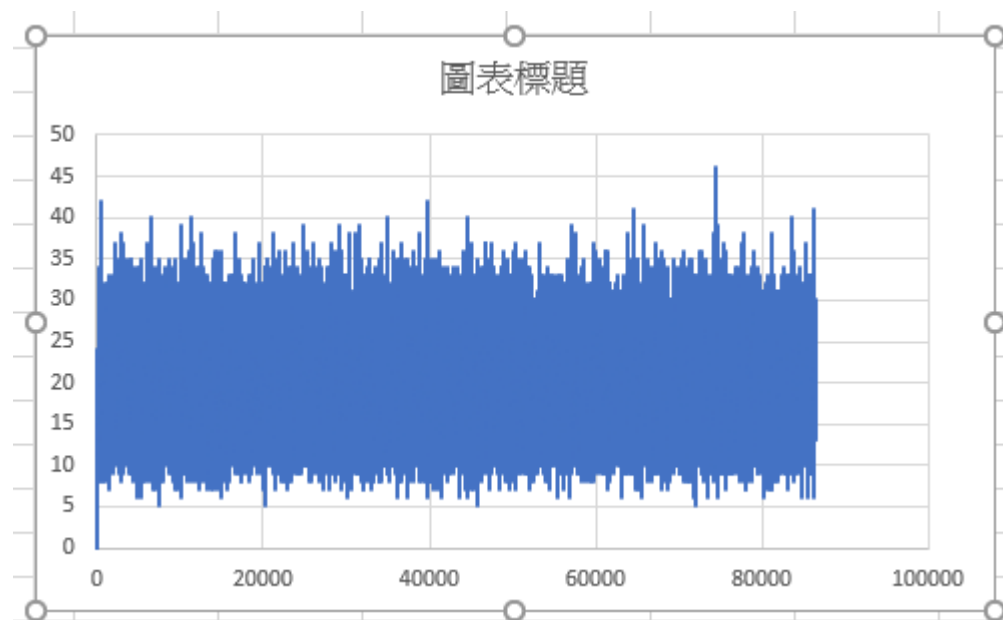
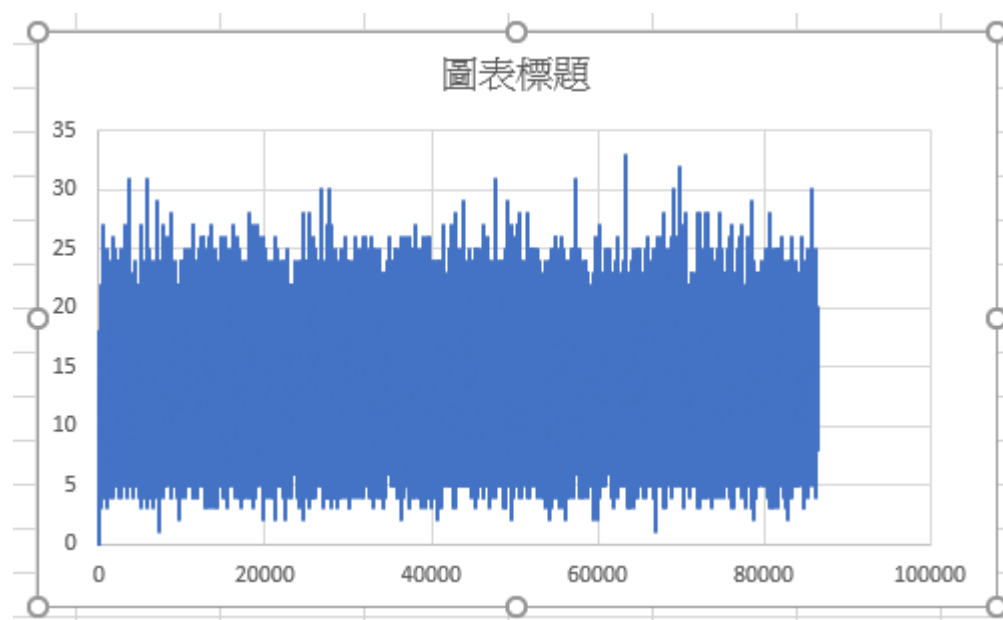


X 軸為時間(秒), Y 軸為 handoff 次數(次)

