## Chapter 7: Storage Management

Part 2: Index Structures

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## Outline<sup>1</sup>

- 1 7.5 Indexes on Sequential Files
- 2 7.6 Tree-based Index Structures
  - B+ Trees
- 3 7.7 Hash-based Index Structures
  - Extensible Hash Tables
  - Linear Hash Tables

<sup>1</sup>Updated on April 2, 2019

## 7.5 Indexes on Sequential Files

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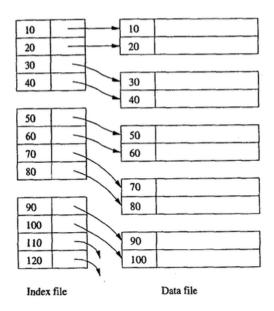
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# Index Structures (索引结构)<sup>2</sup>

- The data file (数据文件) stores sorted data records
- The index file (索引文件) stores key-pointer pairs corresponding to the data records or the data blocks



<sup>&</sup>lt;sup>2</sup>Please refer to Chapter 6 for more details on the concepts and the design of indexes  $\circ$ 

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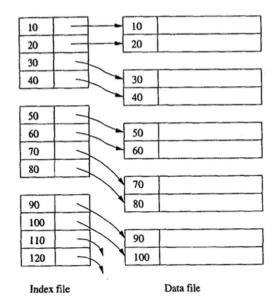
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## Index Structures (Cont'd)

- # of index blocks < # of data blocks (Why?)</li>
- We can use binary search to find a key K in the index file



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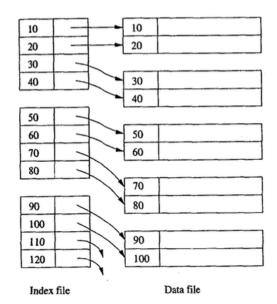
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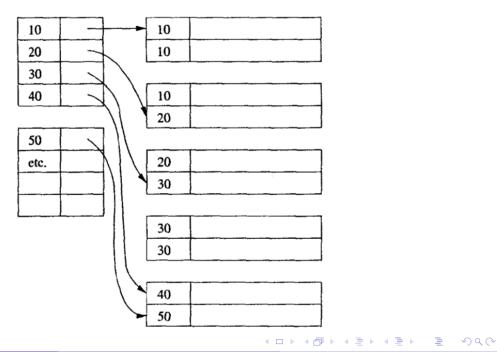
# Dense Indexes (稠密索引) with Unique Search Keys

- The data records are sorted by the search key
- There is a key-pointer entry in the index file for every record of the data file (1条记录←→1个索引项)
- The index entries are also sorted by the search key



## Dense Indexes with Duplicate Search Keys

- There is a key-pointer entry in the index file for each search key K (1个键值 $\longleftrightarrow$ 1个索引项)
- This pointer points to the first of the records with *K*



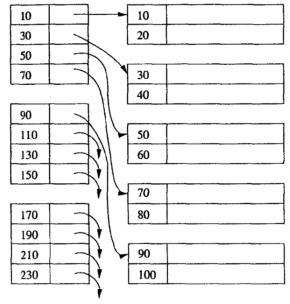
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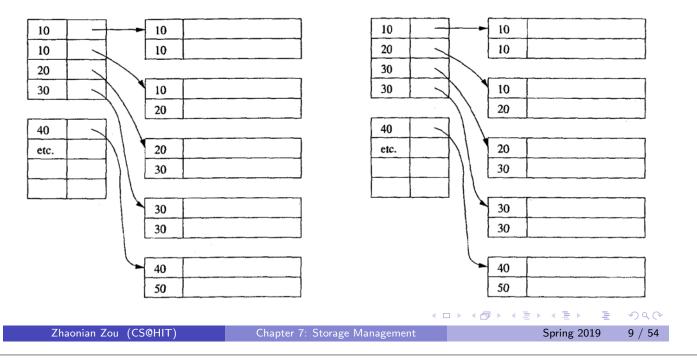
# Sparse Indexes (稀疏索引) with Unique Search Keys

- The data records are sorted by the search key
- There is a key-pointer entry in the index file for every data block. The
- The index entries are also sorted by the search key



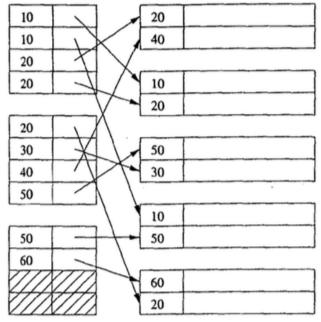
## Sparse Indexes with Duplicate Search Keys

- There is a key-pointer pair in the index file for each data block (1↑ 块←→1个索引项)
- The key is the lowest search key or the lowest new search key on the block



# Secondary Indexes (二级索引)

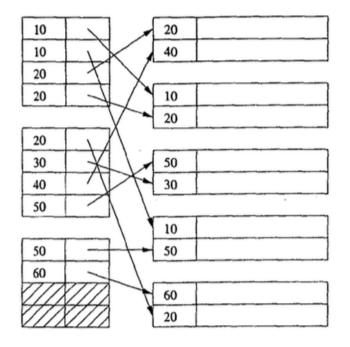
- The data file is sorted by the attributes other than the search key
- The key-pointer entries in the index file are sorted by the search key
- A secondary index must be dense (Why?)



