

# CS156 - LBA - PCA

Tower Bridge, London, UK

In [1]:

```
1 import numpy as np #importing libraries
2 import matplotlib.pyplot as plt #for plotting
3 from glob import glob #for Loading files
4 from PIL import Image #for opening image
5 from sklearn.decomposition import PCA #for principal component analysis
```

In [2]:

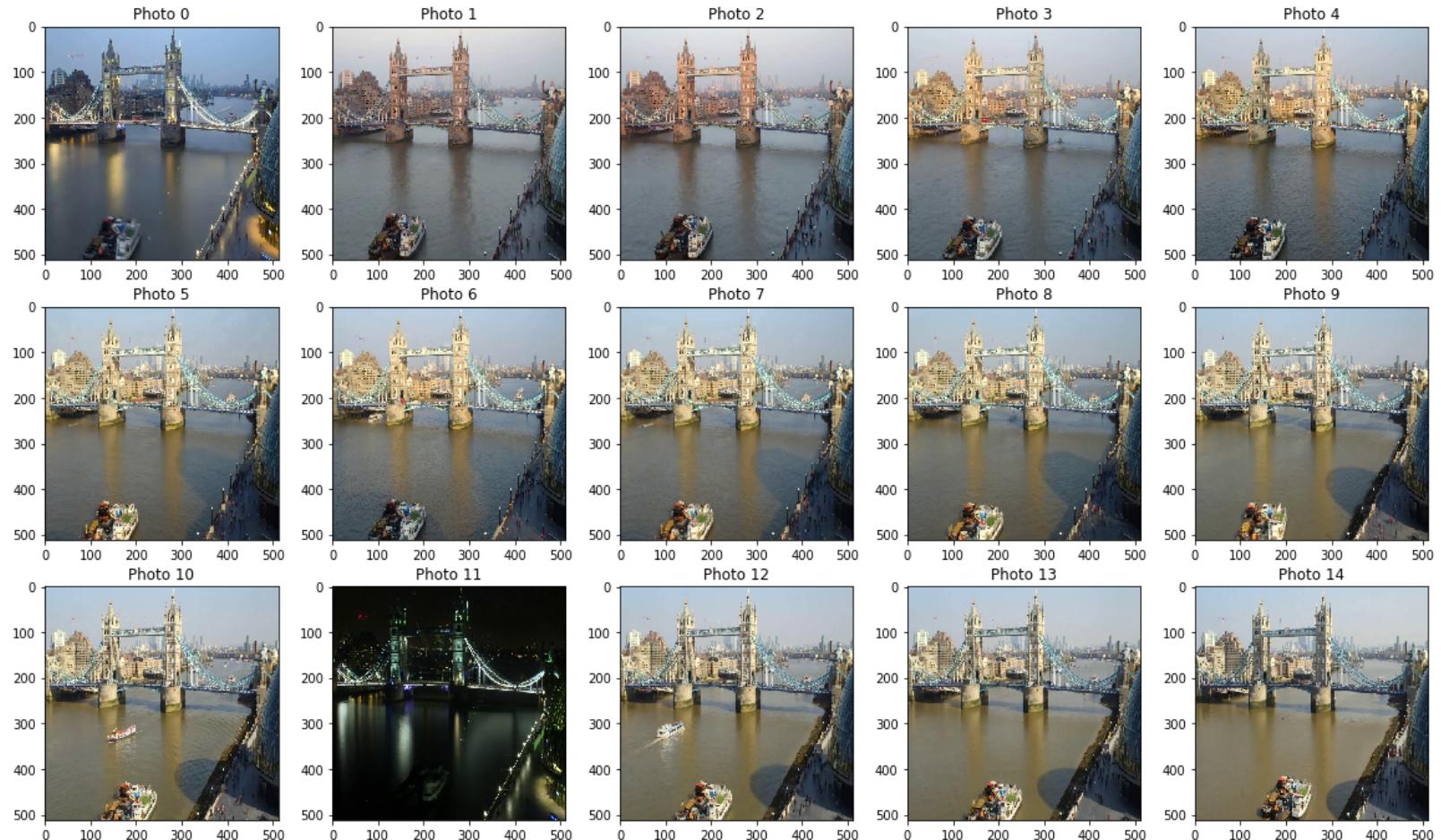
```
1 #####Data Loading & Preprocessing
2
3 #importing images
4 bridge = sorted(glob('bridge/*'))
5 print("Number of photos: ", len(bridge))
6
7 data = []
8
9 for im in bridge: #resizing to 512 X 512 px
10     pic = Image.open(im) #open image file
11     rsz = pic.resize((512, 512), Image.NEAREST) #nearest-neighbor-sampling
12     pics = np.array(rsz) #into array form
13     data.append(pics.flatten()) #flattening the array form
```

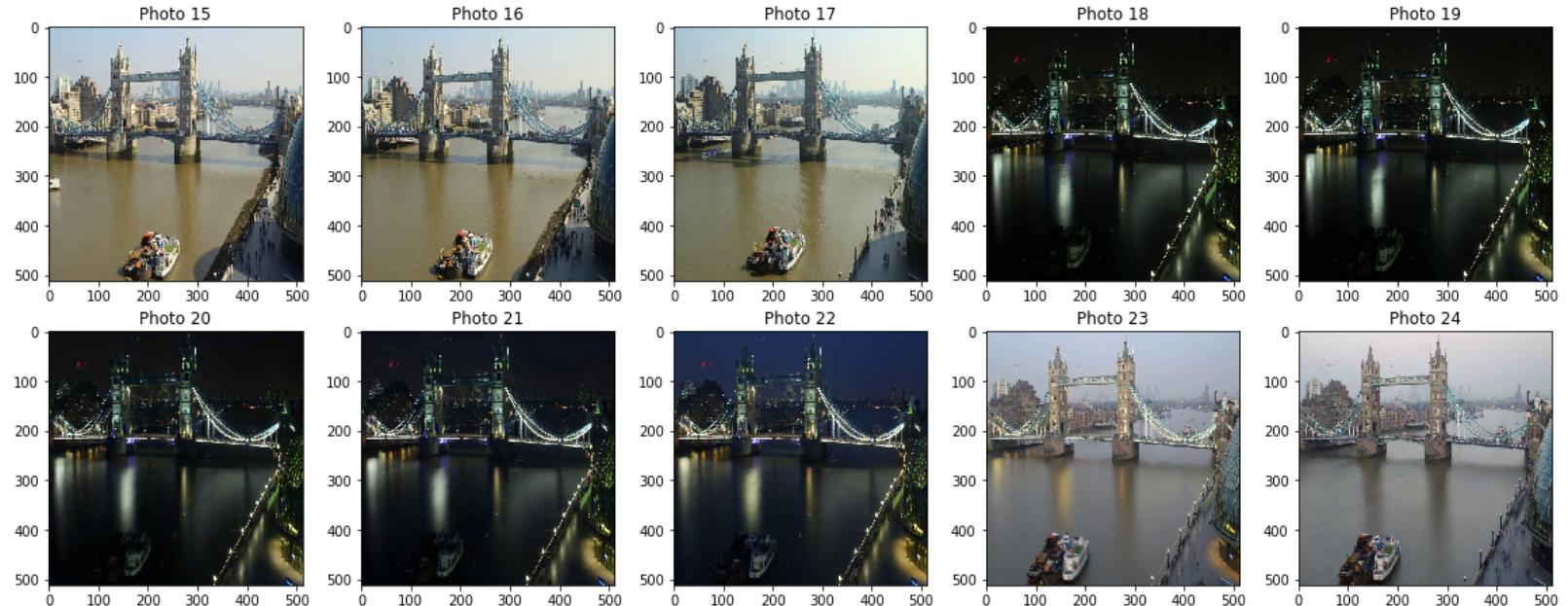
Number of photos: 25

In [3]:

```
1 #plotting the images
2 fig, axes = plt.subplots(5,5,figsize=(20,20))
3 for i,ax in enumerate(axes.flatten()):
4     ax.set_title(f'Photo {i}')
5     ax.imshow(data[i].reshape(512,512,3))
6 print("All Tower Bridge photos")
7 plt.show()
```

All Tower Bridge photos





In [4]:

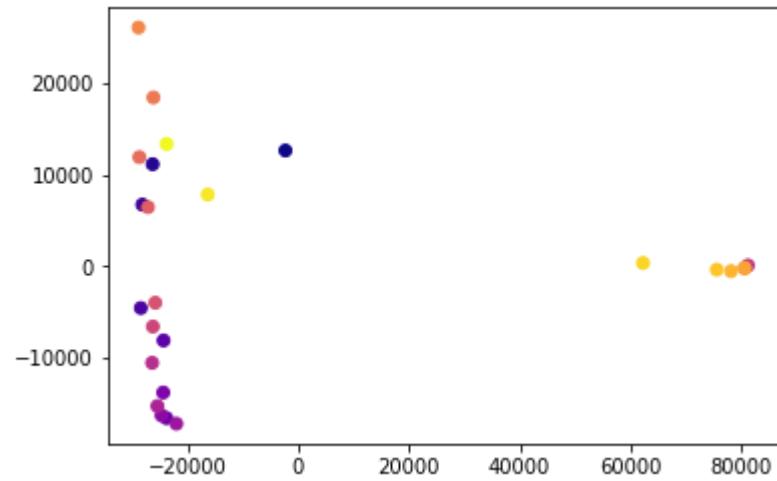
```
1 #projecting photos to 2D, using PCA
2 pca = PCA(n_components = 2) #2 here is the no. of components
3 proj = pca.fit_transform(data) #projections
4 print(np.sum(pca.explained_variance_ratio_[:2])) #variance
```

0.8935741158098824

PCA gives us ~ 89% of variance captured from the images. This is a good value and we were able to achieve this because the photo was taken from a constant angle and the only varying factors were the moving objects like people, boat, and lighting.

