

# Dijkstra's (Djk) Shortest Path Algorithm

This notebook demonstrates,

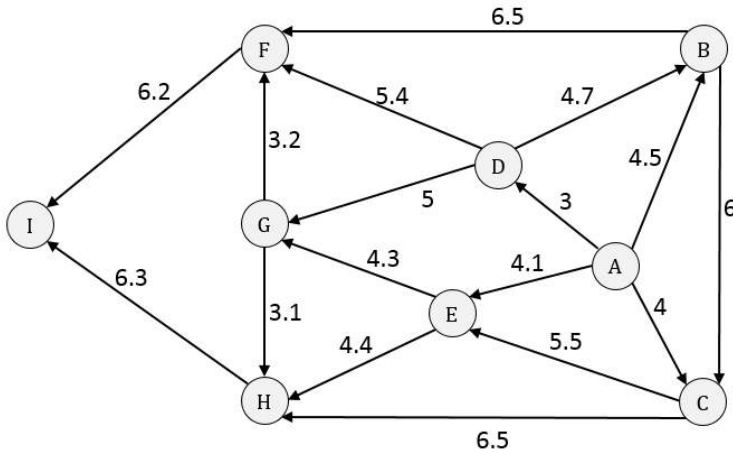
1. Djk algorithm
2. Djk running on example datasets

**The algorithm:**

$A^{(k)}(i, j)$  = Length of the shortest path from node  $i$  to  $j$  where the label of every intermediate node is  $\leq k$

$$A^{(k)}(i, j) = \min(A^{(k-1)}(i, j), A^{(k-1)}(i, k) + A^{(k-1)}(k, j))$$

The following is an example graph with 9 nodes to be traversed by Djk Algorithm. The example uses `networkx` library to draw the graphs.



```
In [1]: def dijkstra(_edges, _origin, _destination):
        """finds the shortest path from the origin to destination node
           edges are vertex1 to vertex2 with weight
        """
        from collections import defaultdict
        from heapq import heappush, heappop

        e = defaultdict(list)
        for v1, v2, w in _edges: # for each v1, fill v2 with weights
            e[v1].append((v2, w))
        # setup the heap - priority queue q
        q, seen, dist = [(0., _origin, ())], set(), {_origin: 0.}
        while q:
            # print(q) # debug
            (totw, v1, path) = heappop(q) # picks with the minimum w
            if v1 in seen:
                continue
            #
            seen.add(v1) # mark as seen
            path += (v1, )
            if v1 == _destination: # did we reach destination?
                return (totw, path)
            #
            for v2, w in e.get(v1, ()):
                if v2 in seen:
                    continue
                if v2 not in dist or totw + w < dist[v2]:
                    dist[v2] = totw + w
                    heappush(q, (totw + w, v2, path))
            #
        return float('inf')
```

```
In [2]: # The graph from above
        E = [
            ('A', 'B', 4.5),
            ('A', 'C', 4.),
            ('A', 'D', 3.),
            ('A', 'E', 4.1),
            ('B', 'C', 6.),
            ('B', 'F', 6.5),
            ('C', 'E', 5.5),
            ('C', 'H', 6.5),
            ('D', 'F', 5.4),
            ('D', 'G', 5.),
            ('E', 'G', 4.3),
            ('E', 'H', 4.4),
            ('F', 'I', 6.2),
            ('G', 'F', 3.2),
            ('G', 'H', 3.1),
            ('H', 'I', 6.3),
        ]
```

```
In [3]: dijkstra(E, 'A', 'I')
```

```
Out[3]: (14.600000000000001, ('A', 'D', 'F', 'I'))
```

```
In [4]: dijkstra(E, 'C', 'F')
```

```
Out[4]: (13.0, ('C', 'E', 'G', 'F'))
```

