

Iterative Refinement and Verified Numerical Linear Algebra

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Outline

Question How do we know the **quality** of **computed error bounds** for solutions in numerical linear algebra?

⇒ We consider **error of error** for solutions of linear systems.

Purpose We answer the question using the following two tools:

- Verified numerical computations
⇒ **error bounds** of computed solutions.
- Iterative refinement
⇒ **error reduction** of computed solutions.

(Usual) verified computation

Notation: For $x = (x_1, \dots, x_n)^T \in \mathbb{R}^n$, $|x| = (|x_1|, \dots, |x_n|)^T$.

Given an approximate solution \tilde{x} of $Ax = b$, the usual verified computation gives an **upper bound** of the error or its norm:

$$|\tilde{x} - A^{-1}b| \leq \epsilon \in \mathbb{R}^n \quad \text{or} \quad \|\tilde{x} - A^{-1}b\|_\infty \leq \max_{1 \leq i \leq n} \epsilon_i = \varepsilon \in \mathbb{R}$$

\implies **At least**, \tilde{x}_i has correct digits (accuracy) corresponding to ϵ_i .

\implies However, ϵ_i may be **overestimated** (too pessimistic).

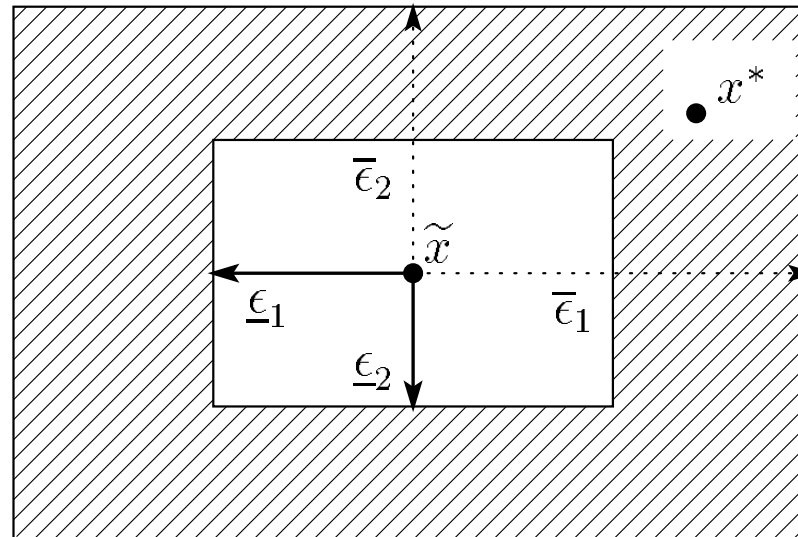
\implies The **quality of the verification** is still not known!

Quality of the verification

How (and whether) can we know it?

Compute both lower and upper error bounds

If both $\underline{\epsilon}$ and $\bar{\epsilon}$ s.t. $\underline{\epsilon} \leq |\tilde{x} - A^{-1}b| \leq \bar{\epsilon}$ and $\bar{\epsilon} \approx \underline{\epsilon}$ are obtained, then the quality of the verification (evaluation) can be confirmed!




 : possible domain where the exact solution x^* exists

Figure 1: Inner and outer enclosure of the exact solution (two-dimensional case)

Question: Is it possible to obtain such $\underline{\epsilon}$ and $\bar{\epsilon}$ without much computational cost?

Answer: Yes. It is not so difficult! Let's see how to do it.

Nonsingularity of A and upper bound of $\|A^{-1}\|$

It needs some effort in terms of computational cost. For example,

- Let R be an **approximate inverse** of A . If $\|I - RA\| < 1$, then A is **proved** to be nonsingular and

$$\|A^{-1}\| \leq \frac{\|R\|}{1 - \|I - RA\|}.$$

- computing a lower bound $\underline{\sigma}$ of the **smallest singular value** of $A \implies$ If $\underline{\sigma} > 0$, then $\|A^{-1}\|_2 \leq 1/\underline{\sigma}$.

Basic theorem for tight error bounds

Theorem 1. [O. et al., 2003] *Let A be a real $n \times n$ matrix and b be a real n -vector. Let \tilde{x} be an approximate solution of $Ax = b$ and $r := b - A\tilde{x}$. Let \tilde{y} be an approximate solution of $Ay = r$. If A is nonsingular, then it holds for $p \in \{1, 2, \infty\}$ that*

$$|A^{-1}b - \tilde{x}| \leq |\tilde{y}| + \|A^{-1}\|_p \|r - A\tilde{y}\|_p e, \quad (1)$$

where $e := (1, \dots, 1)^T \in \mathbb{R}^n$.

