

# MAS472/6004 Computational Inference

Richard Wilkinson

[r.d.wilkinson@sheffield.ac.uk](mailto:r.d.wilkinson@sheffield.ac.uk)

# Computational Inference

Simple computational tools for solving hard statistical problems.

- ▶ Monte Carlo/simulation
- ▶ MC and simulation in frequentist inference
- ▶ Random number generation/ simulating from probability distributions
- ▶ Further Bayesian computation

Methods implemented via simple programs in R.

# Chapter 1: Monte Carlo methods

## Problem 1: estimating probabilities

A particular site is being considered for a wind farm. At that site, the log of the wind speed in m/s on day  $t$  is known to follow an  $AR(2)$  process:

$$Y_t = 0.6Y_{t-1} + 0.4Y_{t-2} + \varepsilon_t, \quad (1)$$

with  $\varepsilon_t \sim N(0, 0.01)$ .

If  $Y_1 = Y_2 = 1.5$ , what is the **probability** that the wind speed  $\exp(Y_t)$  will be below 15 kmh for more than 10 days in a 100 day period?

## Problem 2: estimating variances

Given a sample of 5 standard normal random variables  $X_1, \dots, X_5$ , what is the **variance** of

$$\max_i \{X_i\} - \min_i \{X_i\}$$

## Problem 3: Estimating percentiles

The concentration of pollutant at any point in region following release from point source can be describe by the model

$$C(x, y, z) = \frac{Q}{2\pi u_{10} \sigma_z \sigma_y} \exp \left[ -\frac{1}{2} \left\{ \frac{y^2}{\sigma_y^2} + \frac{(z-h)^2}{\sigma_z^2} \right\} \right], \quad (2)$$

$C$ : air concentration of pollutant,  $Q$ : release rate,  $u_{10}$ : wind speed at 10m above ground,  $\sigma_y$ ,  $\sigma_z$ : diffusion parameters in horizontal and vertical directions,  $h$ : release height,  $(x, y, z)$ : coordinates along wind direction, cross wind and above ground.

Given  $Q = 100$ ,  $h = 50\text{m}$ , but  $u, \sigma_z, \sigma_y$  uncertain. If

$$\log u_{10} \sim N(2, .1) \qquad \log \sigma_y^2 \sim N(10, 0.2) \qquad \log \sigma_z^2 \sim N(5, 0.05)$$

What is the **95th percentile** of  $C(100, 100, 40)$ ?

## Problem 4: Estimating expectations

A hospital ward has 8 beds

- ▶ The number of patients arriving each day is uniformly distributed between 0 and 5 inclusive.
- ▶ The length of stay for each patient is also uniformly distributed between 1 and 3 days inclusive.

If all 8 beds are free initially, what is the **expected** number of days before there are more patients than beds?

# Problem 5: Optimal decisions

## The Monty Hall Problem

On a game show you are given the choice of three doors.

- ▶ Behind one door is a car; behind the others, goats.

The rules of the game are

- ▶ After you have chosen a door, the game show host, Monty Hall, opens one of the two remaining doors to reveal a goat.
- ▶ You are now asked whether you want to stay with your first choice, or to switch to the other unopened door.

What is the **optimal strategy**? And what is the resulting probability of winning?

These 5 problems are all either hard or impossible to tackle analytically. However, the **Monte Carlo method**, can be used to obtain approximate answers to all of them.

*Monte Carlo methods are a broad class of computational algorithms relying on repeated random sampling to obtain numerical results. They use randomness to solve problems that might be deterministic in principle.*



## Some useful results

Monte Carlo is primarily used to calculate integrals. For example

- ▶ Expectation of a random variable  $X \sim f(\cdot)$ , or a function of it

$$\mathbb{E}g(X) = \int g(x)f(x)\mathrm{d}x$$

- ▶ Variance

$$\mathbb{V}\mathrm{ar}(X) = \mathbb{E}(X^2) - \mathbb{E}(X)^2. \quad (3)$$

- ▶ Probability  $\mathbb{P}(X < a)$  is the expectation of  $\mathbb{I}_{X < a}$ , the indicator function which is 1 if  $X < a$  and otherwise is 0. Then

$$\begin{aligned} \mathbb{P}(X < a) &= 1 \times \mathbb{P}(X < a) + 0 \times \mathbb{P}(X \geq a) \\ &= \mathbb{E}\{\mathbb{I}(X < a)\} = \int \mathbb{I}_{X < a}f(X)\mathrm{d}x \end{aligned}$$

