

Universidade Federal de Alagoas - UFAL  
Centro de Tecnologia - CTEC  
Curso de Engenharia Civil

Mecânica dos Sólidos 3 - ECIV051D (2020.2)

**Exercícios:**  
**Deslocamentos em vigas isostáticas usando o método da superposição**  
Encontro Assíncrono

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### Exemplo 9-6

Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

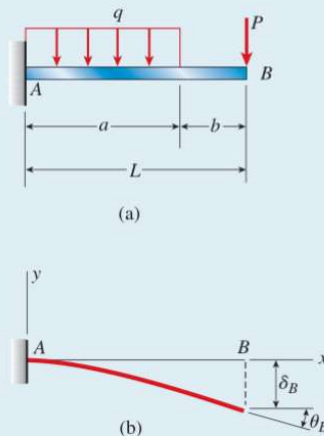
#### Example 9-6

A cantilever beam  $AB$  supports a uniform load of intensity  $q$  acting over part of the span and a concentrated load  $P$  acting at the free end (Fig. 9-18a).

Determine the deflection  $\delta_B$  and angle of rotation  $\theta_B$  at end  $B$  of the beam (Fig. 9-18b). (Note: The beam has length  $L$  and constant flexural rigidity  $EI$ .)

Fig. 9-18

Example 9-6: Cantilever beam with a uniform load and a concentrated load



restart :

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso dos casos 2 e 4 da Tabela G-1.

$$\delta_{B2} := (q, a, L, EI) \rightarrow \frac{q \cdot a^3}{24 \cdot EI} \cdot (4 \cdot L - a) :$$

$$\theta_{B2} := (q, a, EI) \rightarrow \frac{q \cdot a^3}{6 \cdot EI} :$$

$$\delta_{B4} := (P, L, EI) \rightarrow \frac{P \cdot L^3}{3 \cdot EI} :$$

$$\theta_{B4} := (P, L, EI) \rightarrow \frac{P \cdot L^2}{2 \cdot EI} :$$

Usando o método da superposição, tem-se

$$\delta_B := \delta_{B2}(q, a, L, EI) + \delta_{B4}(P, L, EI) = \frac{1}{24} \frac{q a^3 (4 L - a)}{EI} + \frac{1}{3} \frac{P L^3}{EI}$$

$$\theta_B := \theta_{B2}(q, a, EI) + \theta_{B4}(P, L, EI) = \frac{1}{6} \frac{q a^3}{EI} + \frac{1}{2} \frac{P L^2}{EI}$$