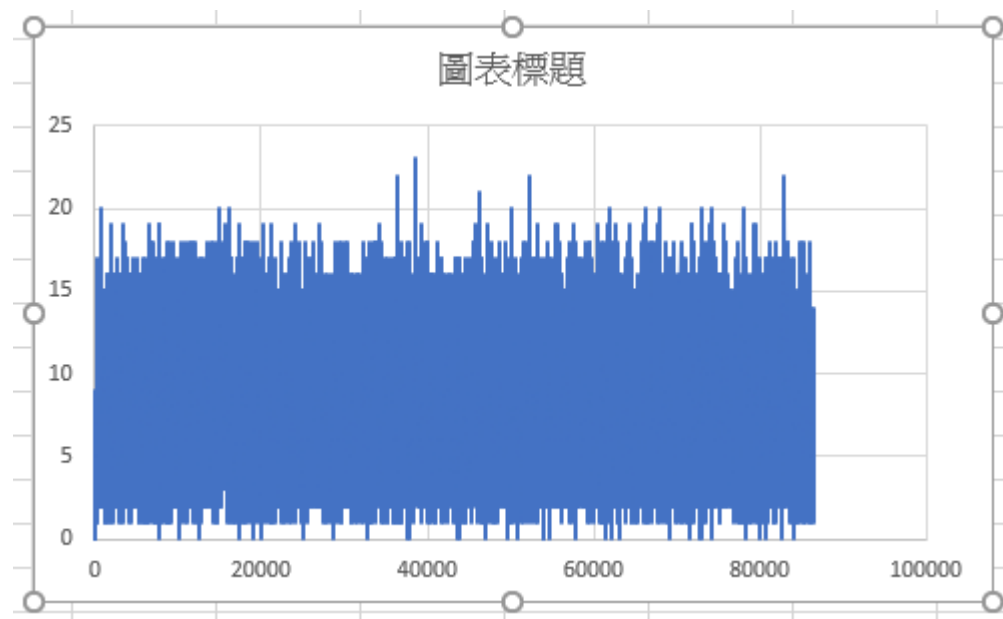
Best Policy $\lambda = 1/2$



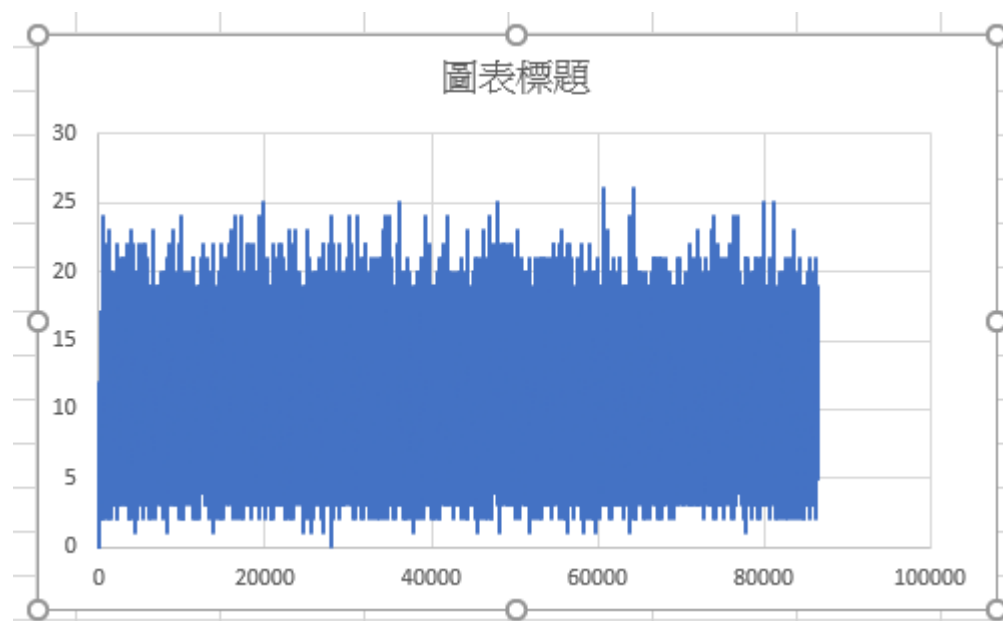
Best Policy $\lambda = 1/3$



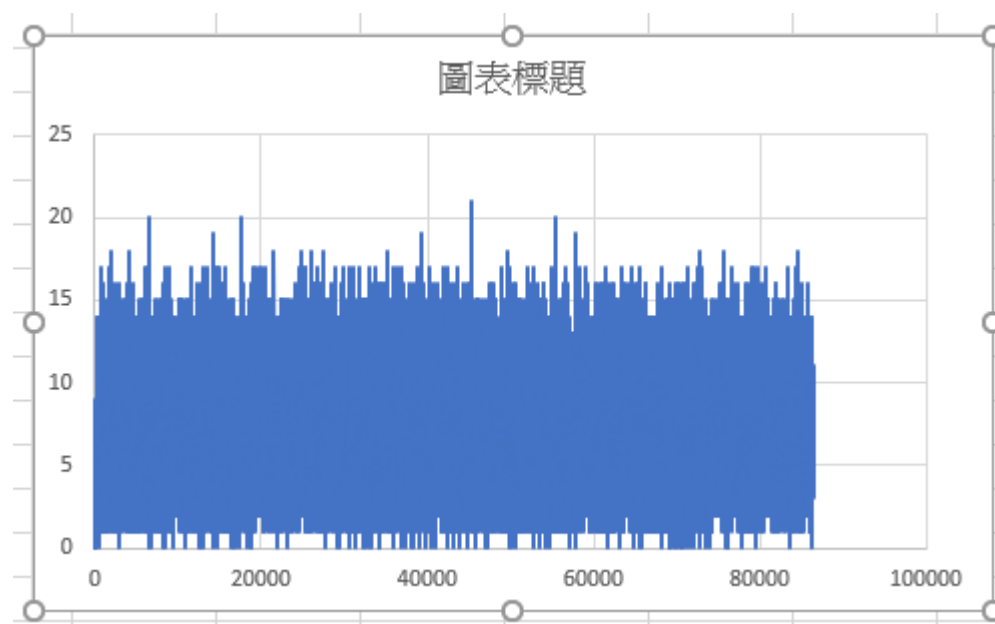
Best Policy $\lambda = 1/5$



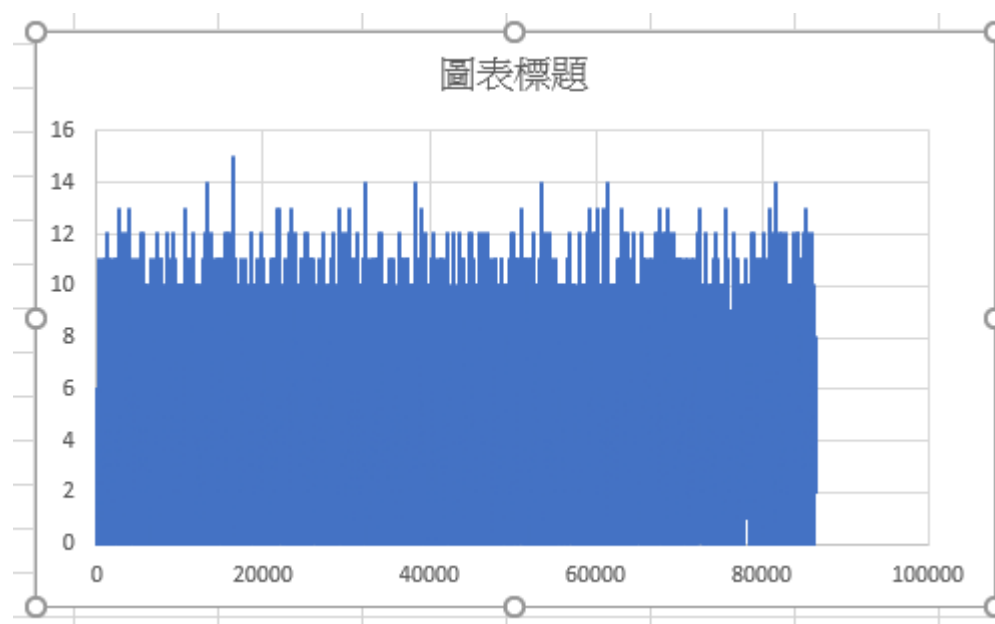
