

# Chapter 4

## Likelihood-based inference

## 4.1 Likelihoods

Data  $\mathbf{x} = \{x_1, \dots, x_n\}$ , joint distribution of  $\mathbf{x}$  depends on unknown  $\theta$ .

Likelihood is density (or probability if  $x_i$  is discrete) of the data  $x$  conditional on the parameter  $\theta$ , i.e.

$$f(\mathbf{x}|\theta).$$

Function of  $\theta$  *for fixed*  $\mathbf{x}$ , so denote the likelihood function by  $L(\theta; \mathbf{x})$ :

$$L(\theta; \mathbf{x}) = f(\mathbf{x}|\theta).$$

If  $x_1, \dots, x_n$  are independent, then

$f(\mathbf{x}|\theta) = f(x_1|\theta) \times f(x_2|\theta) \times \dots \times f(x_n|\theta)$ , and so

$$L(\theta; \mathbf{x}) = \prod_{i=1}^n f(x_i|\theta).$$

Used for point and interval estimation, and hypothesis testing.

# Score statistics, Fisher information and the Cramer-Rao minimum variance bound

The score statistic is defined to be  $\frac{\partial}{\partial \theta} l(\theta; \mathbf{x}) = \frac{\partial}{\partial \theta} \log f(\mathbf{x}|\theta)$ .

$\mathbf{X}$ : unobserved value of  $\mathbf{x}$ . Define the *random variable*

$$\frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) = \frac{\partial}{\partial \theta} \log f(\mathbf{X}|\theta).$$

Transformation of a r.v.  $\mathbf{X}$ , where transformation is derivative, w.r.t.  $\theta$ , of the log of the density of  $\mathbf{X}$ .

N.B. We treat  $l(\theta; \mathbf{X})$  as a function of the random data  $\mathbf{X}$ , *evaluated at the true value of  $\theta$* , rather than a function of the parameter  $\theta$  for fixed data  $\mathbf{x}$ .

$$\begin{aligned}
\frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) &= \frac{\partial}{\partial \theta} \log L(\theta; \mathbf{X}) \\
&= \left\{ \frac{\partial}{\partial \theta} L(\theta; \mathbf{X}) \right\} \times \frac{1}{L(\theta; \mathbf{X})} = \left\{ \frac{\partial}{\partial \theta} f(\mathbf{X}|\theta) \right\} \times \frac{1}{f(\mathbf{X}|\theta)}.
\end{aligned}$$

$$\begin{aligned}
E \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right\} &= \int \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{x}) \right\} f(\mathbf{x}|\theta) d\mathbf{x} \\
&= \int \left\{ \frac{\partial}{\partial \theta} f(\mathbf{x}|\theta) \right\} \times \frac{1}{f(\mathbf{x}|\theta)} f(\mathbf{x}|\theta) d\mathbf{x} \\
&= \frac{\partial}{\partial \theta} \int f(\mathbf{x}|\theta) d\mathbf{x} \\
&= \frac{\partial}{\partial \theta} 1 = 0.
\end{aligned}$$

Expected value of the derivative of the log-likelihood at the true value of  $\theta$  is 0.

Consider example of  $X \sim \exp(\text{rate} = \theta)$ . Then  $l(\theta; X) = \log \theta - \theta X$  and

$$\frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) = \frac{1}{\theta} - X,$$

so

$$\begin{aligned} E \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right\} &= \int \left( \frac{1}{\theta} - x \right) \theta \exp(-\theta x) dx \\ &= \frac{1}{\theta} \int \theta \exp(-\theta x) dx - \int x \theta \exp(-\theta x) dx \\ &= \frac{1}{\theta} - \frac{1}{\theta} = 0. \end{aligned}$$

However, the expected value of the derivative of the log-likelihood evaluated at the *wrong* value of  $\theta$ , say  $\theta^*$ , is not 0. For example,

$$\left. \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right|_{\theta=\theta^*} = \frac{1}{\theta^*} - X,$$

with

$$\begin{aligned} E \left\{ \left. \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right|_{\theta=\theta^*} \right\} &= \int \left( \frac{1}{\theta^*} - x \right) \theta \exp(-\theta x) dx \\ &= \frac{1}{\theta^*} - \frac{1}{\theta}, \end{aligned}$$

which is non-zero for  $\theta^* \neq \theta$ .

