Problem 16

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Generalized board games

Consider a board game such as Go or Chess, where the state space of possible positions on an $n \times n$ board is exponentially large and there is no guarantee that the game only lasts for a polynomial number of moves. Assume for the moment that there is no restriction on visiting the same position twice.

Exercise 16i

We have to prove that board games like chess or go in $n \times n$ boards are in EXP.

The solution

We only have to give an exponential algorithm that solves such a game.

Main idea

We construct a tree T of possible states of the game ,produced from the initial state by moving pieces around. A state is combination of a configuration of pieces on the board and a variable telling whose turn it is to play. For every configuration of pieces, there are (at most) two states/nodes in the tree. One for the case it is white's turn to play, and one for the case that it is black's turn. This tree can be used to discover if a certain player has a winning strategy or not.

Details

In this tree every node does not have a constant number of children. Every possible state can have polynomially many neighbouring states. We can define $max_number_of_neighbours = p(n)$ to be the maximum number of neighbours a state can have. The exact value depends on the game rules.

Let us consider that in any game there are c kinds of pieces. For example, in chess we have c = 6 (king,queen,rook,bishop,knight,pawn). That means that in every square of the board can have none or one of 2*c pieces (every piece can be either black or white). Therefore, the number of possible configurations on a $n \times n$ board is $(2c+1)^{n^2}$.

From the above observation, we conclude that our directed tree has $2(2c+1)^{n^2}$ nodes. Also, there are various edges, that take us back to nodes of higher levels, although these will not trouble us a lot, as shown later. While creating this tree, we find some states in which either black or white wins. These are the leaves of the tree.

Tree construction

The creation of this tree takes exponential time. Why? Let us describe the constuction process with in detail.

Each state is in the form $s_i = \langle board_i, white_plays_i \rangle$. The first variable gives us the board configuration and the second is a boolean that is true if it is white's turn to play and false otherwise.

We begin with an initial state s_0 , given as input to the problem. Then, we start exploring in a BFS manner. Firstly, we create the p(n) states that can be generated by this initial state, where p(n) is a polynomial of size n. We add the newly created states to a queue, and then we repeat the process for each one of the states in the queue, but without creating duplicate states. In this manner, we shall create no more than $2(2c+1)^{n^2}$ nodes, and since for each node we try p(n) moves, the creation of tree is complete after $O((2c+1)^{n^2}p(n))$ steps.

Tree traversal

Now we have this tree. What do we do with it? Consider how the condition "Player I has a winning strategy" is check-able in this tree.

The condition "Player white has a winning strategy from the initial state <b,true>" is equivalent to " \exists a first move for white s.t. \forall second moves of black, \exists a third move for white s.t. \forall fourth moves of black ... \exists a k-th move for black that wins the game. "

This can be verified in our tree, given exponential time. We will describe how in the algorithm given below. Note that the back-edges do not actually affect the solution, as they lead us to previous nodes.

In our algorithm, we define the $dfs_chess()$ function. This takes as input a state (remember that a state is a board configuration and a boolean telling us whose turn it is) and returns true if starting from this state, player WHITE has a possibility of winning regardless of the moves of player black. It can take as input either a state in which white plays, or a state in which black plays.

Depending on the value of white plays our function's behaviour changes:

- if state.white_plays is true, the function checks if *one* of the child-states of this state (in all of which it is black's turn to play) can lead to white's victory, regardless of the black's move. Equivalently, if $\exists child_state$: $fs_chess(child_state) = true$.
- if state.white_plays is false, the function checks if all of the child-states of this state (in all of which it is white's turn to play) can lead to white's victory. Equivalently, if $\forall child_state: dfs_chess(child_state) = true$

There are some importants cases we must cater for:

- While calculating $dfs_chess(state)$ for some State state, as we fall into the rabbit-hole of recursion we might actually reach a point that we need the value $dfs_chess(state)$! This means that in the sequence of moves we are simulating (the very moves that produce the sequence of states currently stored at the stack) there is a move that can force the game to restart from some moves earlier. This move however does not change the outcome of the game, given that White is an omniscient player. The reason for this is that, no matter how many times we go back in time, if we go back to a winning state, by definition we can do nothing to change it. So, we might as well prohibit these "trips in time", and ignore the moves that move us back to a state already in the recursion stack.
- It is also possible that we come across to a state, let's call it $state_old$ that we already checked at some point in the past if it is a winning state or not. In this case, we will be able to evaluate the value $dfs_chess(state_old)$ instantly, because among other things, the $dfs_chess()$ function stores its result to a huge state-indexed array before returning it.

The algorithm in pseudo-C is as follows.

```
function dfs_chess(Node state ) {
if (! visited(state)) {
//this is the first time we see this node.
        set visited (state)=true;
        if (u. whitePlays) then {
                                 = dfs chess (out-neighbour 1) OR
                 result
                                   dfs chess (out-neighbour 2) OR ...
                                    dfs chess (out-neighbour k)
                 set evaluated (state) = true;
                 set stored_result(state)=result;
                return result;
        } else {
                 result
                                 = dfs chess(out-neighbour 1) AND
                                   dfs chess (out-neighbour 2) AND...
                                    dfs chess (out-neighbour k)
                 set evaluated (state) = true;
                 set stored result(state)=result;
                return result;
}else if (!evualuated(state)) {
//here we are closing a directed cycle
//we don't want cycle to affect the result..
        if (u. whitePlays) then {
                 //this means that we are coming from a
                 //black move. Because we don't want to
                 //affect the result of the function just
                 //before this one we return true, because
                 //A1 AND A2 AND ... AND AK AND TRUE =
                 //A1 AND A2 AND ... AND AK.
                 return true;
        }else {
                //now we know that the above level call is
                //from\ a\ state\ where\ White\ plays , so the
                //condition we want to avoid affecting
                //has only OR's. Therefore, we return false
                return false;
} else {
//We know if this node is a winning node or not!
        return stored_result(state);
}
```

This concludes the proof.

Exercise 16b

Given that the game ends after p(n) moves, we must show that the above problem is in PSPACE.

The solution

This solution is based on a crucial observation.

In the previous problem, we did not really have to create the whole graph and then start traversing it. We could have avoided using so much memory, as we can build the tree as we go, and only keep the current branch we are traversing.

How much memory is used in this case? Roughly, it would be

 $memory_consumption = O(longest_branch_length*max_number_of_neighbours)$

$$= O(longest \ branch \ length * p(n))$$

To prove this, we will describe the improved version of the algorithm.

Space efficient algorithm

Add algorithm here...

In conclusion, in the special case of having polynomially limited duration q(n) of the game, we have polynomial space complexity.