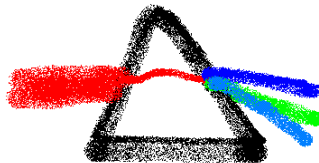


# Geometric Encoding

Forging the High Performance Context  
Sensitive Points-to Analysis for Java

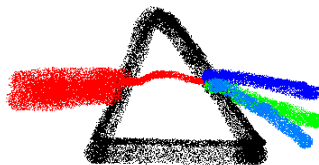
Xiao Xiao, Charles Zhang

The prism research group, HKUST

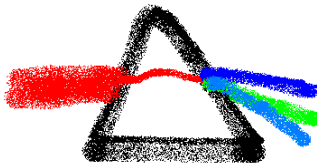
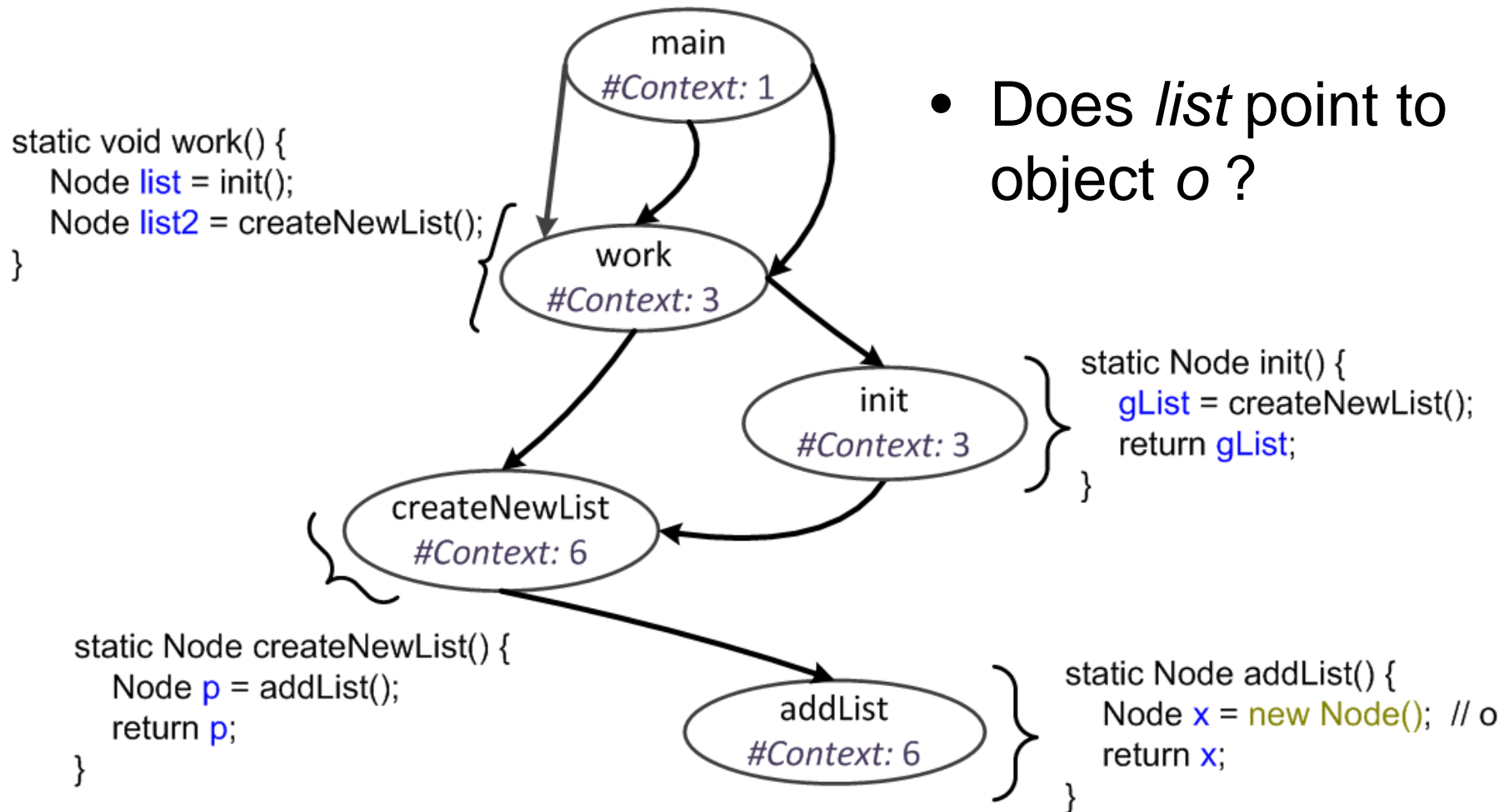


# Definition

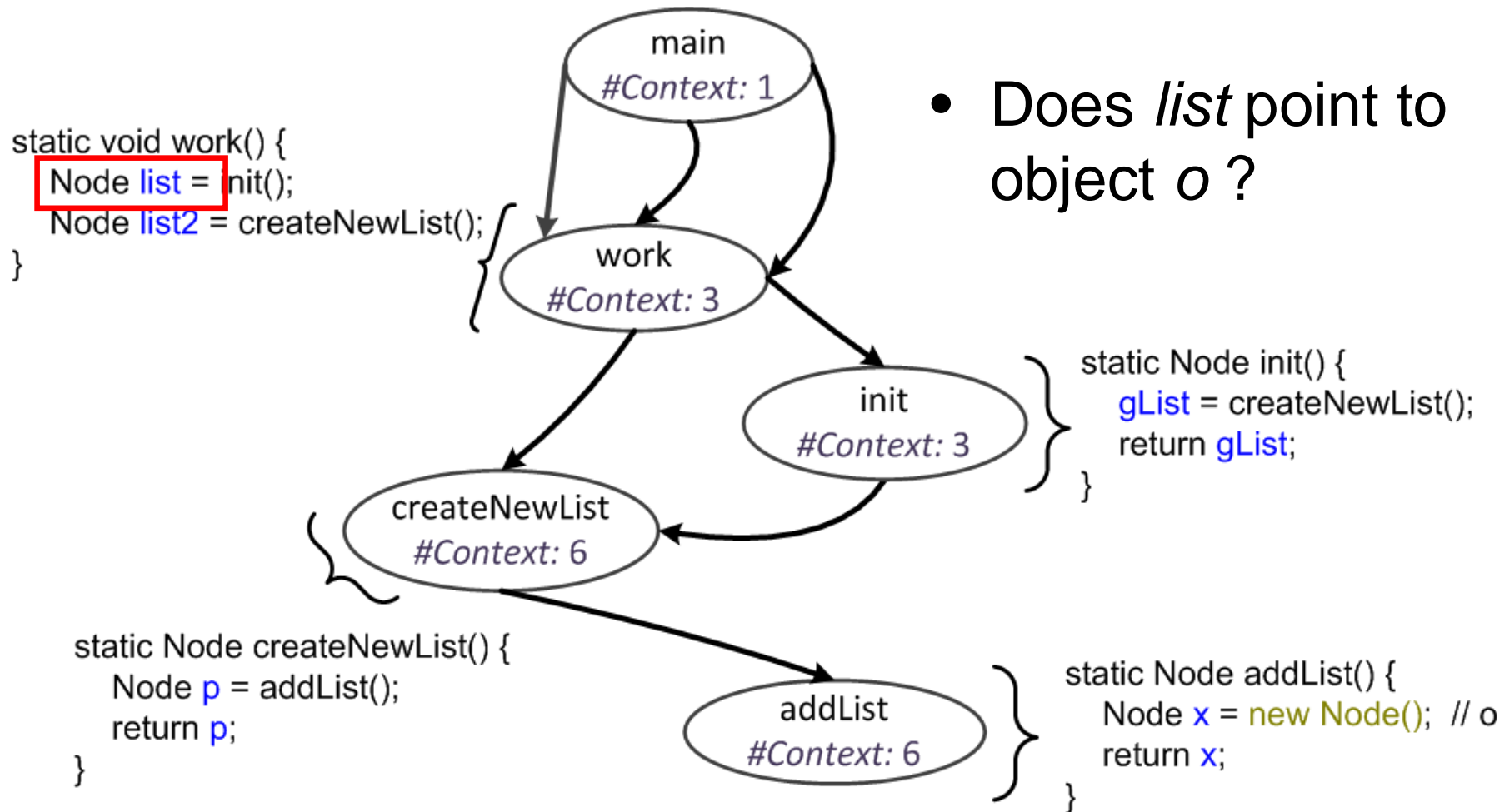
- Points-to analysis:
  - A process to determine the set of variables that are possibly pointed-to by every pointer.



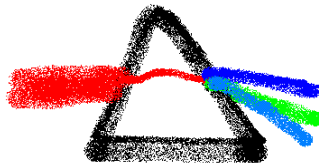
# Points-to Analysis



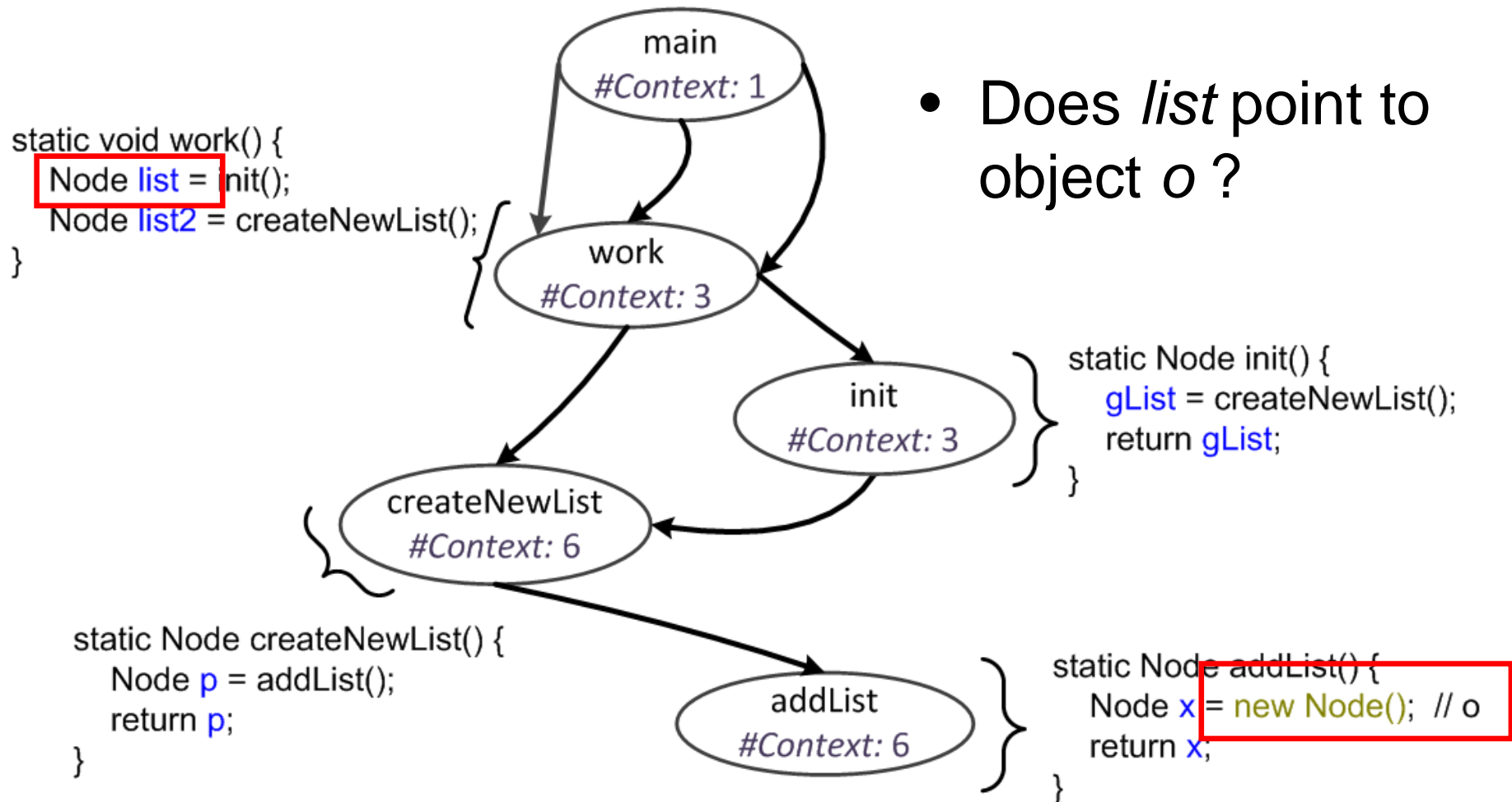
# Points-to Analysis



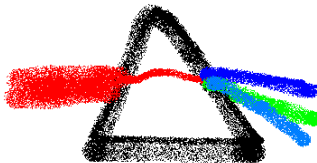
- Does *list* point to object o ?



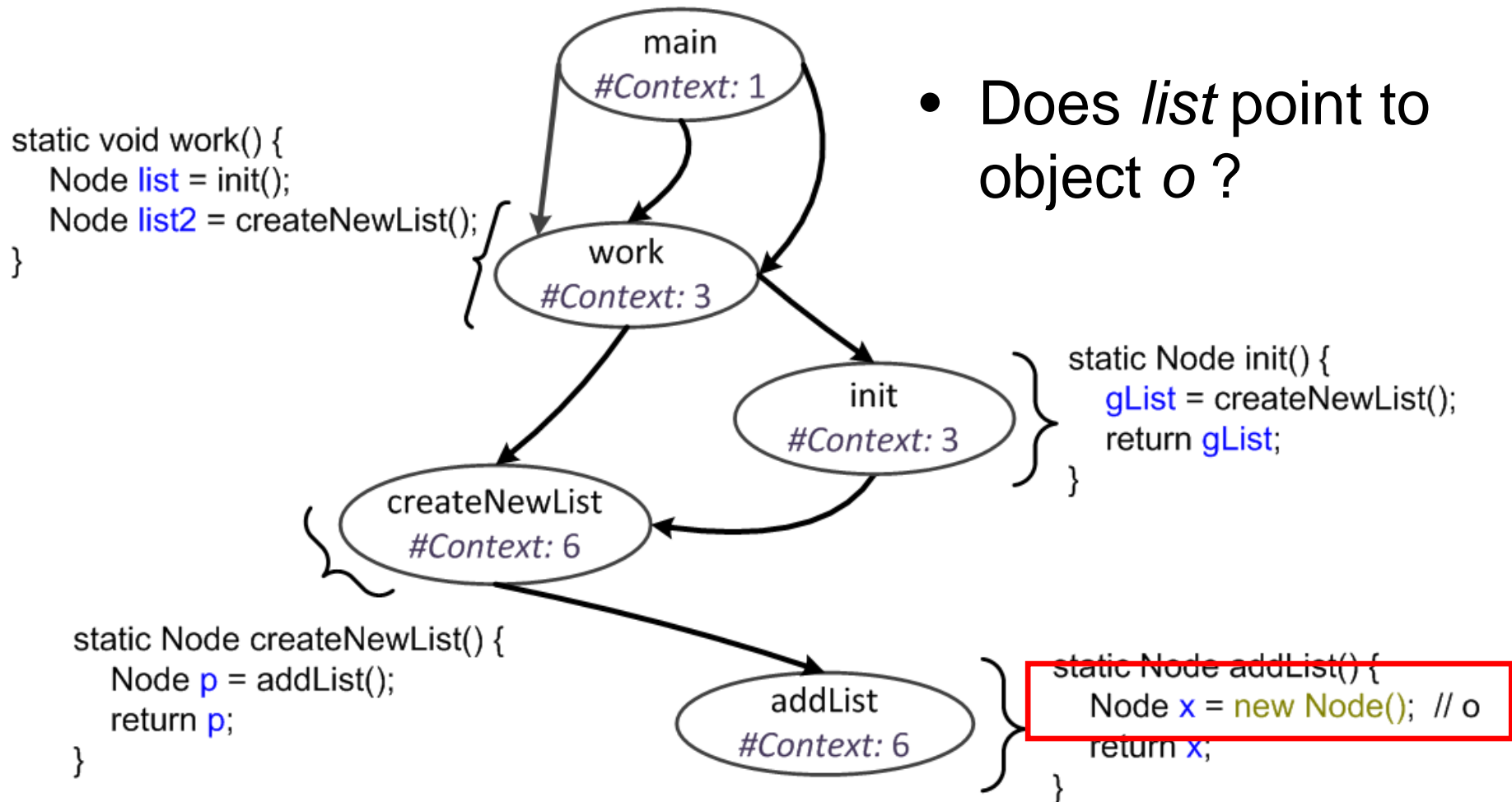
# Points-to Analysis



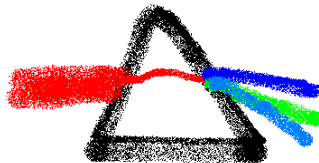
- Does *list* point to object *o* ?



