上 海 交 通 大 学 试 卷(<u>A</u>卷)

(2017 至 2018 学年 第 1 学期)

	班级号		学号	姓名
	课程名称	计算机系统基础(1)		成绩
	4 10			
	em 1: FP (9	points)		
1. [1	.]			
[2	2]			
[3	5]			
2.				
۷.				
_				
3.				
Probl	em 2: HCL (7points)		
1.				
2.				
Probl	em 2: Y86 (17 points)		
1. [1	.]	[2]		
[3	3]	[4]		
[5	5]	[6]		
[7	']			
2.				

题号 1 2 3 4 5 我承诺,我将严 格遵守考试纪律。 得分 承诺人: _____ 批阅人(流水阅 卷教师签名处) Problem 4: Memory Allocation (16 points) 1. 2. 3. 4.

Problem 5: Optimization (16 points)

1.

2.

3.

Problem 6: Processor (35 points)

1.

2.

3. [1]

[2]

[3]

[4]

4. [1]

[2]

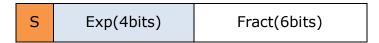
[3]

5.

6.

Problem 1: FP (9 points)

The following figure shows the floating-point format we designed for the exam, called **Float11**. Except for the length, it's the same as the IEEE 754 single-precision format you have learned in the class.



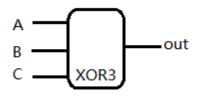
- 1. Fill the blanks with proper values. (3')
 - 1) **Denormalized**: $(-1)^s \times (0.Fract) \times 2^E$, where **E** = [1]
 - 2) NaN (any correct binary form): [2]
 - 3) **Biggest Denormalized Value** (in **binary** form): [3]
- 2. Convert the number (-5.75)₁₀ into the **Float11** representation (in **binary**). (3')
- 3. Assume we use IEEE **round-to-even** mode to do the approximation. Please calculate the subtraction: (1 0000 101100)₂ (0 0100 110010)₂ and write the answer in **binary**. (The answer is represented in **Float11** as well) (3')

Problem 2: HCL (7 points)

Please write down the HCL expressions for the following signals (HINT: you can refer to the **Section 4.2.2** in the CSAPP book).

1. The HCL expression for a signal **nand**, which is equal to **NAND** of inputs **a** and **b**, the truth table is given, and you should **only** use **NOT** (!) and **OR** (||) operators. (3')

2. The HCL expression for **a three-way xor** called XOR3. If and only if all the inputs are the same, output will be true (1). Each input and output is one-bit wise. (Hints: You can use boolean expressions or case expressions.) (4')



Problem 3: Y86 (17 points)

```
0x000:
                            | .pos 0
0x000:
                             | init:
0x000: 30f40002000000000000
                            | irmovq stack, %rsp
0x00a: [1]
                            | irmovq stack, %rbp
0x014: 801e00000000000000
                           | call main
0x01d: 00
                             | halt
0x01e:
                             | main:
0x01e: 30f70003000000000000
                            | irmovq list, %rdi
0x028: 30f60300000000000000
                               [2]
0x032: 803c00000000000000
                            | call calculate
0x03b: 90
                               ret
0x03c:
                             | calculate:
0x03c: 6300
                                [3]
0x03e: 30f30800000000000000
                            | irmovq $8, %rbx
0x048: 2072
                               rrmovq %rdi, %rdx
0x04a: 706d00000000000000
                               jmp test
                            | loop:
0 \times 053:
                            [4]
0x053: 50120000000000000000
0x05d: 6010
                            | addq %rcx, %rax
0x05f: ____[5]____
                            | andq %rsi, %rax
0 \times 061:6032
                            | addq %rbx, %rdx
0x063: 50220000000000000000
                            | mrmovq (%rdx), %rdx
0x06d:
                             | test:
0x06d: 6222
                               andq %rdx, %rdx
0x06f: 745300000000000000
                            | jne loop
0x200:
                             [6]____
0x200:
                            | stack:
0x300:
                             | .pos 0x300
0x300:
                            | .align 8
0x300:
                             | list:
0x300: 0800000000000000
                            | .quad 0x8
                            | .quad ____[7]___
0x308: 2003000000000000
0x310: 0900000000000000
                            | .quad 0x9
0x318: 0000000000000000
                            | .quad 0x0
0x320: 0a00000000000000
                               .quad 0xa
0x328: 1003000000000000
                            | .quad 0x310
```

- 1. Please fill in the blanks within above Y86 binary and assembly code. (2'*7=7')
- 2. Please calculate the value of %rax after the program HALT. (3')

Problem 4: Memory Allocation (16 points)

Now we organize the heap as a sequence of **contiguous** allocated and free blocks, as shown below. **Allocated** blocks are shaded, and **free** blocks are blank (each block represents 1 word = 4 bytes). **Headers** and **footers** are labeled with the number of bytes and allocated bit. The allocator maintains **double-word** alignment. You are given the execution sequence of memory allocation operations (malloc() or free()) from 1 to 6.

									V P1
32/0							32/0	16/1	
									√ P2
	16/1	24/0					24/0	16/1	
 V P3									
	16/1	16/0			16/0	16/1			16/1

- 1.P4 = malloc(10)
- 2.free(P1)
- 3.P5 = malloc(10)
- 4.P6 = malloc(5)
- 5.free(P3)
- 6.P7 = malloc(10)

Please answer the questions below. Assume that **immediate coalescing** strategy and **splitting free blocks** are employed.