Now let's see `networkx` library to draw weighted directed graphs and apply Djk algorithm.

```

In [5]: %matplotlib inline
import warnings
import matplotlib.cbook
warnings.filterwarnings("ignore",category=matplotlib.cbook.mplDeprecation) # Future versions will fix this
import matplotlib.pyplot as plt
import numpy as np
import networkx as nx
print(f'networkx version {nx.__version__}')

g_di = nx.DiGraph()
g_di.add_weighted_edges_from(E)

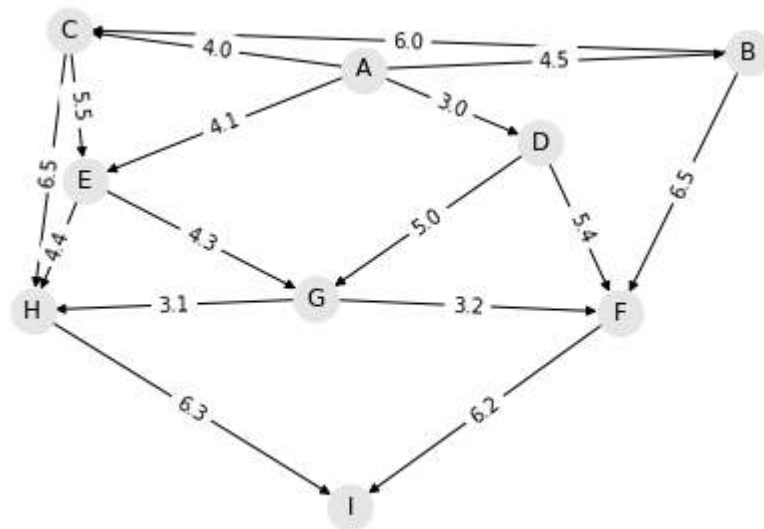
def draw(_gdi):
    pos = nx.kamada_kawai_layout(_gdi)
    # pos = nx.planar_layout(_gdi)
    # pos = nx.spring_layout(_gdi)
    # pos = nx.spectral_layout(_gdi)
    # pos = nx.shell_layout(_gdi)
    nx.draw(_gdi, pos, node_size=500, node_color='0.9', with_labels=True)
    return pos

print('Original graph as above')
pos = draw(g_di)

nx.draw_networkx_edge_labels(g_di, pos, {(v1,v2):str(w) for v1, v2, w
in E});

```

networkx version 2.4  
Original graph as above



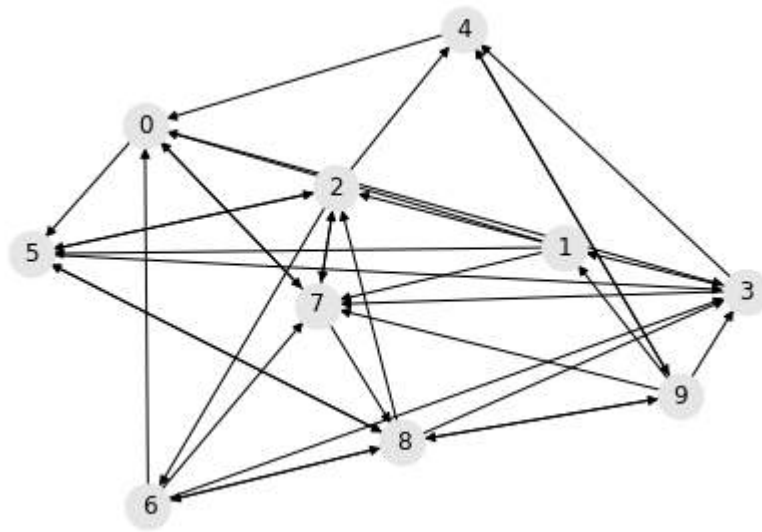
Let's create a random weighted directed graph.

```

In [6]: # Generate the digraph
def gen_digraph(nodes_n):
    g_di = nx.gnp_random_graph(nodes_n, 0.3, directed=True) # args:
    # number of nodes, ratio of number of edges
    E = [(v1,v2) for v1,v2,dt in nx.to_edgelist(g_di)]
    # populate weights from a uniform distribution between [0.5, 1.0]
    for v1, v2 in E:
        g_di[v1][v2]['weight'] = int(10*np.random.uniform()+5)/20.
    # not drawing edge labels
    draw(g_di)
    return g_di

g_di = gen_digraph(10)

