Prediction of Exercise Class

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Executive Summary

This study was commissioned to predict the class of how a subject performed an exercise. The data used for this project was collected from a range of wireless activity wristbands. The wristbands were worn be the subjects as they performed excercies in 5 different ways. To study the data I broke the source data into a training and testing set. I experimented with 2 training models; Decision Tree and Random Forest. The decision tree performed very poorly which is likely to be caused by a lack of homogeneity in the data. We know that random forest is one of the most accurate models and it proved itself here with this data.

Getting and Cleaning

```
library(knitr)
library(dplyr)
library(plyr)
library(ggplot2)
library(gridExtra)
library(caret)
library(party)
#library(e1071)
set.seed(2016)
#download the data if it doesn't already exist
if(!file.exists("pml-training.csv")) {
  trainURL <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv"</pre>
  download.file(trainURL, destfile="pml-training.csv")
}
if(!file.exists("pml-testing.csv")) {
  trainURL <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv"</pre>
  download.file(trainURL, destfile="pml-testing.csv")
}
#Load the data into R
  pmlVal <- read.csv("pml-testing.csv")</pre>
  pmlData <- read.csv("pml-training.csv")</pre>
#Remove all the columns that include NA values
NAcols <- colSums(is.na(pmlData)) == 0
Validcolumns <- sum(NAcols == TRUE)</pre>
pmlData <- pmlData[, NAcols]</pre>
#Remove columns that are not meaningful predictors
nzv <- nearZeroVar(pmlData, saveMetrics = T)</pre>
pmlData <- pmlData[, nzv$nzv==F]</pre>
#pmlData <- head(pmlData, 1000)</pre>
str(pmlData)
```

```
## 'data.frame': 19622 obs. of 59 variables:
## $ X
                      : int 1 2 3 4 5 6 7 8 9 10 ...
                      : Factor w/ 6 levels "adelmo", "carlitos", ...: 2 2 2 2 2 2 2 2
## $ user name
2 2 ...
## $ raw_timestamp_part_1: int 1323084231 1323084231 1323084231 1323084232 1323084232
1323084232 1323084232 1323084232 1323084232 ...
## $ raw timestamp part 2: int 788290 808298 820366 120339 196328 304277 368296 44039
0 484323 484434 ...
## $ cvtd_timestamp : Factor w/ 20 levels "02/12/2011 13:32",..: 9 9 9 9 9 9 9 9
99 ...
## $ num window
                     : int 11 11 11 12 12 12 12 12 12 12 ...
## $ roll_belt
                     : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
## $ pitch_belt
                     : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw_belt
                            -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4
                     : num
-94.4 ...
## $ total accel belt : int 3 3 3 3 3 3 3 3 3 ...
## $ gyros_belt_x : num 0 0.02 0 0.02 0.02 0.02 0.02 0.02 0.03 ...
## $ gyros_belt_y
                     : num 00000.0200000...
                     : num -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02
## $ gyros_belt_z
0 ...
## $ accel_belt_x : int -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel_belt_y
                     : int 4453243424...
## $ accel belt z
                     : int 22 22 23 21 24 21 21 21 24 22 ...
                     : int
## $ magnet belt x
                            -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
                     : int 599 608 600 604 600 603 599 603 602 609 ...
## $ magnet_belt_y
## $ magnet_belt_z
                     : int
                            -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
## $ roll_arm
                     : num
                            ## $ pitch arm
