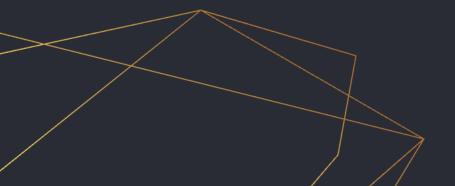
Why Write OS In Rust?

ChCoreCon #7, 3/1/2021



Outline

- Safety
- Expression
- Interoperability
- Performance
- Usability
- Drawbacks
- Summary

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Safety

- Spatial memory safety
- Temporal memory safety
- Thread safety

According to the MSRC blog, 70% of the security issues that it assigns a CVE to are memory safety issues!

How C sucks:

```
int someos_file_write(int fd, void *buf, size_t count) {
    int ret, cnt, remain = count; // implicit conversion
    // ...
    while (remain > 0) {
        fr->count /* ssize_t */ = cnt = MIN(remain, FS_BUF_SIZE);
        memcpy(fr->buf, buf, cnt);
        // write to file, ret is: 1) < 0 for failure; 2) >= 0 for bytes written
        ret = ipc_call(fr);
        buf = (char *)buf + ret; remain -= ret;
        if (ret != cnt) break;
    return count - remain;
```

At least 4 bugs in the above C code!

- 1. int fd: fd can be negative or zero
- 2. void *buf: buf can be null
- 3. remain = count: remain can be negative due to unmatched type
- 4. buf = (char *)buf + ret : ret can be negative, causing out-ofbound access

What features of Rust can help?

- Null safety
- Type safety
- Boundary check
- Error handling

Same thing implemented in Rust:

```
fn someos_file_write(fd: FileDescriptor, buf: &mut [u8]) -> SomeOsResult<usize> {
    let count = buf.len();
    let mut written = Ousize;
    while written < count {</pre>
        let buf_slice = &mut buf[written..min(written + FS_BUF_SIZE, count)];
        let n = ipc_call(buf_slice)?;
        written += n;
        if n < buf_slice.len() {</pre>
            break;
    Ok(written)
```

What if forgot min(written + FS_BUF_SIZE, count)?

```
let buf_slice = &mut buf[written..written + FS_BUF_SIZE];
```

```
If written + FS_BUF_SIZE is larger than buf.len(), it'll panic:
```

thread 'main' panicked at 'range end index 1024 out of range for slice of length 512', src/main.rs:23:30

A bad example in C:

```
void usb_request_async(int req, void *buffer, void (*callback)(int, void *)) {
    qlobal_urb->req = req;
    global_urb->buffer = buffer;
    global_urb->callback = callback;
    usb_send_urb_async(global_urb);
void usb_request_cb(int req, void *buffer) { /* access buffer */ }
void func() {
    unsigned char buf[4096];
    usb_request_async(USB_REQ_GET_XXX, buf, usb_request_cb);
```

What features of Rust can help?

- Lifetime
- Ownership

Try the same in Rust (consider only immutable buffer for simplicity):

```
fn usb_request_async<'a>(
    req: UsbRequest,
    buffer: &'a [u8],
    callback: Box<dyn Fn(UsbRequest, &[u8]) + Send + 'static>,
) {
    std::thread::spawn(move || { // simulate async usb request callback
        callback(req, buffer);
    });
}
```

error[E0759]: `buffer` has lifetime `'a` but it needs to satisfy a `'static` lifetime requirement

Change a little bit according to the error message:

```
fn usb_request_async(
    req: UsbRequest,
    buffer: &'static [u8],
    callback: Box<dyn Fn(UsbRequest, &[u8]) + Send + 'static>,
) {
    std::thread::spawn(move || { // simulate async usb request callback}
        callback(req, buffer);
    });
}
```

Then use usb_request_async:

```
fn usb_request_cb(req: UsbRequest, buffer: &[u8]) {
    println!("{:?}", buffer);
}

fn func() {
    let buffer: [u8; 1024] = [0; 1024];
    usb_request_async(UsbRequest::GetXxx, &buffer, Box::new(usb_request_cb));
}
```

error[E0597]: `buffer` does not live long enough

Possibly a better design:

```
struct Urb {
    req: UsbRequest,
    buffer: Vec<u8>,
    callback: Box<dyn Fn(UsbRequest, &[u8]) + Send + 'static>,
impl Urb {
    fn new(req: UsbRequest, buf_size: usize,
           callback: impl Fn(UsbRequest, &[u8]) + Send + 'static) -> Self {
        Self { req, buffer: vec![0; buf_size], callback: Box::new(callback) }
```

```
fn usb_send_urb_async(urb: Urb) {
    std::thread::spawn(move || { // simulate async usb request callback
        let cb = urb.callback;
        cb(urb.req, &urb.buffer);
    });
fn usb_request_cb(req: UsbRequest, buffer: &[u8]) {
    println!("{:?}", buffer);
fn func() {
    let urb = Urb::new(UsbRequest::GetXxx, 1024, usb_request_cb);
    usb_send_urb_async(urb);
```

Thread safety

Features of Rust to prevent from data races:

Global static variables can't be modified safely

```
static mut GLOBAL_INT: u32 = 1;

fn func() {
    // bad practice
    std::thread::spawn(|| unsafe { GLOBAL_INT = 3 });
    unsafe { GLOBAL_INT = 2 }
}
```

Thread safety

Variables that are shared between threads must imples the synchological s

```
// static GLOBAL_INT_BAD: RefCell<u32> = RefCell::new(1);
lazy_static! {
    static ref GLOBAL_INT: Mutex<u32> = Mutex::new(1);
}

fn func() {
    std::thread::spawn(|| *GLOBAL_INT.lock().unwrap() = 3);
    *GLOBAL_INT.lock().unwrap() = 2;
}
```

Thread safety

Variables that are sent across threads must impl Send

```
fn func() {
   let shared_int = Arc::new(Mutex::new(1));
   let shared_int_clone = shared_int.clone();

   std::thread::spawn(move || *shared_int_clone.lock().unwrap() = 3);
   *shared_int.lock().unwrap() = 2;
}
```

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Can Rust express everything that C can?

