011-Dec 2011 – Co-op Rotation with the System Engineering Branch

- Helped design the initial architecture of a space communications lab that will cut costs and decrease testing time when completed
- Wrote programs and did analysis on Thermal Vacuum Chamber Testing for the CoNNeCT project which will be sent to the ISS this year
- Provided software development advice to a new project team that is working on simulation software for space communications

June 2010 – Aug. 2010 – Internship with Space Communications and Navigation Department

- Designed communications subsystem for conceptual lunar satellite
- Published paper SCience Hybrid Orbiter and Lunar Relay (SCHOLR)
 Architecture and Design for AIAA SPACE 2010 Conference

June 2009 – Aug. 2009 – Internship with Space Communications and Navigation Department

 Used knowledge of networking and wireless technologies to analyze and design communication sub-system for Lunar sortie scenario

Skills

- Experienced in C++, Java, Python and Matlab
- Experienced with ROS framework
- Extensive experience with real robot hardware: Atlas, Nao, CoBots