- Assume **best-fit** algorithm is used to find free blocks. Please draw the **final** status of memory and mark with block size in headers and footers after the operation sequence is executed (4').
- 2. Assume **first-fit** algorithm is used to find free blocks. Please draw the **final** status of memory and mark with block size in headers and footers after the operation sequence is executed (4').
- 3. In our current algorithm, we do immediate coalescing by merging any adjacent free blocks each time a block is freed. However, such policy can hurt performance dramatically sometimes. Please give a simple example of such situation and explain why (4'). (**HINT**: consider the performance influence of frequent coalescing operations)
- 4. To handle such problems, we defer coalescing until some allocation requests fails and then scan the entire heap, coalescing all free blocks. Assume **first-fit** algorithm under such coalescing policy, draw the **final** status of memory and mark with block size in headers and footers after the operation sequence is executed (4').

Problem 5: Optimization (16 points)

```
1.
    typedef struct {
       float *data; /* points to an array */
2.
       long capacity; /* the maximum length of the array */
3
       long length; /* number of elements in the array */
5.
    } array t;
6.
    long get length (array t *arr) {return arr->length;}
7.
    long get capacity (array t *arr) {return arr->capacity;}
    void copy array(array t *dst, array t *src) {
9.
       for (long i = 0; i < get length(src); i++) {</pre>
10.
           if (i >= get capacity(dst))
11.
              break:
12.
           dst->data[i] = src->data[i];
13.
14.
       dst->length = min(get length(src), get capacity(dst));
15. }
16. void sum array(float *arr, long n, long *sum) {
17.
       float ans = 0;
18.
       for (long i = 0; (i+1) < n; i += 2)
19.
           ans = ans + (arr[i] + arr[i + 1]);
20.
       if (i < n)
21.
           ans += arr[i];
22.
       *sum = ans;
23. }
24. .Loop:
25.
     movss (%rax, %rdx, 8), %xmm0
     addss 8(%rax, %rdx, 8), %xmm0
26.
27.
     addss %xmm0, %xmm1
     addq $2, %rdx
28.
29.
      cmpq $rdx, %rbp
30.
      jg .Loop
```

- 1. Please rewrite the function copy_array with a combination of at least 4 different optimizations you learned in class. Comment briefly on the optimization. (2'*4=8') NOTE: your optimizations cannot change the functionality of code above.
- 2. The translation of code in **line 18-19** is presented **in line 24-30**. Please abstract the operations as a data-flow graph and draw the graph. Please also mark the critical path(s) in the graph. (5')
- 3. The code **in line 19** is modified as the following code in the table. After the modification, the CPE measurement increases from **x** to **2x**. Please point out why the CPE measurement increases. (3')

```
      ans = (ans + arr[i]) + arr[i + 1];

      A 卷 总 12 页 第 8 页
```

Problem 6: Processor (35 points)

In Lab 6, you were asked to implement a **ncopy** program, which will copy and count the number of positive integer. Here is the core loop in the initial version:

```
Loop: mrmovq
                (%rdi), %r10
                                // %r10 = *src
                %r10, (%rsi)
                                // *dst = %r10
      rmmovq
      andq
                %r10, %r10
                                // if (%r10 > 0)
      jle
                Npos
                $1, %rax
                                //
      iaddq
                                       %rax++
                                // else, just skip
Npos:
                $8, %rdi
                                // src++
      iaddq
      iaddq
                $8, %rsi
                                // dst++
      iaddq
                $-1, %rdx
                                // cnt--
                                // if cnt > 0, continue
                Loop
      jg
                                // else, halt
      halt
```

1. Assume the input is "1, 2, -3, 4, -5, -6", the program is running on unmodified PIPE implementation. Please show **all hazards** involved and **how many bubbles** will be inserted for each. (6')

As the loop overhead and load-use hazard could be resolved by loop unrolling and code rewriting, the most overhead is from the **misprediction**. Here we will implement a new instruction: selective skip, **cskipxx**, with following encoding:

Name	Value (hex)	Meaning		
ICSKIPXX	E	Code for cskipxx instruction		

This instruction will "skip" the next instruction if the condition is satisfied, which causes the next instruction be treated as a nop. We use always-not-taken prediction, which means you will load the next instruction anyway, then cancel it if necessary. By correctly implementing this instruction, the misprediction penalty will be reduced to 1 cycle.

2. Please rewrite the loop code by replacing jle with cskipxx, and answer the question 1 again. (Note: you do **NOT** need to write comment) (3'+3')

3. There will be a new control hazard called **cskipxx misprediction**. Please list the **detection conditions** like Figure 4.64 and **new control action** like Figure 4.66. (2'*4)

Condition	Trigger					
	[1]					
agkinuu mianmadiation	Pipeline register					
cskipxx misprediction	F	D	E	M	W	
	[2]	[3]	[4]			

4. **cskipxx** misprediction and **ret** hazard could be combined in the above way. Please show how to handle it correctly based on your **cskipxx** implementation. (1'*4)

	Mispredict		ret 1
М		М	
Е	cskipxx	Е	
D		D	ret

Pipeline register					
F	D	E	M	W	
[1]	[2]	[3]	[4]	normal	

- 5. Now we want to extend cskipxx to cskip3xx, which will skip 3 instructions when condition is satisfied. Could cskip3xx misprediction be handled by simply inserting more bubbles when detected in E stage? Why? (3') Please describe your proposed solution in English. (2') And show the main HCL modifications. (4')
- 6. Please analyze the **pros** and **cons** of **cskip3xx** compared to **jxx**. (2')

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