### Exemplo 9-9

Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

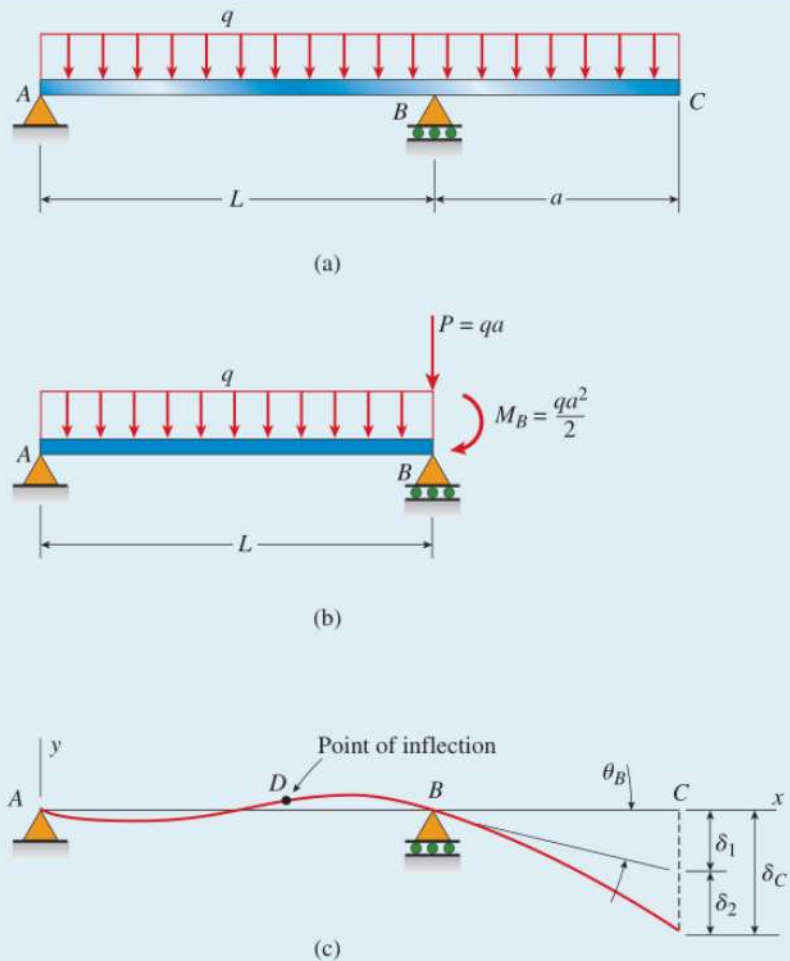
#### ● Example 9-9

A simple beam  $AB$  of span length  $L$  has an overhang  $BC$  of length  $a$  (Fig. 9-21a). The beam supports a uniform load of intensity  $q$  throughout its length.

Obtain a formula for the deflection  $\delta_C$  at the end of the overhang (Fig. 9-21c). (Note: The beam has constant flexural rigidity  $EI$ .)

**Fig. 9-21**

Example 9-9: Simple beam with an overhang



restart :

#### 1) Considerando o trecho biapoiado $AB$ com o binário da carga $P = q \cdot a$

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso dos casos 1 e 7 da Tabela G-2.

$$\theta_{B1} := (q, L, EI) \rightarrow \frac{q \cdot L^3}{24 \cdot EI} :$$

$$\theta_{A7} := (M_0, L, EI) \rightarrow \frac{M_0 \cdot L}{3 \cdot EI} :$$

$$\theta_B := -\theta_{B1}(q, L, EI) + \theta_{A7}\left(\frac{q \cdot a^2}{2}, L, EI\right) = -\frac{1}{24} \frac{q L^3}{EI} + \frac{1}{6} \frac{L q a^2}{EI}$$

$$\delta_1 := \theta_B \cdot a = \left(-\frac{1}{24} \frac{q L^3}{EI} + \frac{1}{6} \frac{L q a^2}{EI}\right) a$$

## 2) Considerando o trecho engastado e livre BC

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso do caso 1 da Tabela G-1.

$$\delta_{BI} := (q, L, EI) \rightarrow \frac{q \cdot L^4}{8 \cdot EI} :$$

$$\delta_2 := \delta_{BI}(q, a, EI) = \frac{1}{8} \frac{q a^4}{EI}$$

**1+2) Usando o método da superposição e assumindo deflexão nula em C, tem-se**

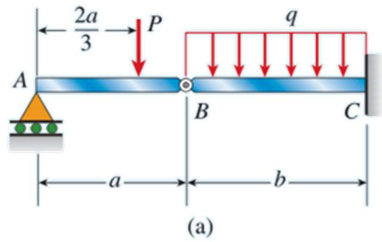
$$\delta_C := \delta_1 + \delta_2 = \left( -\frac{1}{24} \frac{q L^3}{EI} + \frac{1}{6} \frac{L q a^2}{EI} \right) a + \frac{1}{8} \frac{q a^4}{EI}$$

$$\text{simplify} \left( \delta_C - \frac{q \cdot a}{24 \cdot EI} \cdot (L \cdot (4 \cdot a^2 - L^2) + 3 \cdot a^3) \right) = 0$$

### Exemplo 9-8

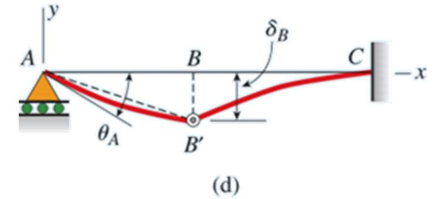
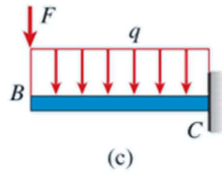
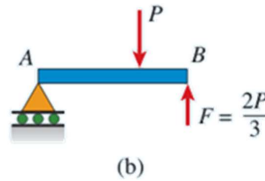
Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

#### Example 9-8: Compound beam with a hinge



A compound beam ABC has a roller support at A, an internal hinge (i.e., moment release) at B, and a fixed support at C (Fig. 9-20a). Segment AB has length  $a$  and segment BC has length  $b$ . A concentrated load  $P$  acts at distance  $2a/3$  from support A and a uniform load of intensity  $q$  acts between points B and C.