In [5]:

```
1 #plotting 2D projected points for the photos
2 plt.scatter([point[0] for point in proj], [point[1] for point in proj],
3             cmap = "plasma", c = range(len(proj)))
4 plt.show()
```

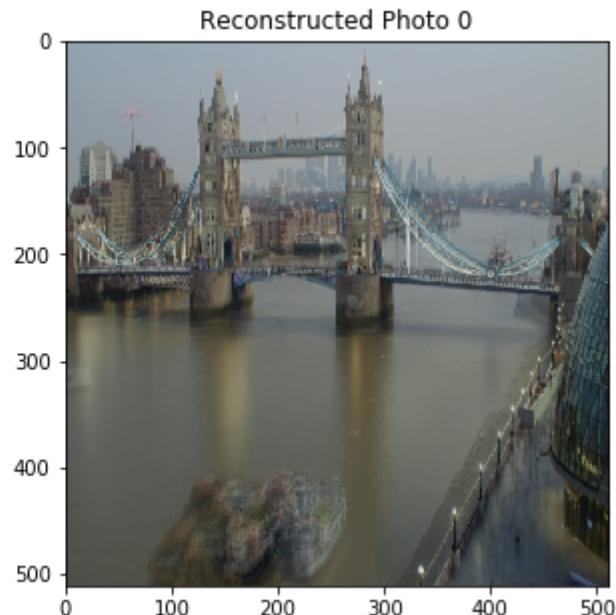
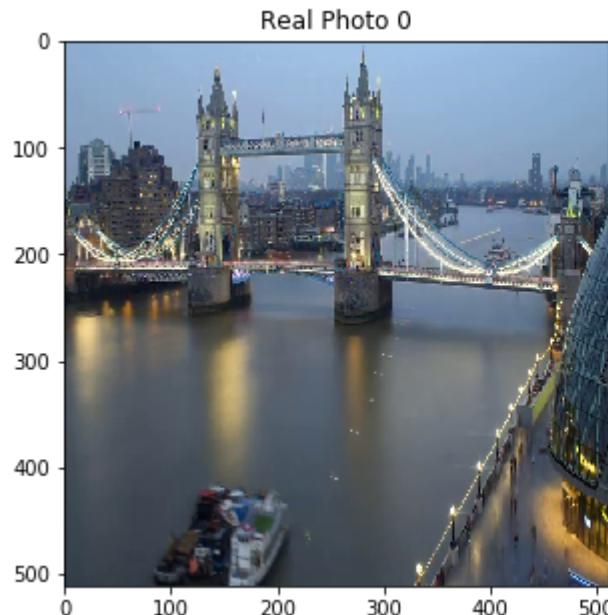


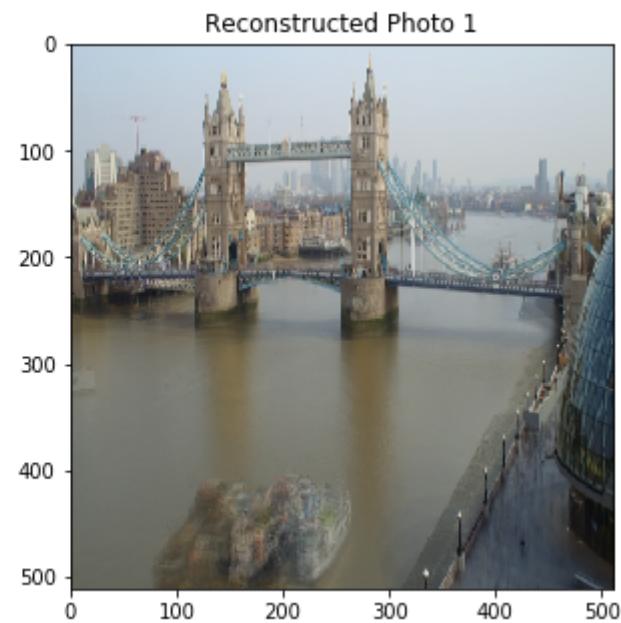
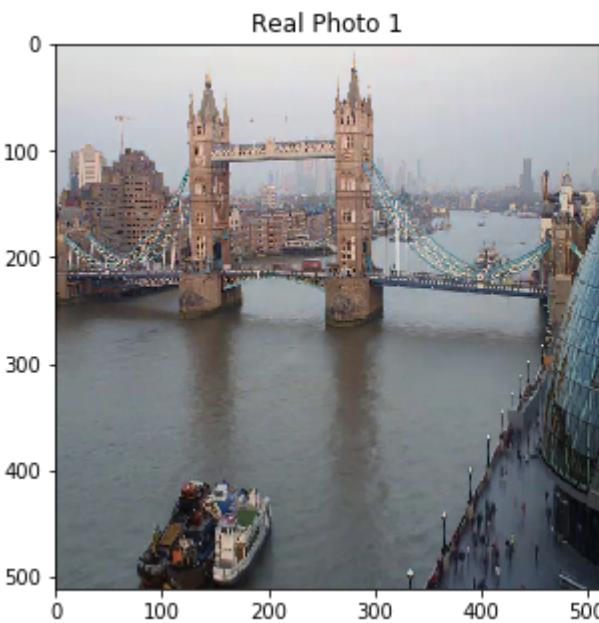
We see many outliers points on the right, in the plot above, which seems to be because we have same number of photos clicked in dark

In [6]:

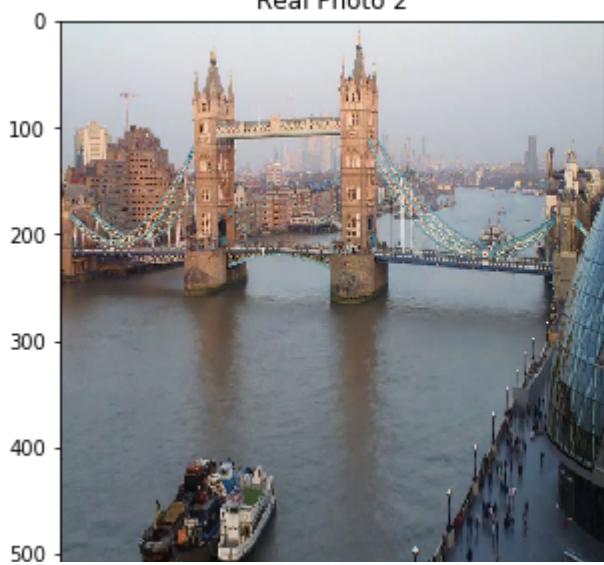
```
1 #showing reconstruction from low dimension projection
2 recon = pca.inverse_transform(proj)
3 for i in range(25):
4     fig, axes = plt.subplots(1, 2, figsize=(15,5))
5     axes[0].set_title(f'Real Photo {i}')
6     axes[0].imshow(data[i].reshape(512,512,3))
7     axes[1].set_title(f'Reconstructed Photo {i}')
8     axes[1].imshow(recon[i].reshape(512,512,3).astype('uint8'))
```

C:\Users\rhyth\Anaconda3\lib\site-packages\matplotlib\pyplot.py:522: RuntimeWarning: More than 20 figures have been opened. Figures created through the pyplot interface (`matplotlib.pyplot.figure`) are retained until explicitly closed and may consume too much memory. (To control this warning, see the rcParam `figure.max\_open\_warning` ).  
max\_open\_warning, RuntimeWarning)