# Monte Carlo Integration - I

Suppose we are interested in the integral

$$I = \mathbb{E}(g(X)) = \int g(x)f(x)dx$$

Let  $X_1, X_2, \dots, X_n$  be independent random variables with pdf  $f(x)$ . Then a **Monte Carlo approximation** to  $I$  is

$$\hat{I}_n = \frac{1}{n} \sum_{i=1}^n g(X_i). \quad (4)$$

**Example:**

## Monte Carlo Integration - II

Some properties of  $\hat{I}$ .

(1)  $\hat{I}_n$  is an unbiased estimator of  $I$ . **Proof:**

## Monte Carlo Integration - III

(2)  $\hat{I}_n$  converges to  $I$  as  $n \rightarrow \infty$ .

**Proof:**

## Monte Carlo Integration - IV

The SLLN tells us  $\hat{I}_n$  converges, but not how fast. It doesn't tell us how large  $n$  must be to achieve a certain error.

(3)

$$\mathbb{E}[(\hat{I}_n - I)^2] = \frac{\sigma^2}{n}$$

where  $\sigma^2 = \text{Var}(g(X))$ . Thus the 'root mean square error' (RMSE) of  $\hat{I}_n$  is

$$\text{RMSE}(\hat{I}_n) = \frac{\sigma}{\sqrt{n}} = O(n^{-1/2}).$$

Thus, our estimate is more accurate as  $n \rightarrow \infty$ , and is less accurate when  $\sigma^2$  is large.  $\sigma^2$  will usually be unknown, but we can estimate it:

$$\hat{\sigma}^2 = \frac{1}{n-1} \sum_{i=1}^n (g(X_i) - \hat{I}_n)^2$$

We call  $\hat{\sigma}$  the *Monte Carlo standard error*.

# Monte Carlo Integration - V

We write<sup>1</sup>

$$\text{RMSE}(\hat{I}_n) = O(n^{-1/2})$$

to emphasise the rate of convergence of the error with  $n$ .

To get 1 digit more accuracy requires a 100-fold increase in  $n$ .  
A 3-digit improvement would require us to multiply  $n$  by  $10^6$ .

Consequently Monte Carlo is not usually suited for problems where we need a very high accuracy. Although the error rate is low (the RMSE decreases slowly with  $n$ ), it has the nice properties that the RMSE

- ▶ does not depend on  $d = \dim(x)$
- ▶ does not depend on the smoothness of  $f$

Consequently Monte Carlo is very competitive in high dimensional problems that are not smooth.

## Monte Carlo Integration - VI

In addition to the rate of convergence, the **central limit theorem** tells us the asymptotic<sup>2</sup> distribution of  $\hat{I}_n$

(4)

$$\frac{\sqrt{n}(\hat{I}_n - I)}{\sigma} \rightarrow N(0, 1) \text{ in distribution as } n \rightarrow \infty$$

Informally,  $\hat{I}_n$  is approximately  $N(I, \frac{\sigma^2}{n})$  for large  $n$ .

This allows us to calculate confidence intervals for  $I$ .

See the R code on MOLE.

- ▶ If we require  $E\{f(X)\}$ , random observations from distribution of  $f(X)$  can be generated by generating  $X_1, \dots, X_n$  from distribution of  $X$ , and then evaluating  $f(X_1), \dots, f(X_n)$ .
- ▶ Preceding results can be applied when estimating variances or probabilities of events.
- ▶ Percentiles estimated by taking the sample percentile from the generated sample of values  $X_1, \dots, X_n$ .
- ▶ We expect the estimate to be more accurate as  $n$  increases. Determining a percentile is equivalent to inverting a CDF. If wish to know the 95th percentile, we must find  $\nu$  such that

$$P(X \leq \nu) = 0.95, \tag{5}$$



# Monte Carlo solutions to the example problems

## Question 1

Define  $E$ : the event that in 100 days the wind speed is below 15kmh for more than 10 days.