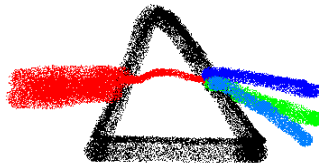
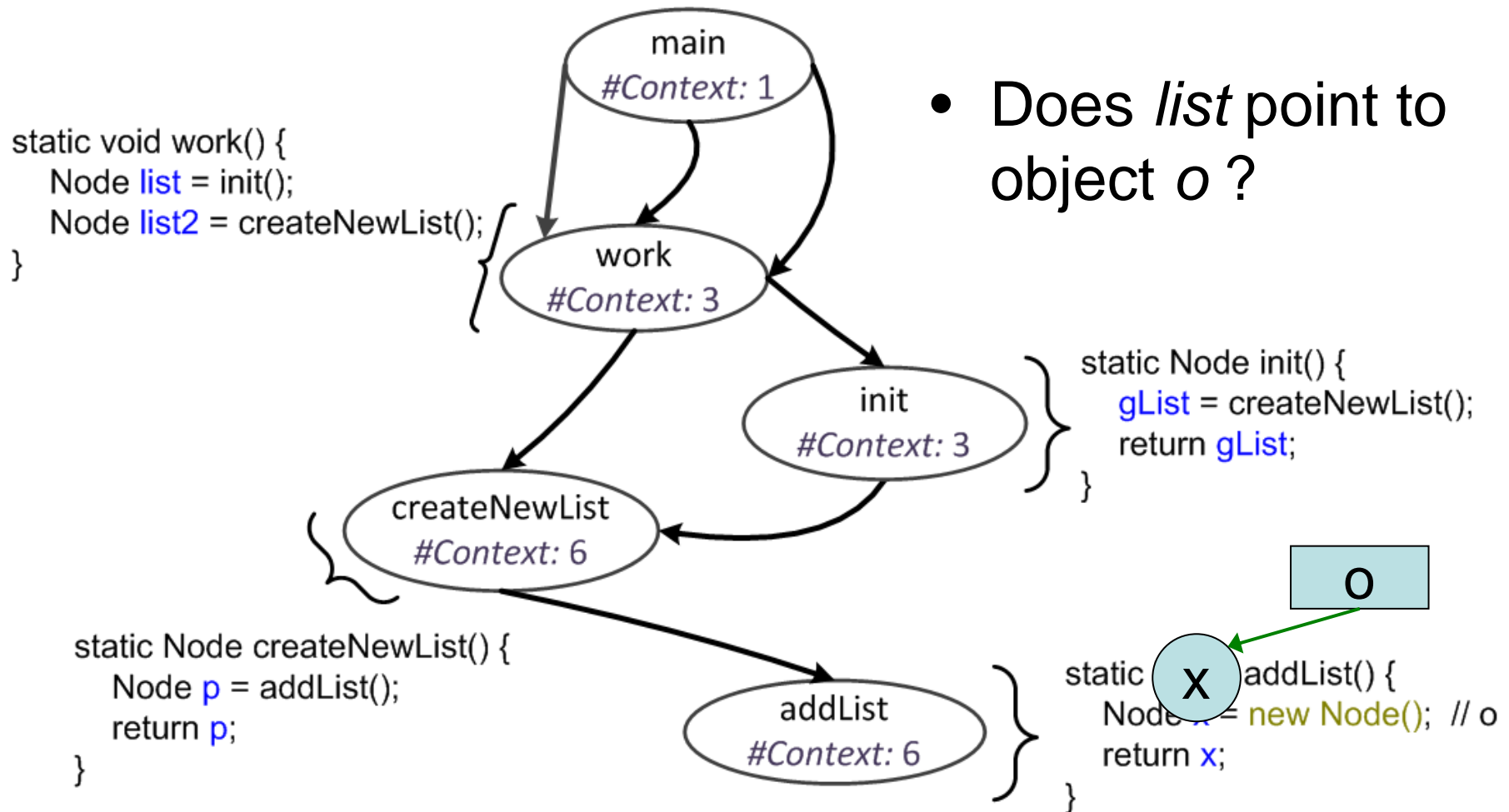
# Points-to Analysis



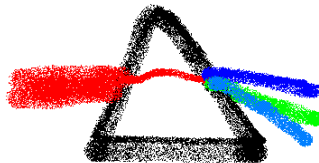
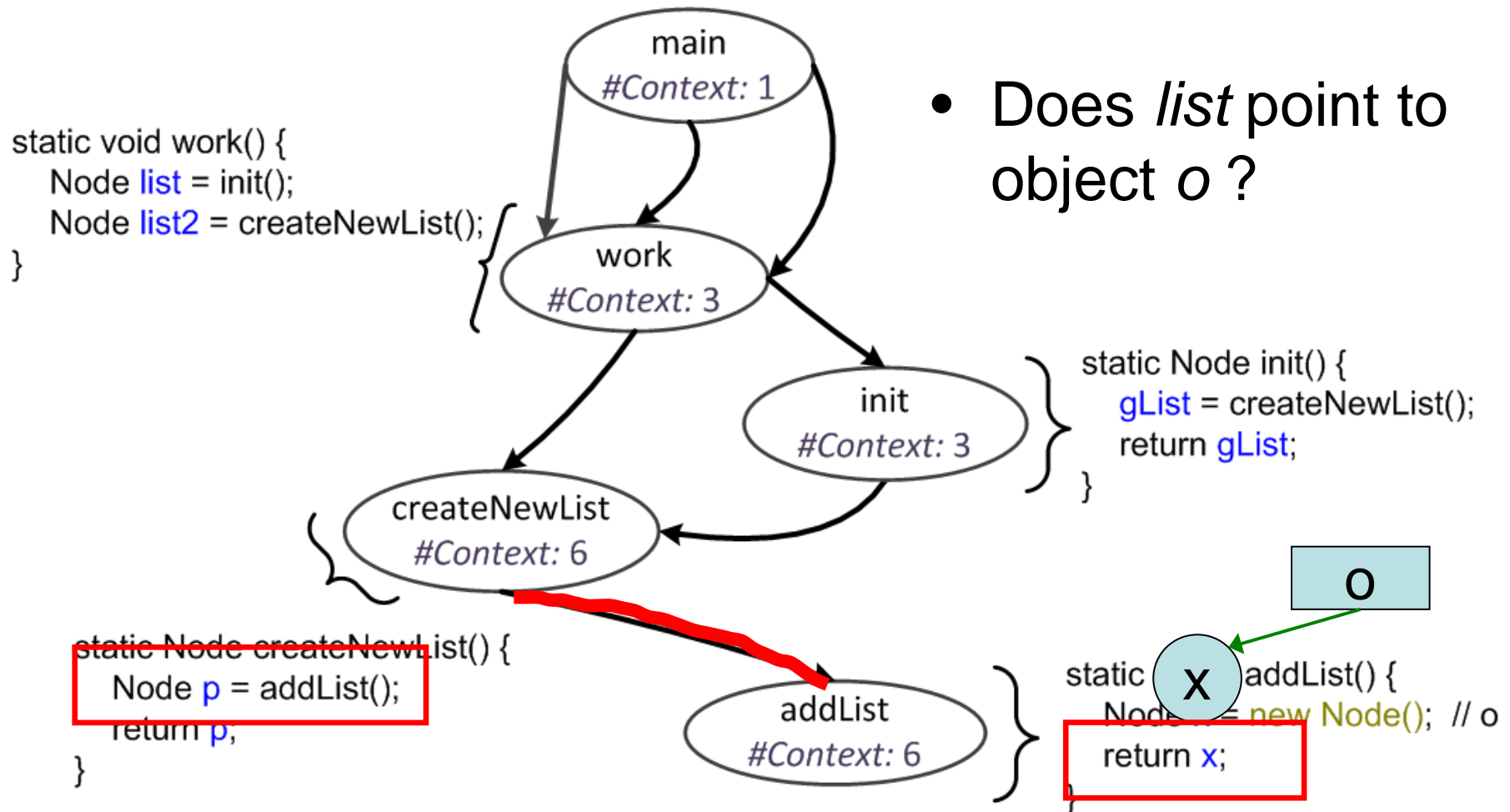
- Does *list* point to object *o* ?



# Points-to Analysis

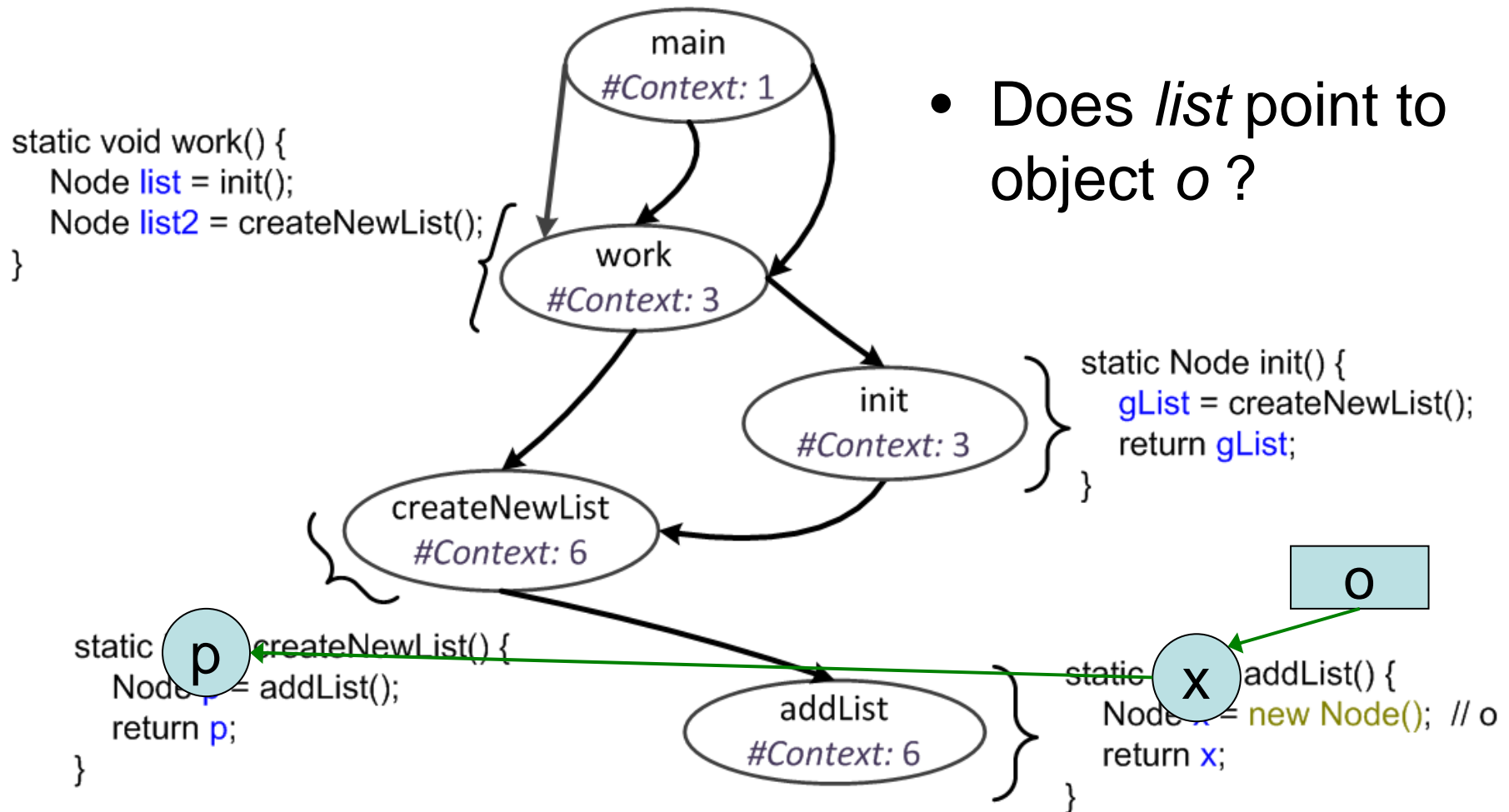


# Points-to Analysis

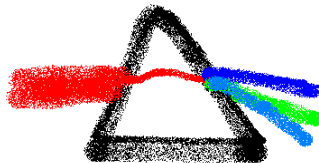




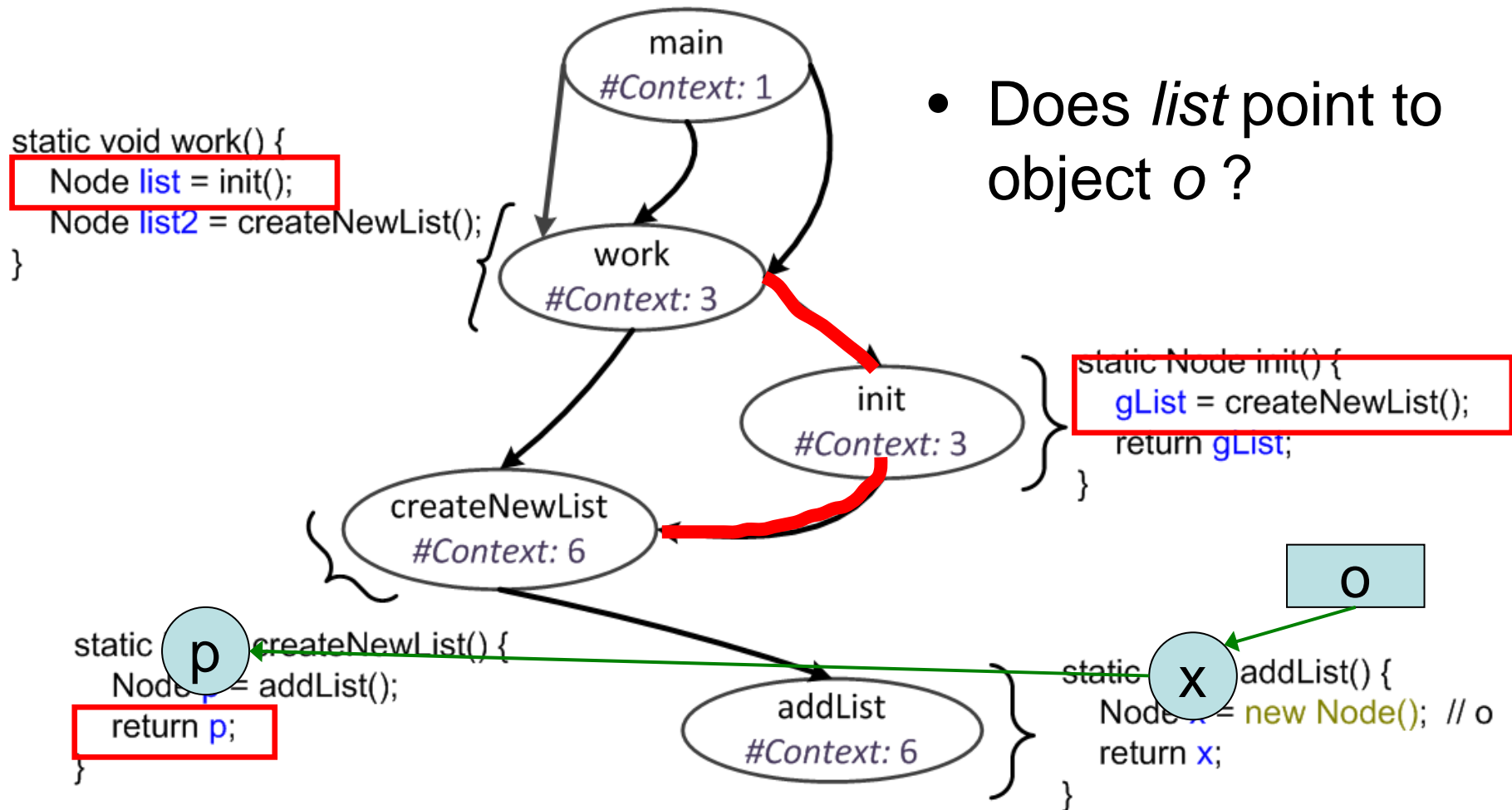
# Points-to Analysis



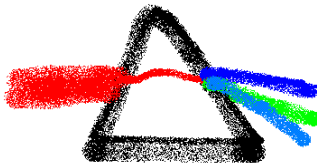
- Does *list* point to object *o* ?