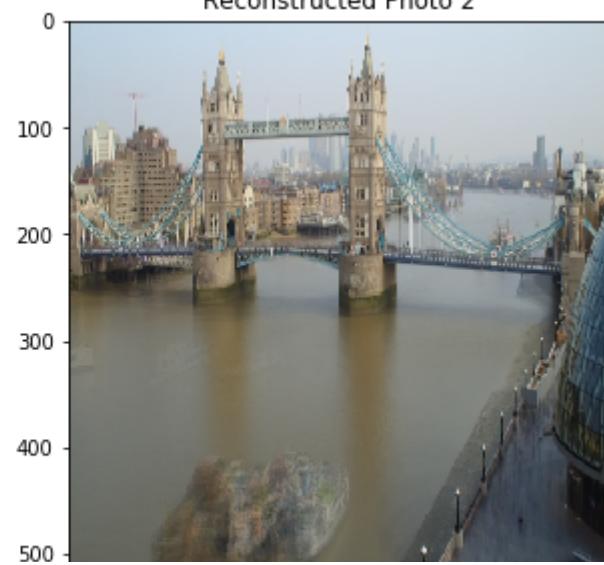




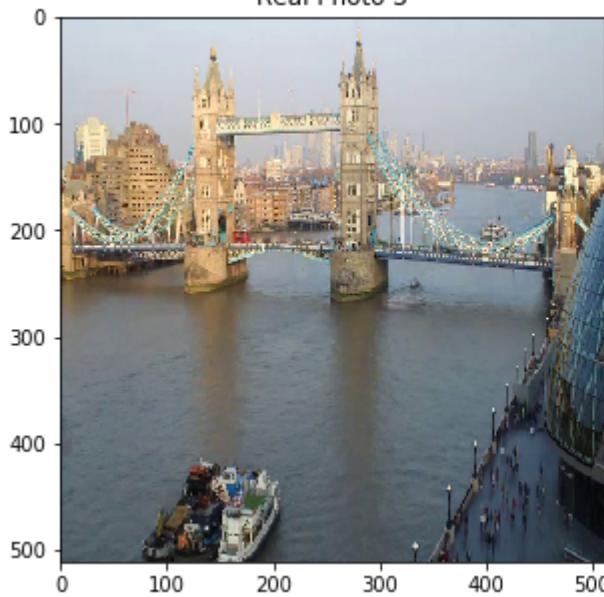
**Real Photo 2**



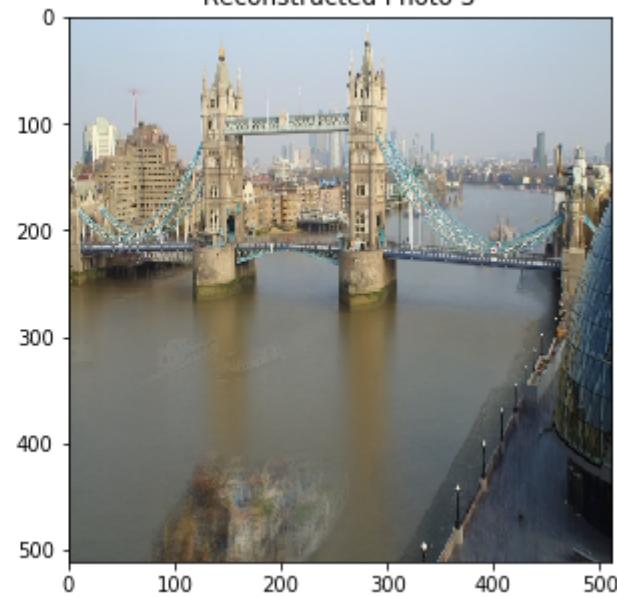
**Reconstructed Photo 2**

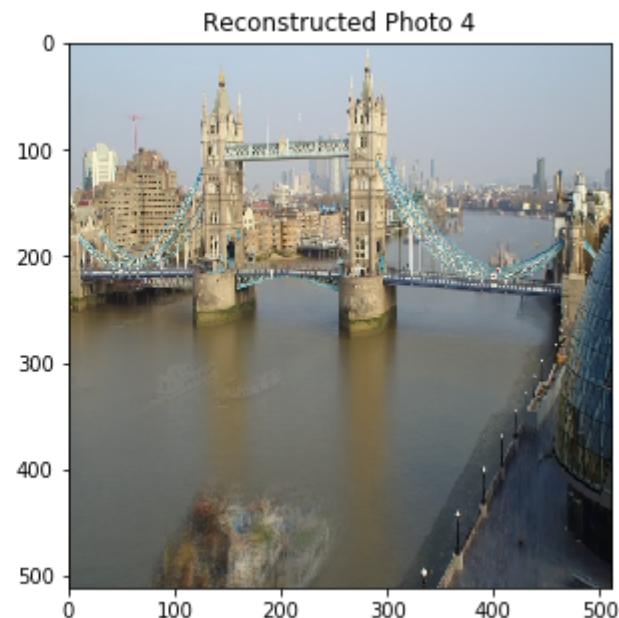
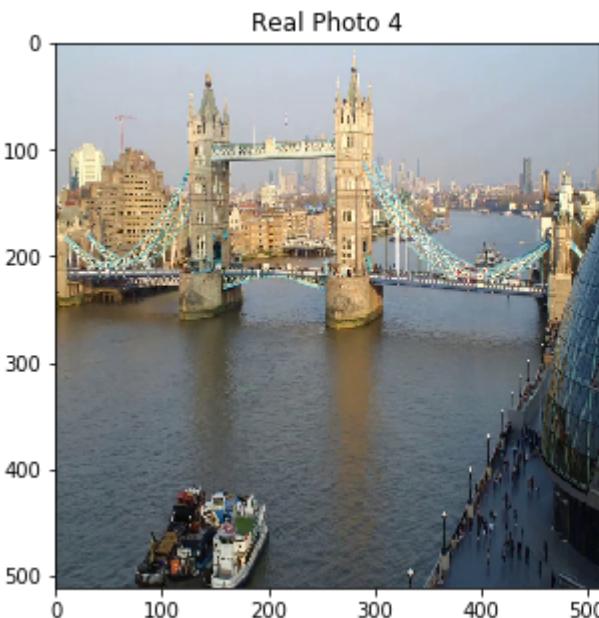