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## Secondary Indexes (Cont'd)

• If a search-key value appears *n* times in the data file, then the value is written *n* times in the index file



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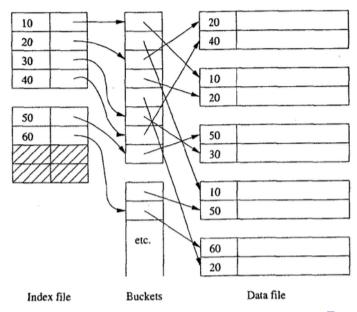
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# Secondary Indexes (Cont'd)

- If a search-key value appears *n* times in the data file, then the value is written *n* times in the index file
- A convenient way to avoid repeating values is to use a level of indirection called buckets



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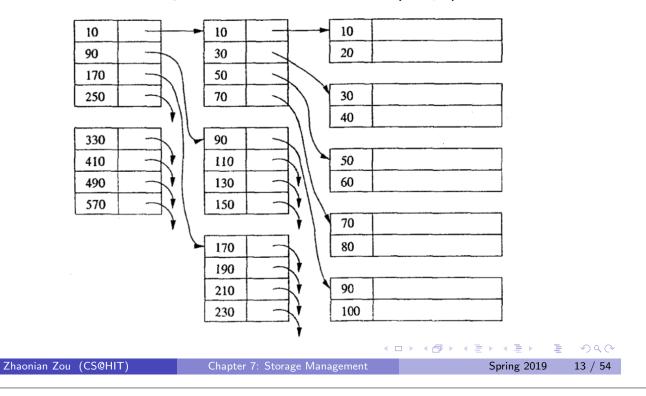
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# Multilevel Indexes (多层索引)

- Put an index on an index
- The first-level index can be either sparse or dense
- The second and higher levels must be sparse (Why?)



7.6 Tree-based Index Structures

# 7.6 Tree-based Index Structures B+ Trees

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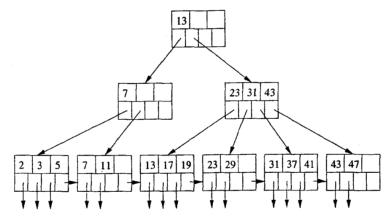
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#### B+ Trees

- A B+ tree is balanced (平衡树)
- 1 node = 1 disk block
- A B+ tree generally consists of three types of nodes
  - ► The root (根节点)
  - ▶ Interior nodes (内节点)
  - ▶ Leaf nodes (叶节点)

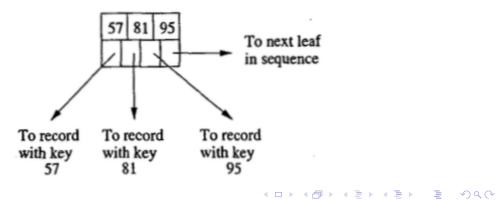


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#### B+ Tree Nodes

#### Leaf Nodes (叶节点)

- (串接) The last pointer points to the next leaf to the right
- (半满至全满) At least  $\lfloor \frac{n+1}{2} \rfloor$  pointers except the last one are used and point to data records
- The ith pointer, if used, points to a record with the ith key
- (有序) All keys in the leaf nodes are ordered in increasing order of the search key



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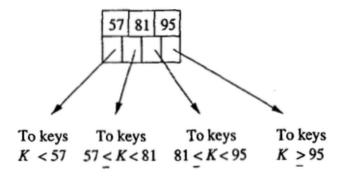
## B+ Tree Nodes (Cont'd)

### The Root (根节点)

● (至少有2个儿子) There are at least two used pointers

#### Interior Nodes (内节点)

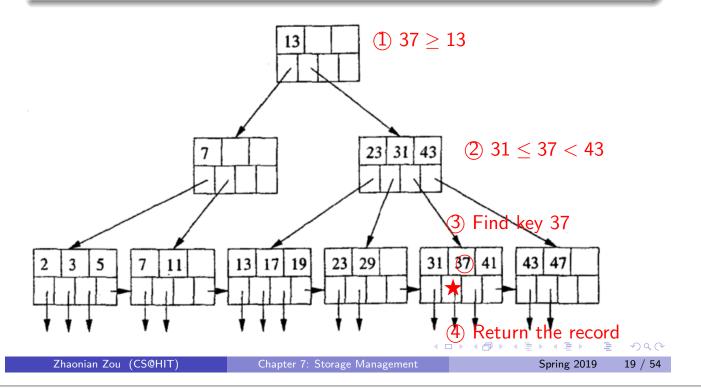
• (半满至全满) At least  $\lceil \frac{n+1}{2} \rceil$  pointers are actually used