Threshold Policy $\lambda = 1/2, T=15$



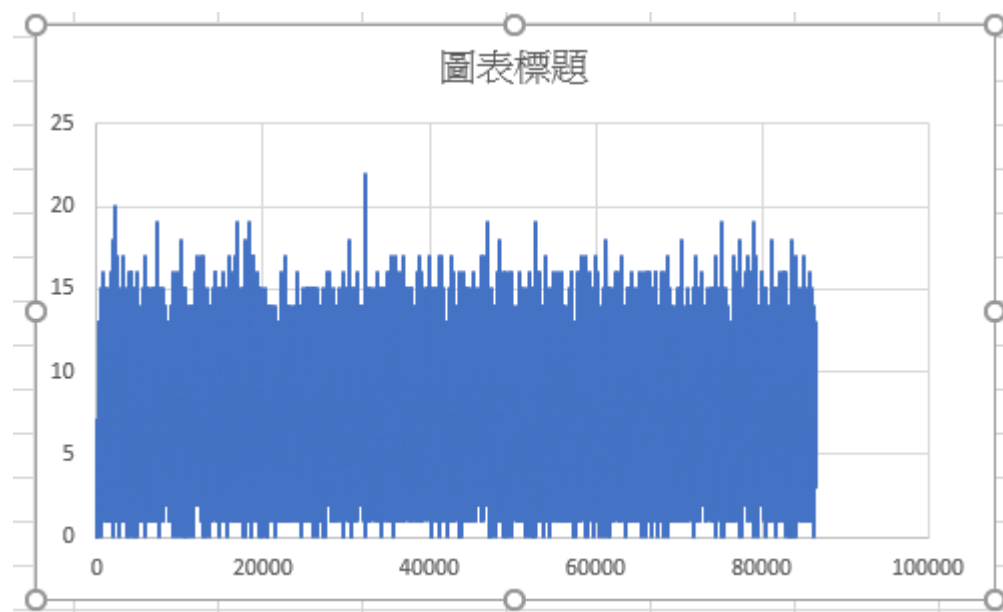
Threshold Policy $\lambda = 1/3, T=15$



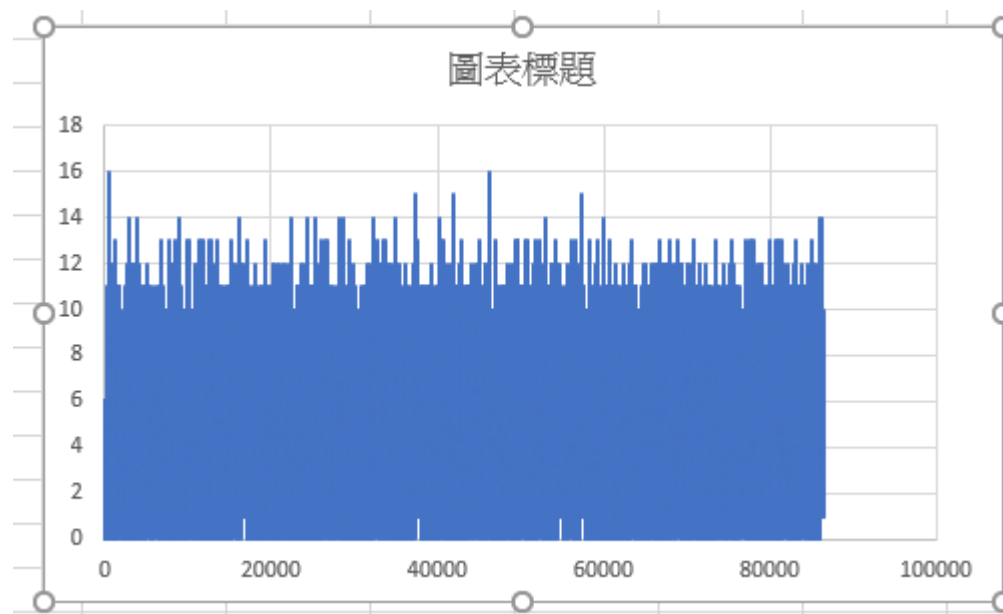
Threshold Policy $\lambda = 1/5, T=15$