To estimate  $\mathbb{P}(E)$ , generate lots of individual time series, and count proportion of series in which  $E$  occurs

1. Generate  $i$ th realisation of the time series process:  
For  $t = 3, 4, \dots, 100$ :
  - ▶ Set  $Y_t \leftarrow 0.6Y_{t-1} + 0.4Y_{t-2} + N(0, 0.01)$
2. Count number of elements of  $\{Y_1, \dots, Y_{100}\}$  less than  $\log 4.167$ :
  - ▶ Set  $X_i \leftarrow \sum_{t=1}^{100} I\{Y_t < \log 4.167\}$
3. Determine if event  $E$  has occurred for time series  $i$ :
  - ▶ Set  $E_i \leftarrow I\{X_i > 10\}$
4. Estimate  $\mathbb{P}(E)$  by  $\frac{1}{N} \sum_{i=1}^N E_i$

## Question 2

Define  $Z$  to be the difference between max and min of 5 standard normal random variables. Estimate the variance

## Question 3

Transformation of a random variable:

Given random variables  $X_1, \dots, X_d$  we want to know the distribution of  $Y = f(X_1, \dots, X_d)$ .

- ▶ The Monte Carlo method can be used
  - ▶ Sample unknown inputs from their distributions,
  - ▶ evaluate the function to obtain output value from its distribution.
- ▶ Given suitably large sample, 95th percentile from distribution of  $C(100, 100, 40)$  can be estimated by the 95th percentile from sample of simulated values of  $C(100, 100, 40)$ .

For  $i = 1, 2, \dots, N$ :

1. Sample a set of input values:

- ▶ Sample  $u_{10,i}$  from  $\log N(2, .1)$
- ▶ Sample  $\sigma_{y,i}^2$  from  $\log N(10, 0.2)$
- ▶ Sample  $\sigma_{z,i}^2$  from  $\log N(5, 0.05)$

2. Evaluate the model output  $C_i$ :

- ▶ Set  $C_i \leftarrow \frac{100}{2\pi u_{10,i} \sigma_{z,i} \sigma_{y,i}} \exp \left[ -\frac{1}{2} \left\{ \frac{40^2}{\sigma_{y,i}^2} + \frac{100}{\sigma_{z,i}^2} \right\} \right]$

3. Return the 95th percentile of  $C_1, C_2, \dots, C_N$ .

## Question 4

- ▶ Define  $W$  to be the number of days before the first patient arrives to find no available beds.
- ▶ The question has asked us to give  $E(W)$ .
- ▶ If we can generate  $W_1, \dots, W_n$  from the distribution of  $W$ , we can then estimate  $E(W)$  by  $\bar{W}$ .

See the R code on MOLE for a way to simulate this process.

# The Monty Hall Problem

- ▶ Simulate  $N$  separate games by randomly letting  $x$  take values in  $\{1, 2, 3\}$  with equal probability.  $x$  represents which door the car is behind.
- ▶ Simulate the contestant randomly picking a door by choosing a value  $y$  in  $\{1, 2, 3\}$  (it doesn't matter how we do this, we can always choose 1 if you like, the results are the same).
- ▶ Now the game show host will open the door which hasn't been picked that contains a goat. For each of the  $N$  games, record the success of the two strategies
  1. stick with choice  $y$
  2. change to the unopened door.
- ▶ Calculate the success rate for each strategy.

## Example 1

Consider the probability  $p$  that a standard normal random variable will lie in the interval  $[0, 1]$ . This can be written as an integral

$$p = \int_0^1 \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx. \quad (6)$$

Two methods for estimating/evaluating this probability are

1. numerical integration/quadrature, e.g., trapezium rule, Simpson's rule etc
2. given a sample of standard normal random variables  $Z_1, \dots, Z_n$ , look at the proportion of  $Z_i$ s occurring in the interval  $[0, 1]$ .

## Example 1: An alternative method

1.  $Y$  is a RV with  $f(Y)$  any function of  $Y$ . To generate a random value from the distribution of  $f(Y)$ , generate a random  $Y$  from the distribution of  $Y$ , and then evaluate  $f(Y)$ .
2. Providing  $\mathbb{E}\{f(Y)\}$  exists, given a sample  $f(Y_1), \dots, f(Y_n)$ ,

$$\frac{1}{n} \sum_{i=1}^n f(Y_i)$$

is an unbiased estimator of  $\mathbb{E}\{f(Y)\}$ .

3. Let  $X$  be a random variable with a  $U[0, 1]$  distribution. For an arbitrary function  $f(X)$ , what is the expectation of  $f(X)$ ?