To derive an expression for the variance of  $\frac{\partial}{\partial \theta} l(\theta; \mathbf{X})$ , we note that

$$\begin{aligned} 0 &= \int \frac{\partial}{\partial \theta} l(\theta; \mathbf{x}) f(\mathbf{x}|\theta) d\mathbf{x} \\ \Rightarrow 0 &= \frac{\partial}{\partial \theta} \int \frac{\partial}{\partial \theta} l(\theta; \mathbf{x}) f(\mathbf{x}|\theta) d\mathbf{x} \\ \Rightarrow 0 &= \int \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{x}) \right\} f(\mathbf{x}|\theta) d\mathbf{x} + \int \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{x}) \right\} \left\{ \frac{\partial}{\partial \theta} f(\mathbf{x}|\theta) \right\} d\mathbf{x} \\ \Rightarrow 0 &= \int \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{x}) \right\} f(\mathbf{x}|\theta) d\mathbf{x} \\ &\quad + \int \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{x}) \right\} \left\{ \frac{\partial}{\partial \theta} f(\mathbf{x}|\theta) \right\} f(\mathbf{x}|\theta) d\mathbf{x} \\ \Rightarrow E \left[ \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right\}^2 \right] &= -E \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{X}) \right\}. \end{aligned}$$

$$E \left[ \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right\}^2 \right] = -E \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{X}) \right\}$$

Since  $E\left\{\frac{\partial}{\partial \theta} l(\theta; \mathbf{X})\right\} = 0$ , we have

$$Var \left\{ \frac{\partial}{\partial \theta} l(\theta; \mathbf{X}) \right\} = -E \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{X}) \right\}.$$

The term  $-E \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{X}) \right\}$  is known as the **Fisher information** which we will denote by  $\mathcal{I}_E(\theta)$ :

$$\mathcal{I}_E(\theta) \equiv -E \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{X}) \right\}.$$



Fisher information: measure of amount of information a sample size of  $n$  contains about  $\theta$ . For independent observations  $X_1, \dots, X_n$ ,

$$l(\theta; \mathbf{X}) = \sum_{i=1}^n \log f(X_i | \theta),$$

$$\mathcal{I}_E(\theta) = -nE \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; X_i) \right\},$$

hence Fisher information is proportional to sample size.

• Example. Consider  $X_1, \dots, X_n \sim N(\theta, \sigma^2)$  with  $\sigma^2$  known. Then

$$\begin{aligned} -E \left\{ \frac{\partial^2}{\partial \theta^2} l(\theta; \mathbf{X}) \right\} &= -E \left\{ \frac{\partial^2}{\partial \theta^2} \frac{-1}{2\sigma^2} \sum_{i=1}^n (X_i - \theta)^2 \right\} \\ &= \frac{n}{\sigma^2}, \end{aligned}$$

Fisher information is  $n/\sigma^2$ . As  $\sigma^2$  decreases, the observations more likely to be close to  $\theta$ , so data more informative about  $\theta$ .

Fisher information can be used to give a bound on the variance of an estimator.

Let  $T(\mathbf{X})$  be an unbiased estimator, with  $X_1, \dots, X_n$  independent. Then it is possible to prove that

$$\text{Var}(T) \geq \frac{1}{\mathcal{I}_E(\theta)}.$$

This is known as the **Cramer-Rao minimum variance bound**.