**Real Photo 3**



**Reconstructed Photo 3**





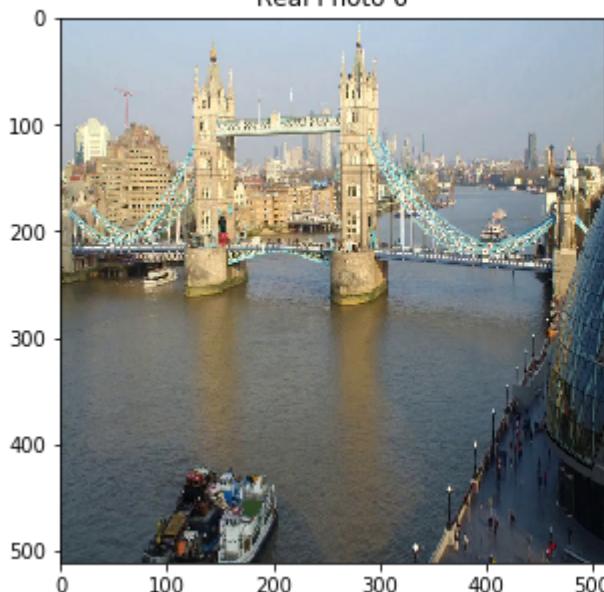
**Real Photo 5**



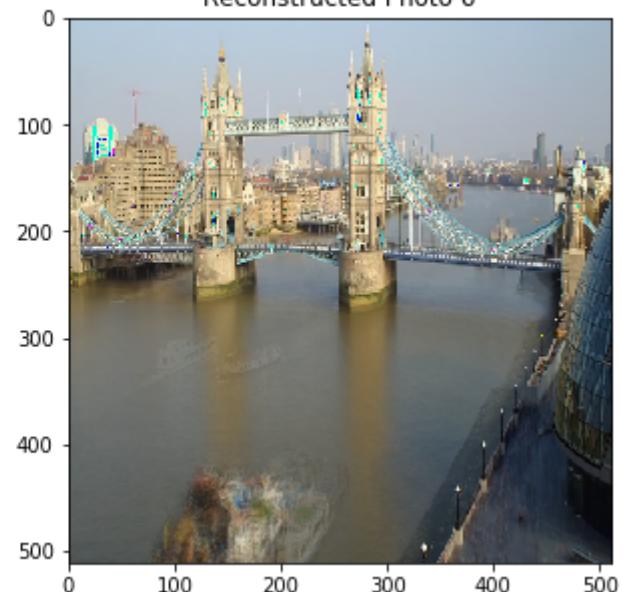
**Reconstructed Photo 5**



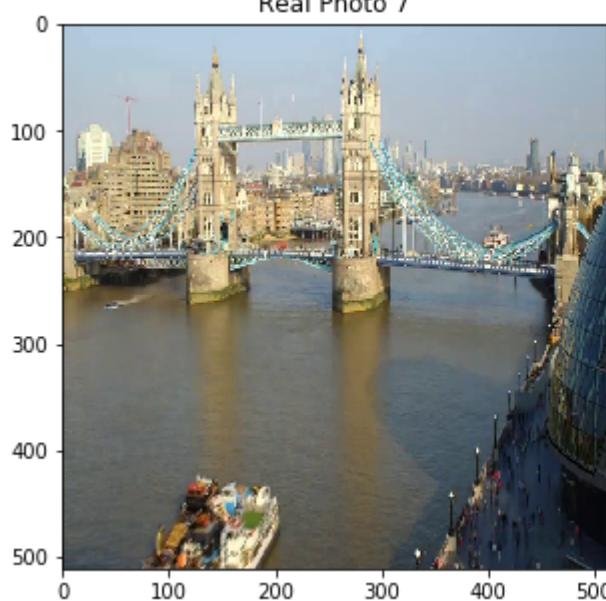
**Real Photo 6**



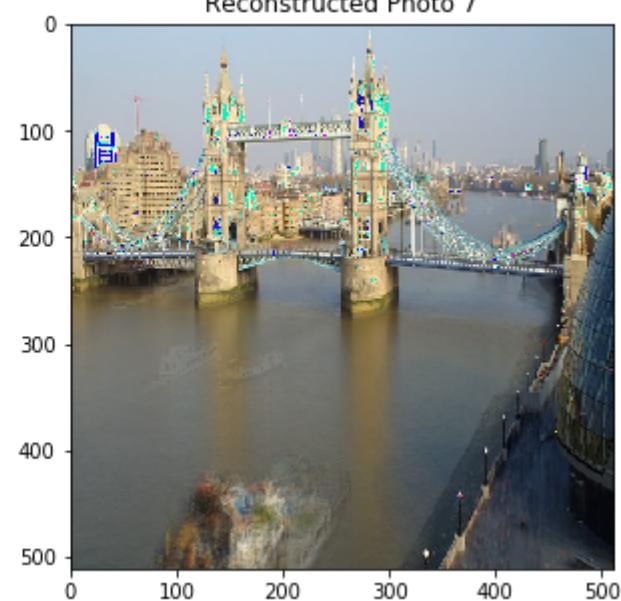
**Reconstructed Photo 6**



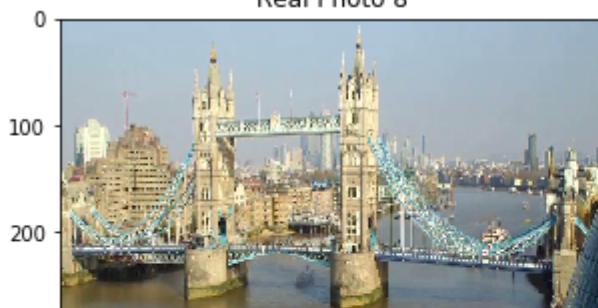
Real Photo 7



Reconstructed Photo 7



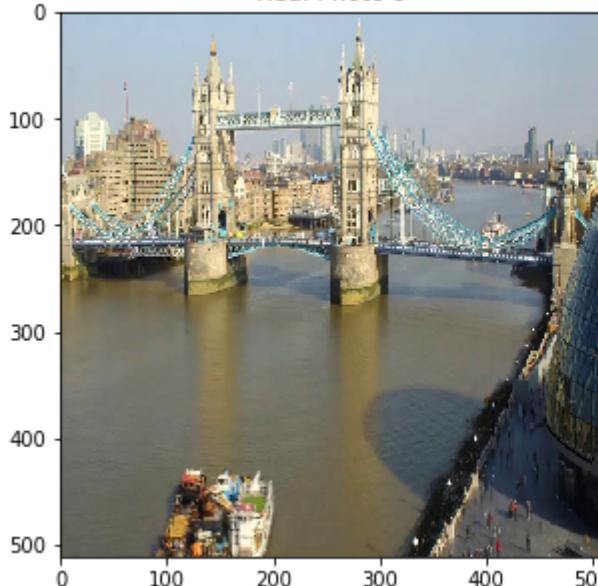
Real Photo 8



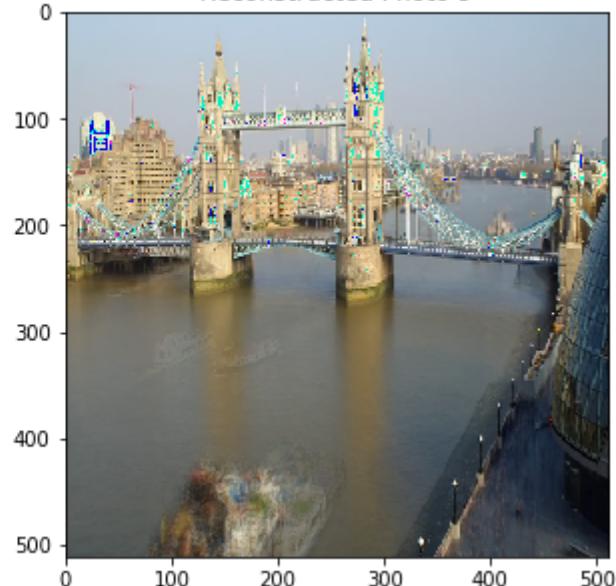