## Lookup in B+ Trees

#### Example (Lookup)

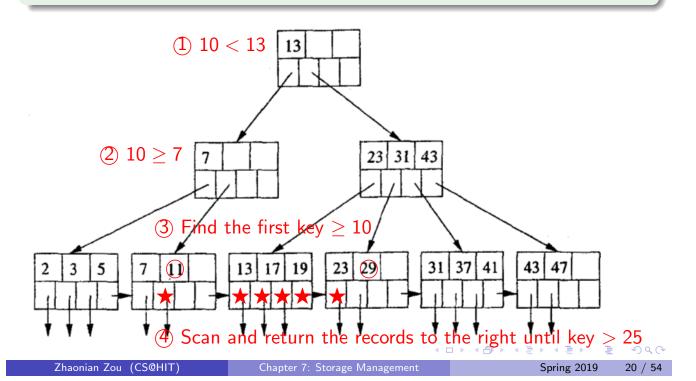
Find a record with search key 37



## Range Queries in B+ Trees

## Example (Range Queries)

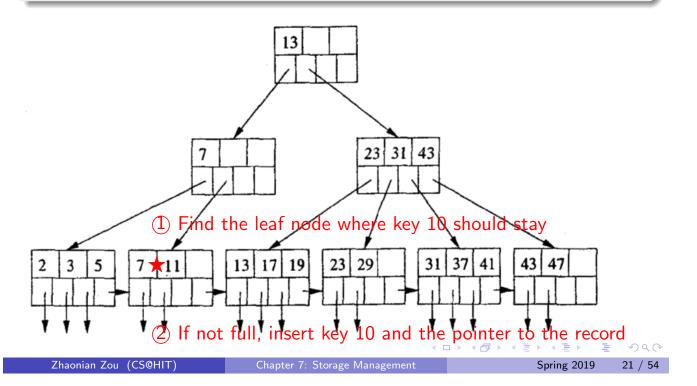
Find records with search keys in [10, 25]



## Insertion into B+ Trees without Splitting

#### Example (Insertion without Splitting)

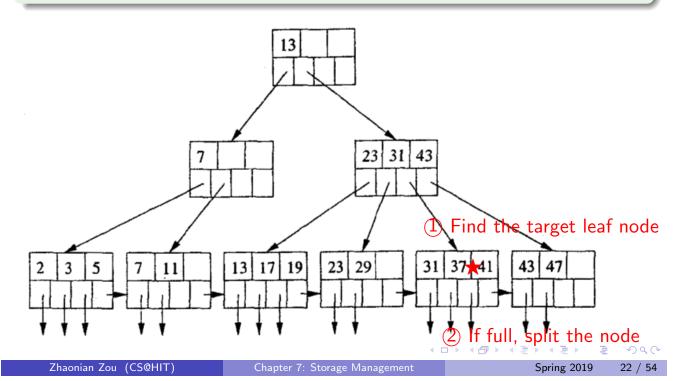
Insert a record with search key 10



## Insertion into B+ Trees with Splitting

Example (Insertion with Splitting, Step 1)

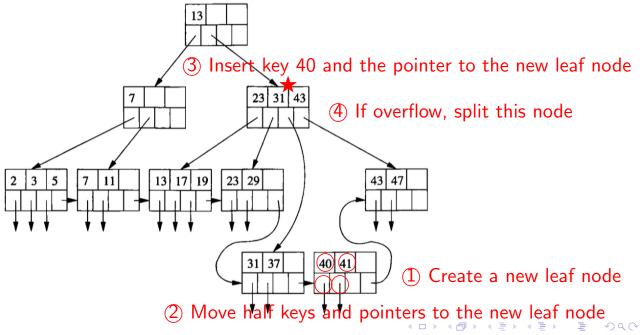
Insert a record with search key 40



## Insertion into B+ Trees with Splitting (Cont'd)

#### Example (Insertion with Splitting, Step 2)

Insert a record with search key 40



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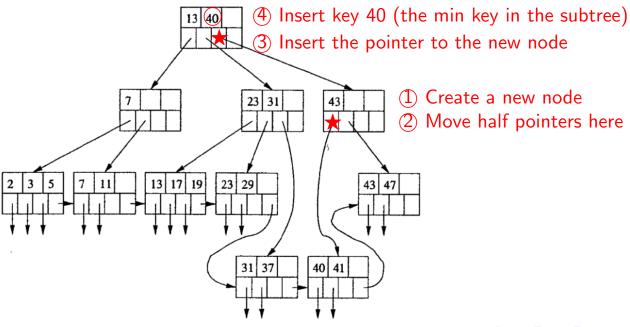
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## Insertion into B+ Trees with Splitting (Cont'd)