## Asymptotic normality

For large  $n$ , the distribution of the m.l.e  $\hat{\theta}$  is approximately normal, with

$$\hat{\theta} \sim N\{\theta, \mathcal{I}_E(\theta)^{-1}\}.$$

Thus for large  $n$ , the m.l.e.  $\hat{\theta}$  is *approximately* unbiased, and achieves the Cramer-Rao minimum variance bound.

In the multivariate case with  $\theta = (\theta_1, \dots, \theta_d)$  we have

$$\mathcal{I}_E(\theta) = \begin{pmatrix} e_{1,1}(\theta) & \cdots & e_{1,d}(\theta) \\ \vdots & & \vdots \\ e_{d,1}(\theta) & \cdots & e_{d,d}(\theta) \end{pmatrix},$$

with

$$e_{i,j}(\theta) = E \left\{ -\frac{\partial^2}{\partial \theta_i \partial \theta_j} l(\theta) \right\}.$$

So for large  $n$ , the distribution of the m.l.e of  $\theta$  is approximately multivariate normal:

$$\hat{\theta} \sim N_d(\theta, \mathcal{I}_E(\theta)^{-1}),$$

## Example: normally distributed data

Consider  $X_1, \dots, X_n$  with  $X_i \sim N(\theta_1, \theta_2)$ , with both  $\theta_1$  and  $\theta_2$  unknown. We write  $\theta = (\theta_1, \theta_2)^T$ .

$$l(\theta; \mathbf{x}) = -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log \theta_2 - \frac{1}{2\theta_2} \sum_{i=1}^n (x_i - \theta_1)^2,$$

$$\hat{\theta}_1 = \frac{1}{n} \sum_{i=1}^n x_i$$

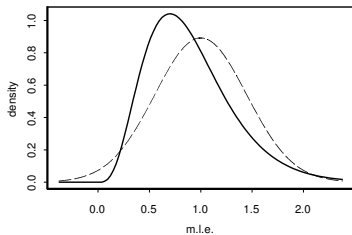
$$\hat{\theta}_2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$$

$$\mathcal{I}_E(\theta) = \begin{pmatrix} \frac{n}{\theta_2} & 0 \\ 0 & \frac{n}{2\theta_2^2} \end{pmatrix}.$$

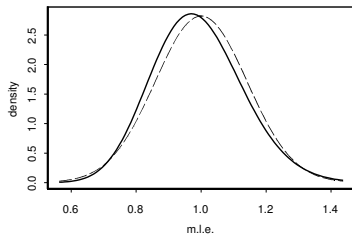
For large  $n$ , the approximate distribution of  $\hat{\theta} = (\hat{\theta}_1, \hat{\theta}_2)^T$  is

$$\begin{pmatrix} \hat{\theta}_1 \\ \hat{\theta}_2 \end{pmatrix} \sim N \left\{ \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix}, \begin{pmatrix} \frac{\theta_2}{n} & 0 \\ 0 & \frac{2\theta_2^2}{n} \end{pmatrix} \right\}$$

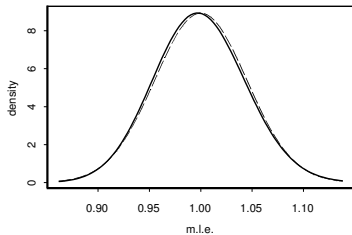
$n=10$



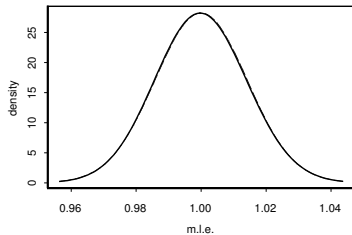
$n=100$



$n=1000$



$n=10000$



## Confidence intervals based on asymptotic normality

Suppose we want a  $100(1 - \alpha)\%$  confidence interval for any particular element of  $\theta$ , say  $\theta_j$ . For suitably large  $n$ , we have

$$\hat{\theta}_j \sim N(\theta_j, \gamma_{j,j}),$$

where  $\gamma_{j,j}$  is the  $\{j, j\}$  element of  $\mathcal{I}_E(\theta)^{-1}$ .