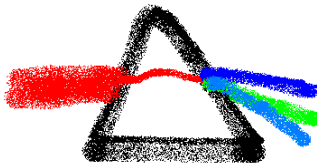
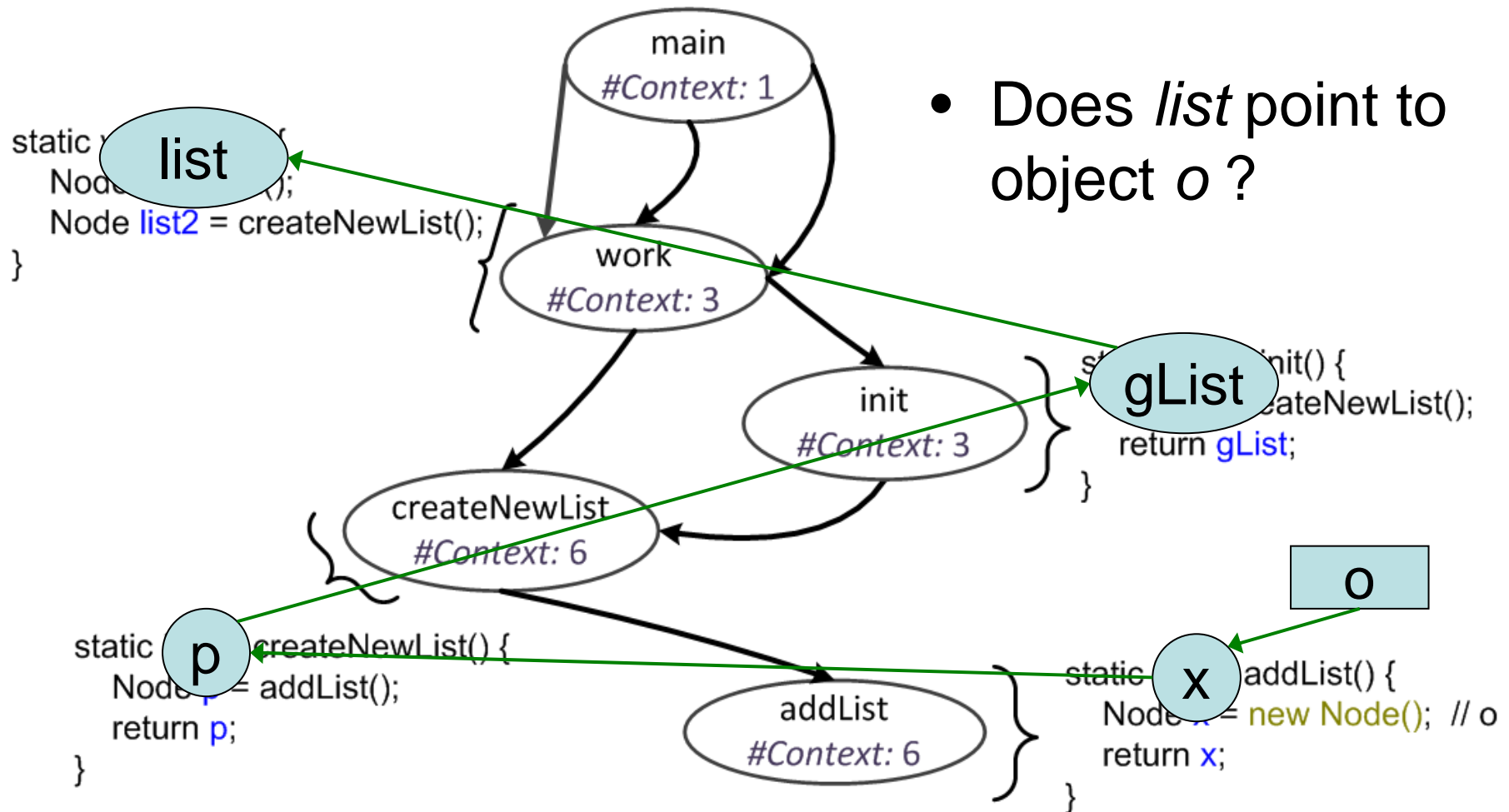
# Points-to Analysis



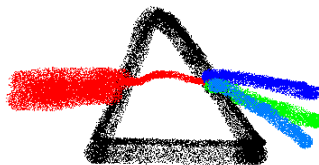
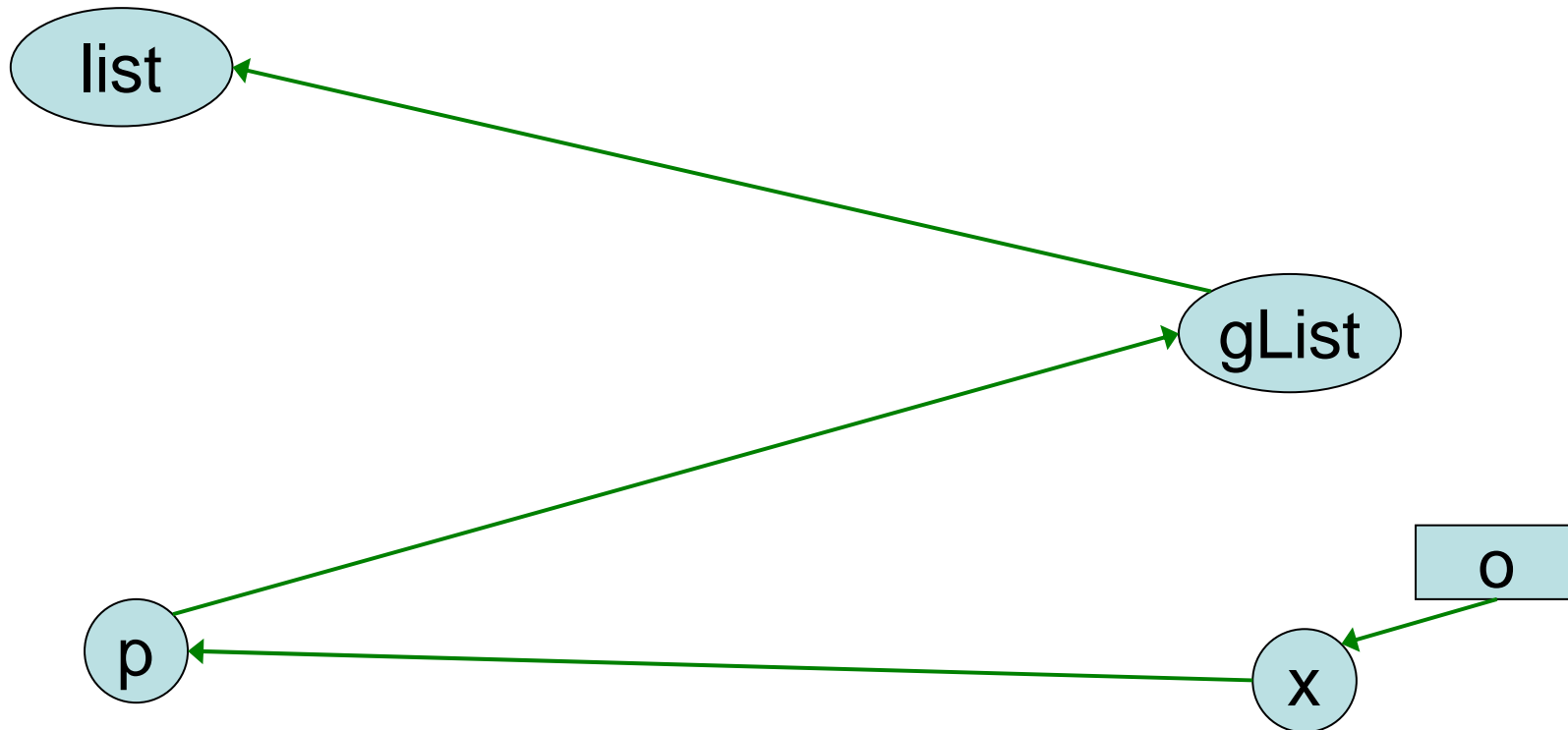
- Does *list* point to object *o* ?



# Points-to Analysis

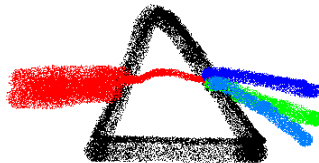
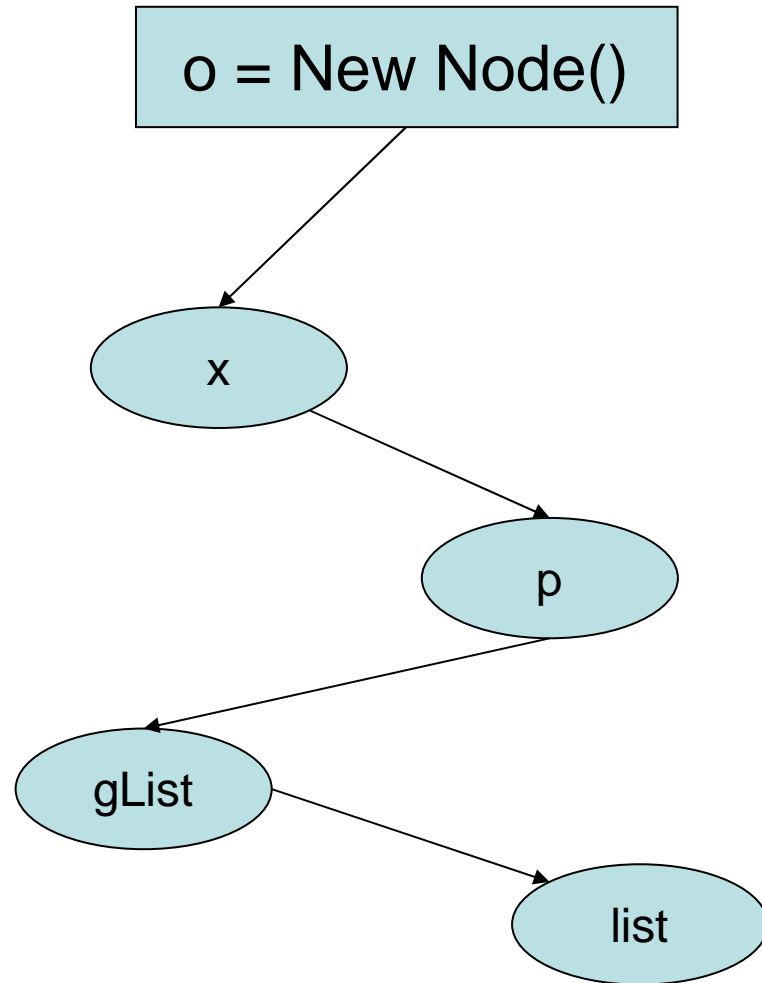


# Points-to Analysis



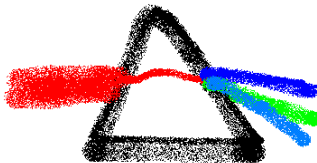
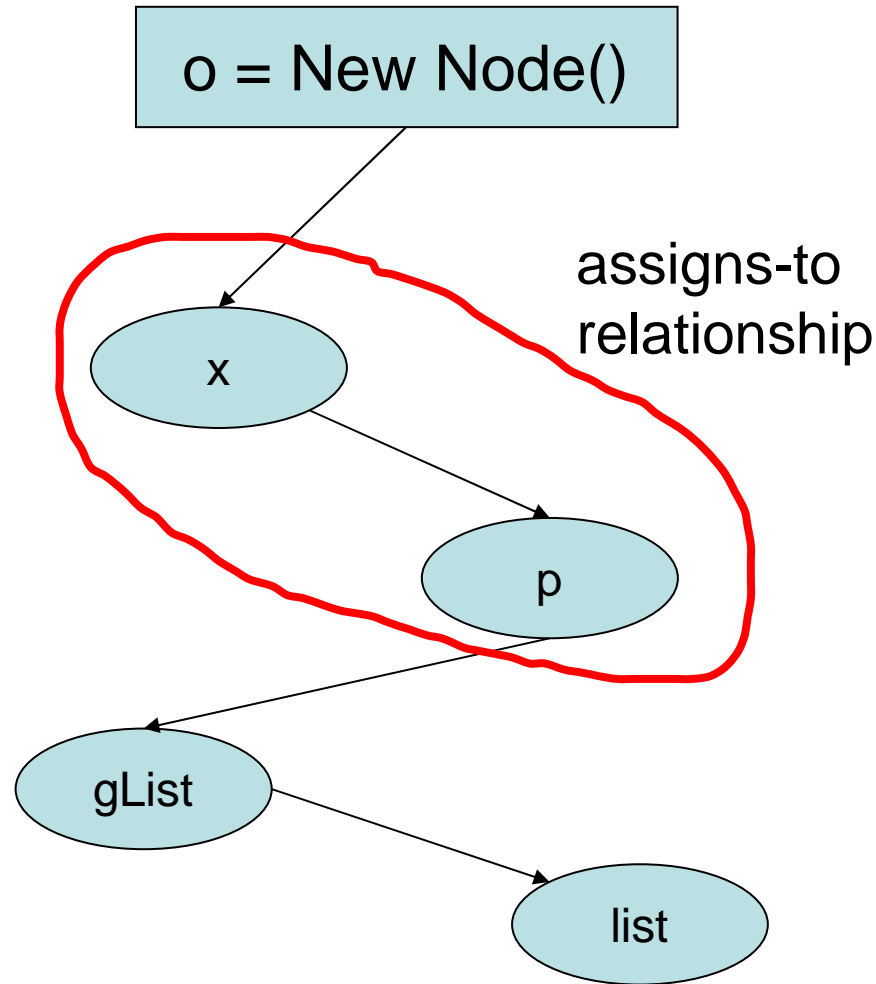
# Points-to Analysis

- Flow graph;

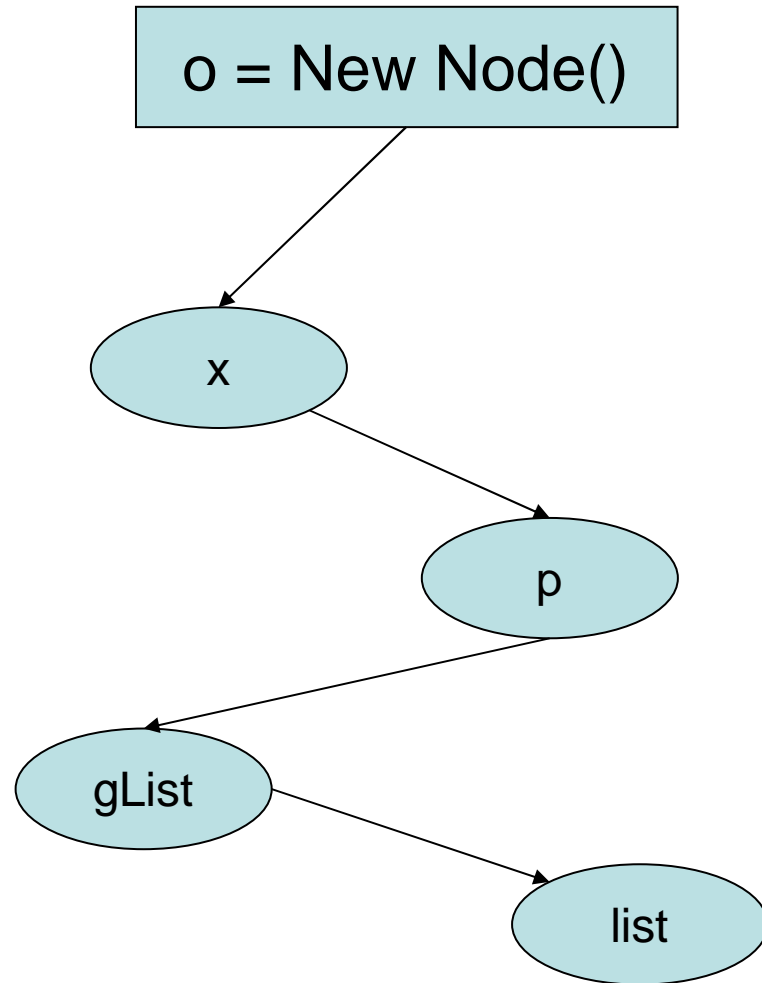


# Points-to Analysis

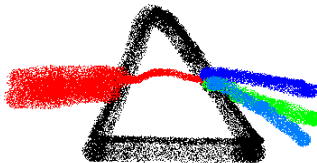
- Flow graph;



# Points-to Analysis

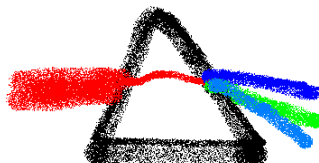


- Flow graph;
- Points-to relations can be obtained via the ***graph reachability analysis***;



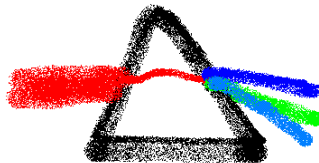
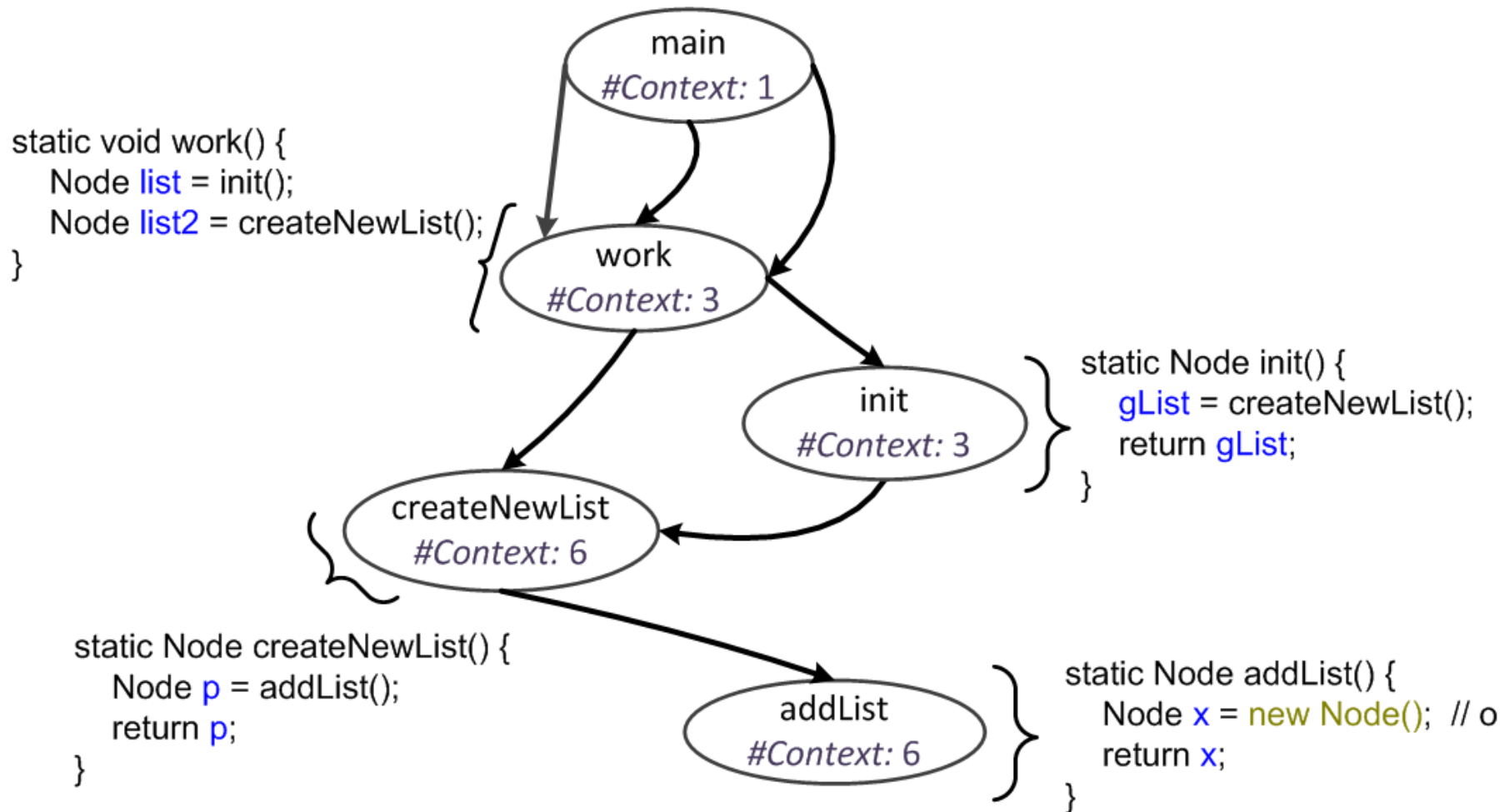
# Definition

- The previous demo is Anderson's analysis, which is *context insensitive*.
- It does not distinguish the runtime instances for the same syntactic variable.
- Cause any problem?