Determine the deflection  $\delta_B$  at the hinge and the angle of rotation  $\theta_A$  at support A (Fig. 9-20d). (Note: The beam has constant flexural rigidity  $EI$ .)



restart :

$$F := \text{solve}\left(-P \cdot \frac{2 \cdot a}{3} + F \cdot a = 0, F\right) = \frac{2}{3} P$$

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso dos casos 1 e 4 da Tabela G-1.

$$\delta_{B1} := (q, L, EI) \rightarrow \frac{q \cdot L^4}{8 \cdot EI} :$$

$$\delta_{B4} := (P, L, EI) \rightarrow \frac{P \cdot L^3}{3 \cdot EI} :$$

Usando o método da superposição, determina-se a deflexão em B

$$\delta_B := \delta_{B1}(q, b, EI) + \delta_{B4}(F, b, EI) = \frac{1}{8} \frac{q b^4}{EI} + \frac{2}{9} \frac{P b^3}{EI}$$

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso do caso 5 da Tabela G-2.

$$\theta_{A5} := (P, a, b, L, EI) \rightarrow \frac{P \cdot a \cdot b \cdot (L + b)}{6 \cdot L \cdot EI} :$$

Usando o método da superposição, determina-se a rotação em A

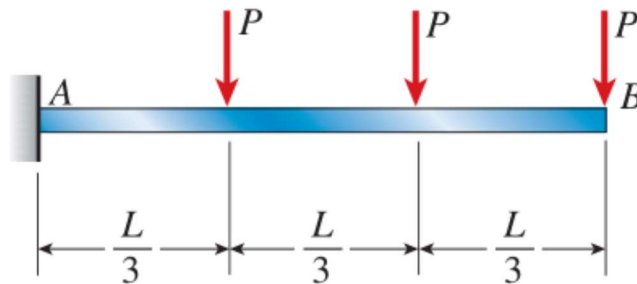
$$\theta_{A,2} := \theta_{A5}\left(P, \frac{2 \cdot a}{3}, \frac{a}{3}, a, EI\right) = \frac{4}{81} \frac{a^2 P}{EI}$$

$$\theta_A := \text{expand}\left(\frac{\delta_B}{a} + \theta_{A,2}\right) = \frac{1}{8} \frac{q b^4}{a EI} + \frac{2}{9} \frac{P b^3}{a EI} + \frac{4}{81} \frac{a^2 P}{EI}$$

**Problema 9.5-1**

Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

**9.5-1** A cantilever beam  $AB$  carries three equally spaced concentrated loads, as shown in the figure. Obtain formulas for the angle of rotation  $\theta_B$  and deflection  $\delta_B$  at the free end of the beam.

**PROB. 9.5-1**

*restart :*

**Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso dos casos 4 e 5 da Tabela G-1.**

$$\delta_{B4} := (P, L, EI) \rightarrow \frac{P \cdot L^3}{3 \cdot EI} :$$

$$\theta_{B4} := (P, L, EI) \rightarrow \frac{P \cdot L^2}{2 \cdot EI} :$$

$$\delta_{B5} := (P, a, L, EI) \rightarrow \frac{P \cdot a^2}{6 \cdot EI} \cdot (3 \cdot L - a) :$$

$$\theta_{B5} := (P, a, EI) \rightarrow \frac{P \cdot a^2}{2 \cdot EI} :$$

**Usando o método da superposição, tem-se**

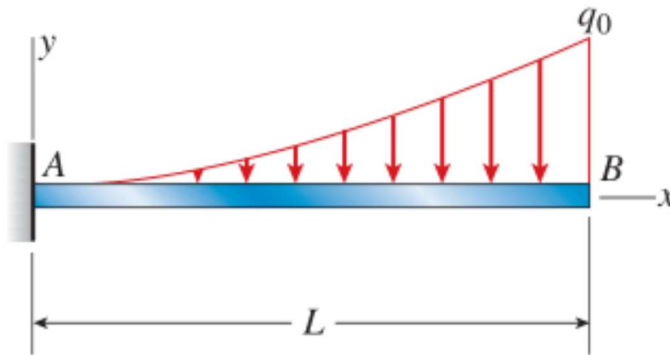
$$\theta_B := \theta_{B5}\left(P, \frac{L}{3}, EI\right) + \theta_{B5}\left(P, \frac{2 \cdot L}{3}, EI\right) + \theta_{B4}(P, L, EI) = \frac{7}{9} \frac{PL^2}{EI}$$

$$\delta_B := \delta_{B5}\left(P, \frac{L}{3}, L, EI\right) + \delta_{B5}\left(P, \frac{2 \cdot L}{3}, L, EI\right) + \delta_{B4}(P, L, EI) = \frac{5}{9} \frac{PL^3}{EI}$$

**Problema 9.5-13**

Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

**9.5-13** Determine the angle of rotation  $\theta_B$  and deflection  $\delta_B$  at the free end of a cantilever beam  $AB$  supporting a parabolic load defined by the equation  $q(x) = q_0 x^2/L^2$  (see figure).