This then gives us an approximate interval as

$$(\hat{\theta}_j - z_{1-\frac{\alpha}{2}} \sqrt{\gamma_{j,j}}, \hat{\theta}_j + z_{1-\frac{\alpha}{2}} \sqrt{\gamma_{j,j}}),$$



$\theta$  unknown, so approximate  $\mathcal{I}_E(\theta)$  by observed information matrix

$$\mathcal{I}_O(\theta) = \begin{pmatrix} -\frac{\partial^2}{\partial \theta_1^2} l(\theta) & \cdots & -\frac{\partial^2}{\partial \theta_1 \partial \theta_d} l(\theta) \\ \vdots & & \vdots \\ -\frac{\partial^2}{\partial \theta_d \partial \theta_1}(\theta) & \cdots & -\frac{\partial^2}{\partial \theta_d^2} l(\theta) \end{pmatrix},$$

evaluated at  $\theta = \hat{\theta}$ .

$\tilde{\gamma}_{i,j}$ : the  $i, j$ th element of the inverse of  $\mathcal{I}_O(\theta)$ , we use

$$(\hat{\theta}_j - z_{1-\frac{\alpha}{2}} \sqrt{\tilde{\gamma}_{j,j}}, \hat{\theta}_j + z_{1-\frac{\alpha}{2}} \sqrt{\tilde{\gamma}_{j,j}}),$$

as an approximate confidence interval. Since we know that  $\hat{\theta} \rightarrow \theta$  as  $n \rightarrow \infty$ , with probability 1, we would expect  $\mathcal{I}_O(\theta)$  to be similar to  $\mathcal{I}_E(\theta)$  for large sample sizes.

## 4.2 Profile Likelihood

- ▶ RV  $X$ , density function  $f$ , parameters  $\boldsymbol{\theta} = \{\theta_1, \dots, \theta_d\}$
- ▶ Given  $\mathbf{x} = (x_1, \dots, x_n)$ , only want inferences about *subset* of  $\boldsymbol{\theta}$ .
- ▶ Partition  $\boldsymbol{\theta}$  into  $\boldsymbol{\theta} = (\boldsymbol{\theta}_1, \boldsymbol{\theta}_2)$  with  $\boldsymbol{\theta}_1$  the parameters of direct interest.
- ▶  $\boldsymbol{\theta}_2$ , the parameters not of direct interest are known as **nuisance parameters**.

- ▶ Example:  $X \sim N(\mu, \sigma^2)$  with both  $\mu$  and  $\sigma^2$  unknown, though we may only be interested in the mean parameter  $\mu$ .
- ▶ Can use asymptotic distribution of m.l.e. to derive confidence intervals for individual parameters.
- ▶ Will now consider an alternative form of likelihood function which in some cases can produce more accurate confidence intervals.

Partitioning  $\boldsymbol{\theta} = (\boldsymbol{\theta}_1, \boldsymbol{\theta}_2)$ , **profile** log-likelihood function for  $\boldsymbol{\theta}_1$  is

$$l_p(\boldsymbol{\theta}_1; \mathbf{x}) = \max_{\boldsymbol{\theta}_2} l(\boldsymbol{\theta}). \quad (1)$$

To get the profile log-likelihood function for  $\theta_1$ :

