

MATH3027: Optimization 2022

Week 3 computer lab: least squares

Prof. Richard Wilkinson

Please send any comments or mistakes to r.d.wilkinson@nottingham.ac.uk

Polynomial fit and denoising

We will replicate the linear regression and regularized linear least squares examples from this week, with a different model. First, we will generate a noisy dataset of 200 samples coming from

$$v_i = u_i^2 + \mathcal{N}(0, 0.04), \quad i = 1, \dots, 200,$$

where the u_i 's are uniformly sampled in $[-1, 1]$, and $\mathcal{N}(0, 0.04)$ means adding Gaussian noise of mean 0 and variance 0.04 for **each** sample.

1. Generate the pairs (u_i, v_i) using suitable random generators. Make a plot illustrating (u_i, v_i) .
2. Describe the least-squares regression problem for finding the optimal parameters in the model

$$v(u) = au^2 + bu + c$$

3. Compute the least squares solution and compute the total least squares error in the ℓ_2 norm.
4. Now, instead of solving a regression problem, use the v_i values to recover a denoised signal using regularized least squares using the same total variation regularization described in the lecture notes.



Conditioning

Consider the linear systems

$$\begin{aligned}x + y &= 2 \\ x + 1.001y &= 2\end{aligned}\tag{1}$$

and

$$\begin{aligned}x + y &= 2 \\ x + 1.001y &= 2.001\end{aligned}\tag{2}$$

- Find the solution of both systems. Check your answer by using the ‘solve’ command in R.

Note that a small change in the RHS (\mathbf{b} in the terminology of the notes) has led to a large change in the solutions (\mathbf{x}).

- We can measure the sensitivity of the linear system

$$\mathbf{Ax} = \mathbf{b}$$

(where \mathbf{A} is a positive definite $n \times n$ matrix) by measuring how much the output \mathbf{x} changes as \mathbf{b} changes. Suppose \mathbf{b} changes to $\mathbf{b} + \delta\mathbf{b}$, and that this results in the solution \mathbf{x} changing to $\tilde{\mathbf{x}} = \mathbf{x} + \delta\mathbf{x}$. Show that the relative change in \mathbf{x} compared to the relative change to \mathbf{b} can be expressed as follows:

$$\frac{\|\delta\mathbf{x}\|/\|\mathbf{x}\|}{\|\delta\mathbf{b}\|/\|\mathbf{b}\|} = \frac{\|\mathbf{A}^{-1}\delta\mathbf{b}\|}{\|\delta\mathbf{b}\|} \frac{\|\mathbf{Ax}\|}{\|\mathbf{x}\|}$$

- The matrix norm induced by the L_2 norm is defined to be

$$\|\mathbf{A}\|_2 = \max\{\|\mathbf{Ax}\|_2 : \|\mathbf{x}\|_2 \leq 1\} = \max_{\mathbf{x} \neq 0} \frac{\|\mathbf{Ax}\|_2}{\|\mathbf{x}\|_2}$$

Show that

$$\max_{\mathbf{b}, \delta\mathbf{b}} \frac{\|\delta\mathbf{x}\|/\|\mathbf{x}\|}{\|\delta\mathbf{b}\|/\|\mathbf{b}\|} = \|\mathbf{A}^{-1}\| \cdot \|\mathbf{A}\|.$$

- Thus show that for the L_2 norm, we have

$$\max_{\mathbf{b}, \delta\mathbf{b}} \frac{\|\delta\mathbf{x}\|/\|\mathbf{x}\|}{\|\delta\mathbf{b}\|/\|\mathbf{b}\|} = \frac{\lambda_{\max}(\mathbf{A})}{\lambda_{\min}(\mathbf{A})}$$

where $\lambda_{\max}(\mathbf{A})$ and $\lambda_{\min}(\mathbf{A})$ are the largest and smallest eigenvalues of \mathbf{A} .

Hint: The two norm of the matrix is equal to the largest eigenvalue:

$$\|\mathbf{A}\|_2 = \lambda_{\max}(\mathbf{A})$$

- This is known as the condition number of \mathbf{A} . Compute \mathbf{A} for the linear systems above.