**PROB. 9.5-13**

restart :

$$q := x \rightarrow q_0 \cdot \frac{x^2}{L^2} :$$

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso do caso 5 da Tabela G-1.

$$\delta_{B5} := (P, a, L, EI) \rightarrow \frac{P \cdot a^2}{6 \cdot EI} \cdot (3 \cdot L - a) :$$

$$\theta_{B5} := (P, a, EI) \rightarrow \frac{P \cdot a^2}{2 \cdot EI} :$$

Usando o método da superposição e integrando para  $0 \leq x \leq L$ , tem-se

$$\theta_B := \int_0^L \theta_{B5}(q(x), x, EI) \, dx = \frac{1}{10} \frac{q_0 L^3}{EI}$$

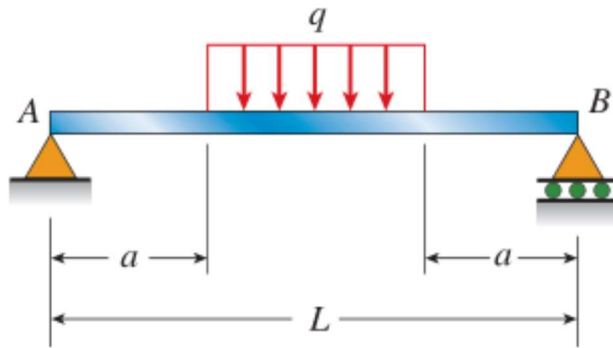
$$\delta_B := \int_0^L \delta_{B5}(q(x), x, L, EI) \, dx = \frac{13}{180} \frac{q_0 L^4}{EI}$$

**Problema 9.5-14**

Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

**9.5-14** A simple beam  $AB$  supports a uniform load of intensity  $q$  acting over the middle region of the span (see figure).

Determine the angle of rotation  $\theta_A$  at the left-hand support and the deflection  $\delta_{\max}$  at the midpoint.

**PROB. 9.5-14**

restart :

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso do caso 5 da Tabela G-2.

$$\theta_{A5} := (P, x, b, L, EI) \rightarrow \frac{P \cdot x \cdot b \cdot (L + b)}{6 \cdot L \cdot EI} :$$

$$\delta_{C5} := (P, x, L, EI) \rightarrow \frac{P \cdot x \cdot (3 \cdot L^2 - 4 \cdot x^2)}{48 \cdot EI} :$$

Usando o método da superposição e integrando para  $a \leq x \leq L - a$ , tem-se

$$\theta_A := \text{simplify} \left( \int_a^{L-a} \theta_{A5}(q, x, L-x, L, EI) \, dx \right) = \frac{1}{24} \frac{q (L^3 - 6 L a^2 + 4 a^3)}{EI}$$

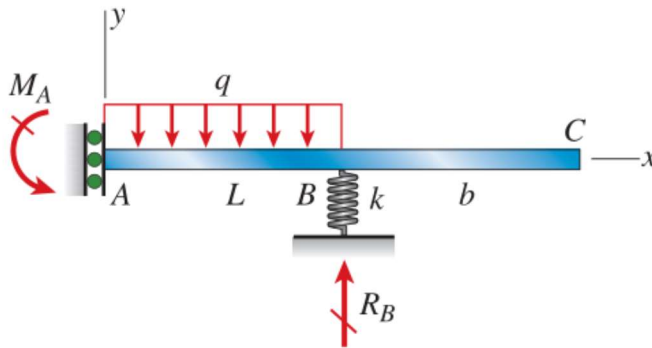
$$\delta_{\max} := \text{simplify} \left( 2 \cdot \int_a^{\frac{L}{2}} \delta_{C5}(q, x, L, EI) \, dx \right) = \frac{1}{384} \frac{q (5 L^4 - 24 L^2 a^2 + 16 a^4)}{EI}$$



**Problema 9.5-17**

Referência: Gere & Goodno (2013). Mechanics of Materials, 8th Edition. Cengage Learning.

