

# Structural VAR: Proxy-VAR

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## 1 Introduction

A central challenge in empirical macroeconomics is the **identification of structural shocks** from reduced-form innovations. In standard Vector Autoregression (VAR), the observed residuals ( $u_t$ ) are typically correlated across equations, reflecting a mixture of various structural disturbances ( $\epsilon_t$ ). To recover the causal impact of a specific policy - such as a monetary policy - one must isolate the "pure" structural shock from the endogenous movements in the data.

To address this, the **proxy-SVAR framework**, popularize by Stock and Watson (2012) and Mertens and Ravn (2013), utilizes **external instruments** ( $Z_t$ ) to achieve identification. Unlike traditional identification schemes that rely on short-run zero restrictions (Cholesky) or sign restrictions, the proxy-SVAR approach leverages information outside the VAR system. An external variable is considered a valid proxy if it satisfies two fundamental conditions:

- **Relevance:** The instrument must be correlated with the structural shock of interest, i.e.,  $\mathbb{E}[Z_t \epsilon'_{i,t}] \neq 0$ .
- **Exogeneity:** The instrument must be uncorrelated with all other structural shocks in the system, i.e.,  $\mathbb{E}[Z_t \epsilon'_{-i,t}] = 0$ .

## 2 Proxy-SVAR Estimation

The Proxy-SVAR relies on the relationship  $u_t = B\epsilon_t$ . We focus on identifying the first column of  $B(b_1)$ , which represents the impact of structural shock ( $\epsilon_{1,t}$ ) of interest, as Gertler and Karadi (2015).

We partition the  $n$  variable in the VAR into the **policy variable** ( $p_t$ , the first variable) and all **other variables** ( $q_t$ , the remaining  $n - 1$  variables). We partition the residuals and the  $B$  matrix accordingly:

$$\begin{bmatrix} u_{pt} \\ u_{qt} \end{bmatrix} = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \begin{bmatrix} \epsilon_{pt} \\ \epsilon_{qt} \end{bmatrix},$$

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## 2.1 2SLS Stage

We start the **Two-Stage-Least-Square (2SLS)**. First, we regress  $u_{pt}$  on the instrument  $Z_t$ :

$$u_{pt} = \beta_{11} + \beta_{12}Z_t + e_{pt}, \quad (1)$$

To include intercept, we ensure that  $\beta_{12}$  captures only the **variation** in the policy residual that moves with the instrument, regardless of any temporary level shifts in the sub-sample. The predicted value  $\hat{u}_{pt}$  represents the part of policy residual driven purely by the instrument (and thus by the structural shock  $\epsilon_{pt}$ ).

Next, we **identify the relative ratio**. We regress the other residuals  $u_{qt}$  on the predicted  $\hat{u}_{pt}$ :

$$u_{qt} = \beta_{21} + \beta_{22}\hat{u}_{pt} + e_{qt}, \quad (2)$$

The coefficient  $\beta_{22}$  is a vector of **relative ratios**:

$$\beta_{22} = \frac{b_{21}}{b_{11}}, \quad (3)$$

It uncovers the "direction" of the shock.

The reduced-form covariance matrix  $\Sigma = \mathbb{E}[u_t u_t']$  is partitioned to match our variables:

$$\Sigma = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix}$$

where  $S_{11} = \mathbb{E}[u_{pt}^2]$ , the variance of the policy residual,  $S_{21} = \mathbb{E}[u_{qt}u_{pt}']$ , the covariance between policy and others, and  $S_{22} = \mathbb{E}[u_{qt}u_{qt}']$ , the covariance matrix of other variables.

Now, we map covariance matrix  $\Sigma$  to the structural  $B$  matrix. Since  $\Sigma = BB'$ , we expand the partitioned multiplication:

$$\begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \begin{bmatrix} b'_{11} & b'_{12} \\ b'_{21} & b'_{22} \end{bmatrix} \quad (4)$$

This gives us three identity equations:

$$S_{11} = b_{11}^2 + b_{12}b'_{12}, \quad (5)$$

$$S_{21} = b_{21}b'_{11} + b_{22}b'_{12}, \quad (6)$$

$$S_{22} = b_{21}b'_{21} + b_{22}b'_{22}, \quad (7)$$

From 2SLS, we have the identified vector  $\beta_{22} = b_{21}b_{11}^{-1}$ , which mean we can write  $b_{21} = \beta b_{11}$ . Plug it into equations (5) and (6), and obtain

$$b_{12}b'_{12} = S_{11} - b_{11}^2,$$

$$S_{21} = \beta b_{11}b'_{11} + b_{22}b'_{12},$$

$Q$  is defined as the covariance matrix of the term  $(u_{qt} - \beta_{22}u_{pt})$ :

$$Q = \mathbb{E}[(u_{qt} - \beta_{22}u_{pt})(u_{qt} - \beta_{22}u_{pt})'],$$

We have  $S_{11} = \mathbb{E}[u_{pt}u_{pt}']$ ,  $S_{21} = \mathbb{E}[u_{qt}u_{pt}']$ , and  $S_{22} = \mathbb{E}[u_{qt}u_{qt}']$ . Then,

$$\begin{aligned} Q &= \mathbb{E}[u_{qt}u_{qt}' - u_{qt}u_{pt}'\beta'_{22} - \beta_{22}u_{pt}u_{qt}' + \beta_{22}u_{pt}u_{pt}'\beta'_{22}], \\ &= S_{22} - (S_{21}\beta'_{22} + \beta_{22}S'_{21}) + \beta_{22}S_{11}\beta'_{22}, \end{aligned}$$

$$b_{11}^2 = S_{11} - (S_{21} - \beta_{22}S_{11})'Q^{-1}(S_{21} - \beta_{22}S_{11}), \quad (8)$$

## References

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