#### Example (Insertion with Splitting, Step 3)

Insert a record with search key 40



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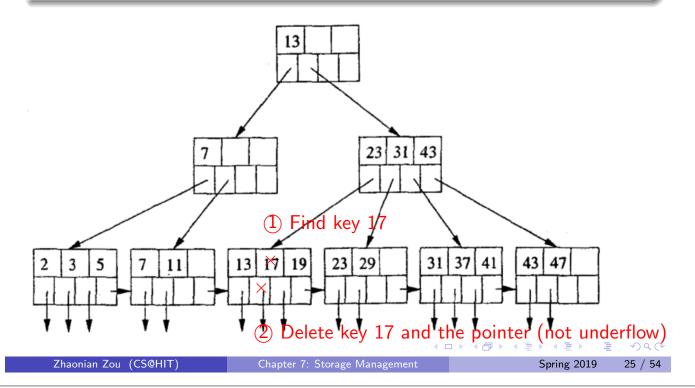
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## Deleting Non-minimum Key in Leaf Node

Example (Deleting Non-minimum Key in Leaf Node)

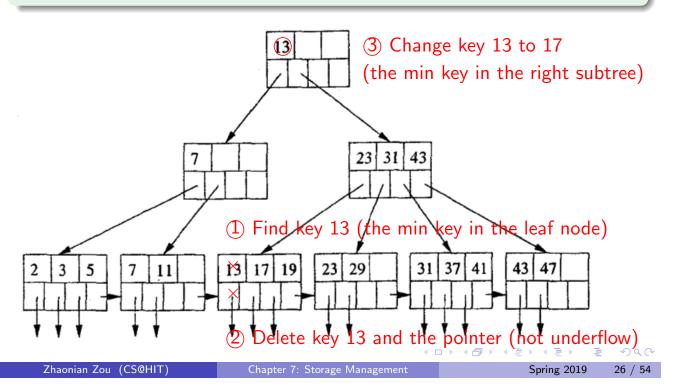
Delete a record with search key 17



## Deleting the Minimum Key in Leaf Node

Example (Deleting the Minimum Key in Leaf Node)