4 Now choose  $f$  to be the function  $f(X) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{X^2}{2}\right)$ .  
Then if  $X \sim U[0, 1]$

$$\mathbb{E}\{f(X)\} = \int_0^1 \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) 1dx \quad (8)$$

Given a sample  $f(X_1), \dots, f(X_n)$  from the distribution of  $f(X)$ , we can estimate  $E\{f(X)\}$  by the *unbiased* **Monte Carlo** estimator  $\hat{p}$

$$\hat{p} = \frac{1}{n} \sum_{i=1}^n f(X_i), \quad (9)$$

where  $X_i$  is drawn randomly from the  $U[0, 1]$  distribution.

### Key idea

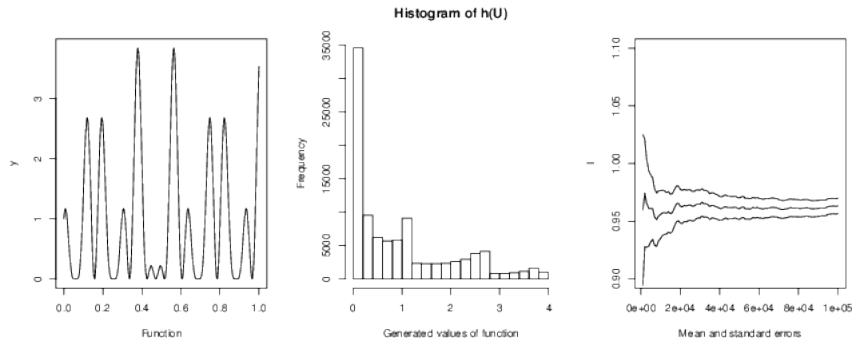
re-express the integral of interest (6) as an *expectation*.

## Example 2

Consider the integral  $\int_0^1 h(x)dx$  where

$$h(x) = [\cos(50x) + \sin(20x)]^2$$

Generate  $X_1, \dots, X_n$  from  $U[0, 1]$  and estimate with  $\hat{I}_n = \frac{1}{n} \sum h(X_i)$ .



## The general framework

$$R = \int f(x)dx \quad (10)$$

Let  $g(x)$  be some density function that is easy to sample from. How do we re-write (10) as the expectation of a function of a random variable  $X$  with density function  $g(x)$ ?

So we now have  $R = E\{h(X)\}$ , where  $X$  has the density function  $g(x)$ . If we now sample  $X_1, \dots, X_n$  from  $g(x)$ , then evaluate  $h(X_1), \dots, h(X_n)$ ,

$$\hat{R} = \frac{1}{n} \sum_{i=1}^n h(X_i) \quad (12)$$

is an unbiased estimator of  $R$ .

## Example 3

Use Monte Carlo integration to estimate

$$R = \int_{-1}^1 \exp(-x^2) dx. \quad (13)$$

We'll consider two different choices for  $g(x)$ .

1. A uniform density on  $[-1, 1]$ :  $g(x) = 0.5$  for  $x \in [-1, 1]$ .

We sample  $X_1, \dots, X_n$  from  $U[-1, 1]$ , and estimate  $R$  by

$$\hat{R} = \frac{1}{n} \sum_{i=1}^n \frac{\exp(-X_i^2)}{g(X_i)} = \frac{1}{n} \sum_{i=1}^n 2 \exp(-X_i^2). \quad (14)$$

2 A normal density function  $N(0, 0.5)$ .

Note: sampled value  $X$  from  $g(x)$  not constrained to lie in  $[-1, 1]$ .

Re-write  $R$  as

$$R = \int_{-\infty}^{\infty} I\{-1 \leq x \leq 1\} \exp(-x^2) dx, \quad (15)$$

where  $I\{\}$  denotes the indicator function.

We now sample  $X_1, \dots, X_n$  from  $N(0, 0.5)$  and estimate  $R$  by

$$\hat{R} = \frac{1}{n} \sum_{i=1}^n \frac{I\{-1 \leq X_i \leq 1\} \exp(-X_i^2)}{g(X_i)} = \frac{1}{n} \sum_{i=1}^n \pi^{1/2} I\{-1 \leq X_i \leq 1\} \quad (16)$$

Key idea

$g(x)$  needs to mimic  $f(x)$  as closely as possible. Consider again  $R = \int_{-1}^1 \exp(-x^2) dx$ .