                     : num
                            22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
## $ yaw_arm
                            : num
## $ total accel arm
                            34 34 34 34 34 34 34 34 ...
                     : int
## $ gyros_arm_x
                      ## $ gyros_arm_y
                     : num 0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.02 -0.03 -0.0
3 ...
                  : num
## $ gyros_arm_z
                            -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
                     ## $ accel_arm_x
                     : int 109 110 110 111 111 111 111 111 109 110 ...
## $ accel_arm_y
                            -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
## $ accel arm z
                     : int
                            -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
## $ magnet arm x
                     : int
## $ magnet_arm_y
                     : int
                            337 337 344 344 337 342 336 338 341 334 ...
## $ magnet_arm_z
                     : int
                            516 513 513 512 506 513 509 510 518 516 ...
## $ roll_dumbbell
                     : num
                            13.1 13.1 12.9 13.4 13.4 ...
## $ pitch_dumbbell
                            -70.5 -70.6 -70.3 -70.4 -70.4 ...
                     : num
## $ yaw dumbbell
                     : num
                            -84.9 -84.7 -85.1 -84.9 -84.9 ...
## $ total_accel_dumbbell: int 37 37 37 37 37 37 37 37 37 37 ...
## $ gyros_dumbbell_x : num
                            00000000000...
## $ gyros dumbbell y
                     : num
                            -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02
-0.02 ...
## $ gyros dumbbell z : num 000-0.02000000...
## $ accel_dumbbell_x : int -234 -233 -232 -233 -234 -232 -234 -232 -235 ...
## $ accel_dumbbell_y
                     : int 47 47 46 48 48 48 47 46 47 48 ...
## $ accel dumbbell z : int -271 -269 -270 -269 -270 -269 -270 -272 -269 -270 ...
## $ magnet_dumbbell_x : int
                            -559 -555 -561 -552 -554 -558 -551 -555 -549 -558 ...
## $ magnet dumbbell y : int 293 296 298 303 292 294 295 300 292 291 ...
```

```
$ magnet dumbbell z : num -65 -64 -63 -60 -68 -66 -70 -74 -65 -69 ...
## $ roll forearm
                             28.4 28.3 28.3 28.1 28 27.9 27.9 27.8 27.7 27.7 ...
                       : num
## $ pitch_forearm
                             -63.9 -63.9 -63.9 -63.9 -63.9 -63.9 -63.8 -63.8
                      : num
-63.8 ...
## $ yaw_forearm
                       ## $ total accel forearm : int 36 36 36 36 36 36 36 36 36 ...
## $ gyros_forearm_x
                      : num 0.03 0.02 0.03 0.02 0.02 0.02 0.02 0.03 0.02 ...
## $ gyros_forearm_y
                      : num 0 0 -0.02 -0.02 0 -0.02 0 -0.02 0 0 ...
## $ gyros forearm z
                             -0.02 -0.02 0 0 -0.02 -0.03 -0.02 0 -0.02 -0.02 ...
                      : num
## $ accel forearm x
                      : int 192 192 196 189 189 193 195 193 193 190 ...
## $ accel_forearm_y
                      : int 203 203 204 206 206 203 205 205 204 205 ...
## $ accel_forearm_z
                      : int -215 -216 -213 -214 -214 -215 -215 -213 -214 -215 ...
## $ magnet_forearm_x
                      : int -17 -18 -18 -16 -17 -9 -18 -9 -16 -22 ...
## $ magnet_forearm_y
                      : num 654 661 658 658 655 660 659 660 653 656 ...
## $ magnet_forearm_z : num 476 473 469 469 473 478 470 474 476 473 ...
## $ classe
                       : Factor w/ 5 levels "A", "B", "C", "D", ...: 1 1 1 1 1 1 1 1 1 1 1
```