1. Treat  $\boldsymbol{\theta}_1$  as a constant in  $l(\boldsymbol{\theta}; \mathbf{x})$ .
  2. Find the maximum likelihood estimate  $\hat{\boldsymbol{\theta}}_2$  in terms of the data  $\mathbf{x}$  and  $\boldsymbol{\theta}_1$ .
  3. Plug in this expression for  $\hat{\boldsymbol{\theta}}_2$  into the full log-likelihood  $l(\boldsymbol{\theta}; \mathbf{x})$  to get the profile log-likelihood  $l_p(\boldsymbol{\theta}_1; \mathbf{x})$ .
- ▶ Writing  $\boldsymbol{\theta} = (\theta_i, \boldsymbol{\theta}_{-i})$ , plotting  $l_p(\theta_i)$  gives us profile of log-likelihood surface viewed from  $\theta_i$  axis.
  - ▶ If  $\hat{\boldsymbol{\theta}} = (\hat{\boldsymbol{\theta}}_1, \hat{\boldsymbol{\theta}}_2)$  maximises  $l(\boldsymbol{\theta})$ , then  $\hat{\boldsymbol{\theta}}_1$  maximises  $l_p(\boldsymbol{\theta}_1)$  and  $\hat{\boldsymbol{\theta}}_2$  maximises  $l_p(\boldsymbol{\theta}_2)$ .
  - ▶ Useful exploratory tool; allows you to plot a likelihood  $l_p(\theta_i)$  for a single parameter  $\theta_i$ .
  - ▶ Can be used to derive more accurate confidence intervals.

## Example 1

$X_1, \dots, X_n \sim N(\mu, \sigma^2)$  i.i.d.

$$l(\mu, \sigma^2; \mathbf{x}) = -n \log \sigma - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2. \quad (2)$$

Fixing  $\mu$ , the MLE of  $\sigma^2$  is  $\frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$ . Substituting this back into the full log-likelihood  $l(\mu, \sigma^2; \mathbf{x})$ , we get

$$l_p(\mu; \mathbf{x}) = -\frac{n}{2} \log \left\{ \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2 \right\} - \frac{n}{2}. \quad (3)$$

Fixing  $\sigma^2$ , the MLE of  $\mu$  is  $\bar{x}$ . The profile log-likelihood for  $\sigma^2$  is

$$l_p(\sigma^2; \mathbf{x}) = -n \log \sigma - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x})^2. \quad (4)$$

## Inference using the deviance function

- ▶ Can construct CI for  $\theta$  based on asymptotic normality of MLE. Alternative approach: use **deviance function**.
- ▶ For arbitrary  $\theta^*$ ,

$$D(\theta^*) = 2\{l(\hat{\theta}; \mathbf{x}) - l(\theta^*; \mathbf{x})\}. \quad (5)$$

$\hat{\theta}$  maximises log-likelihood, so  $D(\theta^*) \geq 0$ .

- ▶ If  $D(\theta^*)$  is small, then  $l(\theta^*)$  must be close to  $l(\hat{\theta})$ , which suggests that  $\theta^*$  is a plausible estimate for the true unknown value of  $\theta$ .
- ▶ A confidence interval (or region if  $\theta$  is a vector) could then be of the form

$$C = \{\theta^* : D(\theta^*) \leq c\}, \quad (6)$$

for some suitable value of  $c$ .

- ▶ With data  $x_1, \dots, x_n$ , for sufficiently large  $n$ , it can be shown that at the true value of  $\boldsymbol{\theta}$ ,  $D(\boldsymbol{\theta}) \sim \chi_d^2$ , where  $d$  is the dimensionality of  $\boldsymbol{\theta}$ .
- ▶ An approximate  $(1 - \alpha)$  confidence region for  $\boldsymbol{\theta}$  is then given by

$$C_\alpha = \{\boldsymbol{\theta}^* : D(\boldsymbol{\theta}^*) \leq c_\alpha\}, \quad (7)$$

with  $c_\alpha$  the  $(1 - \alpha)$  percentage point of the  $\chi_d^2$  distribution.

- ▶ Usually more accurate than asymptotic normality approximation, may require greater computational effort.



