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Research Interests

Computational Design, Human-Computer Interaction, Deep Learning, Digital Fabrication

Education

Ph.D. in Human-Computer Interaction (in progress)

CARNEGIE MELLON UNIVERSITY, SCHOOL OF COMPUTER SCIENCE

· Advisor: Lining Yao

B.S. in Electrical and Computer Engineering

SHANGHAI JIAO TONG UNIVERSITY, SCHOOL OF INFORMATION AND ELECTRICAL

ENGINEERING

[CHI 2019]

• Advisor: Xinbing Wang

Aug. 2018 - Present

Pittsburgh, PA, USA

Sept. 2014 - Apr. 2018

Shanghai, China

Publications

PEER-REVIEWED CONFERENCE PAPERS

Inverse Design Tool for Asymmetrical Self-Rising Surfaces with Color Texture

Jianzhe Gu, Vidya Narayanan, Guanyun Wang, Danli Luo, Harshika Jain, Kexin Lu, Fang Qin, Sijia [SCF 2020]

Wang, James McCann, and Lining Yao

In Symposium on Computational Fabrication. ACM.

E-seed: Shape-Changing Interfaces that Self Drill

[UIST 2020] Danli Luo, Jianzhe Gu, Fang Qin, Guanyun Wang, and Lining Yao

In Proceedings of the 33rd Annual ACM Symposium on User Interface Software and Technology

SimuLearn: Fast and Accurate Simulator to Support Morphing Materials Design and Workflows

Humphrey Yang, Kuanren Qian, Haolin Liu, Yuxuan Yu, Jianzhe Gu, Matthew McGehee, Yongjie [UIST 2020]

Jessica Zhang, and Lining Yao

In Proceedings of the 33rd Annual ACM Symposium on User Interface Software and Technology

Material characterization and precise finite element analysis of fiber reinforced thermoplastic composites for 4D printing

[CAD 2020] Yuxuan Yu, Haolin Liu, Kuanren Qian, Humphrey Yang, Matthew McGehee, Jianzhe Gu, Danli Luo,

Lining Yao and Yongjie Jessica Zhang

Computer-Aided Design 2020

Geodesy: Self-rising 2.5D Tiles by Printing along 2D Geodesic Closed Path

Jianzhe Gu, David E. Breen, Jenny Hu, Lifeng Zhu, Ye Tao, Tyson Van de Zande, Guanyun Wang,

Yongjie Jessica Zhang, and Lining Yao

In Proceedings of the 2019 CHI Conference on Human Factors in Computing Systems

4DMesh: 4D Printing Morphing Non-Developable Mesh Surfaces

[UIST 2018] Guanyun Wang, Humphrey Yang, Zeyu Yan, Nurcan Gecer Ulu, Ye Tao, **Jianzhe Gu**, Levent Burak

Kara, and Lining Yao

In Proceedings of the 31st Annual ACM Symposium on User Interface Software and Technology

Printed Paper Actuator: A Low-cost Reversible Actuation and Sensing Method for Shape Changing Interfaces

Changing Interfaces

[CHI 2018] Guanyun Wang, Tingyu Cheng, Youngwook Do, Humphrey Yang, Ye Tao, **Jianzhe Gu**, Byoungkwon

An, and Lining Yao

In Proceedings of the 2018 CHI Conference on Human Factors in Computing Systems

Thermorph: Democratizing 4D printing of self-folding materials and interfaces

[CHI 2018] Kwon An, Ye Tao, **Jianzhe Gu**, Tingyu Cheng, Anthony Chen, Xiaoxiao Zhang, Wei Zhao, Youngwook

Do, Shigeo Takahashi, Hsiang-Yun Wu, Teng Zhang, and Lining Yao

In Proceedings of the 2018 CHI Conference on Human Factors in Computing Systems

DEMONSTRATIONS AND POSTERS

4DTexture: A Shape-Changing Fabrication Method for 3D Surfaces with Texture

[CHI EA'20] Lingyun Sun, Jiaji Li, Yu Chen, Yue Yang, Ye Tao, Guanyun Wang, and Lining Yao

In Proceedings of the 2018 CHI Conference on Human Factors in Computing Systems

Research Experience_____

Computational 4D Printing (advised by Lining Yao and Jim McCann)

Aug. 2018 - 2020

HUMAN-COMPUTER INTERACTION INSTITUTE, CARNEGIE MELLON UNIVERSITY

Pittsburgh, PA, USA

With optimized printing tool paths and local layer height, 3D printed flat sheets can self-transform into 3D shapes under heat. By viewing 3D printing as a programming system, we encode the internal morphing energy into the material through basic machine operations. We built an end-to-end tool that optimized the printing G-code to enable flat sheets to self-transform into arbitrary input height field. The tool flattens the height field into a 2D layout with stress information using a geometry-based optimization algorithm, and computes printing tool paths with a local path planning algorithm. Such a system enables rapid prototyping, flat-packaging and self-deployment.

Haptic Origami (adviced by Lining Yao)

April. 2020 - Present

HUMAN-COMPUTER INTERACTION INSTITUTE, CARNEGIE MELLON UNIVERSITY

Pittsburgh, PA, USA

The research is focusing on building an Al-generated elastic-origami-based haptic feedback system that generates force-displacement feedback by designing specific origami structures. Using pattern-generation graph network and a differentiable simulator, the system will design an optimized origami pattern for a specific 2D force feedback. Users can move around a joystick fixed on a half-folded origami, and sense a varying 2D force diagram.

Service

Paper Reviewing CHI (2019), **UIST** (2019-2020)

Courses & Technical Skills_

Programming Python, C/C++, Javascript, Objective-C, Matlab, LTEX

Frameworks Tensorflow, Pytorch, OpenGL, Eigen

Tools Unix/Linux, Adobe Illustrator, Blender, Rhino/Grasshopper

Courses

Deep Learning, Deep Reinforcement Learning, Convex Optimization, Computer Graphics,

Discrete Differential Geometry, Optimal Control