Reconstructed Photo 8



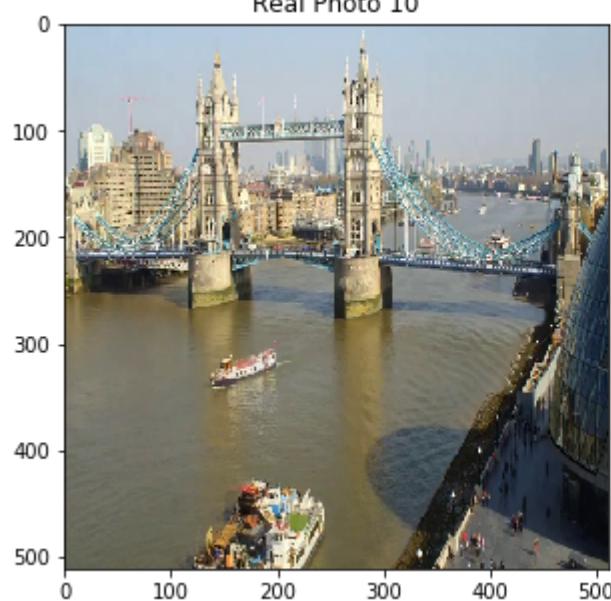
Real Photo 9



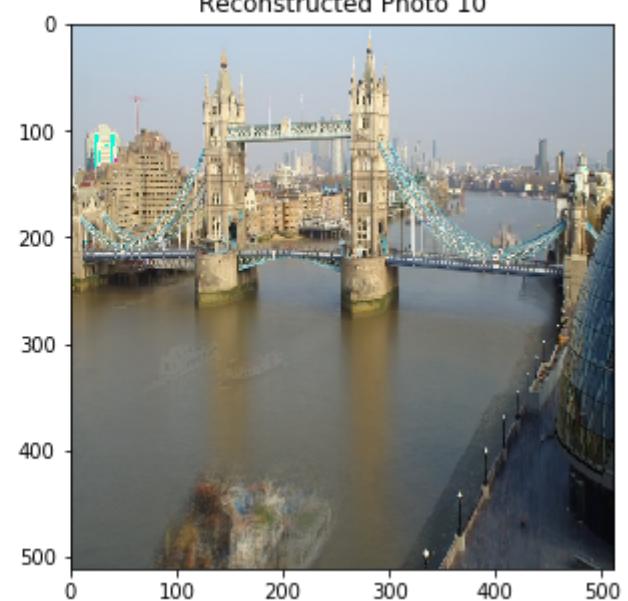
Reconstructed Photo 9



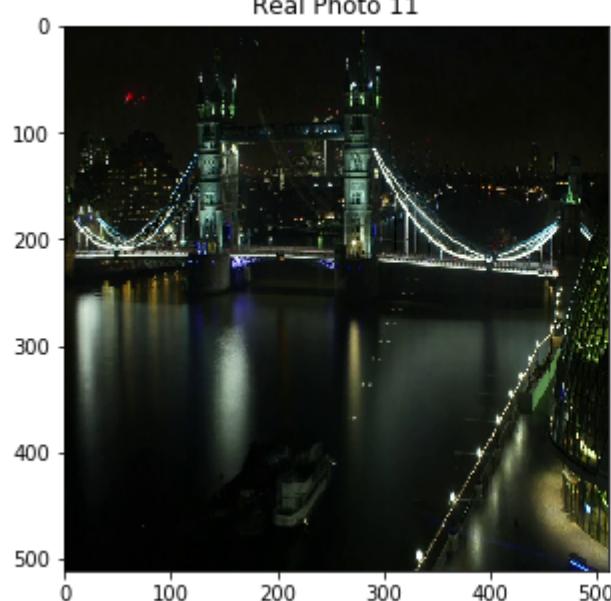
Real Photo 10



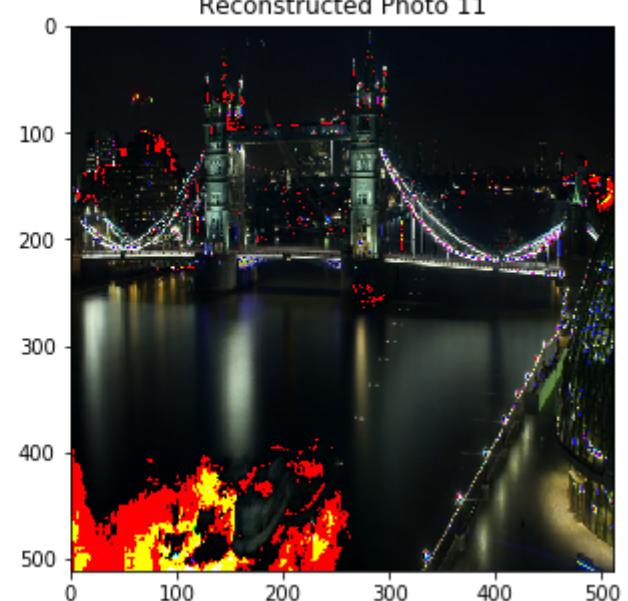
Reconstructed Photo 10



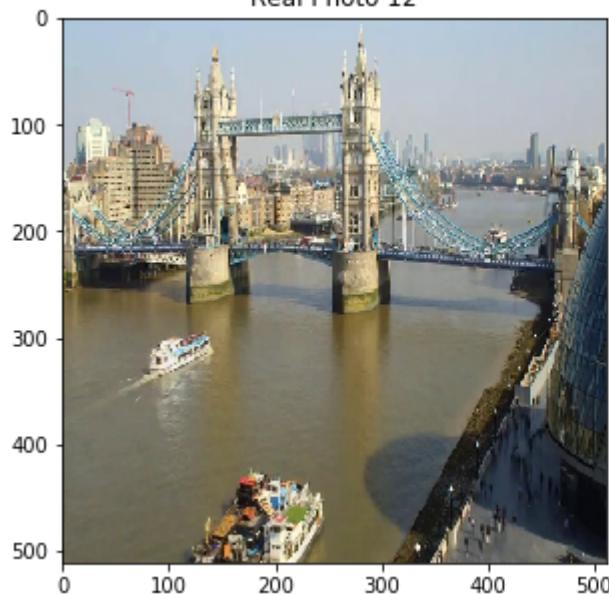
Real Photo 11



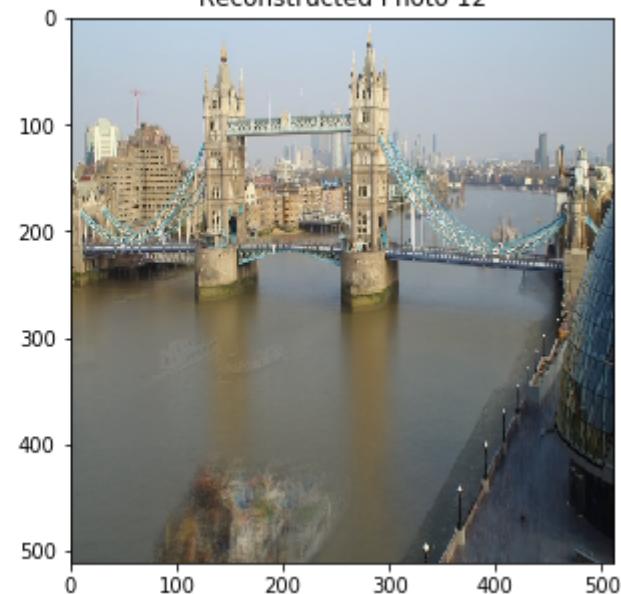
Reconstructed Photo 11



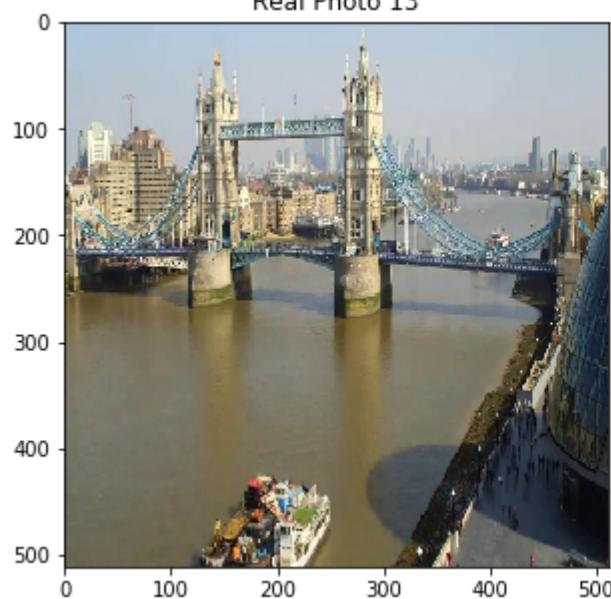
Real Photo 12



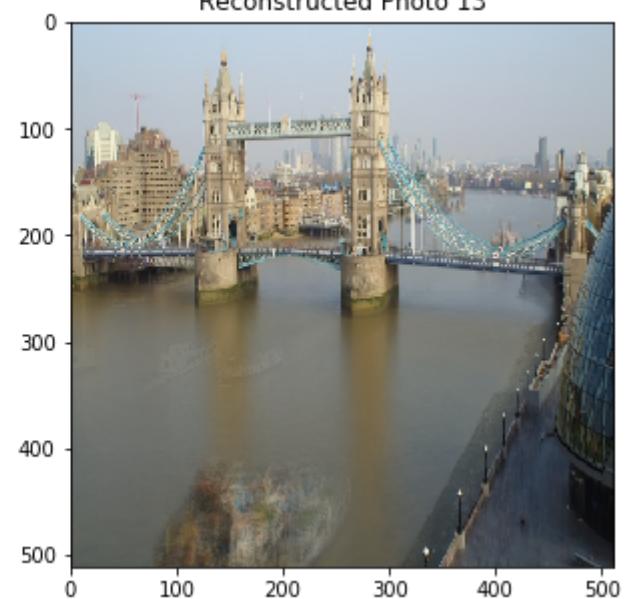