Tight enclosure of the solution

For an arbitrary $y \in \mathbb{R}^n$, we have

$$A^{-1}b - \tilde{x} = A^{-1}b - (\tilde{x} + y) + y.$$

It follows that

$$|y| - \epsilon_y \leq |A^{-1}b - \tilde{x}| \leq |y| + \epsilon_y \quad \text{with} \quad \epsilon_y := |A^{-1}b - (\tilde{x} + y)|.$$

Using this and Theorem 1, we have the following proposition.

Proposition 1. *Let A, b, \tilde{x} and r be as in Theorem 1. Let \tilde{y} be an approximate solution of $Ay = r$. Assume that A is nonsingular and ρ satisfies $\|A^{-1}\|_p \leq \rho$ for any $p \in \{1, 2, \infty\}$. Then*

$$\max(|\tilde{y}| - \epsilon, \mathbf{o}) \leq |A^{-1}b - \tilde{x}| \leq |\tilde{y}| + \epsilon, \quad (2)$$

where $\epsilon := \rho \|r - A\tilde{y}\|_p e$ and $\mathbf{o} = (0, \dots, 0)^T \in \mathbb{R}^n$.

\implies If $|\tilde{y}_i| \gg \epsilon_i$, the error bounds are very tight!

\implies Such $|\tilde{y}|$ can be obtained by the **iterative refinement method**.

Iterative refinement and staggered correction

To obtain a tight enclosure of an approximate solution \tilde{x} of a linear system $Ax = b$, we introduce a so-called “**staggered correction**”.

\mathbb{F} : a set of floating-point numbers

Using **iterative refinements**, we can obtain $\tilde{x} + y$ with **arbitrarily higher precision**: For $R \approx A^{-1}$

$$y^{(\ell+1)} = R * (b - A(\tilde{x} + y^{(\ell)})),$$

where $y^{(\ell)} = \sum_{k=1}^M y_k^{(\ell)}$ with $y_k^{(\ell)} \in \mathbb{F}^n$. \implies The correction term y can be expressed by the sum of floating-point vectors.

This makes only sense for calculating the residual $b - A(\tilde{x} + y^{(\ell)})$ **accurately**.

\implies Fortunately, we have **accurate dot product** algorithms.

[1] O., Rump, Oishi: *Accurate sum and dot product*, SISC, 26:6 (2005).

[2] Rump, O., Oishi: *Accurate floating-point summation: Part I/Part II*, SISC, 31:1/2 (2008).

On the other hand, to obtain tight error bounds, we need to compute

$$\epsilon_i = \rho \|r - A\tilde{y}\|_p = \rho \|b - A(\tilde{x} + \tilde{y})\|_p.$$

This is compatible with the iterative refinements!

Behavior of iterative refinement

Assume that an approximate inverse $R \in \mathbb{F}^{n \times n}$ of A is computed by a backward stable algorithm, e.g. LU factorization with partial pivoting. Then, the following is known as a rule of thumb: For $\mu := \text{cond}_\infty(A) < \mathbf{u}^{-1}$ and $G := I - RA$,

$$\alpha := \|G\|_\infty = \mathcal{O}(n\mathbf{u})\mu. \quad (3)$$

Let $\tilde{x} = Rb$ and $e := (1, \dots, 1)^T$. Since

$$|A^{-1}b - \tilde{x}| = |A^{-1}b - Rb| = |(I - RA)A^{-1}b| \leq |G||A^{-1}b|,$$

it holds that

$$|A^{-1}b - \tilde{x}| \leq \|A^{-1}b\|_\infty |G|e. \quad (4)$$

After an iterative refinement by using $y^{(1)} = R(b - A\tilde{x})$, it follows that

$$\begin{aligned} |A^{-1}b - (\tilde{x} + y^{(1)})| &= |A^{-1}b - \tilde{x} - R(b - A\tilde{x})| \\ &= |(I - RA)(A^{-1}b - \tilde{x})| \\ &\leq |G||A^{-1}b - \tilde{x}|. \end{aligned} \tag{5}$$

Inserting (4) into (5) yields

$$|A^{-1}b - (\tilde{x} + y^{(1)})| \leq \|A^{-1}b\|_{\infty} |G|^2 e.$$

For $k \geq 2$, it can inductively be proved for $y^{(k)} = y^{(k-1)} + R(b - A(\tilde{x} + y^{(k-1)}))$ that

$$|A^{-1}b - (\tilde{x} + y^{(k)})| \leq \|A^{-1}b\|_{\infty} |G|^{k+1} e$$

and

$$|A^{-1}b - (\tilde{x} + y^{(k)})| \leq \alpha^{k+1} \|A^{-1}b\|_{\infty} e. \quad (6)$$

Therefore, if $\alpha < 1$, then the iterative refinement converges with the factor $\alpha = \mathcal{O}(n\mathbf{u})\mu$ for each iteration.

