Riccardo Periotto

Computer Scientist | Autonomous Systems Engineer

dec 2023-



About me

Driven by my passion for learning and technology, I approached the ICT world during high school and delved into the subject until I graduated in Computer Science. Between my bachelor's and master's degrees, I worked in the field for a year to better understand which specialization was the most suitable for me. I have now completed my master's degree in Autonomous Systems, and I know that my primary goal is to develop software solutions for robots, as this will allow me to use the wide range of knowledge I've acquired throughout my education. Robotics, control, and deep learning are the subjects I prefer, and I am eager to apply them to my next challenge!

— Personal information —

- **†** Born on 15/09/1998
- riccardo.periotto@gmail.com
- 38080 Carisolo (TN), Italy
- in riccardoperiotto
- riccardoperiotto

- Languages

- 🚺 Italian Native Language
- # English Professional Knowledge
- German Basic Knowledge

Programming languages



Hard skills



EDUCATION

sep 2021- nov 2023	MSc Autonomous Systems EIT Digital	Q Europe	
	European double degree program focusing gies, entrepreneurship, and business.	on new technolo-	
	First year: Royal Institute of Technology (KTH) Summer school: Technical University of Munich (TUM)		
	Second year: University of Trento (UniTN)		
sep 2017-	BSc Computer Science	🕈 Trento, Italia	
jul 2020	University of Trento		
	Main subjects: Algorithms, Software Engineering		
	Grade: 110/110 with honours		
sep 2014-	HS Computer Science	Rovereto, Italia	
jul 2017	ITT Marconi Rovereto		

EVDEDIENCE (S. 41 - C-11 - C-4...1-.)

Software Engineer for Robotics 9 Munich, Germany

Main subjects: Programming, Network Systems

(in the field of study)

Grade: 100/100 with honours

ongoing द	Agile Robots AG Recently joined the backend team to work on AgileCore, the company software platform facilitating the development and deployment of automation solutions.		
jan 2023- jul 2023 ≸ ERICSSON	Research Intern Ericsson Degree project in ROS 2 focusing teleoperation with obstacle avoidance	O	
	Project title: Safety-Critical Teleop Delays. MPC-CBF-based approache	, 0	
jan 2021- sep 2021 ••• polytec	Software Engineer BM Group Polytec S.p.A. Development of cloud solutions for the main project I worked on link.	♥ Borgo Chiese, Italy industrial plants. Video to	
oct 2019- feb 2020	Computer Science Intern SpazioDati S.r.l. Development of the bachelor's degree	♥ Trento, Italy tee thesis project. Javascript	

(MAIN) "TOOLS"

- ROS 2: advanced
- Linux & git: advanced
- SQL & Databases: advanced
- PyTorch: intermediate
- Unity: intermediate

application focusing on the company APIs and large datasets.

• Node.js/React.js: intermediate

• .NET: advanced

I live in a tourist area and have always done **seasonal jobs**. Sometimes, I am far too meticulous, and indeed my scout totem is *Precise Hedge-hog*. I love sports, climbing and snowboarding in particular, even if my only addiction is **running**; I don't do it competitively, but I can't go more than 4 days without it!

Updated version of this document available at: CV-RiccardoPeriotto. Date: February 28, 2024.