Reconstructed Photo 12



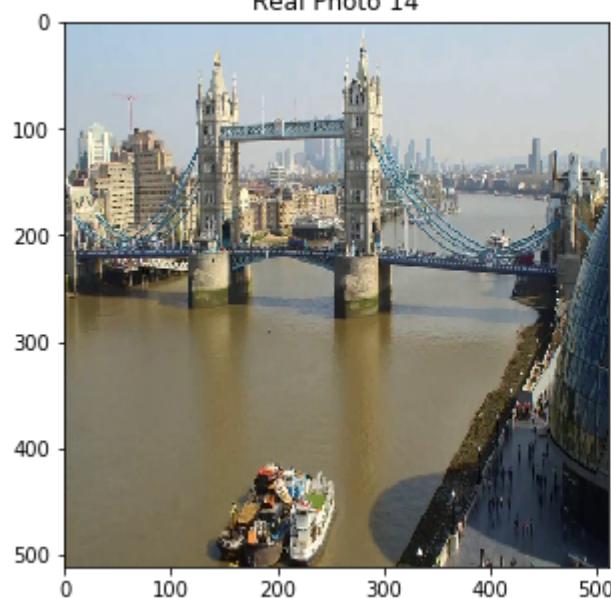
Real Photo 13



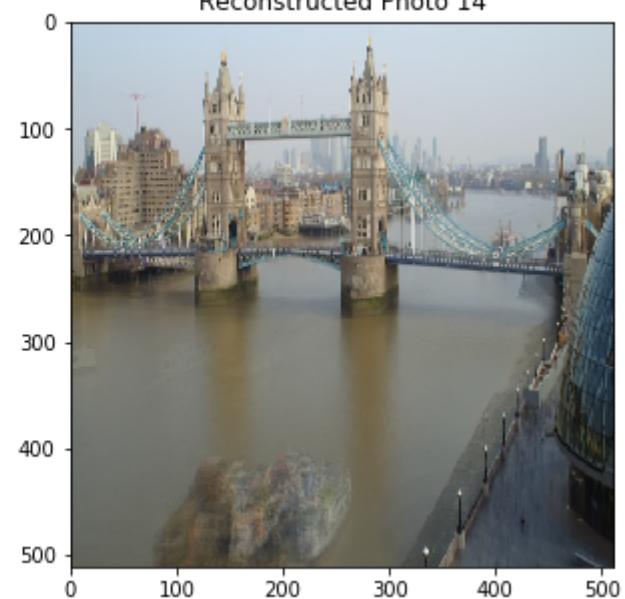
Reconstructed Photo 13

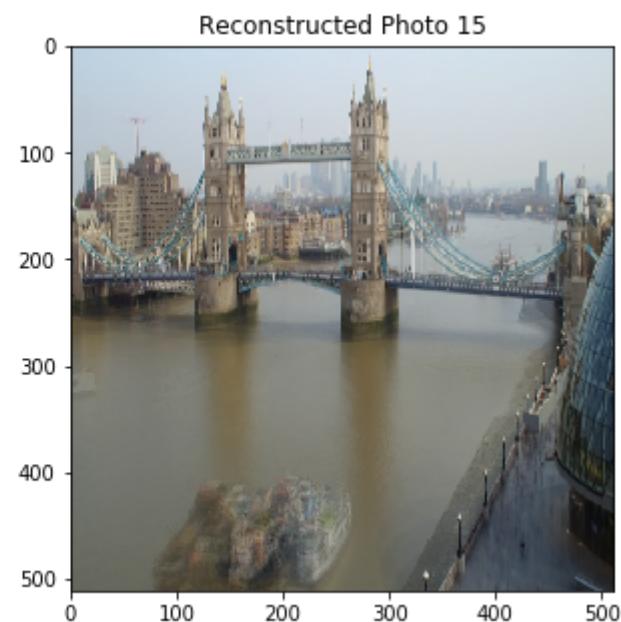
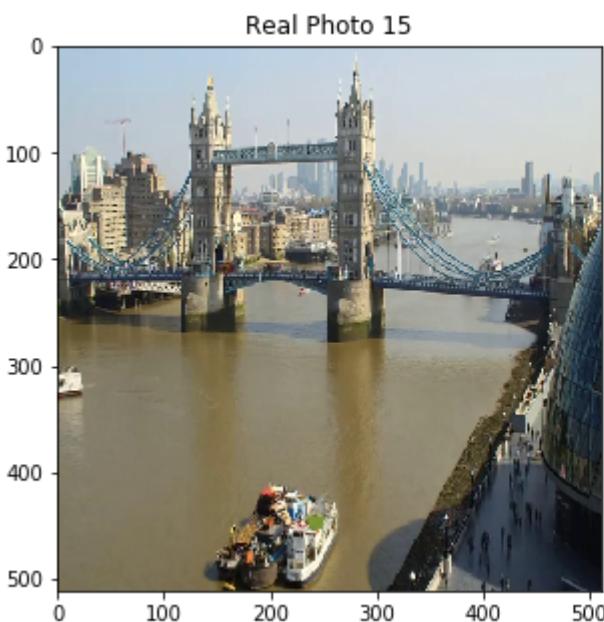


Real Photo 14



Reconstructed Photo 14





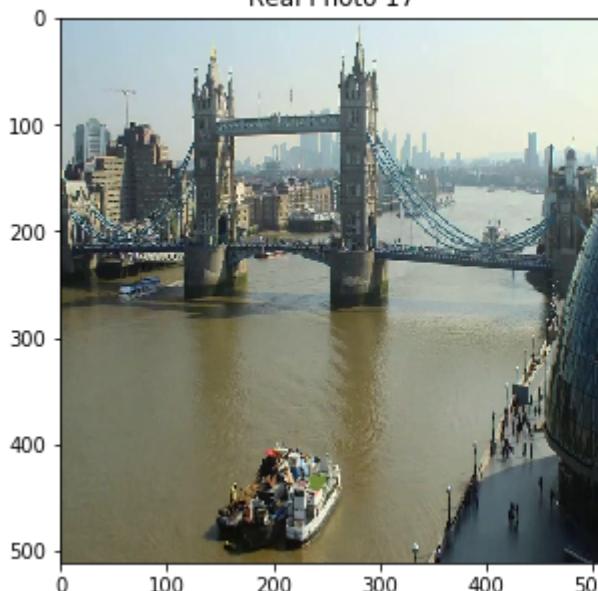
Real Photo 16



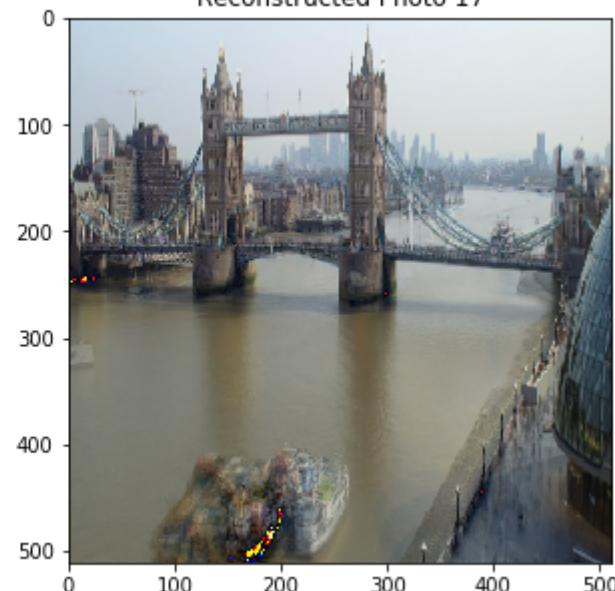
Reconstructed Photo 16

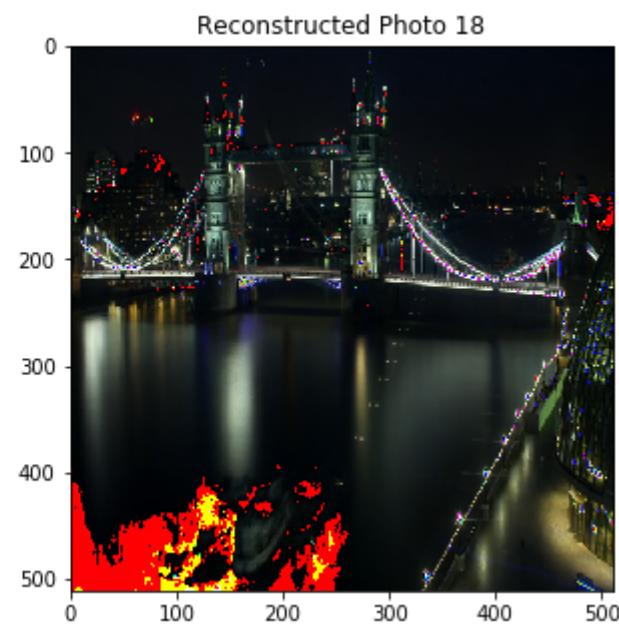
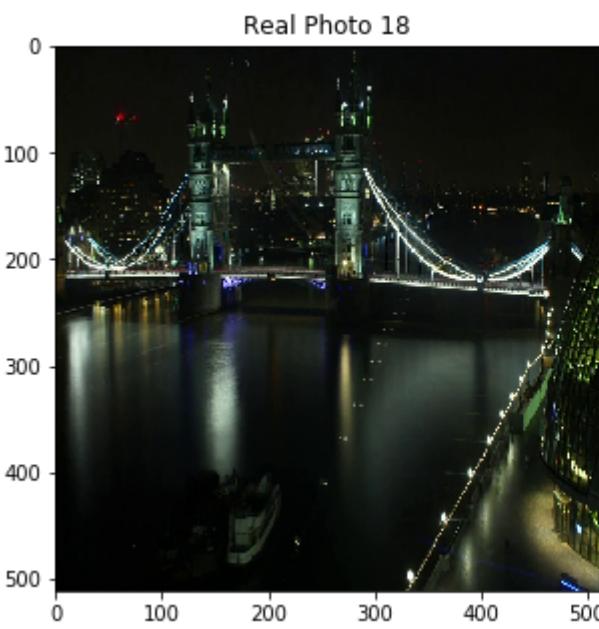