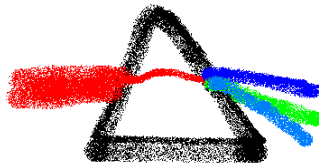
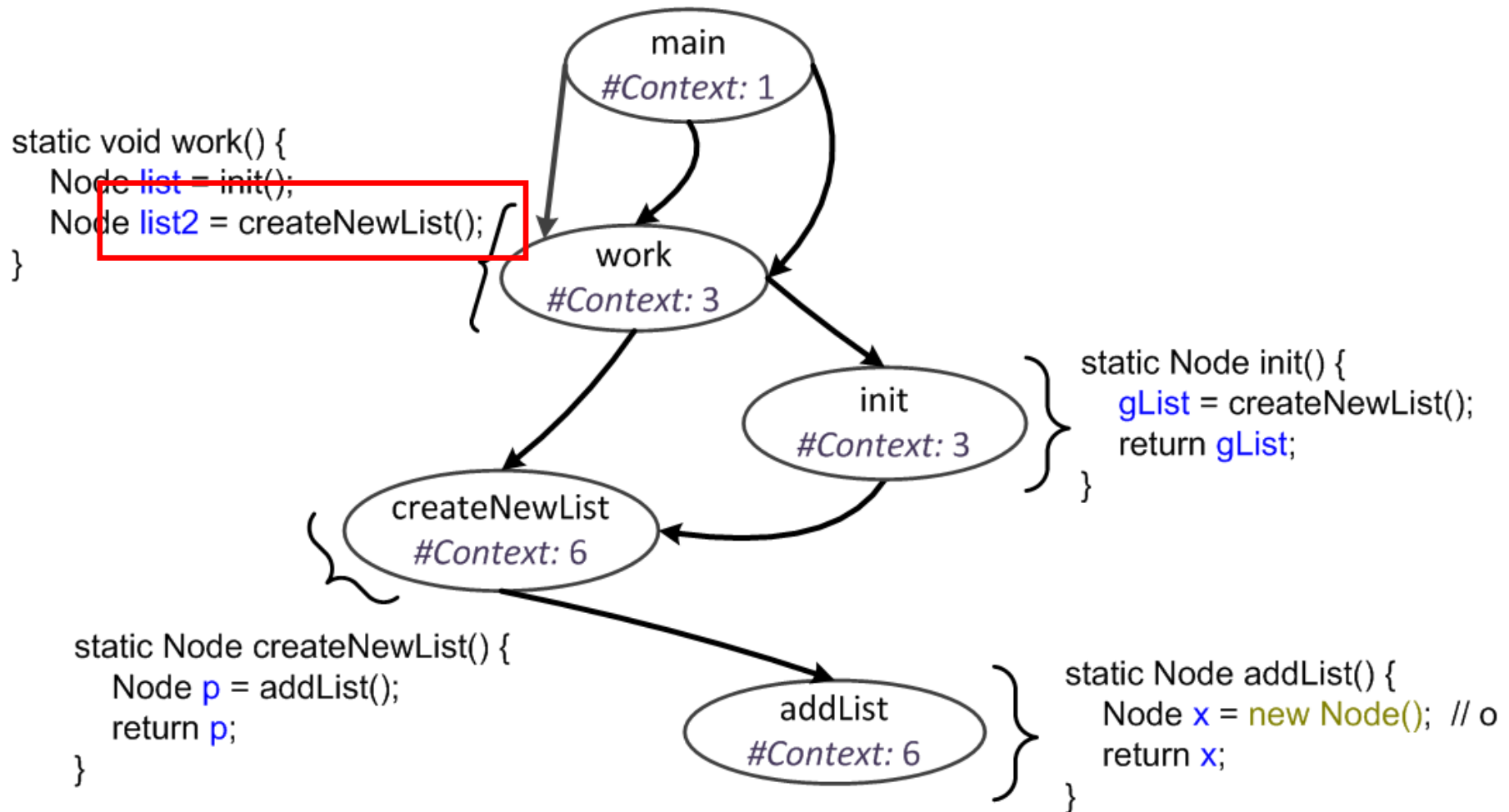




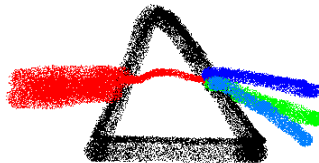
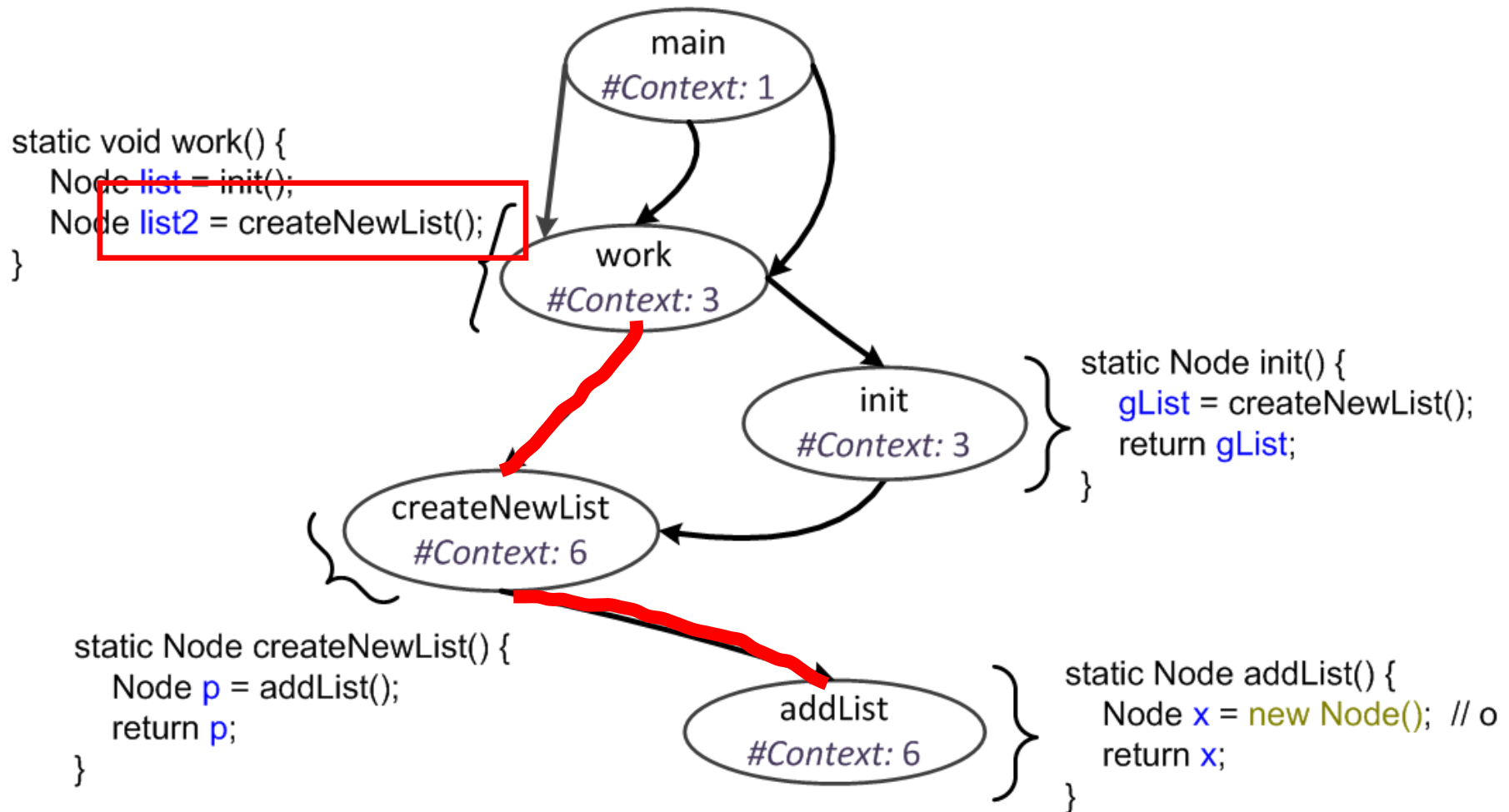
# Context Sensitivity



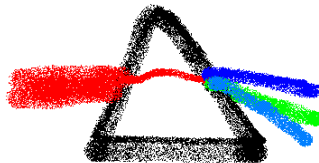
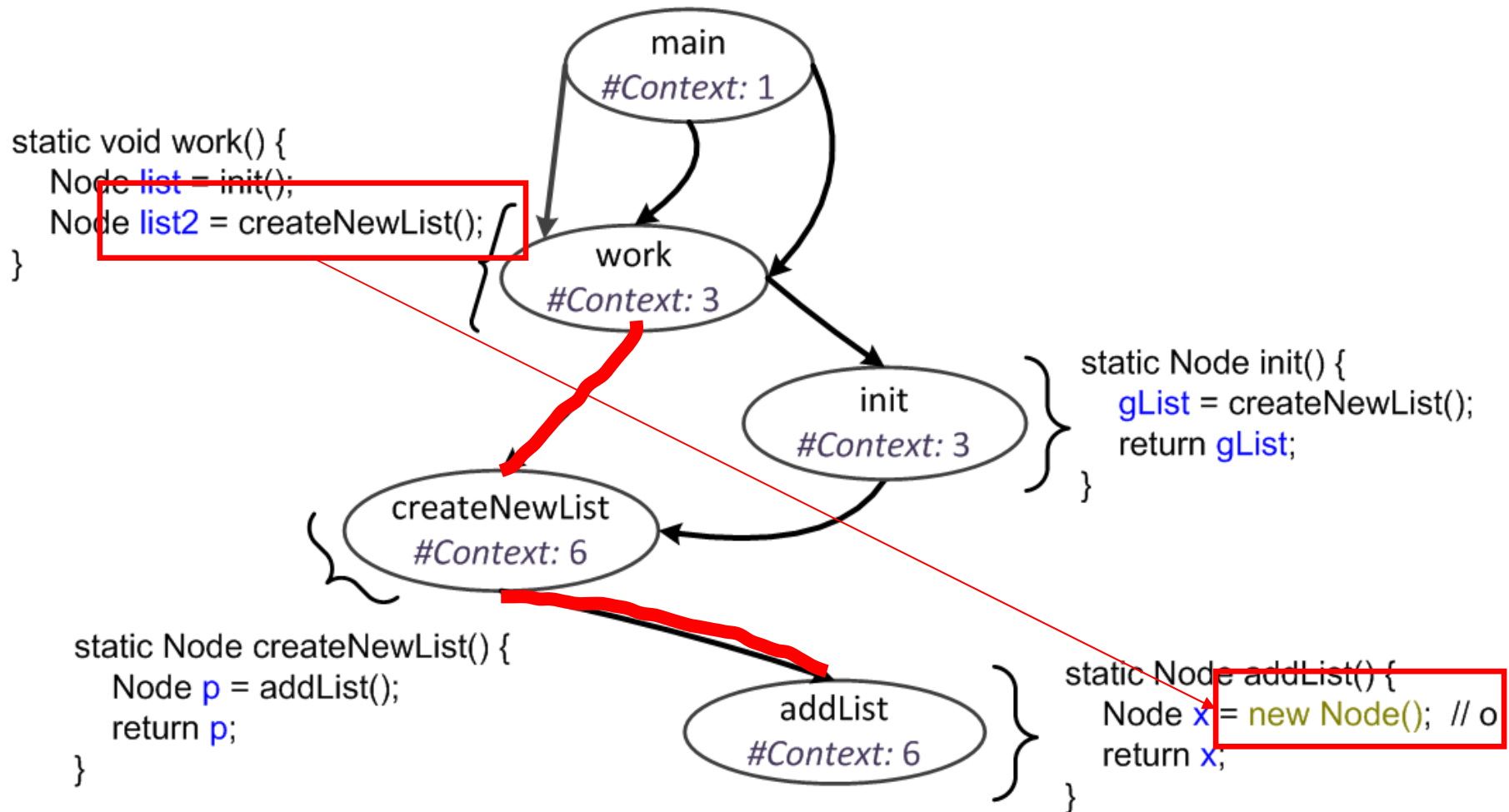
# Context Sensitivity



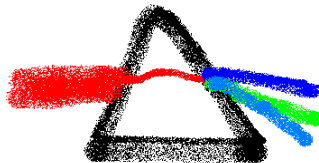
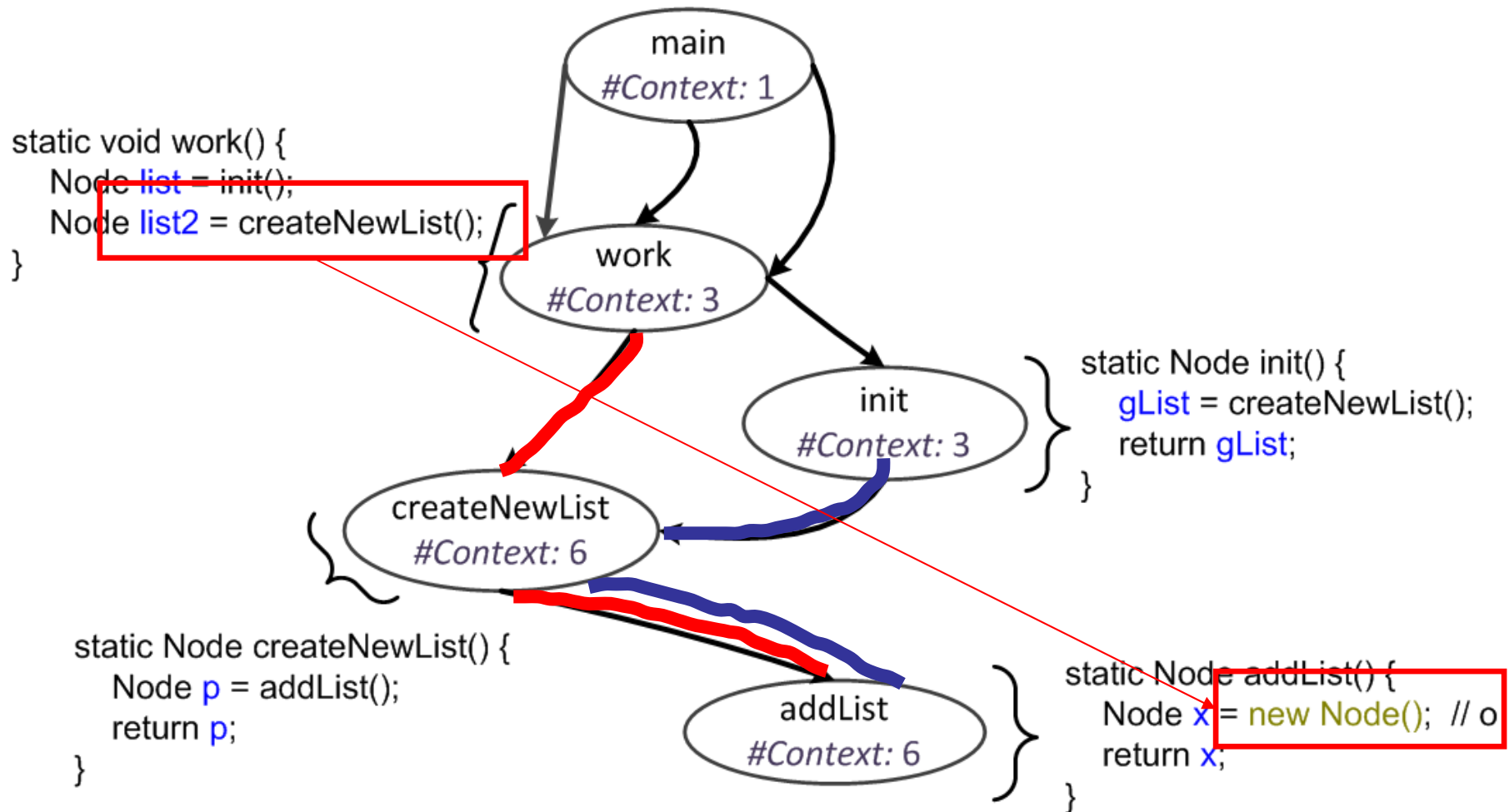
# Context Sensitivity



