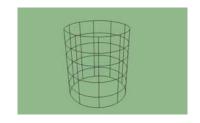
- So far, every geometric primitive has been drawn as either a solid color or smoothly shaded between the colors at its vertices, that is, they've been drawn without texture mapping.
- Texture mapping allows you to glue an image to a polygon.
- Texture mapping ensures that all the right things happen as the polygon is transformed and rendered.





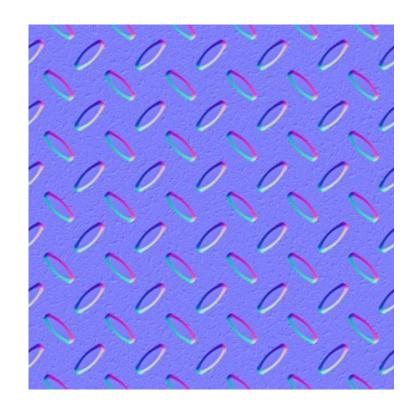


 Other uses for texture mapping include depicting vegetation on large polygons representing the ground in flight simulation; wallpaper patterns; and textures that make polygons look like natural substances such as marble, wood, and cloth.



- Texture mapping is a fairly large, complex subject, and you must make several programming choices when using it.
- Most people intuitively understand a two-dimensional texture, but a texture may be **one-dimensional** or even **three-dimensional**.
- You can map textures to surfaces made of a set of polygons or to curved surfaces, and you can repeat a texture in one, two, or three directions (depending on how many dimensions the texture is described in) to cover the surface.

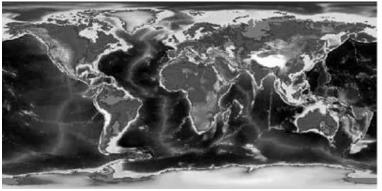
 You can automatically map a texture onto an object in such a way that the texture indicates contours or other properties of the item being viewed.

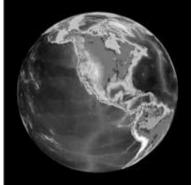


- For 2D texture mapping, we use a 2D coordinate, often called **uv**, which is used to create a reflectance R(u, v).
- The key is to take an image and associate a (u, v) coordinate system on it so that it can, in turn, be associated with points on a 3D surface.

Example:

• If the latitudes and longitudes on the world map are associated with a polar coordinate system on the sphere, we get a globe





- As a convention, the coordinate system on the image is set to be the unit square $(u, v) \in [0, 1]^2$.
- For (u, v) outside of this square, only the fractional parts of the coordinates are used resulting in a tiling of the plane.
- Note that the image has a different number of pixels horizontally and vertically, so the image pixels have a non-uniform aspect ratio in (*u*, *v*) space.

- To map this $(u, v) \in [0, 1]^2$ image onto a sphere, we first compute the polar coordinates.
- Recall the spherical coordinate system described by Equations

```
x = r \cos \varphi \sin \vartheta,

y = r \sin \varphi \sin \vartheta,

z = r \cos \vartheta.
```

- For a sphere of radius R with center (cx, cy, cz), the parametric equation of the sphere is
- $x = xc + R\cos \phi \sin \theta$,
- $y = yc + Rsin \phi sin \theta$,
- $z = zc + R\cos\theta$.

- We can find (θ, ϕ) :
- $\theta = arcos(\frac{z-z_c}{R})$
- $\varphi = \arctan_2(y y_c, x x_c)$
- where arctan2(a, b) is the atan2 of most math libraries which returns the arctangent of a/b.

- Because $(\theta, \phi) \in [0, \pi] \times [-\pi, \pi]$, we convert to (u, v) as
- follows, after first adding 2π to φ if it is negative:

•
$$U = \frac{\varphi}{2\pi}$$

•
$$v = \frac{\pi - \theta}{\pi}$$