After the data was loaded, it was important to remove the NA columns as they could mislead the results. I also removed the columns that did not contribute any variance to the prediction model.

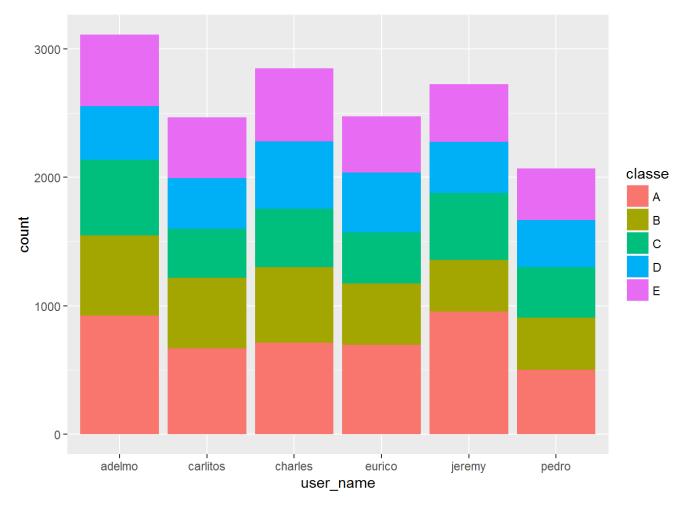
Setup Cross-Validation

```
partition <- createDataPartition(pmlData$classe, p=0.8, list=F)</pre>
inTrain <- pmlData[partition, ]</pre>
inTest <- pmlData[-partition, ]</pre>
i <- data.frame("Total"=c(nrow(inTrain), nrow(inTest)))</pre>
DT <- matrix(NA, nrow=2, ncol=5)
TR <- as.data.frame(table(inTrain$classe))</pre>
TE <- as.data.frame(table(inTest$classe))</pre>
DT[1, ] \leftarrow TR[,2]
DT[2, ] <- TE[,2]
g <- as.data.frame(DT)</pre>
colnames(g) <- c("A", "B", "C", "D", "E")</pre>
e<- cbind(g, i)
f <- colSums(e)
r <- rbind(e, f)
rownames(r) <- c('Training Data','Testing Data','Total')</pre>
kable(r)
```

	Α	В	С	D	E	Total
Training Data	4464	3038	2738	2573	2886	15699
Testing Data	1116	759	684	643	721	3923
Total	5580	3797	3422	3216	3607	19622

This shows the break-down of the outcome variable.

```
qplot(user_name, data=inTrain, fill=classe)
```



Build Decision Tree Model

In this section

```
treeFit <- train(classe ~., method="rpart", data=inTrain)</pre>
treePred <- predict(treeFit, newdata=inTest)</pre>
treeMatrix <- confusionMatrix(inTest$classe, treePred)</pre>
treeMatrix$overall['Accuracy']
```

```
Accuracy
## 0.6614836
```

treeMatrix\$table

```
##
             Reference
## Prediction
                 Α
                                      Ε
                                      0
##
            A 1116
##
            В
                 1 758
                                 0
                                      0
                                 0 684
##
            C
                 0
##
            D
                 0
                      0
                            0
                                 0 643
##
            Ε
                                 0 721
```

Random Forest

```
ctrl <- trainControl(allowParallel = T, method="cv", number=4)</pre>
rfFit <- train(classe ~., method="rf", data=inTrain, trControl=ctrl)</pre>
rfPred <- predict(rfFit, newdata=inTest)</pre>
rfMatrix <- confusionMatrix(inTest$classe, rfPred)</pre>
rfMatrix$overall['Accuracy']
```

```
## Accuracy
## 0.9997451
```

rfMatrix\$table

```
##
        Reference
         A B C
                    D E
## Prediction
      A 1116
##
       В
         1 758 0
                    0
                       0
       C 0 0 684 0
##
                       0
##
       D 0 0 0 643
                       0
       E 0 0 0 0 721
##
```

Out of Sample Error

```
err <- 1-rfMatrix$overall['Accuracy']</pre>
err
```

```
##
      Accuracy
## 0.000254907
```

The expected Out of Sample Error is 0.02% which is very good for prediction. Therefore we will use the random forest.

Predict New Data

```
pmlVal <- pmlVal[, NAcols]</pre>
pmlVal <- pmlVal[, nzv$nzv==F]</pre>
testing <- pmlVal[, 1:58]</pre>
testPred <- predict(rfFit, newdata=testing)</pre>
```