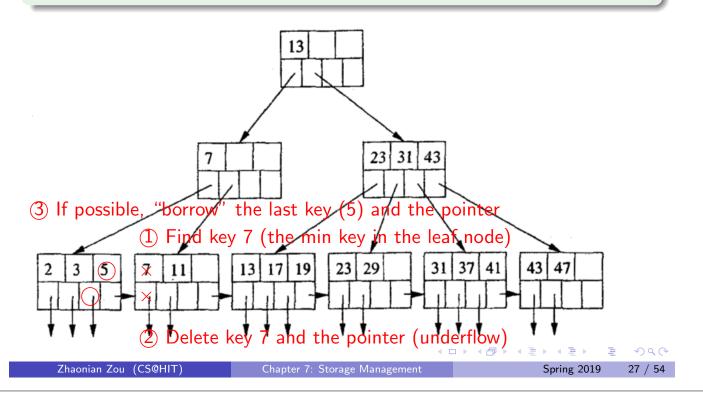
Delete a record with search key 13



## Deletion from B+ Trees with Merge

#### Example (Deletion with Merge)

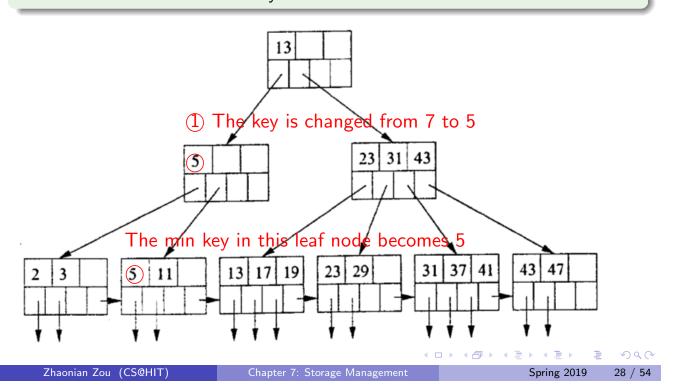
Delete a record with search key 7



## Deletion from B+ Trees with Merge (Cont'd)

#### Example (Deletion with Merge (Cont'd))

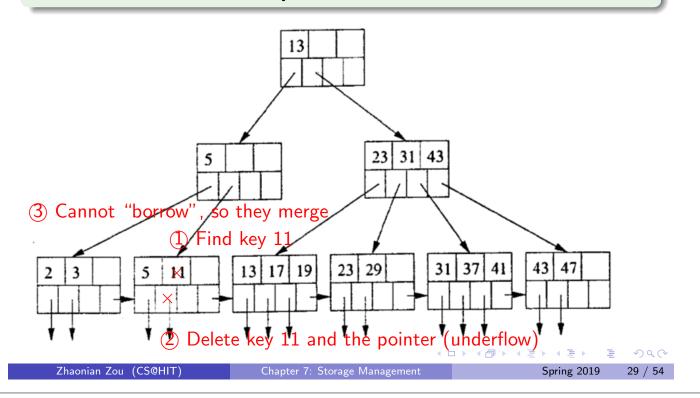
Delete a record with search key 7



## Deletion from B+ Trees with Merge (Cont'd)

#### Example (Deletion with Merge)

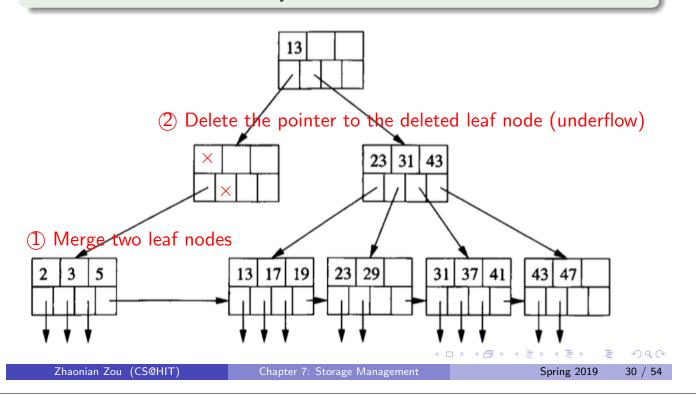
Delete a record with search key 11



## Deletion from B+ Trees with Merge (Cont'd)

#### Example (Deletion with Merge (Cont'd))

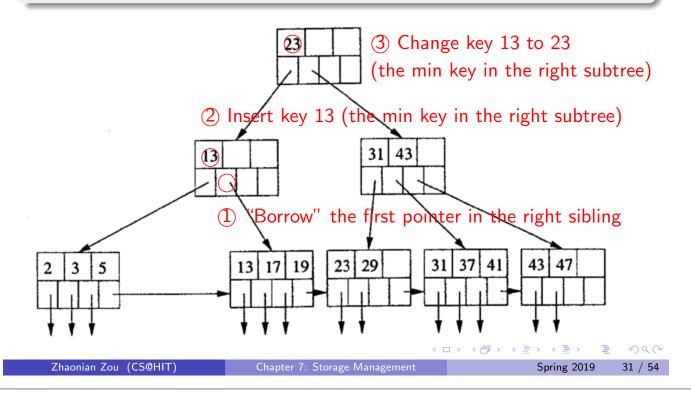
Delete a record with search key 11



## Deletion from B+ Trees with Merge (Cont'd)

#### Example (Deletion with Merge (Cont'd))

Delete a record with search key 11



# Key Compression in B+ Trees

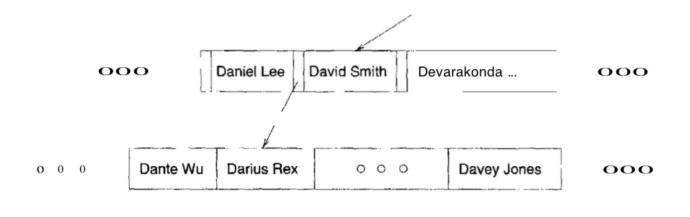
#### Why Compressing Search Key Values?

- The number of disk I/Os to retrieve a data entry in a B+ tree = the height of the tree  $\approx \log_{fan\_out}(\# \text{ of data entries})$
- The fan-out (扇出) of the tree is the number of index entries fit on a page, which is determined by the size of index entries
- The size of an index entry depends primarily on the size of the search key value
- Search key values are very long  $\Longrightarrow$  the fan-out is low  $\Longrightarrow$  the tree is high  $\Longrightarrow$  the query time is long

## Key Compression in B+ Trees (Cont'd)

#### Basic Idea

- Search key values in index entries are used only to direct traffic to the appropriate leaf
- We need not store search key values in their entirety in index entries



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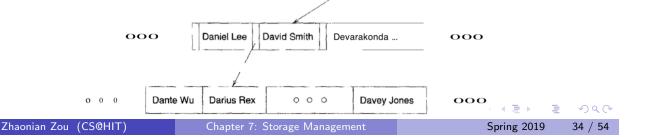
# Prefix Key Compression (前缀压缩)

