Project 2A

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What is this project about?

Update a shared variable

- A simple integer in part 1
- A list in part 2

To demonstrate the existence of race conditions

...and how to avoid them

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```
void add(long long *pointer, long long value) {
    long long sum = *pointer + value;
    *pointer = sum;
}
```

Multi threaded applications

Initially, your main() program comprises a single thread

- All other threads will have to be explicitly created
 - Done using pthread_create()
- Upon exit, wait on all other threads to complete
 - Using pthread_join
- Time each run for each thread
 - Using clock_gettime()
- Optionally providing protection from race conditions
 - Mutexes, spin locks, compare and swap adds
- Optionally creating conflicts
 - When adding, or when modifying the linked list

Measuring run times

Success: 0 // Error: errno

int clock_gettime(clockid_t clk_id, struct timespec *tp);

The specified clock:

- CLOCK REALTIME
- CLOCK MONOTONIC
- CLOCK_PROCESS_CPUTIME_ID
- CLOCK_THREAD_CPUTIME_ID

```
struct timespec {
    time_t tv_sec; /* seconds */
    long tv_nsec; /* nanoseconds */
};
```

Rmk: A clock may be system wide or per-process/per thread. Which do we want?

-> A system wide clock

pthread_create

Goal: Create a thread

Success: 0 // Error : errno, *thread left undefined

Attribute object, set to 'NULL' for default values. These include:

- Detached or joinable state
- Scheduling inheritance
- Scheduling policy
- Scheduling parameters
- Scheduling contention scope
- Stack size
- Stack address
- Stack guard (overflow) size

Opaque identifier returned by the routine

The C routine to be executed on creation

A single argument to be passed to start routine: Passed by reference as a pointer cast of type void.

Can be set to "NULL'.

pthread_join()

Goal: Join with a terminated thread

Success: 0 // Error: errno

int pthread_join(pthread_t thread, void **retval)

Thread we're waiting on to terminate

Return value of thread we're waiting on:

- Can be set to 'NULL'
- If the target thread is cancelled,
 PTHREAD_CANCELED is placed in

Initializing a mutex

2 ways:

• Statically, when declared:

```
pthread_mutex_t mymutex = PTHREAD_MUTEX_INITIALIZER;
```

Dynamically, which permits to set attributes:

```
Success: 0 // Error : errno
```

int pthread_mutex_init(pthread_mutex_t *restrict mutex,
const pthread_mutexattr_t *restrict attr);

Mutex object

int pthread_mutex_destroy(pthread_mutex_t *mutex);

Rmk: Attempting to destroy a locked mutex results in a 'busy' error

Setting attributes

Mutex attributes include:

- The type (deadlocking, deadlock-detecting, recursive...)
- The robustness (if you acquire a mutex and original owner died while processing it)
- Process-shared attributes (sharing a mutex across process boundaries)
- Protocol (how a thread behaves when higher priority thread wants the mutex)
- Priority ceiling (of the critical section, can prevent priority inversion)

Rmk: you need to call init/destroy to create the 'attributes' object

Locking and Unlocking a Mutex

```
Success: 0 // Error: errno

int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_trylock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

Sync lock test and set

Goal: Implement a spin lock

```
Writes 'value' into *ptr, and returns the previous contents of *ptr

type sync lock test and set (type *ptr, type value, ...)
```

```
__sync_lock_release (type *ptr, ...)
```

Releases lock pointed at by ptr

Compare and swap

Goal: Atomic compare and swap, if the current value of *ptr is oldval, then write newval into *ptr

True if comparison is successful and newval is written

bool __sync_bool_compare_and_swap (type *ptr, type oldval type newval, ...)

type __sync_val_compare_and_swap (type *ptr, type oldval type newval, ...)

Contents of *ptr before the operation

Variable to modify

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