In practice, due to the rounding error, we have $\tilde{x}^{(k)} = \text{fl}(\tilde{x} + y^{(k)})$ with $\tilde{x}^{(0)} = \tilde{x}$ and

$$|A^{-1}b - \tilde{x}^{(k)}| \leq \mathbf{u}|A^{-1}b| + \mathcal{O}(\alpha^{k+1})\|A^{-1}b\|_{\infty}e. \quad (7)$$

This is a *componentwise* error bound and explains the behavior of the iterative refinement.

Example

Let us consider the case where $A \in \mathbb{F}^{5 \times 5}$ with $\text{cond}_{\infty}(A) \approx 10^{10}$ and the *exact* solution $A^{-1}b = (1, 10^3, 10^6, 10^9, 134217728)^T$.

All computations are done in double precision arithmetic on Matlab, so that $\mathbf{u} = 2^{-53} \approx 10^{-16}$.

An approximate inverse R : computed by a Matlab function `inv` \implies
 $\alpha = \|I - RA\|_{\infty} \approx 10^{-6} \quad (\mathbf{u} \cdot \text{cond}_{\infty}(A) \approx 10^{-6})$

$$\tilde{x}^{(0)} = \text{fl}(Rb)$$

Let's see the result of iterative refinements.

Table 1: History of iterative refinement for $k = 0, 1, 2$

i	$\tilde{x}^{(0)}$	$\tilde{x}^{(1)}$
1	$-1.711885408 \cdot 10^2$	<u>0.999935694692795</u>
2	<u>$1.021301738 \cdot 10^3$</u>	<u>$1.0000000011437893 \cdot 10^3$</u>
3	<u>$1.000055792 \cdot 10^6$</u>	<u>$0.999999999979213 \cdot 10^6$</u>
4	<u>$1.0000000083 \cdot 10^9$</u>	<u>$0.9999999999999980 \cdot 10^9$</u>
i	$\tilde{x}^{(2)}$	
1	<u>1.00000000000002729</u>	
2	<u>$1.0000000000000000 \cdot 10^3$</u>	
3	<u>$1.0000000000000000 \cdot 10^6$</u>	
4	<u>$1.0000000000000000 \cdot 10^9$</u>	

Table 2: True absolute errors ϵ and tight error bounds

i	$\epsilon^{(0)}$	$\epsilon^{(1)}$	$\epsilon^{(2)}$
1	$1.7218854 \cdot 10^2$	$6.430530 \cdot 10^{-5}$	$2.728484 \cdot 10^{-12}$
2	$2.1301738 \cdot 10^1$	$1.143789 \cdot 10^{-5}$	$3.410605 \cdot 10^{-13}$
3	$5.5792398 \cdot 10^1$	$2.078711 \cdot 10^{-5}$	0
4	$8.3648966 \cdot 10^1$	$2.026557 \cdot 10^{-5}$	0

i	$[\underline{\epsilon}_i^{(0)}, \bar{\epsilon}_i^{(0)}]$	$[\underline{\epsilon}_i^{(1)}, \bar{\epsilon}_i^{(1)}]$	$[\underline{\epsilon}_i^{(2)}, \bar{\epsilon}_i^{(2)}]$
1	$1.72188_{53}^{55} \cdot 10^2$	$6.4305_{28}^{34} \cdot 10^{-5}$	$2.728_4^6 \cdot 10^{-12}$
2	$2.13017_{37}^{39} \cdot 10^1$	$1.1437_{86}^{92} \cdot 10^{-5}$	$3.410_4^9 \cdot 10^{-13}$
3	$5.57923_{97}^{99} \cdot 10^1$	$2.0787_{09}^{15} \cdot 10^{-5}$	$[0, 2.05] \cdot 10^{-17}$
4	$8.36489_{65}^{67} \cdot 10^1$	$2.0265_{55}^{61} \cdot 10^{-5}$	$[0, 2.05] \cdot 10^{-17}$

Thanks!