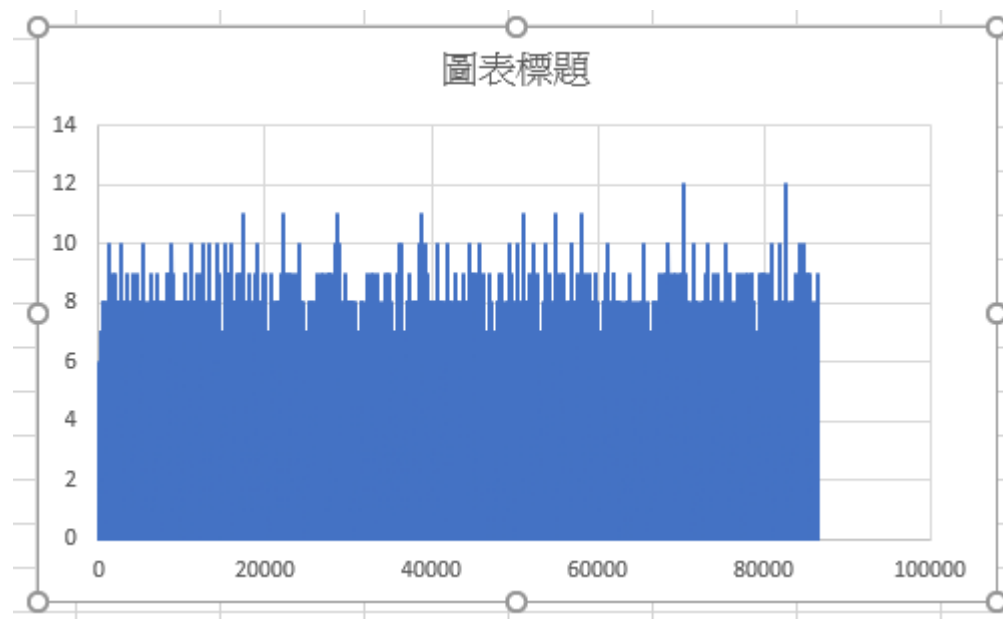
Entropy Policy $\lambda = 1/2, E=13$



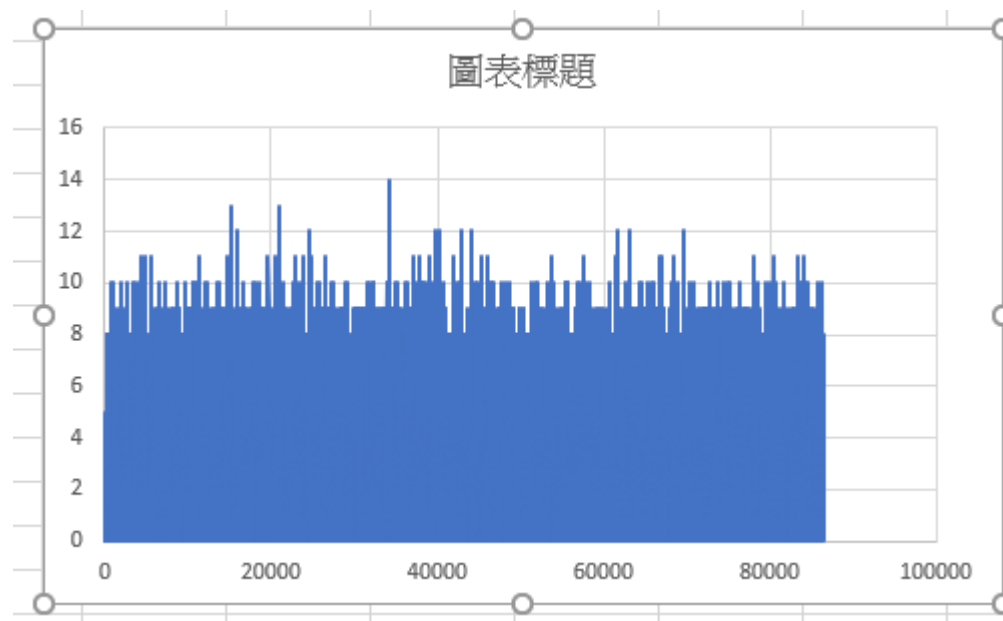
Entropy Policy $\lambda = 1/3, E=13$



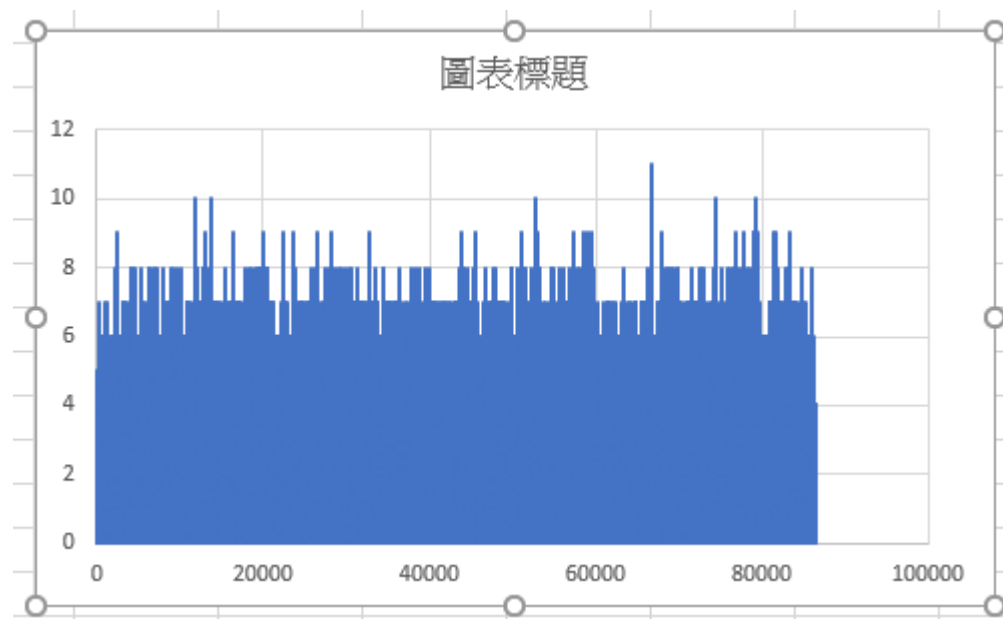
Entropy Policy $\lambda = 1/5$, $E=13$