**9.5-17** An overhanging beam  $ABC$  with flexural rigidity  $EI = 45 \text{ N} \cdot \text{m}^2$  is supported by a guided support at  $A$  and by a spring of stiffness  $k$  at point  $B$  (see figure). Span  $AB$  has length  $L = 0.75 \text{ m}$  and carries a uniform load. The overhang  $BC$  has length  $b = 375 \text{ mm}$ . For what stiffness  $k$  of the spring will the uniform load produce no deflection at the free end  $C$ ?

**PROB. 9.5-17**

restart :

Consultando o Anexo G (Gere & Goodno, 2013), faz-se uso do caso 1 da Tabela G-2.

$$\theta_{BI} := (q, L, EI) \rightarrow \frac{q \cdot L^3}{24 \cdot EI} :$$

**1) Considerando um apoio simples em B**

Trecho AB: metade de uma viga biapoiada com carregamento uniforme (cortante nula em A)

$$\delta_{CI} := \theta_{BI}(q, 2 \cdot L, EI) \cdot b = \frac{1}{3} \frac{q L^3 b}{EI}$$

**2) Considerado o efeito do apoio elástico**

$$R_B := q \cdot L :$$

$$\delta_B := \text{solve}(k \cdot \delta_B = R_B, \delta_B) = \frac{q L}{k}$$

**1+2) Usando o método da superposição e assumindo deflexão nula em C, tem-se**

$$\delta_C := -\delta_{CI} + \delta_B = -\frac{1}{3} \frac{q L^3 b}{EI} + \frac{q L}{k}$$

$$k := \text{solve}(\delta_C = 0, k) = \frac{3 EI}{L^2 b}$$

**\* Verificação: Resolvendo pela equação diferencial da elástica**

*restart :*

**Reações de apoio**

$$\text{assign}\left(\text{solve}\left(\left\{R_B - q \cdot L = 0, M_A + (q \cdot L) \cdot \frac{L}{2} = 0\right\}, \{R_B, M_A\}\right)\right) :$$

$$R_B, M_A = q L, -\frac{q L^2}{2}$$

**Momento fletor**

$$M_{AB} := \text{solve}\left(M + M_A + (q \cdot x) \cdot \frac{x}{2} = 0, M\right) :$$

**Deflexão**

$$bc := D[1](v)(0) = 0, v(L) = -\frac{R_B}{k} :$$

$$v := \text{unapply}\left(\text{simplify}\left(\text{rhs}\left(\text{dsolve}\left(\left\{\text{diff}(v(x), x\$2) = \frac{M_{AB}}{EI}, bc\right\}, v(x)\right)\right), x\right) :$$

**Cálculo da deflexão em C**

$$v(L) = -\frac{q L}{k}$$

$$D[1](v)(L) = \frac{L^3 q}{3 EI}$$

$$v_C := v(L) + D[1](v)(L) \cdot b :$$

**Cálculo de  $k$  assumindo deflexão nula em C**

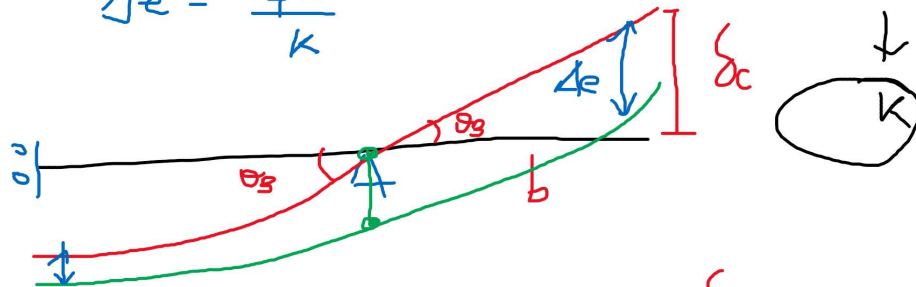
$$\text{solve}(v_C = 0, k) = \frac{3 EI}{L^2 b}$$

Esquema ilustrativo

$$K \Delta e = R_B = qL$$

$$\Delta e = \frac{qL}{K}$$

$$b \cdot \theta_B - \frac{qL}{K} = 0$$



$$\frac{\sin \theta_B}{\cos \theta_B} = \tan \theta_B = \frac{\Delta e}{b}$$

$$\theta_B \ll 1 \Rightarrow \sin \theta_B \approx \theta_B$$

$$\cos \theta_B \approx 1$$

$$\boxed{\Delta e = b \cdot \theta_B}$$