```



```

In [7]: # Find the path
def find_djk(g_di):
    # Get the edges from the random graph
    E = [(v1,v2,dt['weight']) for v1,v2,dt in nx.to_edgelist(g_di)]
    # Compute Djk from vertex 0 to the rest
    nodes_n = len(g_di)
    for v2 in range(1,nodes_n):
        djk = dijkstra(E, 0, v2)
        extra = ' - no path found' if djk == float('inf') else ''
        print(f'path from node {0} to node {v2}: {djk}' + extra)

find_djk(g_di)

```

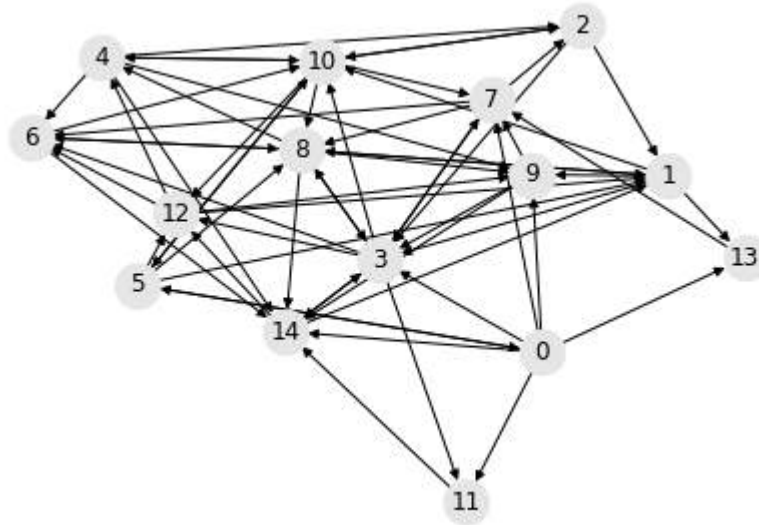
```

path from node 0 to node 1: (0.95, (0, 3, 1))
path from node 0 to node 2: (0.7, (0, 7, 2))
path from node 0 to node 3: (0.65, (0, 3))
path from node 0 to node 4: (1.1, (0, 7, 2, 4))
path from node 0 to node 5: (0.4, (0, 5))
path from node 0 to node 6: (1.0499999999999998, (0, 7, 8, 6))
path from node 0 to node 7: (0.4, (0, 7))
path from node 0 to node 8: (0.7, (0, 7, 8))
path from node 0 to node 9: (1.25, (0, 7, 8, 9))

```

```
In [8]: # Example
g_di = gen_digraph(15)
find_djk(g_di)
```

```
path from node 0 to node 1: (1.0, (0, 14, 1))
path from node 0 to node 2: (0.8999999999999999, (0, 7, 2))
path from node 0 to node 3: (0.35, (0, 3))
path from node 0 to node 4: (1.0499999999999998, (0, 3, 12, 4))
path from node 0 to node 5: (0.65, (0, 5))
path from node 0 to node 6: (0.9999999999999999, (0, 3, 8, 6))
path from node 0 to node 7: (0.6, (0, 7))
path from node 0 to node 8: (0.6499999999999999, (0, 3, 8))
path from node 0 to node 9: (0.7, (0, 9))
path from node 0 to node 10: (1.0499999999999998, (0, 3, 10))
path from node 0 to node 11: (0.4, (0, 11))
path from node 0 to node 12: (0.6499999999999999, (0, 3, 12))
path from node 0 to node 13: (0.3, (0, 13))
path from node 0 to node 14: (0.45, (0, 14))
```



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## Exercises

Try the above code for higher number of nodes and verify the algorithm actually works.

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