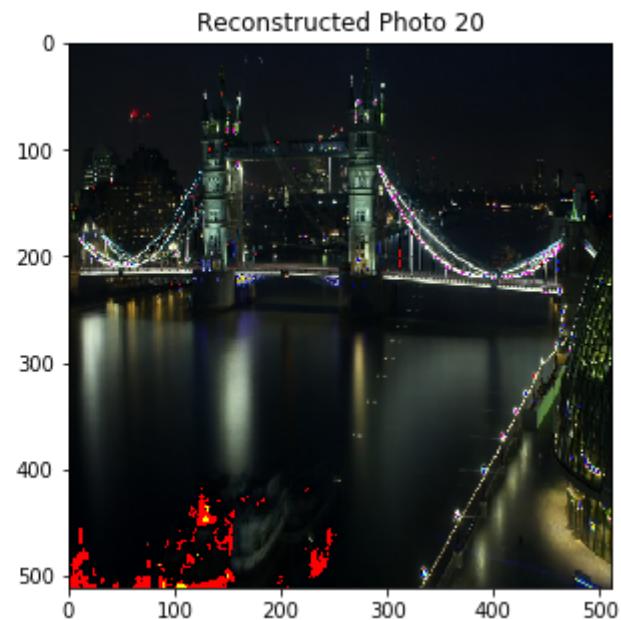
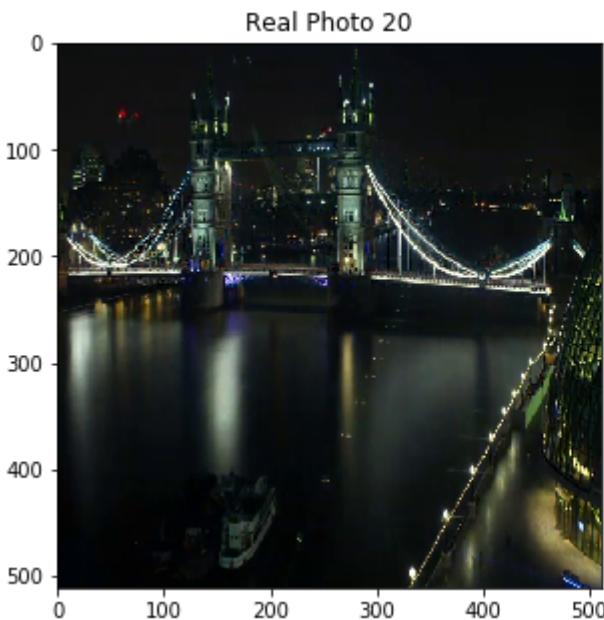
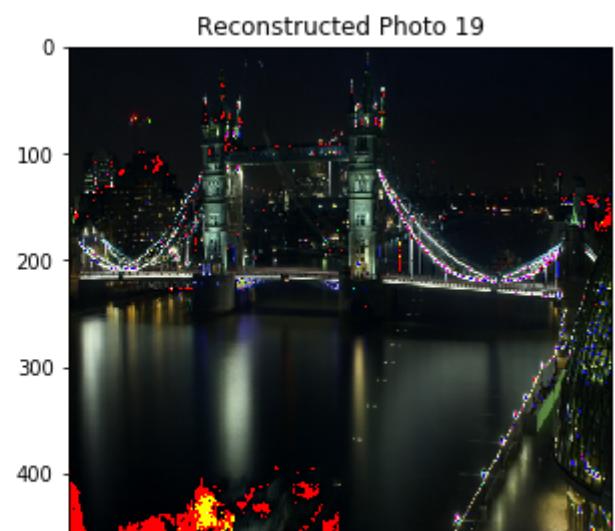
Real Photo 17

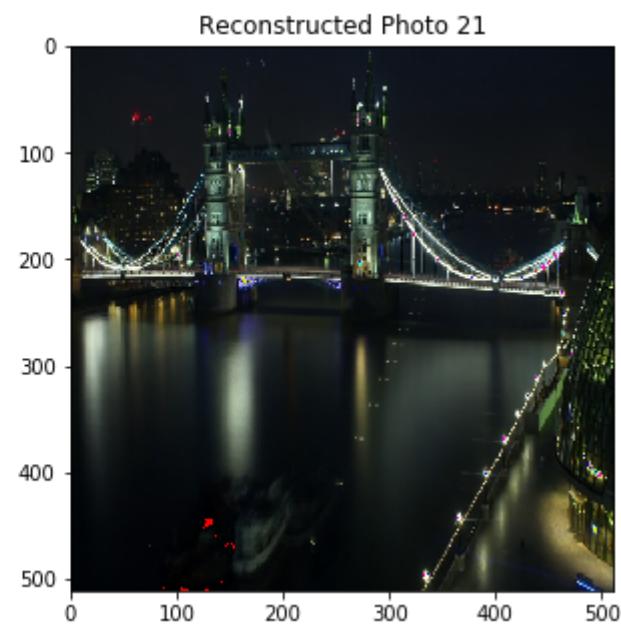
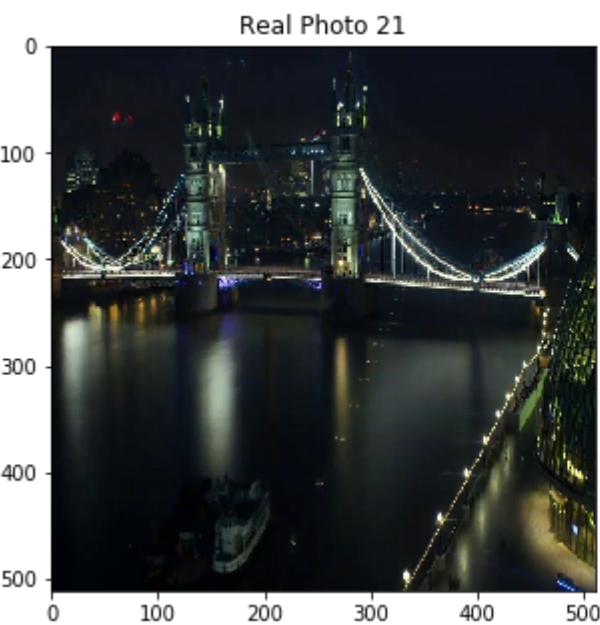


