

# Parallel Ports (GPIOs)

Laboratory Report Practice 5

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# **Objectives**

The main objective of this laboratory is to become familiar with the basic instructions for configuring and operating the microcontroller general purpose input/output (GPIO) ports. The student will create the microcontroller firmware that runs the basic operational logic behind a game called Wack-a-mole.

## Introduction

The Curiosity HPC Development Board is an 8-bit prototyping board. It is designed from the ground-up to take full advantage of Microchip MPLAB X integrated development environment and supports Microchip 28- and 40-pin 8-bit PIC MCUs. Programming/debugging is accomplished through the PICkit On Board (PKOB) circuitry, eliminating the need for external programming/debugging tools.

MPLAB X Integrated Development Environment (IDE) is an expandable, highly configurable software program that incorporates powerful tools to help you discover, configure, develop, debug and qualify embedded designs for most of Microchip microcontrollers and digital signal controllers. MPLAB X IDE works seamlessly with the MPLAB development ecosystem of software and tools, many of which are completely free.

# **MPLAB Libraries / Directives / Data Types**

In the first section (figure 1) it's shown the libraries, it's where the libraries are defined, in this case are two; device\_config.h and math.h. Below the libraries are the directives section, this is in order to reference the pin we want to execute in code. For example PORTDbits.RD3 instead of writing the name of the port it's easy to identify as BUTTON\_RD3. The last part of this section is named data types, it's in order to have two states; input (1) and output (0). And in last are the int, that are the ones the Pat tide fine depths variables we're going to use later.

```
#include "device_config.h"
#include <math.h>
 #define _XTAL FREQ 1000000
 #define WAIT TIME 250
 #define BUTTON_RDO PORTDbits.RDO //Button SO
 #define BUTTON RD1 PORTDbits.RD1 //Button S0
 #define BUTTON RD2 PORTDbits.RD2 //Button S0
 #define BUTTON RD3 PORTDbits.RD3 //Button S0
 #define BUTTON_RD4 PORTDbits.RD4 //Button S0
 #define BUTTON RD5 PORTDbits.RD5 //Button S0
 #define BUTTON RD6 PORTDbits.RD6 //Button S0
 #define BUTTON RD7 PORTDbits.RD7 //Button S0
 // digital = 0, analog = 1
 int LED RAND;
 int Estatus;
 int i = 0;
 int n = 8:
 int numero = 0x00;
```

# Main program

```
L // ISR for high priority
   void __interrupt ( high_priority ) high_isr( void );
   void __interrupt ( low_priority ) low_isr( void );
34
35
   36
   void portsInit( void );
37
   38
39 - void main ( void ) {
40
     portsInit();
41
     LED RAND = 0;
     Estatus = 0;
42
     int i = 0;
43
     int n = 8;
44
45
     int numero = 0x00;
46
     while(1){
             // Main loop
47
       LED RAND = rand() % 8;
                               //Gives you a random number from 0 to 7
49
       encender(LED_RAND);
                               //Turns Led on randomly
       pb_matching(LED_RAND);
                               // Checks port D status (push bottons) and if true then win!
        __delay_ms(100);
```

Here is where the main program is executed, portsInit() is the function that will inicialize the variables. LED\_RAND, Estatus, and i = 0, n = 8 and número = 0x00.

In the mail loop (while), that starts with LED\_RAND is a function that will give random numbers from 0 to 7. This is followed up by encender, that basically depending on the random number that we get in the last function, it'll turn on the corresponding led.

# **Functions**

```
58 - void portsInit( void ){
59
      TRISD = input;
                                          // Set Port B as output (LEDs)
      ANSELD = digital;
                                            // Set Port B as digital signal
60
      PORTD = 0x00;
                                          // Initial value = OFF
62
      TRISB = output;
                                          // Set Port B as output (LEDs)
63
      ANSELB = digital;
                                            // Set Port B as digital signal
64
      PORTB = 0x00;
                                         // Initial value = OFF
66
67
68 = int encender(int x){
   switch(x){
70
           case 0:
           LATB = 0x01; // Turn on RB LED delay_ms(WAIT_TIME); // Delay function
71
           LATB = 0x01;
                                         // Delay function XC8 compiler
72
73
            break;
74
75
          case 1:
                                        // Turn on RB LED
          LATB = 0x02;
76
           __delay_ms(WAIT_TIME);
77
                                        // Delay function XC8 compiler
           break;
78
79
          case 2:
80
81
           LATB = 0x04;
                                         // Turn on RB LED
             delay_ms(WAIT_TIME);
                                         // Delay function XC8 compiler
82
```

This function with TRISD will set the port B as output, ANSELD is the function that sets the signal to digital and PORTD is the initial value. The function encender, will turn on the LED corresponding to the number randomly generated.

```
int knight_rider_effect( int y) {
      int i = 0;
      int n = 8;
     int numero = 0x01;
      while (y) {
        numero = 0x01;
         for( i = 0 ; i < n ; i++ ) {
        LATB = numero;
           delay ms (75);
                                   // Delay function XC8 compiler
         numero = numero * 2;
        numero = 0x80;
         for( i = 0 ; i < n ; i++ ) {
         LATB = numero;
           delay ms (75);
                                   // Delay function XC8 compiler
         numero = numero / 2;
        1
      1
```

Knight rider will create a led lightning sequence, while y is on, it will execute the first for, that will start in I = 0 until 7, in increments of 1, this is the going secuence. And the return u

```
140 [ int pb_matching( int a ){
        143
                                            // Otherwise
144
            encender(a);
                                       // Keep turning leds on randomly
        147
148
149
         encender(a);
                                      // Keep turning leds on randomly
150
151
         knight_rider_effect(1);
153
                                  // Otherwise
// Keep turning leds on randomly
154
    encender(a);
155
156
     if((BUTTON_RD3 == pushed) & (a == 3))
knight_rider_effect(1);
157
                                        // If button is pushed and matches current led then
                                            // Otherwise
                                      // Keep turning leds on randomly
160
161
        if((BUTTON_RD4 == pushed) & (a == 4))
162
                                        // If button is pushed and matches current led then
           knight_rider_effect(1);
                                      // WIN!!
163
        else
                                            // Otherwise
164
                                       // Keep turning leds on randomly
         if((BUTTON_RD5 == pushed) & (a == 5))
                                       // If button is pushed and matches current led then
```

pb\_matching will check the push buttons that corresponds to the led that is turn on, for example if push button 2 is pressed and led 1 is on, it will still lighting random leds, in case led 2 is on and push button 2 is on, you will win the game.

#### Video:

https://drive.google.com/file/d/1gkgNzW-j1s-F0nV4UM8H2RUgLwZOyzCL/view?usp=drivesdk

## **Conclusions**

## **Sebastian Medina**

This laboratory practice was a very helpful way to get to know better how the PIC18 microcontroller works and how it interacts with the compiler of MPLAB.

## Ricardo Cárdenas

In this practice we set up the curiosity with the MPLAB software,in which we create a simple game, for as simple as it seems the logic was a little tricky. I'm excited to see what we can achieve with this tools

## **Eduardo Perez**

This practice was useful for the introduction and application of the parallel ports of the PIC18, I think this is a very powerful tool for future projects, also the understanding of the concepts was a bit hard at the beginning.

## Reference

 Matiaz, V. (2022). Introduction to MPLAB X IDE. Retrieved from: https://github.com/matias-vazquez/microcontroladores/tree/main/Lab04