- The prefix key compression technique is supported in many commercial implementations of B+ trees
- 前缀压缩≠前缀索引(第6章)

#### Example (Prefix Key Compression)

The search key value "David Smith" is compressed into "Davi"

- "Davi" is larger than the largest key value, "Davey Jones", in the subtree to the left of "David Smith"
- "Davi" is smaller than the smallest key value in the subtree to the right of "David Smith"
- "Davi" is the shortest among such prefix of "David Smith"



### Bulk-Loading a B+ Tree

#### Definition (Bulk-loading (批量加载))

Creating a B+ tree on an existing collection of data records

#### Top-Down Approach

- Method: Insert records one at a time
- Limitation: This approach is likely to be quite expensive because each entry requires to start from the root and go down to the appropriate leaf page

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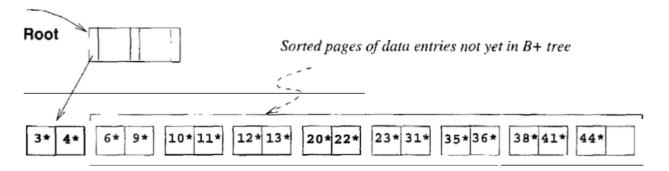
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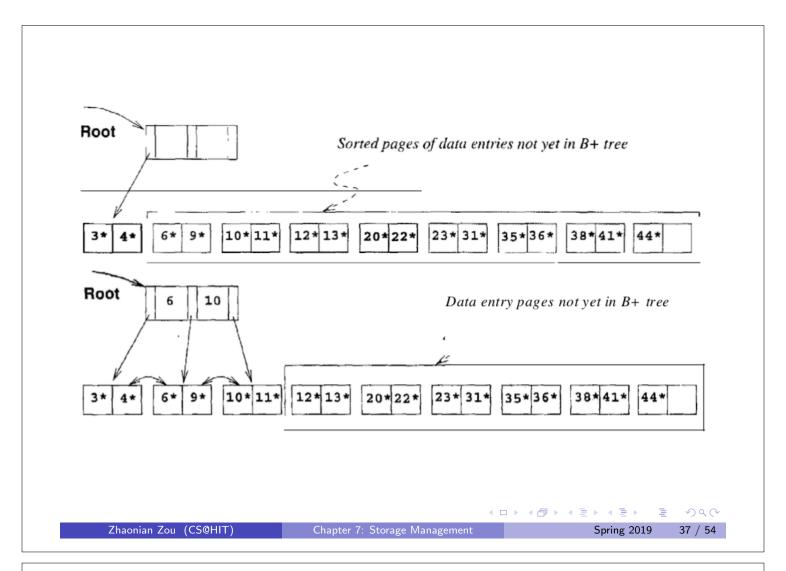
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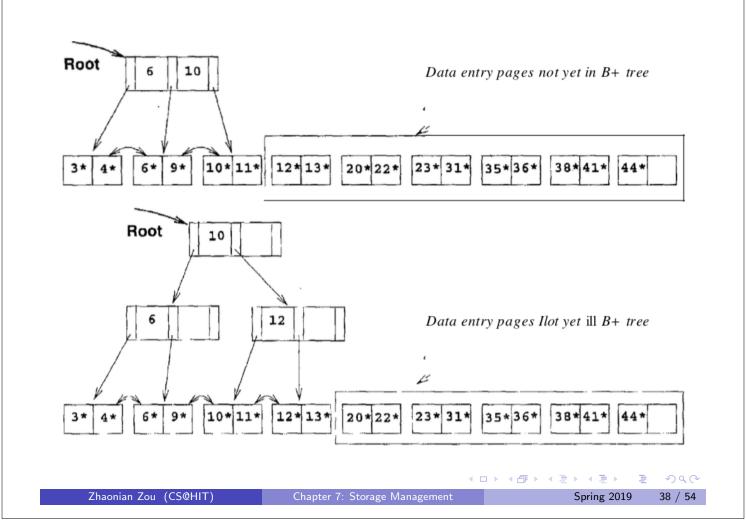
## Bulk-Loading a B+ Tree (Cont'd)

