

**PID TUNER** **VIEW**

Plant: Plant  
Type: PDF  
Form: Parallel  
Domain: Time  
Inspect Options Add Plot

PLANT CONTROLLER DESIGN

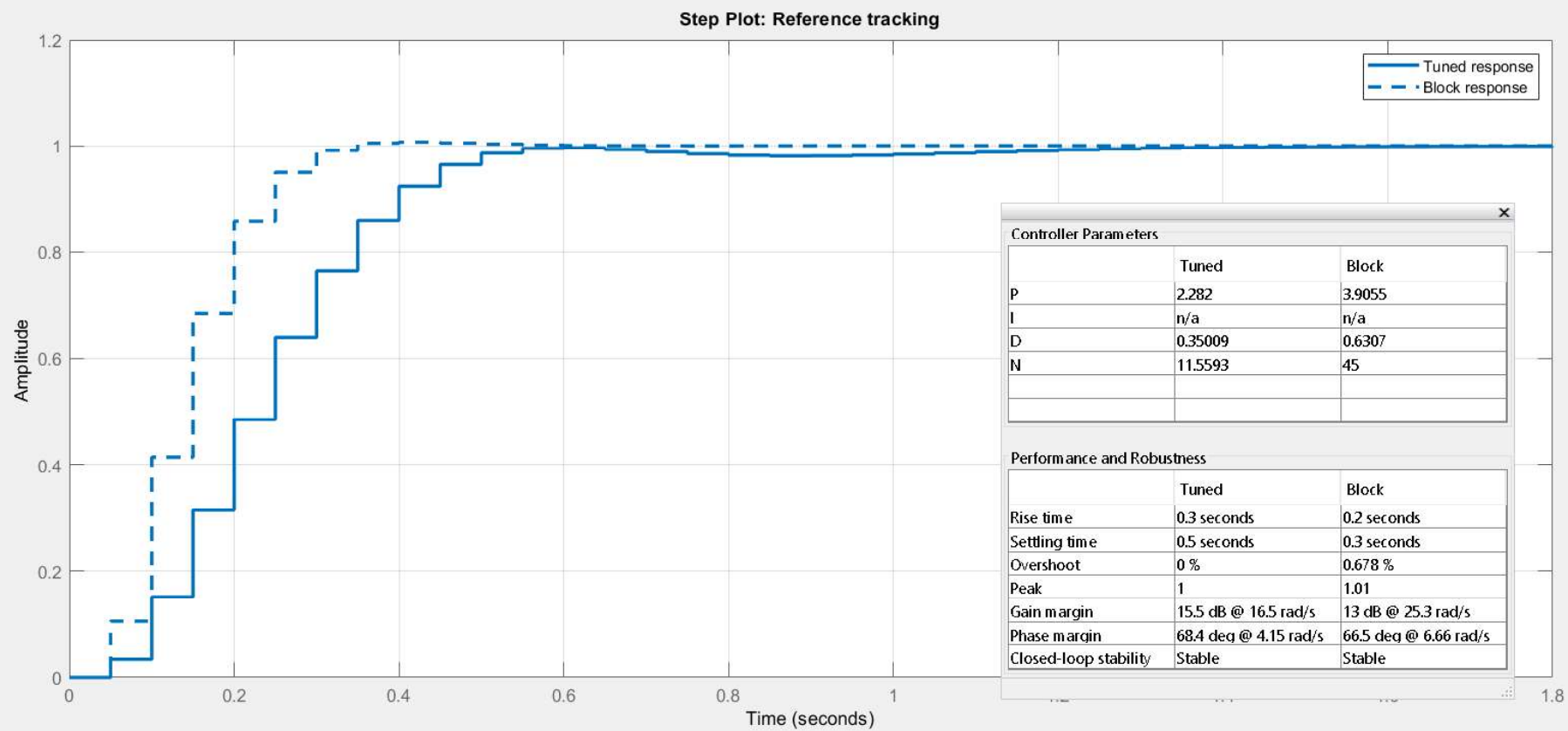
Slower Response Time (seconds) Faster  
Aggressive Transient Behavior Robust

0.4816  
0.684

Reset Design Show Parameters Update Block

TUNING TOOLS RESULTS

Step Plot: Reference tracking



Controller Parameters: P = 2.282, D = 0.3501, N = 11.56