

Solution

Problem 1: (17 points)

1 `A\n`

`counter =3`

2 `A\n or B\n or A\n B\n`

`counter = 3 or 1 or 4`

OR

`B\n or A\n B\n , counter = 1 or 4`

3 `A\n or B\n or A\n B\n or A\n B\n B\n or B\n B\n`

OR

`B\n or A\n B\n or A\n B\n B\n or B\n B\n`

Because the sequential 2 `sigusr1` will cause signal pending and which will make some signal thrown away. So there are many possible outputs for `B\n`

Problem 2: (14 points)

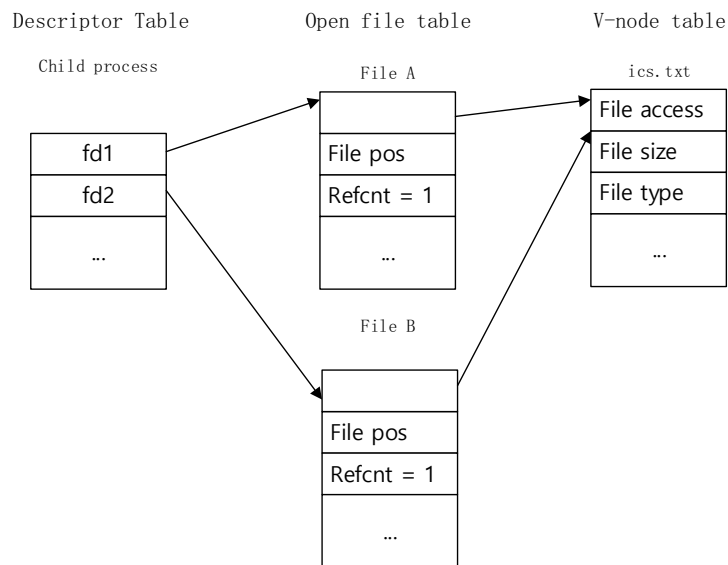
1 Child fd1 S

Child fd2 S

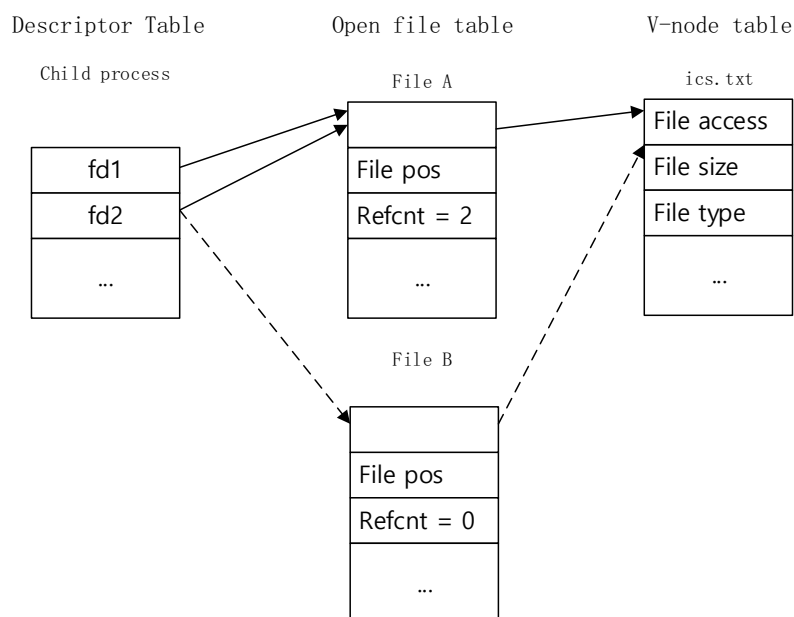
2 Child fd1 S

Child fd2 J

Before: (If Refcnt of File A is 2, it's also right)



After: (If Refcnt of File A is 3, it's also right)



3 Parent fd1 T

Parent fd2 S

4 Parent fd1 H

Parent fd2 S

The content of ics.txt is SHTU120

Problem 3: (16 points)

1

16/1			16/1	16/1			16/1	16/1	
	16/1	24/0					24/0	16/1	
	16/1	16/1					16/1		

Internal fragments: 45 bytes

2

16/1			16/1	16/1			16/1	16/1	
	16/1	16/1			16/1	8/0	8/0	16/1	
	16/1	16/0				16/0			

Internal fragments: 45 bytes

3 For first-fit: Yes. Internal fragments: 69 bytes

For best-fit: No. Failure in step 6, P7 = malloc(2)

Problem 4: (20 points)

1 [1] 12 [2] 2 [3] 2

2. 1) 32 bytes

2) [1] 1 [2] Hit [3] 0xca

[4] 1 [5] Hit [6] 0xff

[7] 0 [8] Miss [9] --

[10] 2 [11] Miss [12] --

[13] 0 [14] Miss [15] 0x34 OR --

Problem 5: (13 points)

- 1 25%
- 2 100%
- 3 25%
- 4 Only miss rate on cache C3 is reduced.

The cache misses in `matrix_sum1()` are cold miss. A larger cache block will fetch more bytes on cache line replacement and make them ready for subsequent accesses.

Problem 6: (20 points)

1

```
#define K 2 // (number of ways)
void dosth_and_find1(pixels_t *p, pixel_t *mintrans)
{
    int i, j;
    /* Eliminating Loop Inefficiencies */
    int length = get_length(p);
    int limit = length - K;
    /* Used record index of mintrans pixel(Reducing Unneeded
Reference) */
    int minIndex1, minIndex2 = 0;
    int minAlpha1, minAlpha2 = 255;

    /* Used to reduce procedure call */
    pixel_t *cur1, *cur2;

    for ( i = 1; i < 4; i++ ) {
        for ( j = 0; j < limit; j+=2 ) {

            cur1 = get_pixel_at(j);
            cur2 = get_pixel_at(j+1);

            /* Unrolling & Parallelism */
            cur1->argb[i] = cur1->argb[i] * 2 % 255;
            cur2->argb[i] = cur2->argb[i] * 2 % 255;
```

```

        if ( cur1->argb[0] < minAlpha1 ) {
            minIndex1 = j;
            minAlpha1 = cur1->argb[0];
        }
        if ( cur2->argb[0] < minAlpha2 ) {
            minIndex2 = j+1;
            minAlpha2 = cur2->argb[0];
        }
    }

    for ( ; j < length; j++) {
        cur1 = get_pixel_at(j);
        cur1->argb[i] = cur1->argb[i] * 2 % 255;
        if ( cur1->argb[0] < minAlpha1 ) {
            minIndex1 = j;
            minAlpha1 = cur1->argb[0];
        }
    }

    mintrans = get_pixel_at( minIndex1 < minIndex2 ?
                            minIndex1 : minIndex2 );
}

```

2

```

void dosth_and_find3(pixels_t *p, pixel_t *mintrans)
{
    int i;
    /* Eliminating Loop Inefficiencies */
    int length = get_length(p) * 4;
    /* Used record index of mintrans pixel(Reducing Unneeded
Reference) */
    int minIndex = 0;
    int minAlpha = 255;
    /* treat data as one-dimension array */
    int *data = (int *)get_pixel_at(0);

    /* length is multiple of 4, don't need limit */
    for ( i = 0; i < length; i+=4 ) {
        data[i+1] = data[i+1] * 2 % 255;
        data[i+2] = data[i+2] * 2 % 255;
        data[i+3] = data[i+3] * 2 % 255;

        if ( data[i] < minAlpha ) {

```

```
        minIndex = i/4;
        minAlpha = data[i];
    }
}
mintrans = get_pixel_at(minIndex);
}
```