## Profile likelihood and the deviance function

- ▶  $\boldsymbol{\theta} = (\boldsymbol{\theta}_1, \boldsymbol{\theta}_2)$ , with  $\boldsymbol{\theta}_1$  a  $k$ -dimensional subset of  $\boldsymbol{\theta}$ . **Profile deviance:**

$$D_p(\boldsymbol{\theta}_1^*) = 2\{l(\hat{\boldsymbol{\theta}}; \mathbf{x}) - l_p(\boldsymbol{\theta}_1^*; \mathbf{x})\}, \quad (8)$$

with  $\hat{\boldsymbol{\theta}}$  the maximum likelihood estimator of  $\boldsymbol{\theta}$ .

- ▶ Based on a sample of size  $n$ , with  $n$  sufficiently large,

$$D_p(\boldsymbol{\theta}_1) \sim \chi_k^2. \quad (9)$$

- ▶ Can obtain a confidence interval for any element  $\theta_i$  as

$$C_\alpha = \{\theta_i^* : D_p(\theta_i^*) \leq c_\alpha\}, \quad (10)$$

again, with  $c_\alpha$  the  $(1 - \alpha)$  percentage point of the  $\chi_1^2$  distribution.

- ▶ This will often be more accurate than the interval

$$\hat{\theta}_i \pm z_{\frac{\alpha}{2}} \sqrt{\psi_{i,i}} \quad (11)$$

stated earlier.

## Example: leukaemia data

- ▶ Leukaemia patients given drug, 6-mercaptopurine (6-MP), and the number of days  $t_i$  until freedom from symptoms is recorded:

6\*, 6, 6, 6, 7, 9\*, 10\*, 10, 11\*, 13, 16, 17\*, 19\*, 20\*, 22, 23, 25\*, 32\*, 32\*,

A \* denotes an observation censored at that time.

- ▶ Weibull model:

$$f_T(t) = \alpha\beta(\beta t)^{\alpha-1} \exp\{-(\beta t)^\alpha\} \quad (12)$$

for  $t > 0$ .  $\alpha = 1$  gives exponential distribution.

- ▶ For censored data

$$P(T > t) = \exp\{-(\beta t)^\alpha\}. \quad (13)$$

$d$ : no. of uncensored observations,  $\sum_u \log t_i$ : sum of all logs of the uncensored observations.

$$l(\alpha, \beta; \mathbf{x}) = d \log \alpha + \alpha d \log \beta + (\alpha - 1) \sum_u \log t_i - \beta^\alpha \sum_{i=1}^n t_i^\alpha. \quad (14)$$

Treat  $\alpha$  as fixed, and find MLE of  $\beta$  as function of data and  $\alpha$ .

$$\hat{\beta} = \left( \frac{d}{\sum_{i=1}^n t_i^\alpha} \right)^{\frac{1}{\alpha}}. \quad (15)$$

The profile log-likelihood of  $\alpha$  is then given by

$$\begin{aligned} l_p(\alpha) &= l(\alpha, \hat{\beta}) \\ &= d \log \alpha + \alpha d \log \left( \frac{d}{\sum_{i=1}^n t_i^\alpha} \right)^{\frac{1}{\alpha}} + (\alpha - 1) \sum_u \log t_i - d \end{aligned}$$

- ▶ Finding the full MLE  $(\hat{\alpha}, \hat{\beta})$  cannot be done analytically, so numerical methods have to be used.
- ▶ To construct the confidence interval, only need  $\hat{\alpha}$  that maximises  $l_p(\hat{\alpha})$ , as  $l_p(\hat{\alpha}) = l(\hat{\alpha}, \hat{\beta})$ .
- ▶ For a 95% confidence interval, the 95th percentage point of the  $\chi^2_1$  distribution is 3.841. The confidence interval is then given by

$$C_{0.05} = \{\alpha^* : D_p(\alpha^*) \leq 3.841\} \quad (16)$$

$$= [\alpha^* : 2\{l_p(\hat{\alpha}) - l_p(\alpha^*)\} \leq 3.841] \quad (17)$$

$$= \{\alpha^* : l_p(\alpha^*) > l_p(\hat{\alpha}) - 3.841/2\}. \quad (18)$$

- ▶ Numerically, we estimate the MLE  $\hat{\alpha}$  to be 1.35, with  $l_p(\hat{\beta}) = -41.66$ .
- ▶ From the graph, we can then read off the 95% confidence interval for  $\alpha$  as (0.73, 2.2).
- ▶ This contains the value 1, so the simpler exponential distribution is plausible for this dataset.