Two terrible choices of  $g$ :

1. A uniform density on  $[0, 1]$ :  $g(x) = 1$  for  $x \in [0, 1]$ .

$$R = \int_{-\infty}^{\infty} I\{-1 \leq x \leq 1\} \exp(-x^2) dx, \quad (17)$$

For  $x \in [-1, 0)$ , we have  $f(x) > 0$  and  $g(x) = 0$ . Must have  $g(x) > 0$  for all  $x$  where  $f(x) > 0$ .

2. A normal density  $N(0, 0.09)$ .

In this case, we have  $g(x) > 0$  for  $x \in [-1, 1]$ , but we when we sample  $x$  from  $g$ , we expect around 95% of the values to lie in the range  $(-0.6, 6)$ .

The Monte Carlo estimate of  $R$  is given by

$$\hat{R} = \frac{1}{n} \sum_{i=1}^n I\{-1 \leq X_i \leq 1\} \frac{\exp(-X_i^2) \sqrt{0.18\pi}}{\exp(-5.56X_i^2)}. \quad (18)$$

# Convergence

- ▶ Provided  $f(x) > 0 \Rightarrow g(x) > 0$ ,  $\hat{R}$  will converge to  $R$  as  $n \rightarrow \infty$ .
- ▶ Use the central limit theorem to derive a confidence interval for  $\hat{R}$ :

$$\hat{R} \sim N\left(R, \frac{\sigma^2}{n}\right), \quad (19)$$

where we estimate  $\sigma^2$  by

$$\hat{\sigma}^2 = \frac{1}{n-1} \sum_{i=1}^n \left\{ h(X_i) - \hat{R} \right\}^2 \quad (20)$$

- ▶ We can then report the confidence interval as

$$\hat{R} \pm Z_{1-\alpha/2} \sqrt{\hat{\sigma}^2/n}, \quad (21)$$

- ▶ Estimates of  $\sigma^2$  in the example:  $U[-1, 1] : 0.16$ ,  
 $N(0, 0.5) : 0.42$ ,  $N(0, 0.09) : 6.81$ .

# Comparison of Monte Carlo with numerical integration

## Mid-ordinate rule

Consider finding  $I = \int_0^1 f(x) \, dx$ . There are many different numerical integration schemes we might use. For example, the mid-ordinate rule is one of the simplest methods, and approximates  $I$  by a sum

$$\tilde{I}_n = \frac{1}{n} \sum_{i=1}^n f(x_i),$$

The points  $x_i = (i - \frac{1}{2})h$  are equally spaced at intervals of  $h = 1/n$ .



# Comparison of MC with numerical integration II

## Mid-ordinate rule error analysis

For smooth 1-d functions the error rates for quadrature rules can be much better than Monte Carlo

For example, if  $f : [0, 1] \rightarrow \mathbb{R}$  and  $f''(x)$  is continuous, then

$$|I - \tilde{I}_n| \leq \frac{1}{24n^2} \max_{0 \leq x \leq 1} |f''(x)|$$

So

$$\text{RMSE}(\tilde{I}) = O(n^{-2})$$

i.e., it is a second order method. Other rules achieve higher error rates. For example, Simpson's rule is a fourth order method.

This is much faster than Monte Carlo: to get an extra digit of accuracy we only need multiply  $n$  by a factor of  $\sqrt{10} = 3.2$

# Comparison of MC with numerical integration III

## Curse of dimensionality

Classical quadrature methods work well for smooth 1d problems. But for  $d$ -dimensional integrals we have a problem. Suppose

$$I = \int_0^1 \int_0^1 \dots \int_0^1 f(x_1, \dots, x_d) dx_1 \dots dx_d$$

We can use the same  $N$  point 1-d quadrature rules on each of the  $d$  integrals.

This uses  $n = N^d$  evaluations of  $f$ . The 1d mid-ordinate rule has error  $O(N^{-2})$ , so the  $d$ -dimensional mid-ordinate rule has error

$$|I - \tilde{I}| = O(N^{-2}) = O(n^{-2/d})$$

For  $d = 4$  this is the same as Monte Carlo. For larger  $d$  it is worse.

In addition, we require  $f$  to be smooth ( $f''(x)$  to be continuous) for the method to work well.

Monte Carlo has the same  $O(n^{-1/2})$  error rate regardless of  $\dim(x)$  or  $f''(x)$