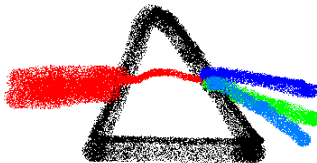
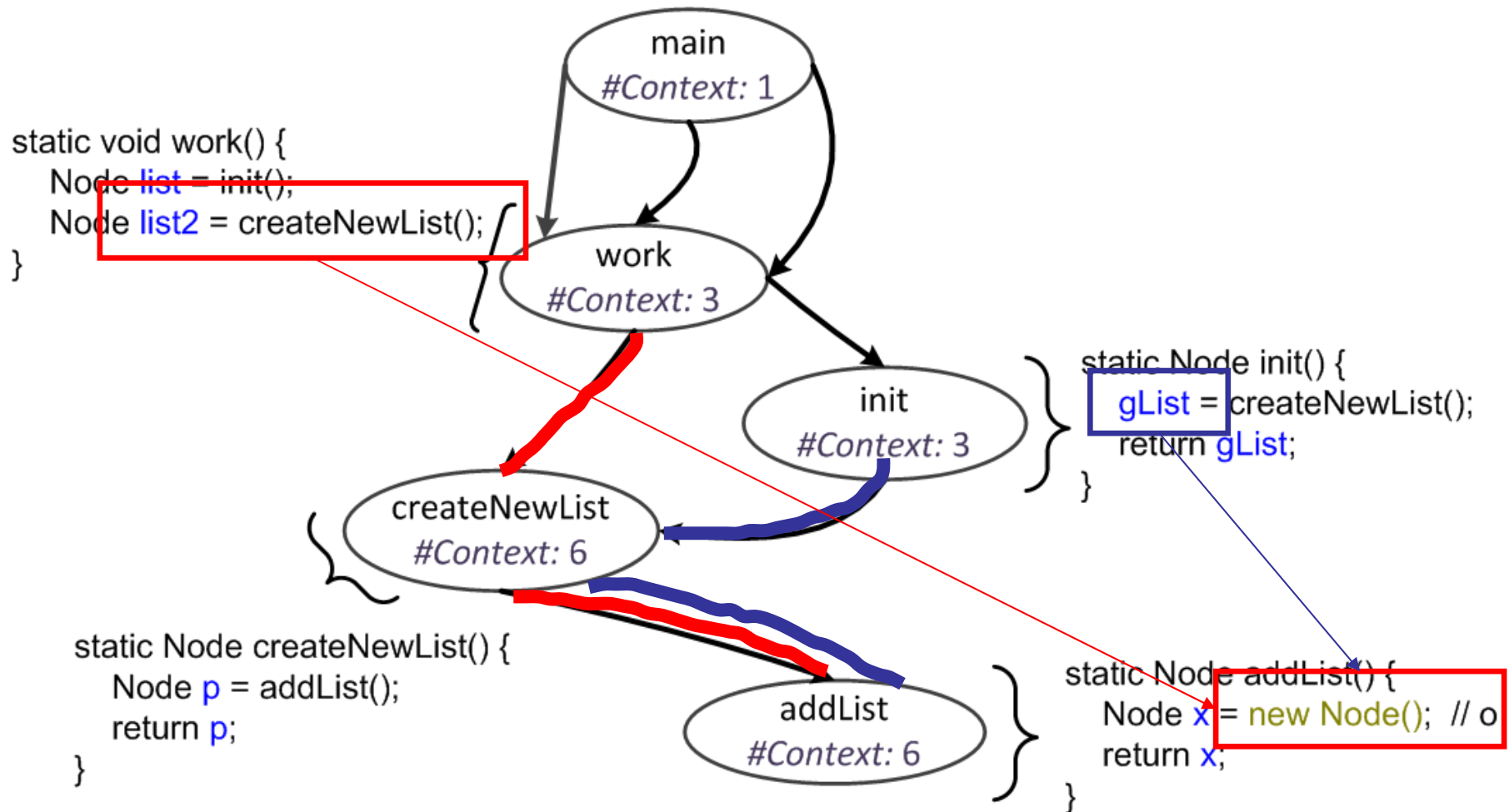
# Context Sensitivity



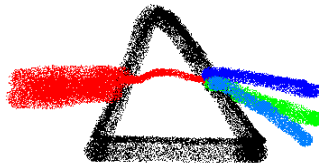
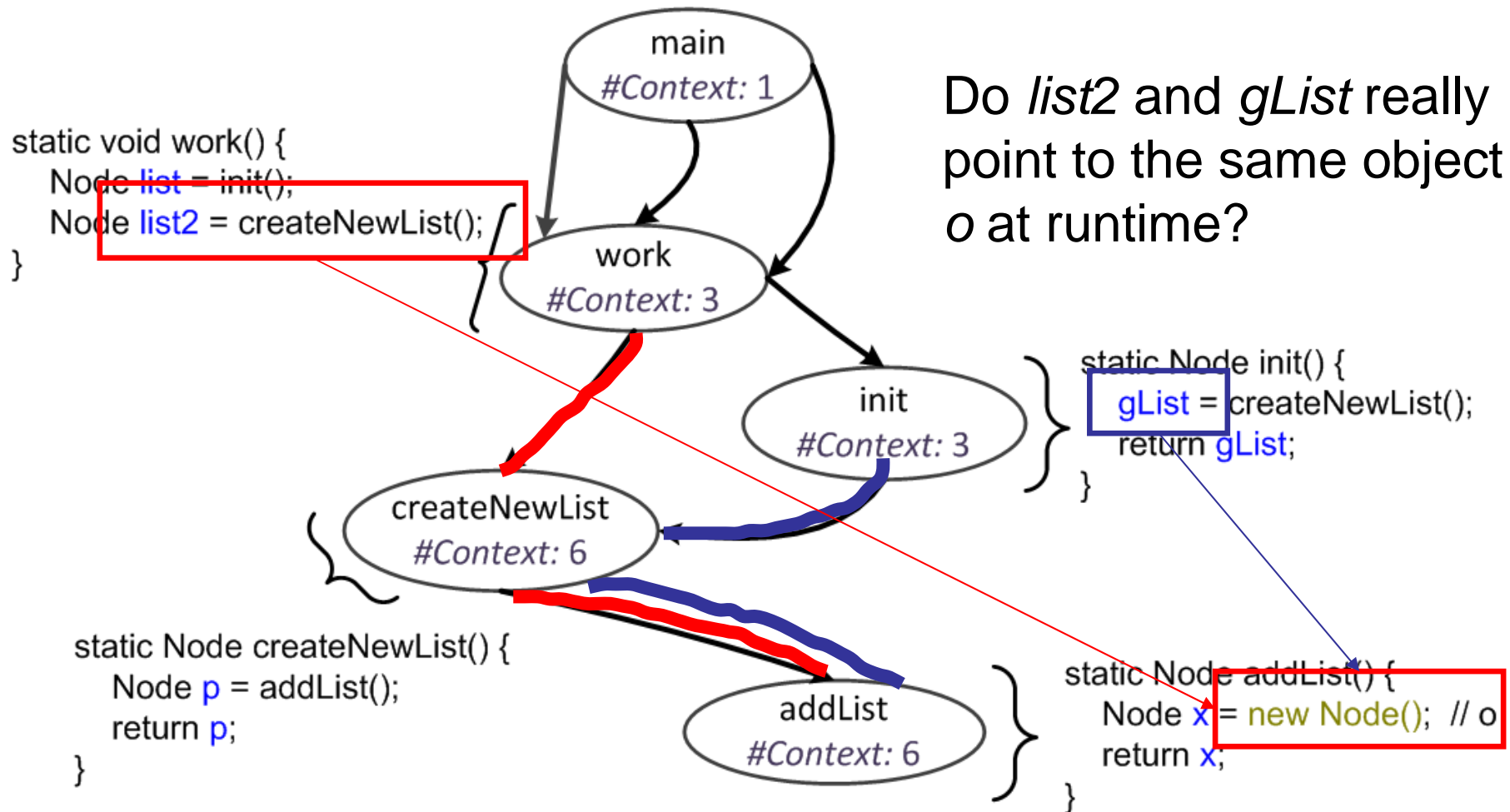
# Context Sensitivity



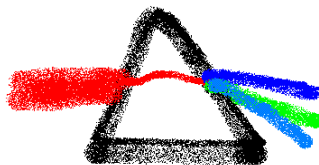
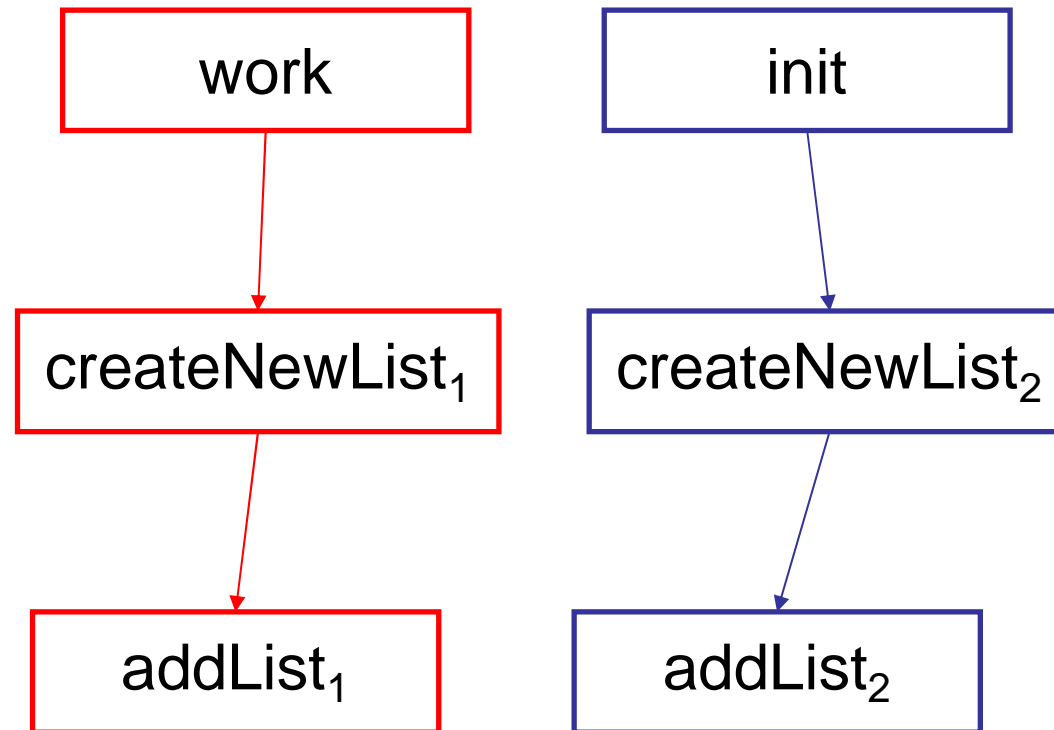
# Context Sensitivity



# Context Sensitivity

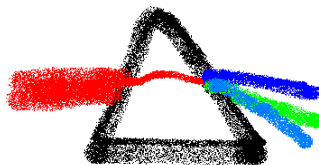
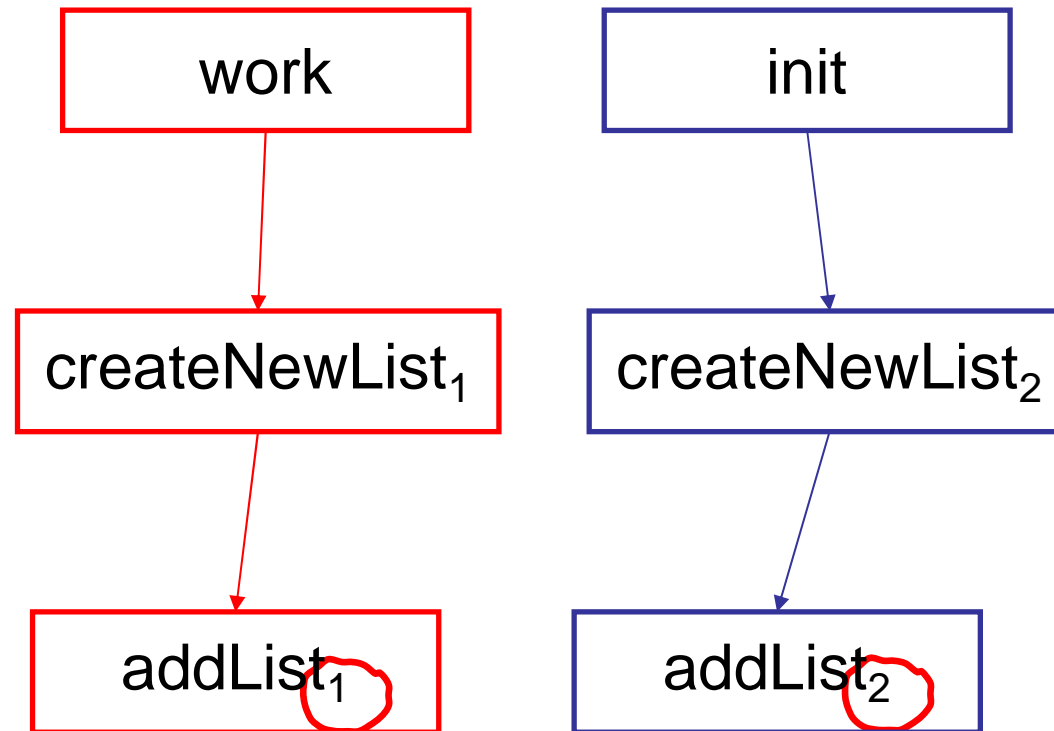


# Context Sensitivity



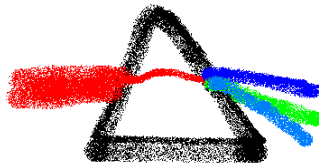


# Context Sensitivity

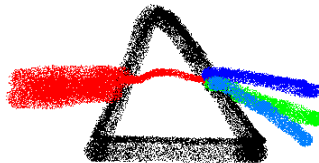
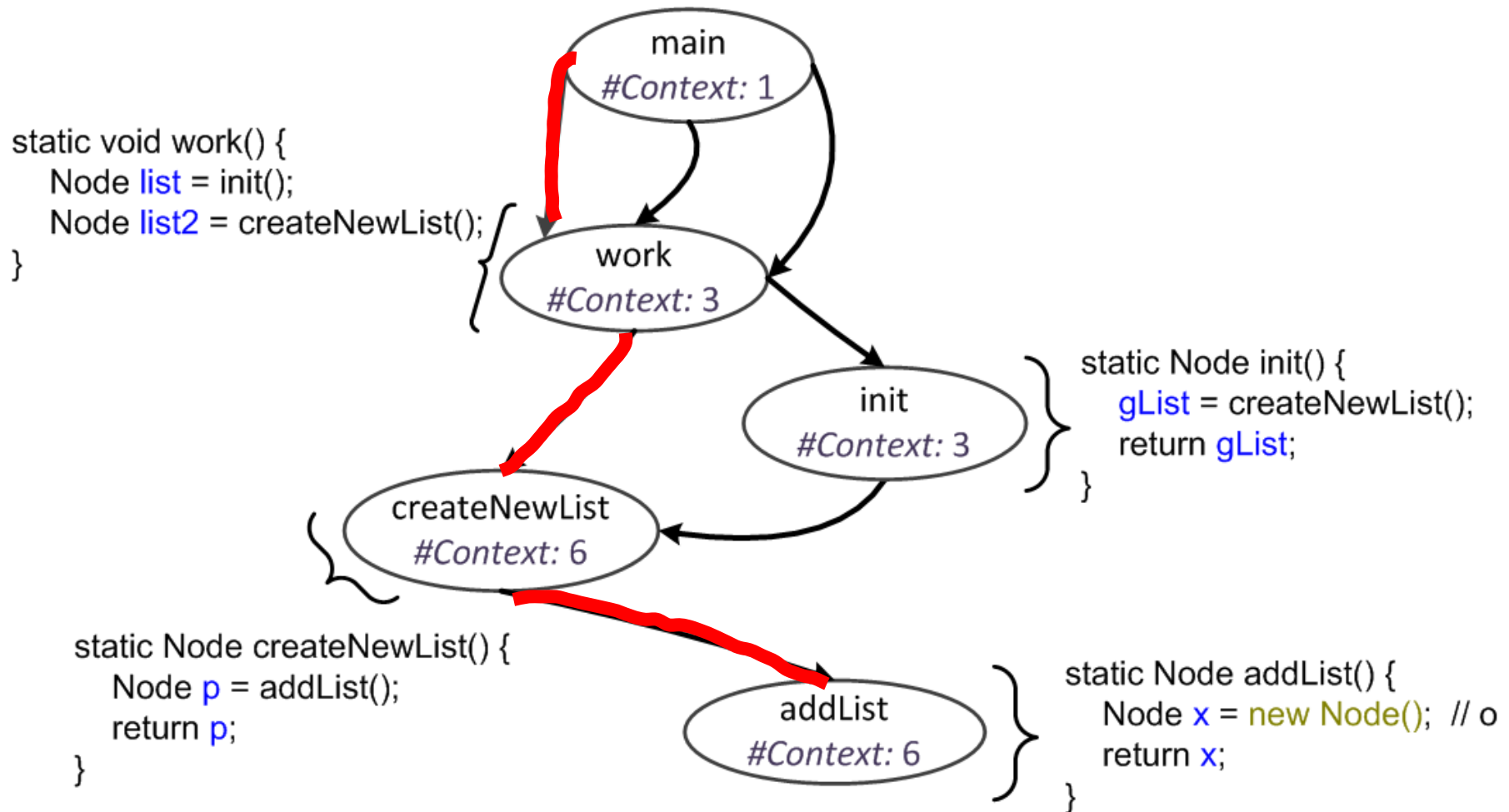