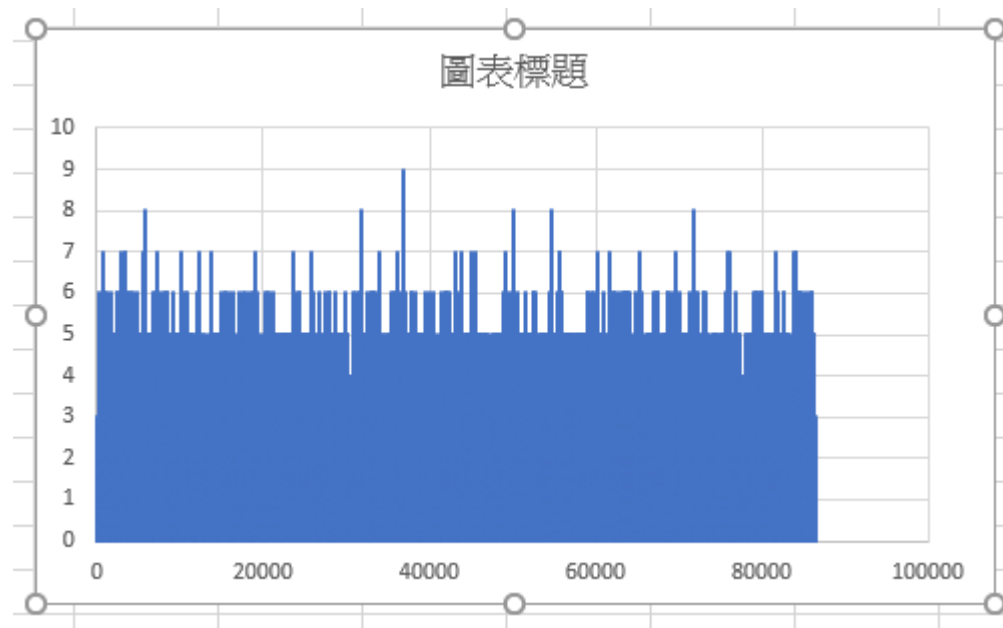
My Policy $\lambda = 1/2$



My Policy $\lambda = 1/3$



My Policy $\lambda = 1/5$



介紹 My Policy

My Policy 是運用

$P_{old} < 15 \ \& \ P_{new} > P_{old} + 13$

來做為我的 Handoff Policy

My Policy 與 Best Policy 比較起來，在於 My Policy 能減少較多的 handoff 次數(優點)，而相對的也減少較多的 AVG_Power(缺點)

My Policy 與 Threshold Policy 比較起來，在於 My Policy 能減少一些的 handoff 次數(優點)，而相對的也減少一些的 AVG_Power(缺點)

My Policy 與 Entropy Policy 比較起來，在於 My Policy 能減少些許的 handoff 次數(優點)，而相對的也減少些許的 AVG_Power(缺點)