In theory, YES, both are turing-complete.

In practice, ALMOST, with some unsafe code. When you can't implement some logic in Rust, you probably should rethink the design.

Example for booting:

```
#[no_mangle]
#[link_section = ".text.boot"]
extern "C" fn _start_rust() -> ! {
    #[link_section = ".data.boot"]
    static START: spin::Once<()> = spin::Once::new();
    START.call_once(|| {
        clear_bss();
        memory::create_boot_pt();
    });
    memory::enable_mmu();
    unsafe { _start_kernel() }
```

Example for driver:

```
fn handle_irq(&self) {
    loop {
        let irqstat = self.read_cpu_reg(GICC_IAR);
        let irqnr = irqstat & GICC_IAR_INT_ID_MASK;
        match irqnr {
            0..=15 => crate::irq::handle_inter_processor(irqnr),
            16..=31 => crate::irq::handle_local(irqnr - 16),
            32..=1020 => crate::irq::handle_shared(irqnr - 32),
            _ => break,
        self.write_cpu_reg(GICC_EOIR, irqstat);
```

Much better than C:

- Module: better modularity
- Ownership & Lifetime: memory safety
- Trait: generic programming
- Result & Error: better error handling
- Closure & Iterator: functional programming
- Macro: meta programming

Compared to C++:

- Similar funtionality
- Safe by default
- core and alloc crates without need for std

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Interoperability

Call C from Rust:

```
extern "C" {
    fn some_function_in_c(buf: *mut u8, n: usize) -> usize;
}

fn func() {
    let mut buf = [0u8; 1024];
    let buf_raw_ptr = &mut buf[0] as *mut u8;
    let ret = unsafe { some_function_in_c(buf_raw_ptr, buf.len()) };
}
```

Interoperability

Call Rust from C:

```
#[no_mangle]
extern "C" fn some_function_in_rust(buf: *mut u8, n: usize) -> usize {
   let buf = unsafe { core::slice::from_raw_parts_mut(buf, n) };
   println!("{:?}", buf); buf.len()
}
```

```
extern size_t some_function_in_rust(unsigned char *buf, size_t n);
void func() {
   unsigned char buf[1024];
   some_function_in_rust(buf, 1024);
}
```

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Performance

According to <u>The Computer Language Benchmarks Game</u>, Rust achieves same or even better performance than C and C++.

Features that make Rust fast:

Cross-language LTO

•••••

- Zero-cost abstractions, e.g. <u>Iterators</u>
- Faster impl for single-threaded context, e.g. Rc vs Arc
- Carefully implemented builtin data structures, e.g. <u>BTreeMap</u>

30

Performance

Open source projects (re)written in Rust that're proved to be fast(er):

- <u>ripgrep</u>
- <u>alacritty</u>
- <u>fd</u>
- actix-web
- <u>serde</u>
- <u>servo</u>

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Usability

Tools:

- Rustup makes toolchain management easy
- <u>Cargo</u> makes dependency management easy
- <u>rust-analyzer</u> is an excellent language server
- rustc produces comprehensible error messages
- <u>rustfmt</u> formats Rust code according to style guide
- rust-clippy can catch common mistakes in Rust code
- bindgen helps generate Rust FFI bindings to C and C++ libraries

33

Usability

Example for dependency management:

```
[dependencies]
spin = "0.7.0"
buddy_system_allocator = { git = "https://github.com/richardchien/buddy_system_allocator.git" }
log = "0.4.0"
lazy_static = { version = "1.4.0", features = ["spin_no_std"] }
bitflags = "1.2.1"

[target.'cfg(target_arch = "aarch64")'.dependencies]
aarch64 = { git = "https://github.com/richardchien/aarch64", rev = "5dc2a13" }
```

Usability

Debug trait for easy debugging:

```
#[repr(u8)]
#[derive(Debug)]
enum IntType {
    SyncEl1t = 1,
    IrqEl1t = 2,
    // ...
#[no_mangle]
extern "C" fn _handle_interrupt(int_type: IntType) {
    println!("Interrupt occurred, type: {:?}", int_type);
```

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Drawbacks

- Steep learning curve
- Many unstable features
- Slow compile speed
- Small ecosystem (but growing quickly)

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Summary

- Safe by default
- Rich language features without need for std
- Harder to write, but easier to be correct once compiled
- Easy-to-use tools
- Backed by some big companies: Google, Microsoft, Mozilla, ...
- Future seems bright

Special thanks to Alex Chi for reviewing the slides.

References

- The Rust Programming Language & The Rustonomicon
- Considering Rust by Jon Gjengset
- Why Rust for safe systems programming by MSRC
- <u>Implications of Rewriting a Browser Component in Rust</u> by Diane Hosfelt
- Speed of Rust vs C by kornelski
- C++ Is Faster and Safer Than Rust: Benchmarked by Yandex by Roman Proskuryakov

OSes Written in Rust

- Redox: A Unix-like OS with a modern microkernel
- <u>Tock</u>: An embedded OS for low-memory and low-power microcontrollers
- <u>RedLeaf</u>: A new OS aimed at leveraging Rust language features for developing safe systems
- <u>Theseus</u>: A new OS for experimenting with novel OS structure, better state management, and how to shift OS responsibilities like resource management into compiler
- <u>rCore</u>: A teaching OS based on <u>BlogOS</u>, providing a subset of Linux syscalls