Reconstructed Photo 17

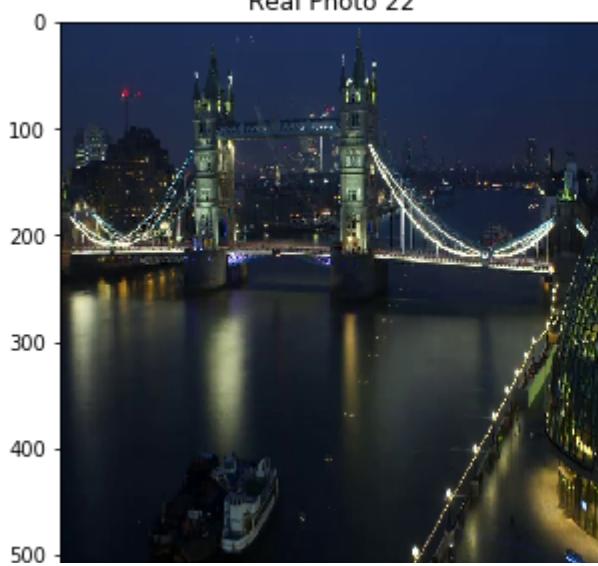




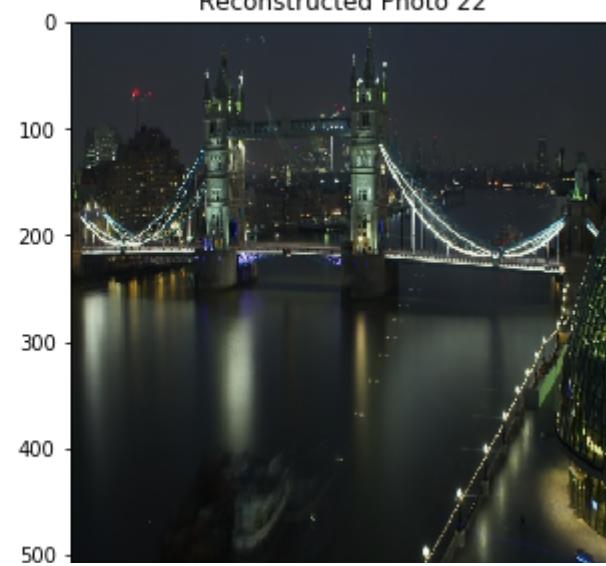




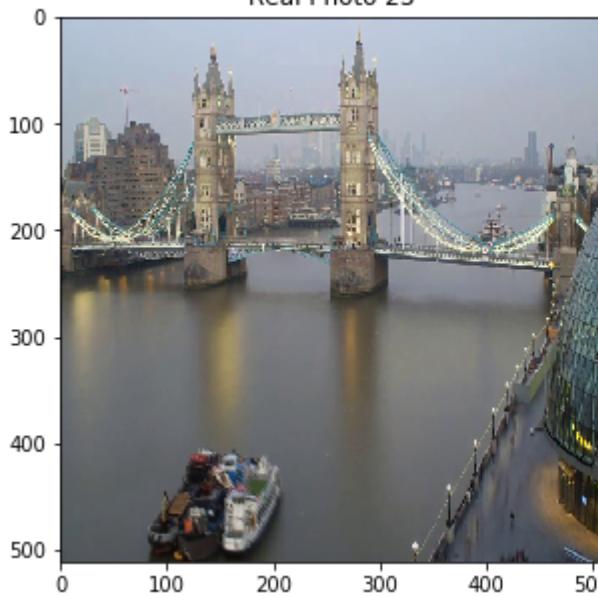
Real Photo 22



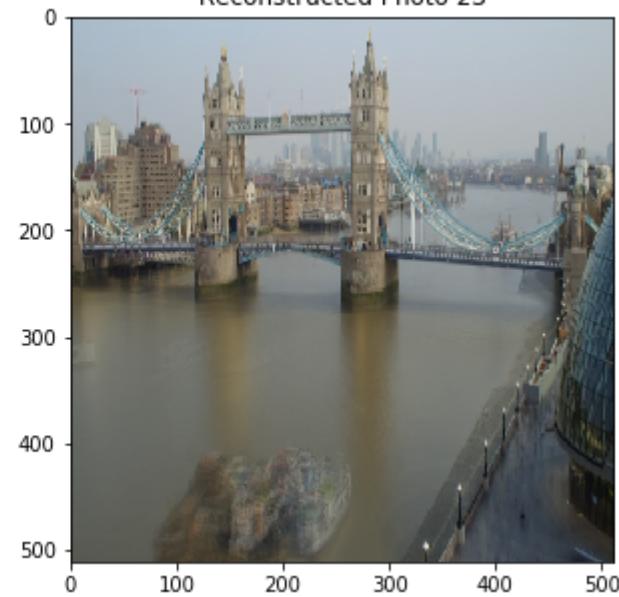
Reconstructed Photo 22

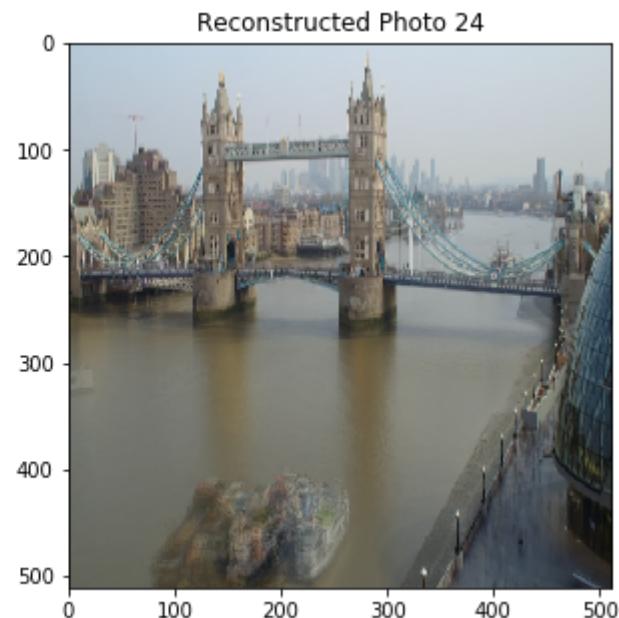
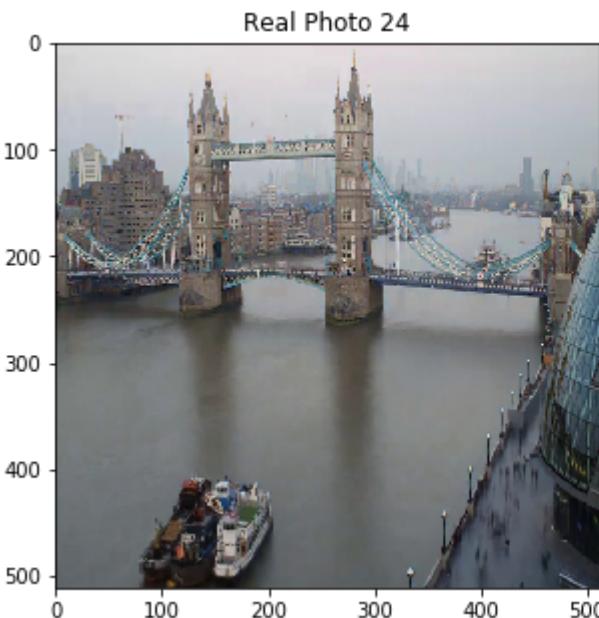


Real Photo 23



Reconstructed Photo 23

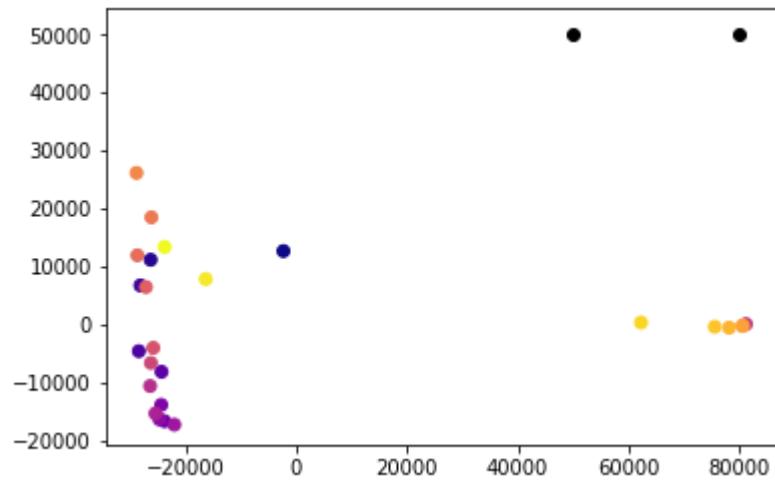




Reconstruction of real photos look quite accurate. Although a few of the photos have noisy colored spots where the reconstruction isn't as good as the others, mostly of photos clicked in dark this could due to less data of pictures clicked in dark. Also, the boat and public isn't reconstructed properly in any as they weren't captured identical in any photo.

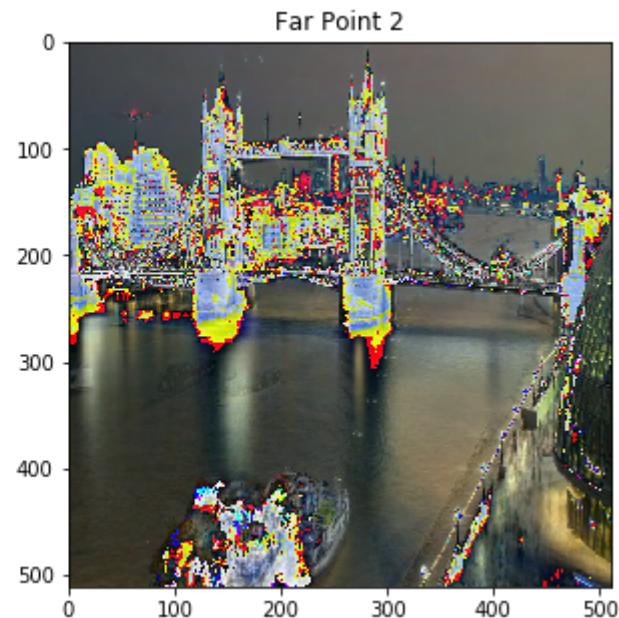
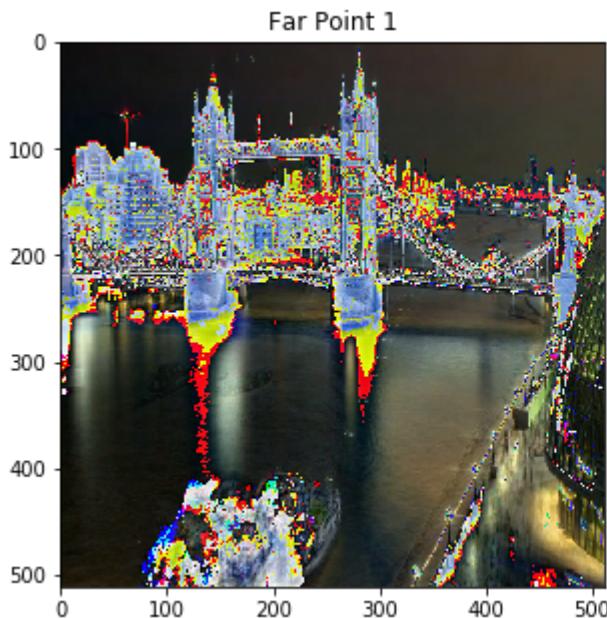
In [7]:

```
1 plt.scatter([point[0] for point in proj], [point[1] for point in proj],  
2             cmap = "plasma", c = range(len(proj)))  
3 plt.scatter(80000, 50000, c = "black") #plotting a FAR point  
4 plt.scatter(50000, 50000, c = "black") #plotting a FAR point  
5 plt.show()
```



In [8]:

```
1 #plotting the reconstruction of black far points plotted above
2 far1 = pca.inverse_transform([80000,50000]) #far point 1
3 far2 = pca.inverse_transform([50000,50000]) #far point 2
4 fig, axes = plt.subplots(1,2,figsize=(15,5))
5 axes[0].set_title(f'Far Point 1')
6 axes[0].imshow(far1.reshape(512,512,3).astype('uint8'))
7 axes[1].set_title(f'Far Point 2')
8 axes[1].imshow(far2.reshape(512,512,3).astype('uint8'))
9 plt.show()
```



Reconstruction of far points seem terrible but they do restore a few parts accurate and the structure/skeleton of the image although with noisy colors.