# Context Sensitivity

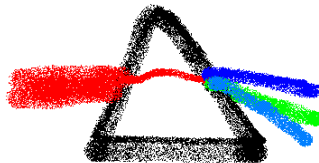
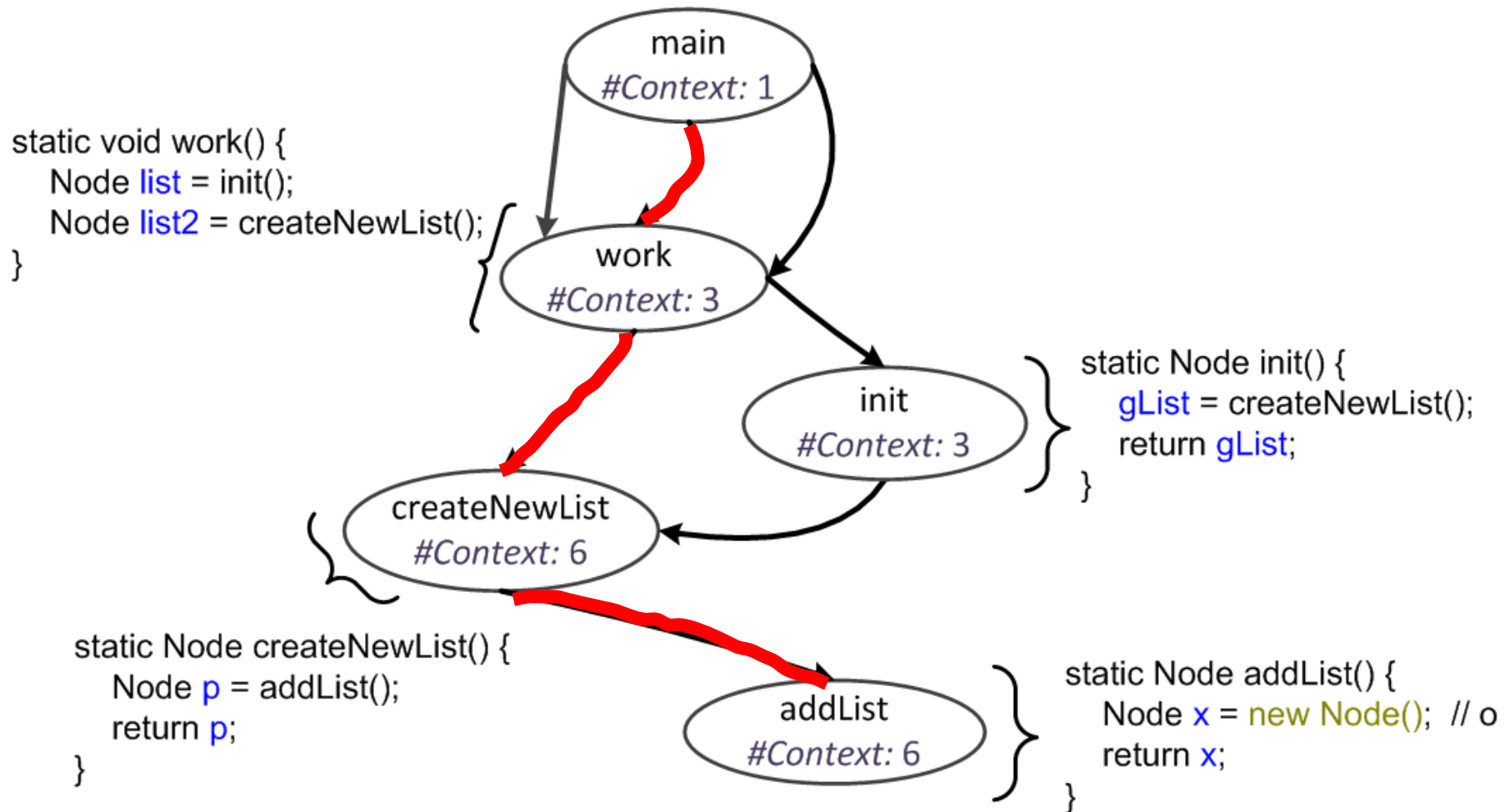
- 6 paths to **addList()** from **main()**;



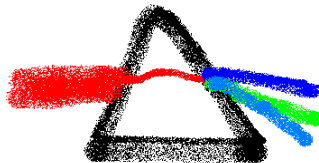
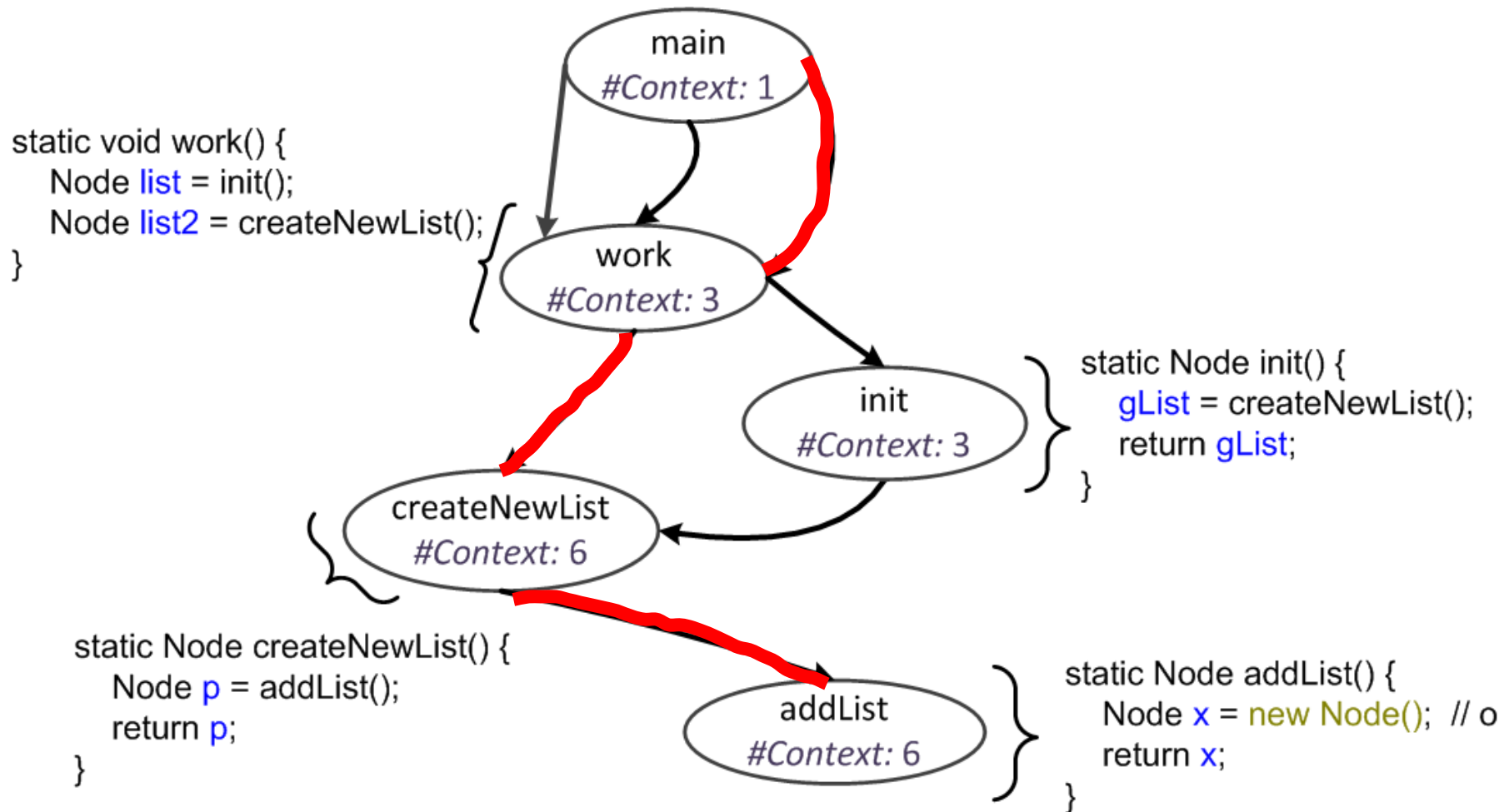
# Context Sensitivity



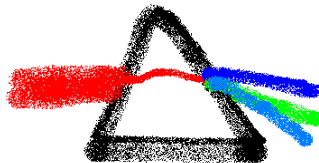
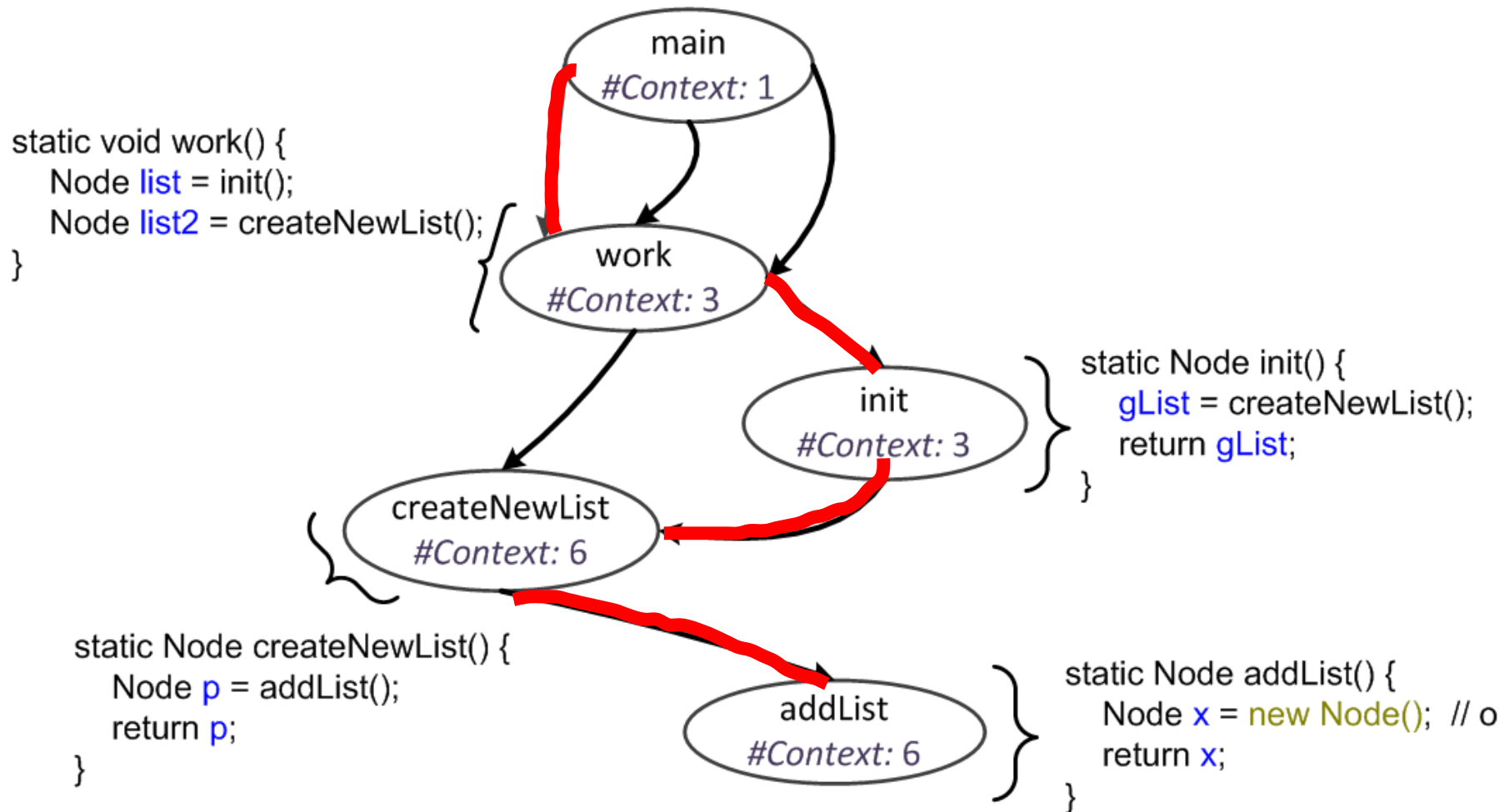
# Context Sensitivity



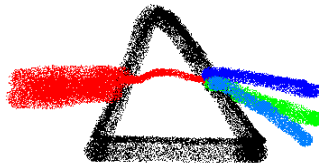
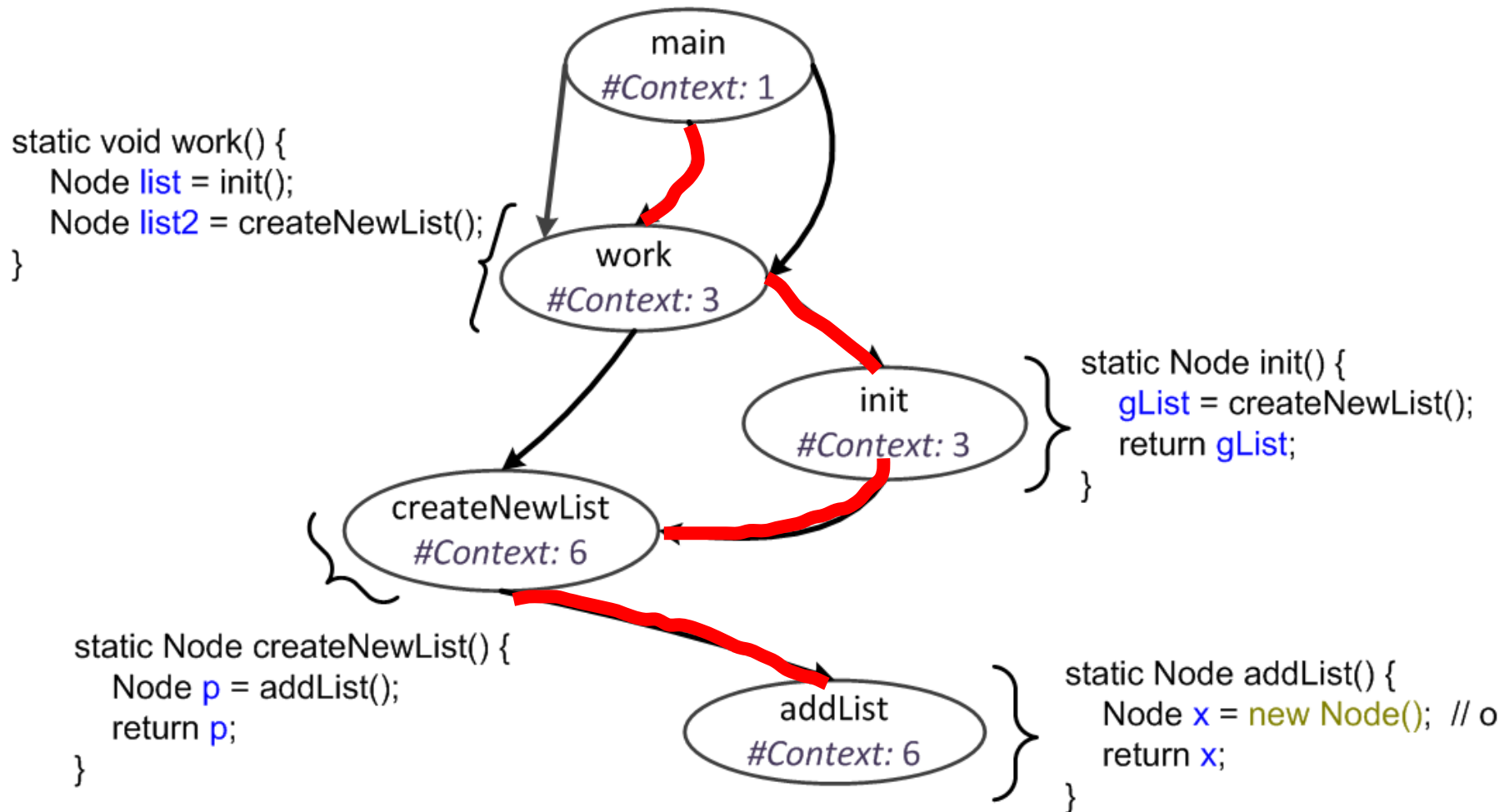
# Context Sensitivity