## Example: machine component failure

- ▶ Level of corrosion  $w$  in a machine component recorded and component tested until a failure is observed, at time  $t$ .
- ▶ Denote each observation by  $(w_i, t_i)$ , where  $w_i$  is the level of corrosion, and  $t_i$  is the failure time.
- ▶ Possible model:  $T \sim \text{Exponential}(\lambda)$  distribution, with  $\lambda$  a function of the corrosion level  $w$ :

$$\lambda = \alpha w^\beta. \quad (19)$$

$w$  treated as fixed, i.e. model distribution of the failure time conditional on the corrosion.

- ▶  $\beta = 0$  implies same expected time to failure,  $\alpha^{-1}$  for all components, regardless of the corrosion level  $w$ .

The density of a single observation  $(w, t)$  is given by

$$f_T(t) = \alpha w^\beta \exp\{-\alpha w^\beta t\}. \quad (20)$$

$$l(\alpha, \beta; \mathbf{x}) = n \log \alpha + \beta \sum_{i=1}^n \log w_i - \alpha \sum_{i=1}^n w_i^\beta t_i. \quad (21)$$

We can derive an expression for the profile log-likelihood of  $\beta$ :  
Treating  $\beta$  as fixed, we obtain the MLE of  $\alpha$  as

$$\hat{\alpha} = \frac{n}{\sum_{i=1}^n w_i^\beta t_i}. \quad (22)$$

We then substitute this expression for  $\alpha$  in the full log-likelihood  $l(\alpha, \beta)$  to get the profile log-likelihood for  $\beta$ :

$$l_p(\beta; \mathbf{x}) = n \log \left( \frac{n}{\sum_{i=1}^n w_i^\beta t_i} \right) + \beta \sum_{i=1}^n \log w_i - n. \quad (23)$$

- ▶ Numerically, estimate  $\hat{\beta} = 0.473$ , with  $l_p(\hat{\beta}; \mathbf{x}) = -20.01$ .
- ▶ From graph, read off 95% confidence interval for  $\beta$  as  $(0.11, 0.95)$ .
- ▶ Doesn't contain zero, and so there is clear evidence that  $\beta \neq 0$
- ▶ For comparison, compute confidence interval for  $\beta$  using normal approximation.
- ▶ Observed information matrix is given by

$$\begin{pmatrix} -\frac{\partial^2 l}{\partial \alpha^2} & -\frac{\partial^2 l}{\partial \alpha \partial \beta} \\ -\frac{\partial^2 l}{\partial \alpha \partial \beta} & -\frac{\partial^2 l}{\partial \beta^2} \end{pmatrix} = \begin{pmatrix} n\alpha^{-2} & \sum w_i^\beta t_i \log w_i \\ \sum w_i^\beta t_i \log w_i & \alpha \sum w_i^\beta t_i (\log w_i)^2 \end{pmatrix} \quad (24)$$

- ▶ Obtain  $\hat{\alpha}$  by substituting  $\beta = 0.473$  into formula, gives  $\hat{\alpha} = 1.099$ .
- ▶ Substitute  $\alpha = 1.099$ ,  $\beta = 0.473$  into observed information matrix, invert to get

$$V = \begin{pmatrix} 0.0534 & -0.0241 \\ -0.0241 & 0.0442 \end{pmatrix}. \quad (25)$$

- ▶ CI for  $\beta$  using asymptotic normality is

$$\hat{\beta} \pm 1.96 \times 0.0442^{0.5}, \quad (26)$$

which gives (0.0611,0.8849).