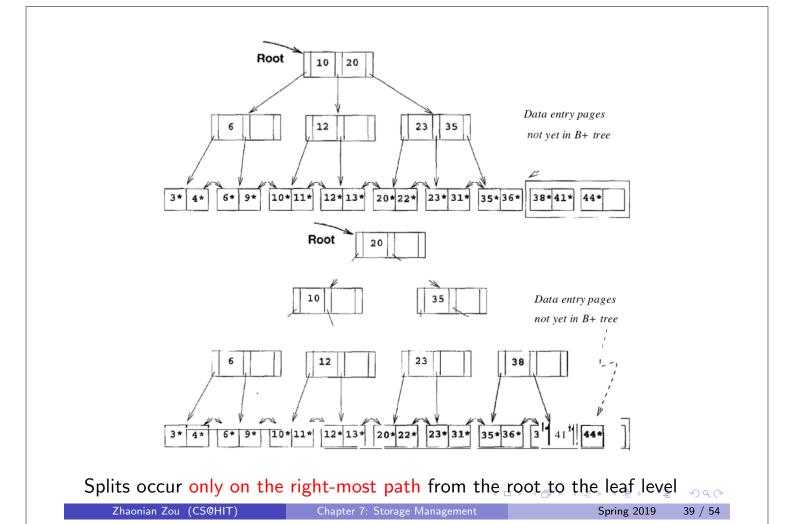
#### Bottom-Up Approach

- Sort the entries to be inserted into the B+ tree according to the search key
- 2 Allocate an empty page to serve as the root and insert a pointer to the first page of sorted entries into it
- 3 Entries for the leaf pages are always inserted into the right-most index page just above the leaf level. When that page fills up, it is split





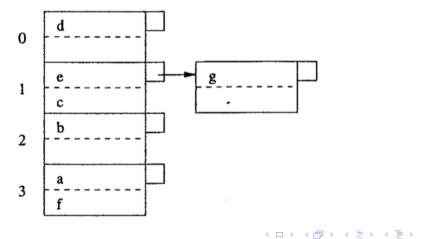




7.7 Hash-based Index Structures

## Secondary-Storage Hash Tables

- The bucket array consists of blocks, rather than pointers to the headers of lists
- A record with search key K is put in the block for the bucket numbered h(K), where h is the hash function
- If a bucket overflows, then a chain of overflow blocks can be added to the bucket to hold more records
- Operations: lookup (查找), insertion (插入), deletion (删除)



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## Types of Secondary-Storage Hash Tables

- Static Hash Tables (静态哈希表): the number of buckets never changes
- Dynamic Hash Tables (动态哈希表): the number of buckets is allowed to vary so that there is about one block per bucket
  - ▶ Extensible hash tables (可扩展哈希表)
  - ► Linear hash tables (线性哈希表)

# 7.7 Hash-based Index Structures Extensible Hash Tables

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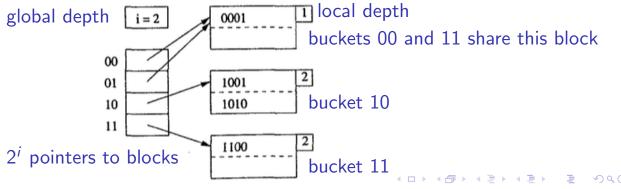
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# Extensible Hash Tables (可扩展哈希表)

- For each key K, h(K) consists of k bits
- A record with search key K is placed in the bucket numbered by the first i bits of h(K) (i is called the global depth)
- Certain buckets can share a block if the total number of records in those buckets can fit in the block
- There is an array of  $2^i$  pointers to blocks
- The number j (local depth) appearing in the nub of each block indicates how many bits of h(K) is used to determine membership of records in this block. We must have local depth  $j \leq \text{global depth } i$



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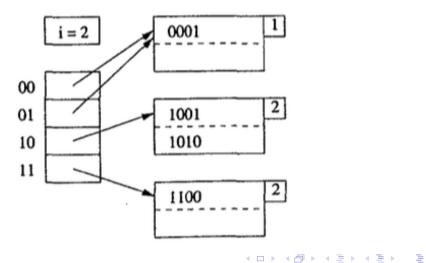
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#### Lookup in Extensible Hash Tables

#### Example (Lookup)

Find a record whose key hashes to 1010

- The global depth is 2. The record could be found in the bucket numbered 10.
- 2 Find the record in the block of bucket 10



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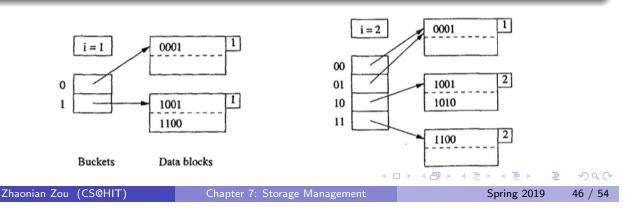
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#### Insertion into Extensible Hash Tables

#### Example (Insertion)

Insert a record whose key hashes to 1010

- 1. The global depth is currently 1. The record should be inserted into bucket 1.
- ② After insertion, bucket 1 will overflow, so the global depth is increased by 1 (the number of buckets is doubled)
- Oreate a new block for bucket 11 and set pointers to the blocks
- Redistribute the records in bucket 1 to buckets 10 and 11. Insert the record to bucket 10
- Increase the local depth of buckets 10 and 11 by 1

