

PID TUNER **VIEW**

Plant: Plant Type: PIDF Domain: Time Form: Parallel Add Plot

Inspect Options

PLANT CONTROLLER DESIGN

Step Plot: Reference tracking

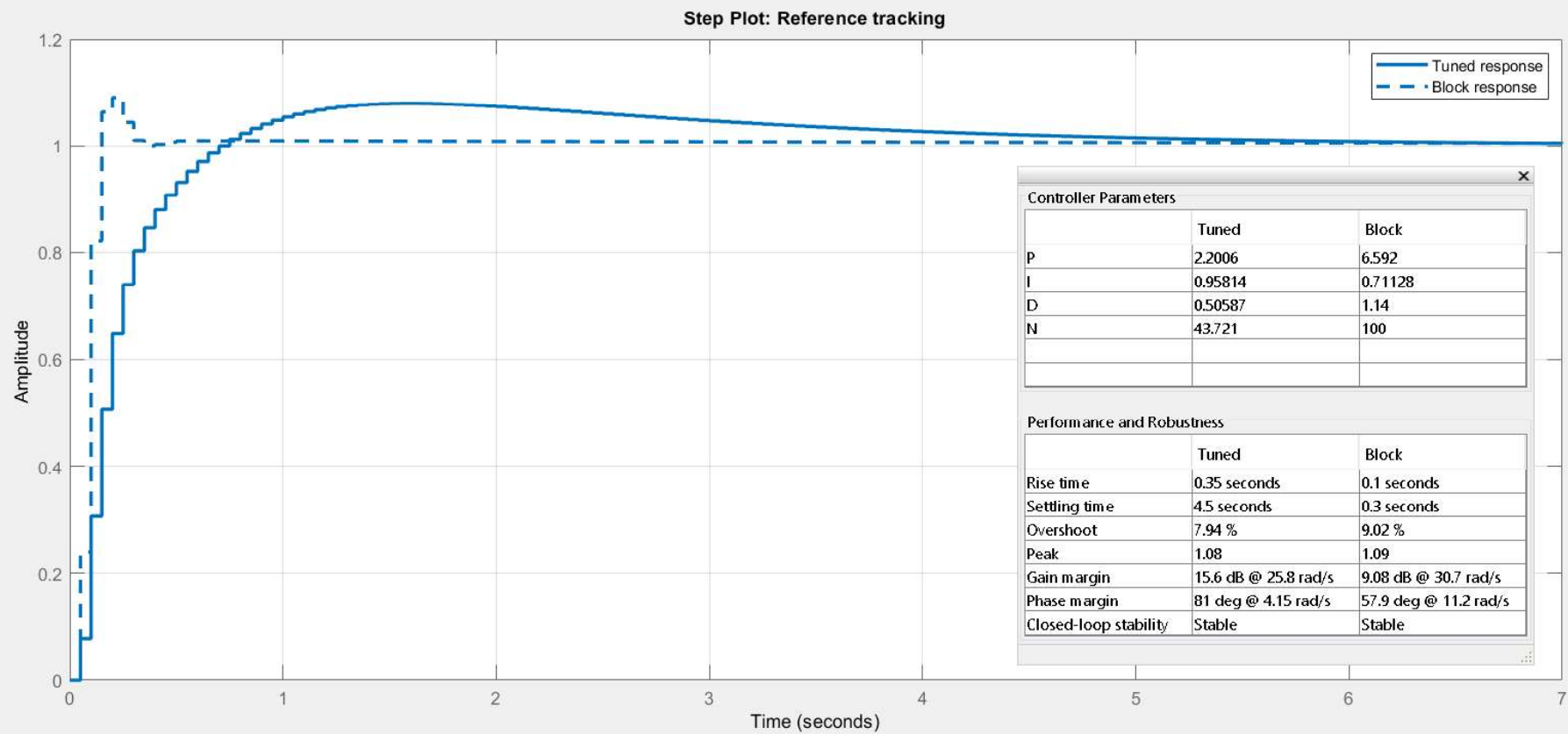
Slower Response Time (seconds) Faster 0.4816

Aggressive Transient Behavior Robust 0.81

TUNING TOOLS

Reset Design Show Parameters Update Block

RESULTS



Controller Parameters: P = 2.201, I = 0.9581, D = 0.5059, N = 43.72