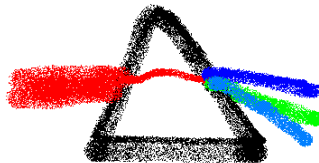
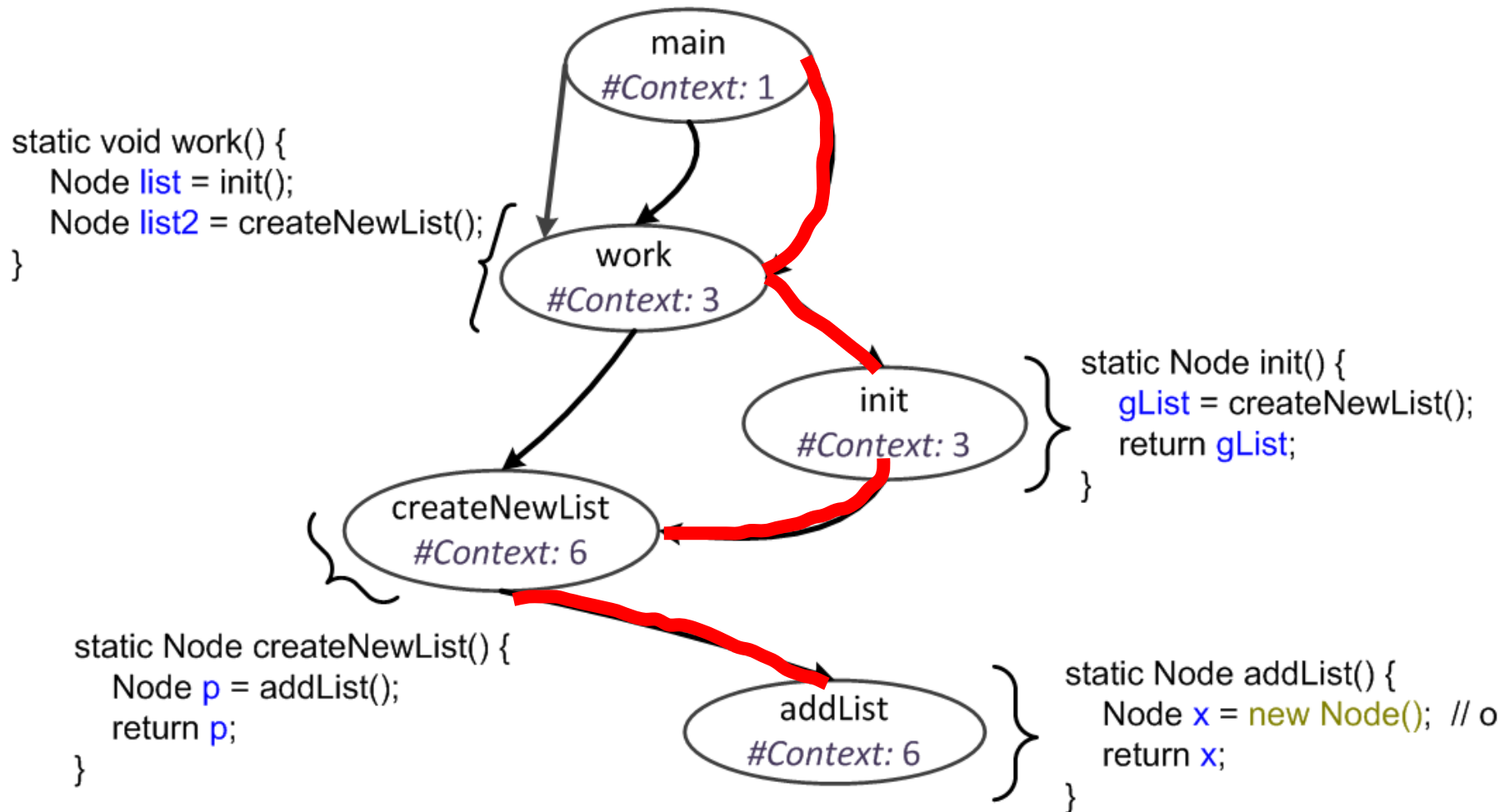
# Context Sensitivity



# Context Sensitivity



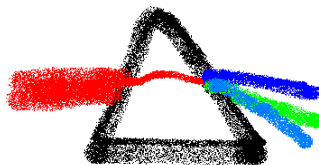
# Context Sensitivity





# New Algorithm

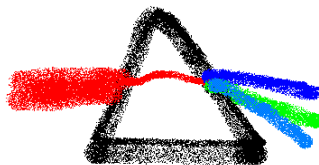
- How do we design an algorithm that can take advantage of the *context* ?



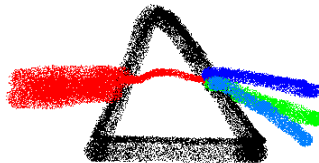
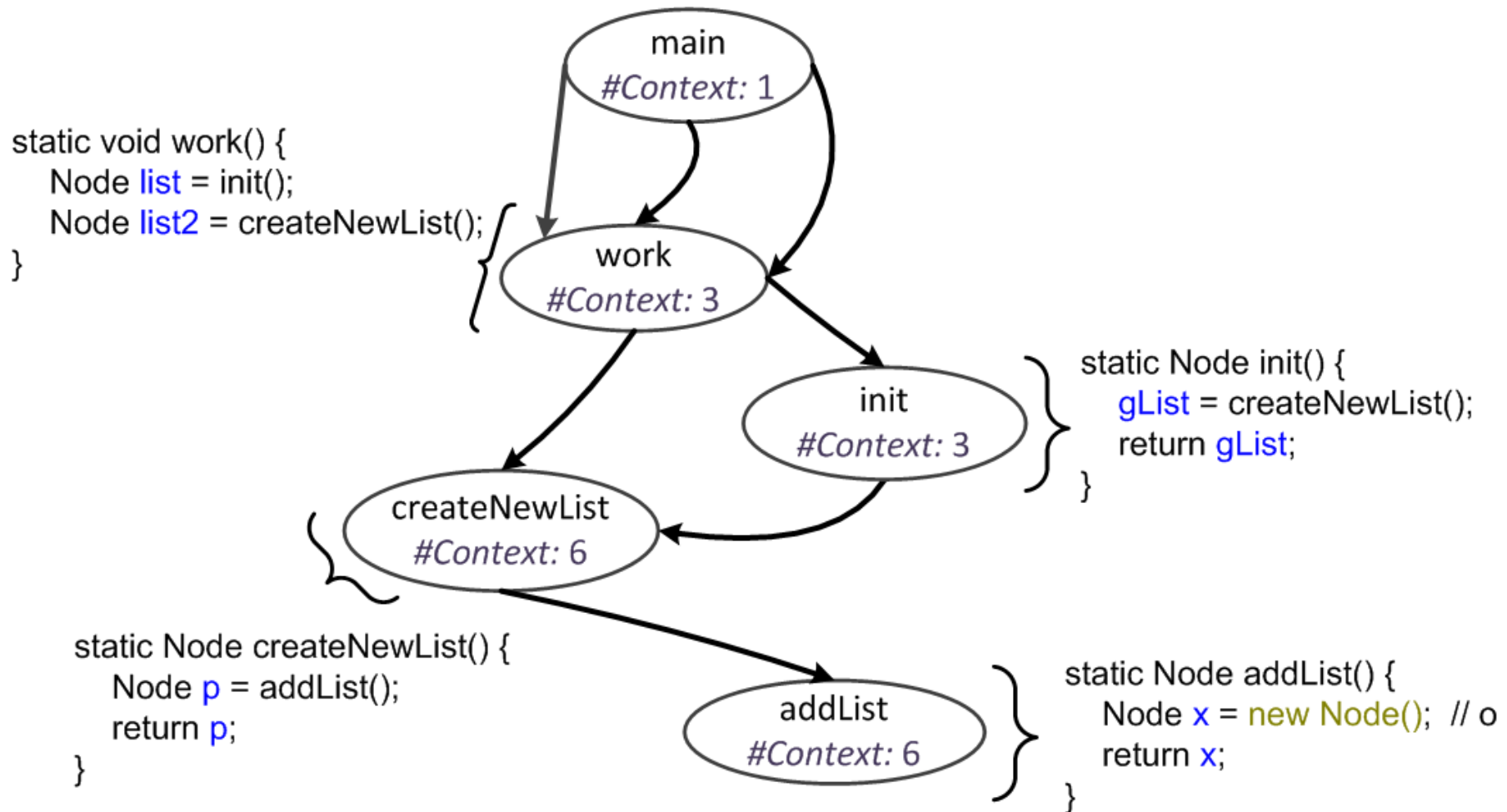
# Context Sensitive Points-to Analysis

## Step 1

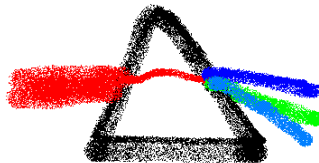
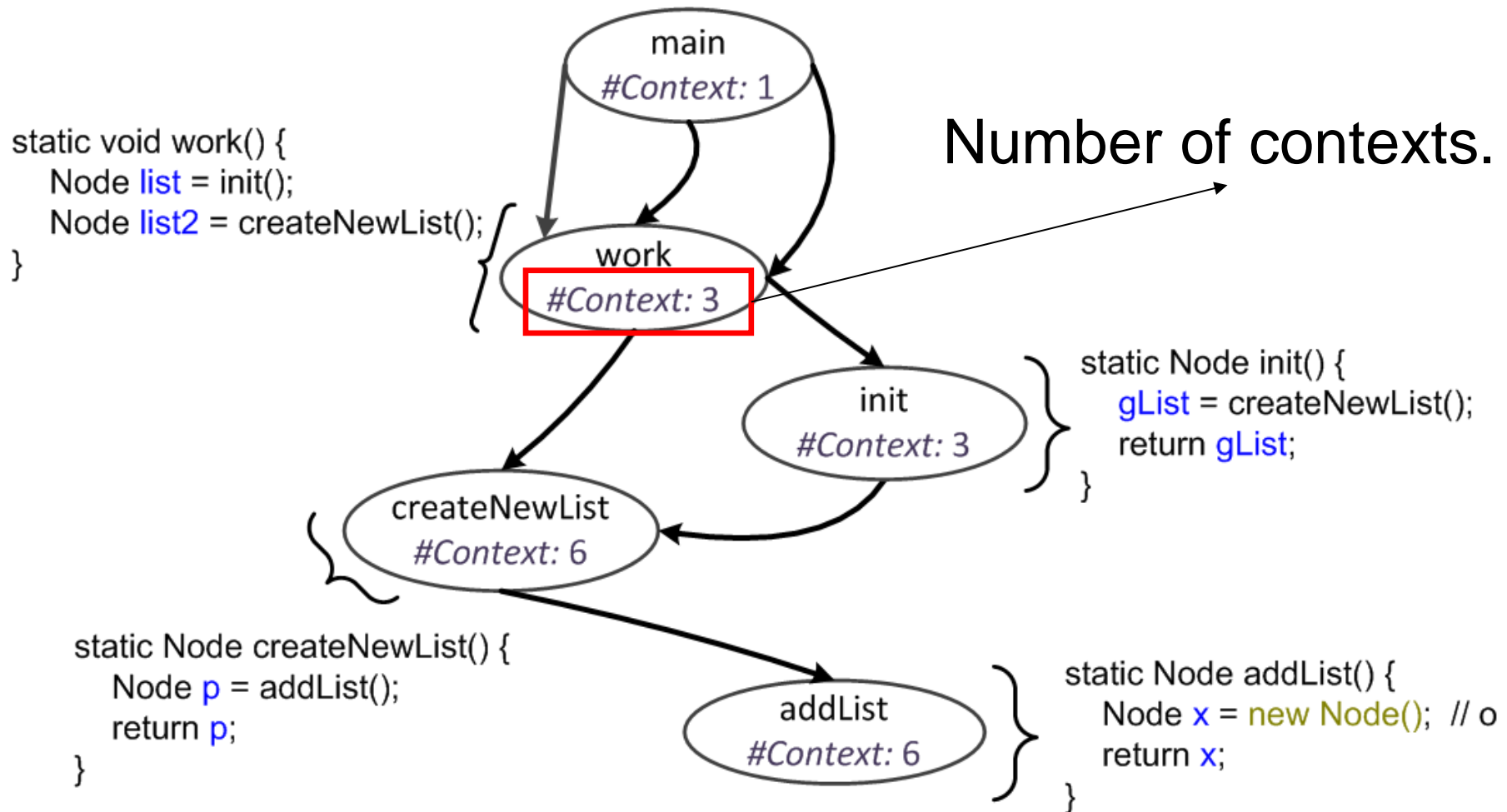
- Build a context sensitive call graph by duplicating every function  $N$  times if it has  $N$  contexts.

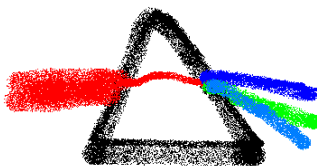
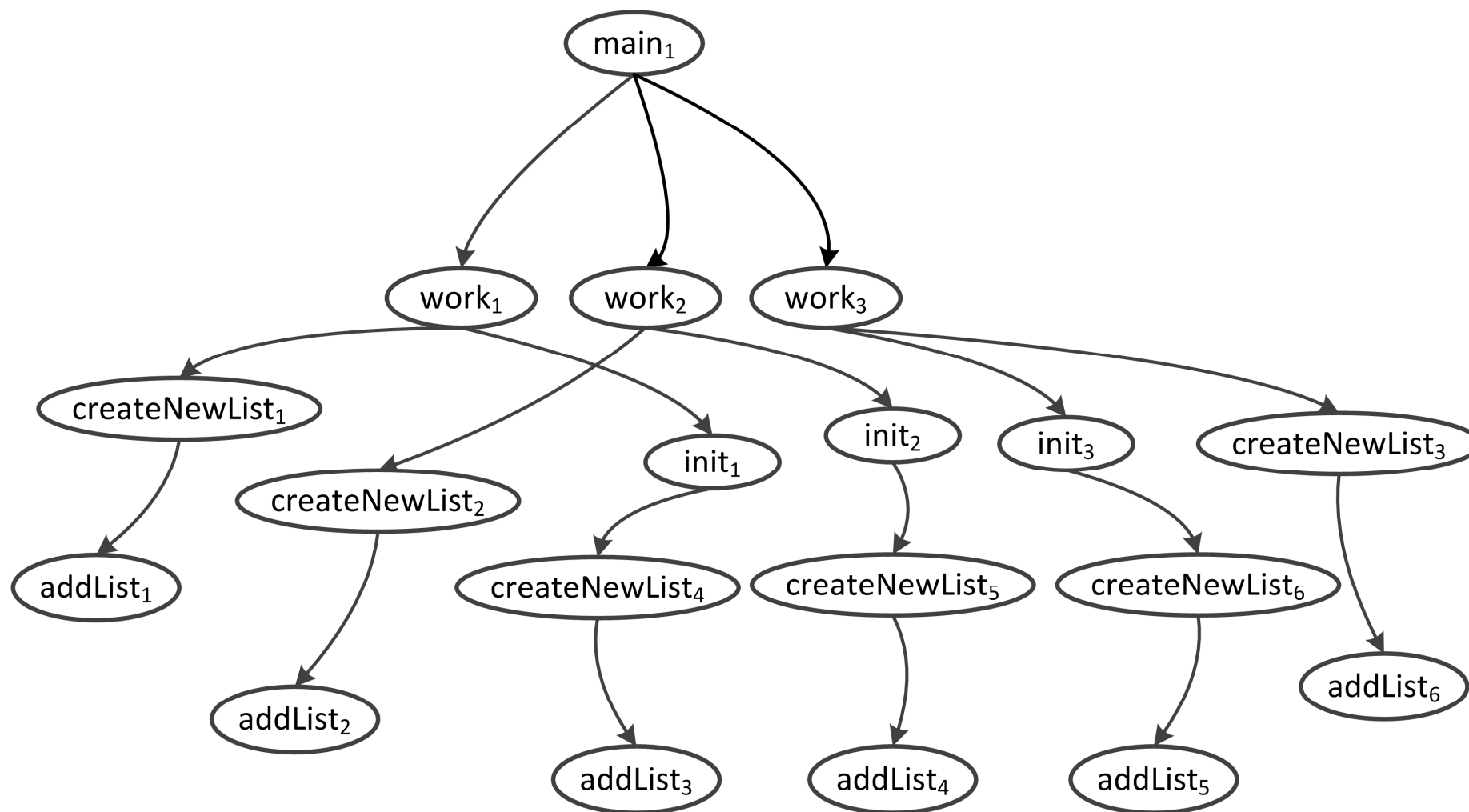


# Context Sensitive Call Graph

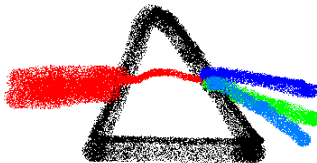
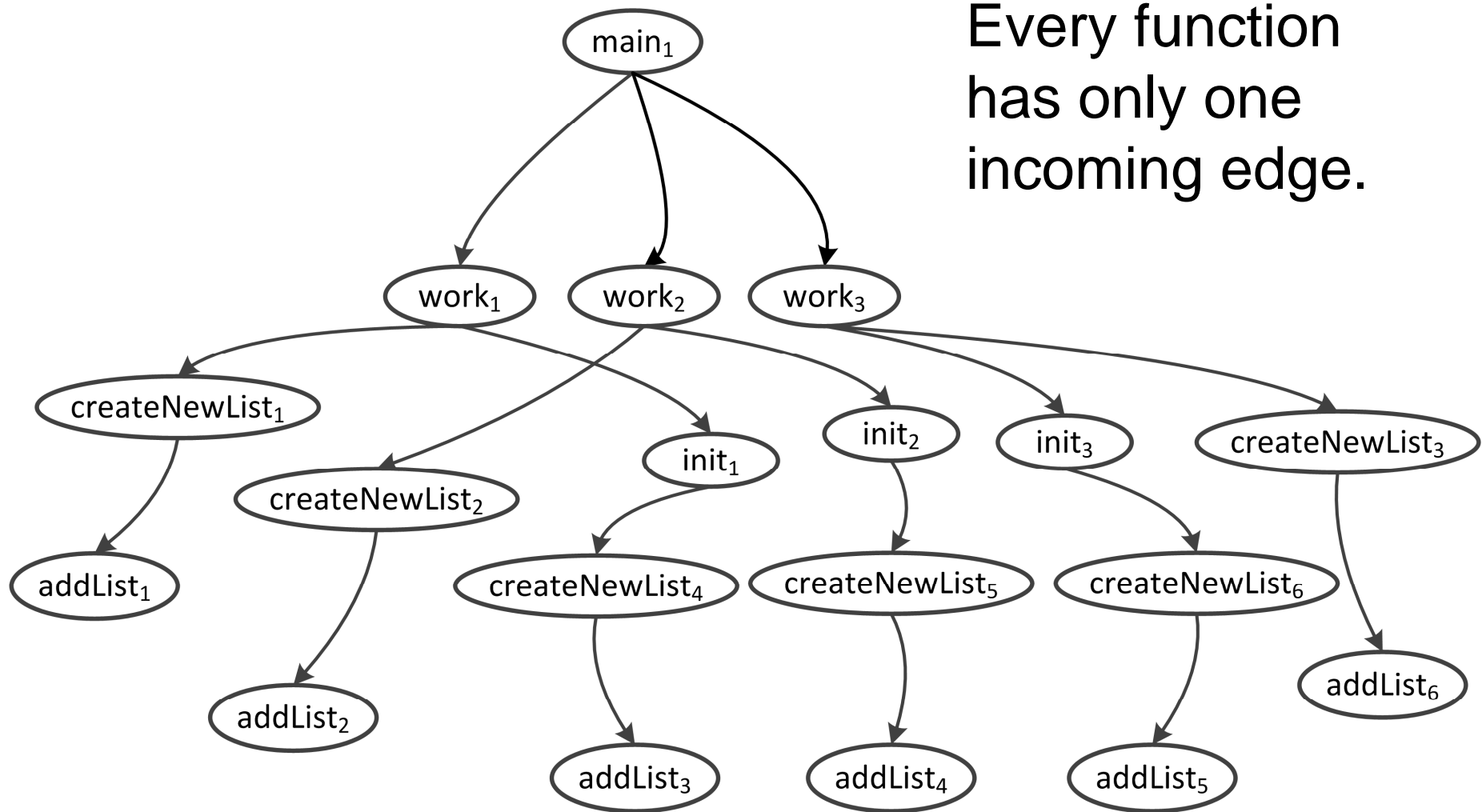


# Context Sensitive Call Graph





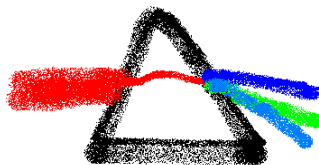
Every function  
has only one  
incoming edge.



