Week 7:

* Initialize camera acquisition
  + Make camera device for stereoscopic image acquisition
* Image calibration (front view -> top view)
* Grass filter

Week 8:

* Line detection
* Identify barrels/cones
  + Using patterns
  + Using stereoscopic vision to detect spatial location
* Overflow

Week 9:

* Flag detection
* Report to robot (occupancy grid)
* Overflow

Week 10:

* Overflow week – we present on Monday so any time after that before Friday will be used to clean up and maybe make last-minute refinements