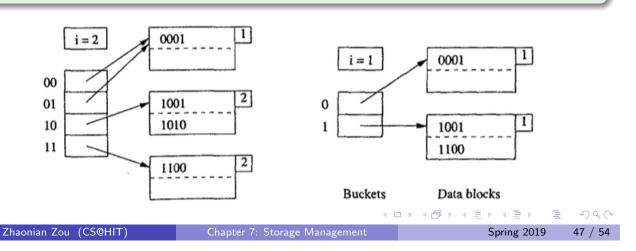


#### Deletion from Extensible Hash Tables

- The deleted data entry is located and removed
- If the deletion leaves the bucket empty, it can be merged with its split image, although this step is often omitted in practice
- We can halve the directory and reduce the global depth, although this step is not necessary for correctness

#### Example (Deletion)

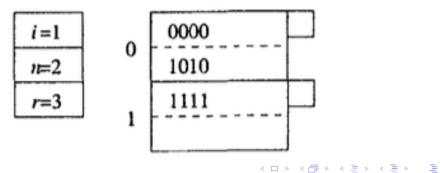
Delete a record whose key hashes to 1010



# 7.7 Hash-based Index Structures Linear Hash Tables

# Linear Hash Tables (线性哈希表)

- n: the current number of buckets
- r: the current number of records
- A record with search key K is placed in the bucket determined by the last i bits of h(K)
  - $\blacktriangleright$  m: the integer represented by the last i bits of h(K)
  - If m < n, the record is placed in bucket m
  - ▶ If  $n \le m < 2^i$ , the record is placed in bucket  $m 2^{i-1}$
- It is required that  $r/bn \le \theta$ , where b is the maximum number of records a block can contain, and  $0 < \theta < 1$  is a threshold (e.g.,  $\theta = 85\%$ )



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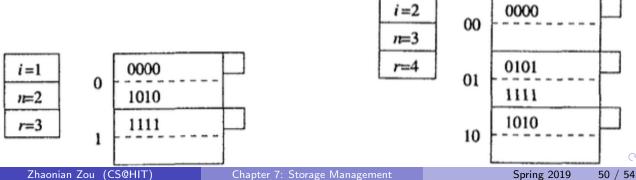
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#### Insertion into Linear Hash Tables

- $\bullet$  A record with search key K is placed in the bucket determined by the last i bits of h(K)
  - $\blacktriangleright$  m: the integer represented by the last i bits of h(K)
  - If m < n, the record is placed in bucket m
  - ▶ If  $n \le m < 2^i$ , the record is placed in bucket  $m 2^{i-1}$
- 2 If  $r/bn > \theta$ , we add a new bucket numbered n+1
- 3 If  $n+1 \ge 2^{i-1}$ , split the bucket numbered  $n+1-2^{i-1}$

#### Example (Insertion)

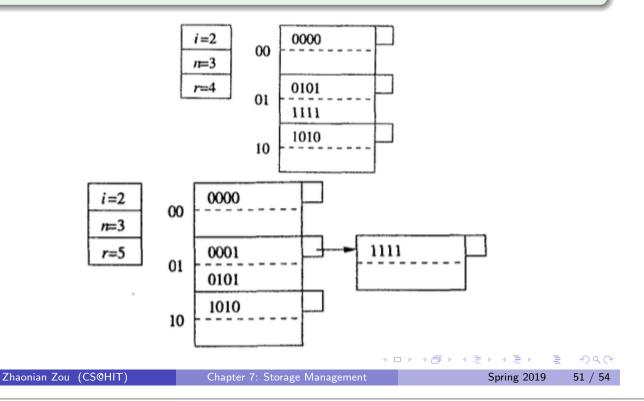
Insert a record whose key hashes to 0101 ( $\theta = 0.85$ )



## Insertion into Linear Hash Tables (Cont'd)

#### Example (Insertion)

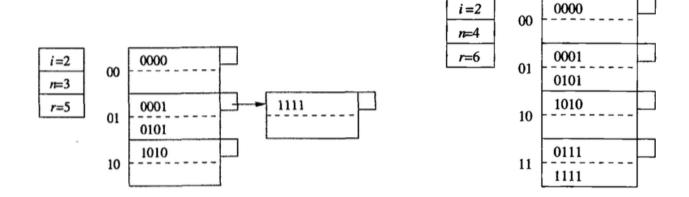
Insert a record whose key hashes to 0001 ( $\theta = 0.85$ )



## Insertion into Linear Hash Tables (Cont'd)

## Example (Insertion)

Insert a record whose key hashes to 0111 ( $\theta = 0.85$ )



## Deletion from Linear Hash Tables

Deletion is essentially the inverse of insertion

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## Summary

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