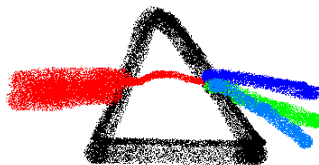
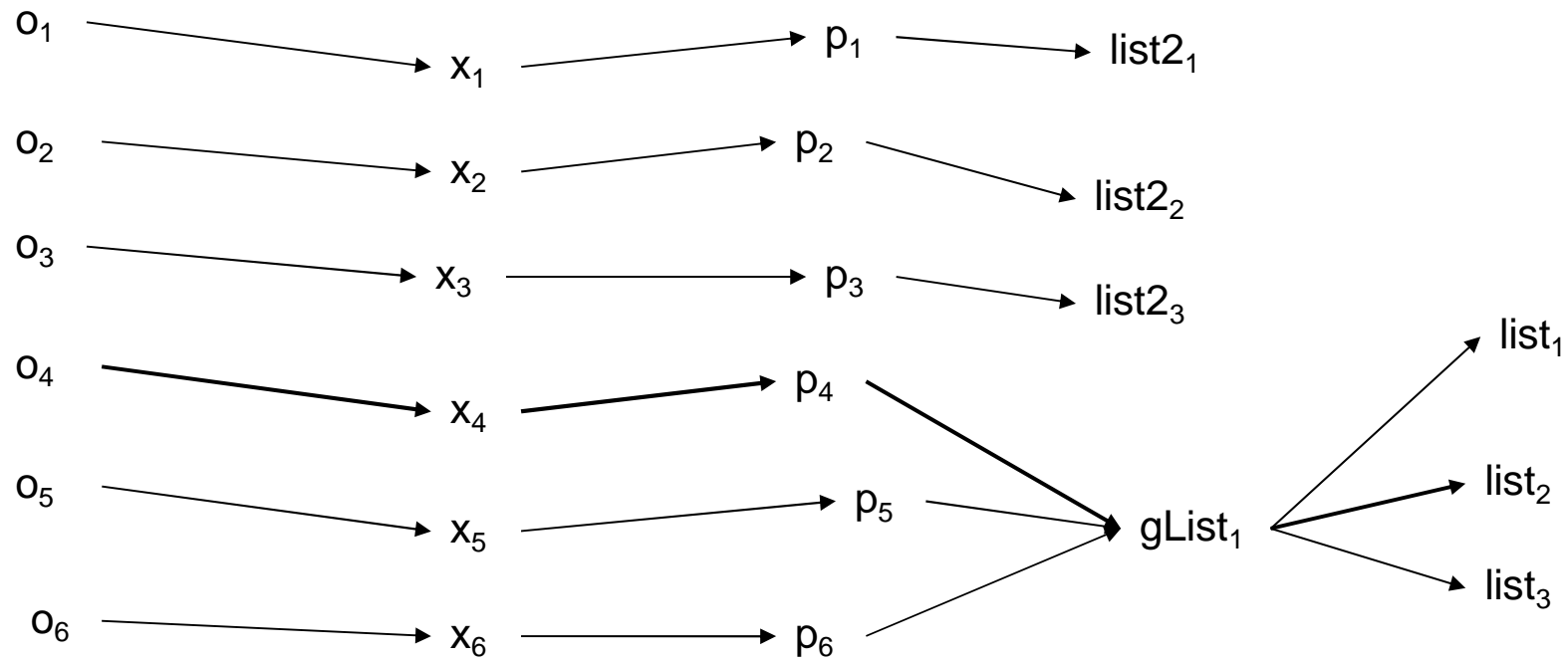
# Context Sensitive Points-to Analysis

## Step 2

- Apply the Anderson's analysis to the context sensitive call graph.



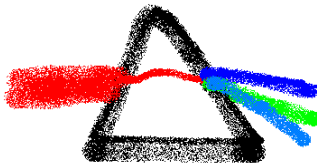
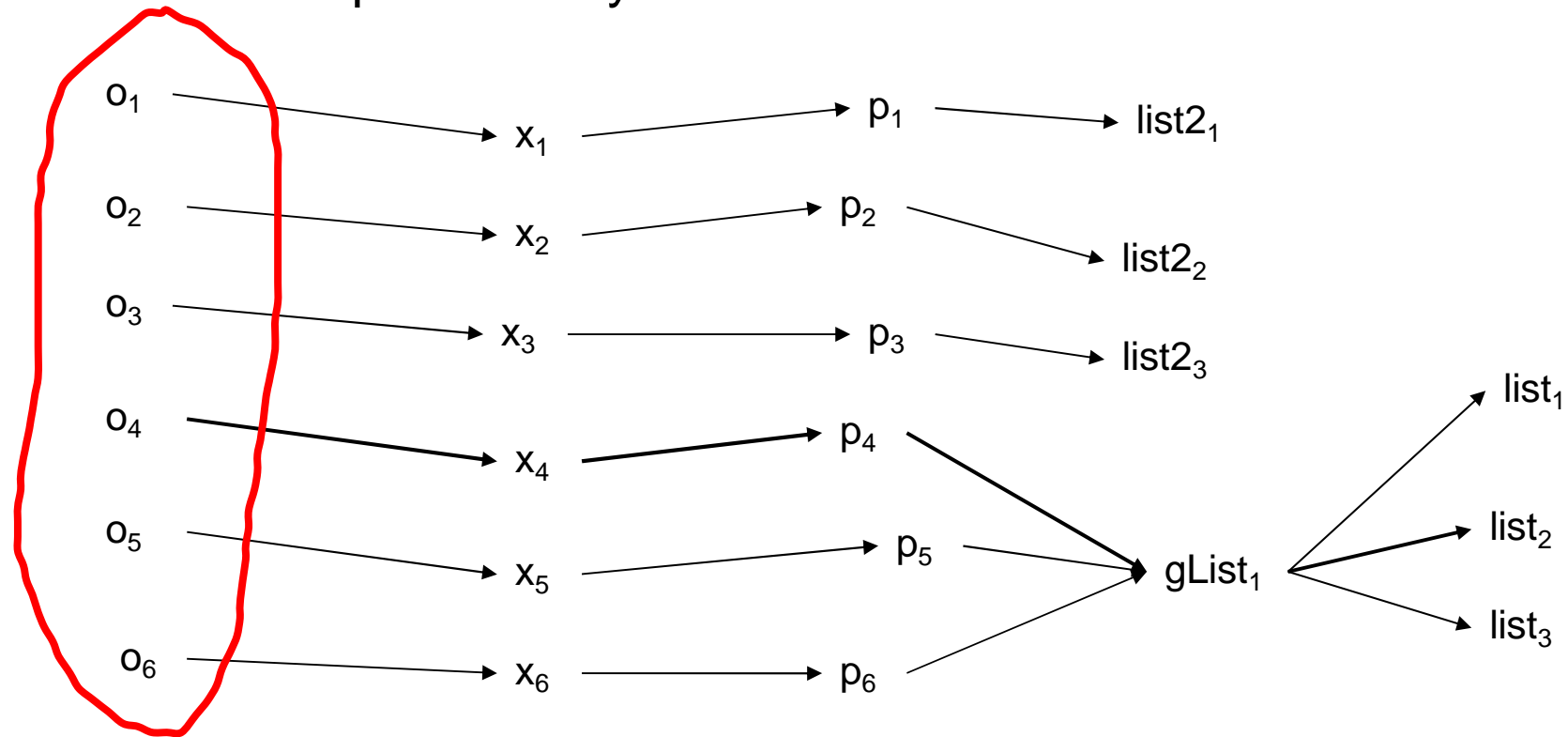
# Context Sensitive Flow Graph



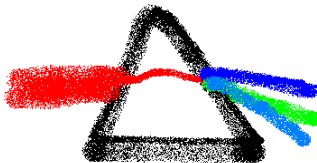
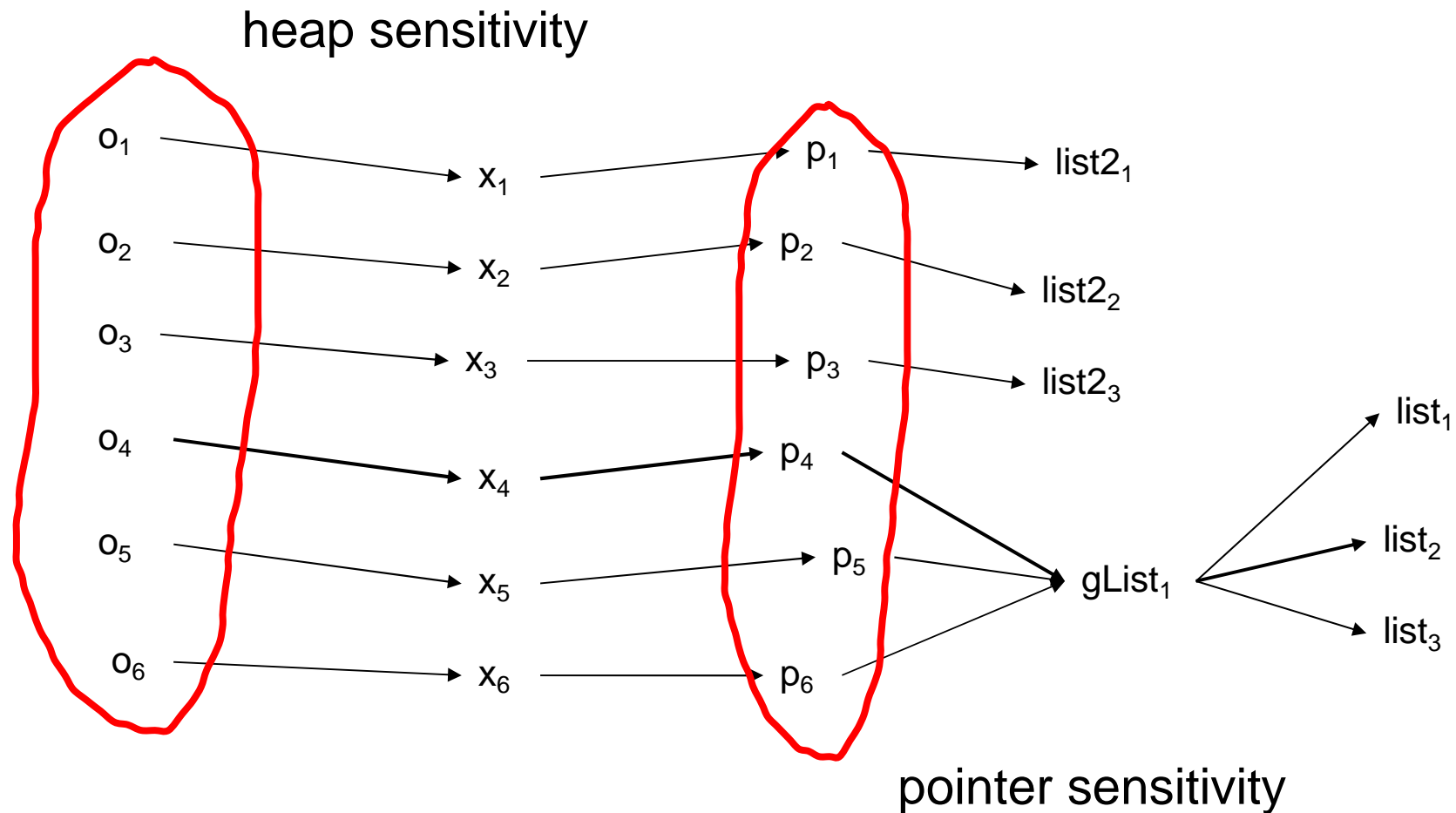


# Context Sensitive Flow Graph

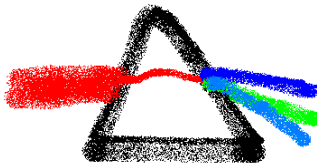
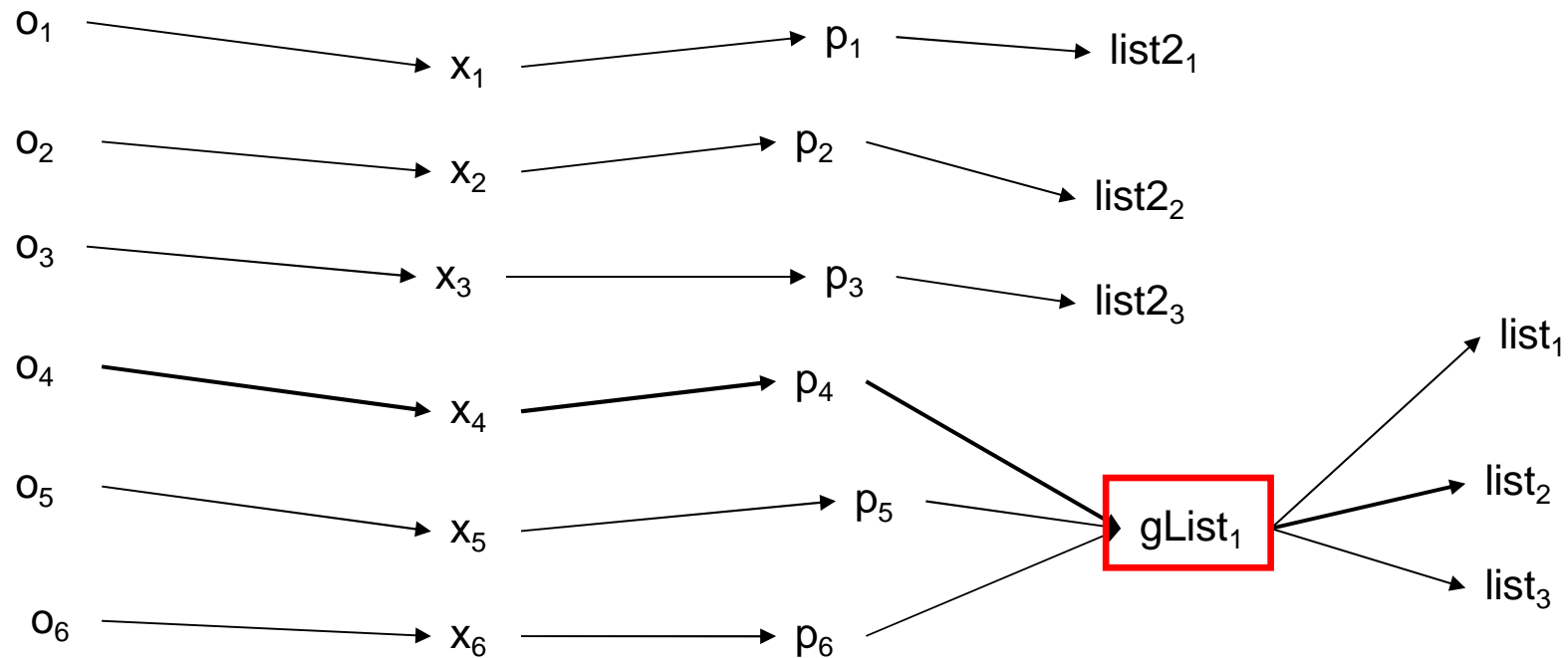
heap sensitivity



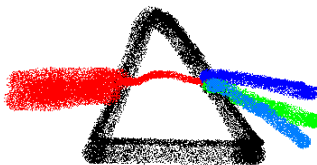
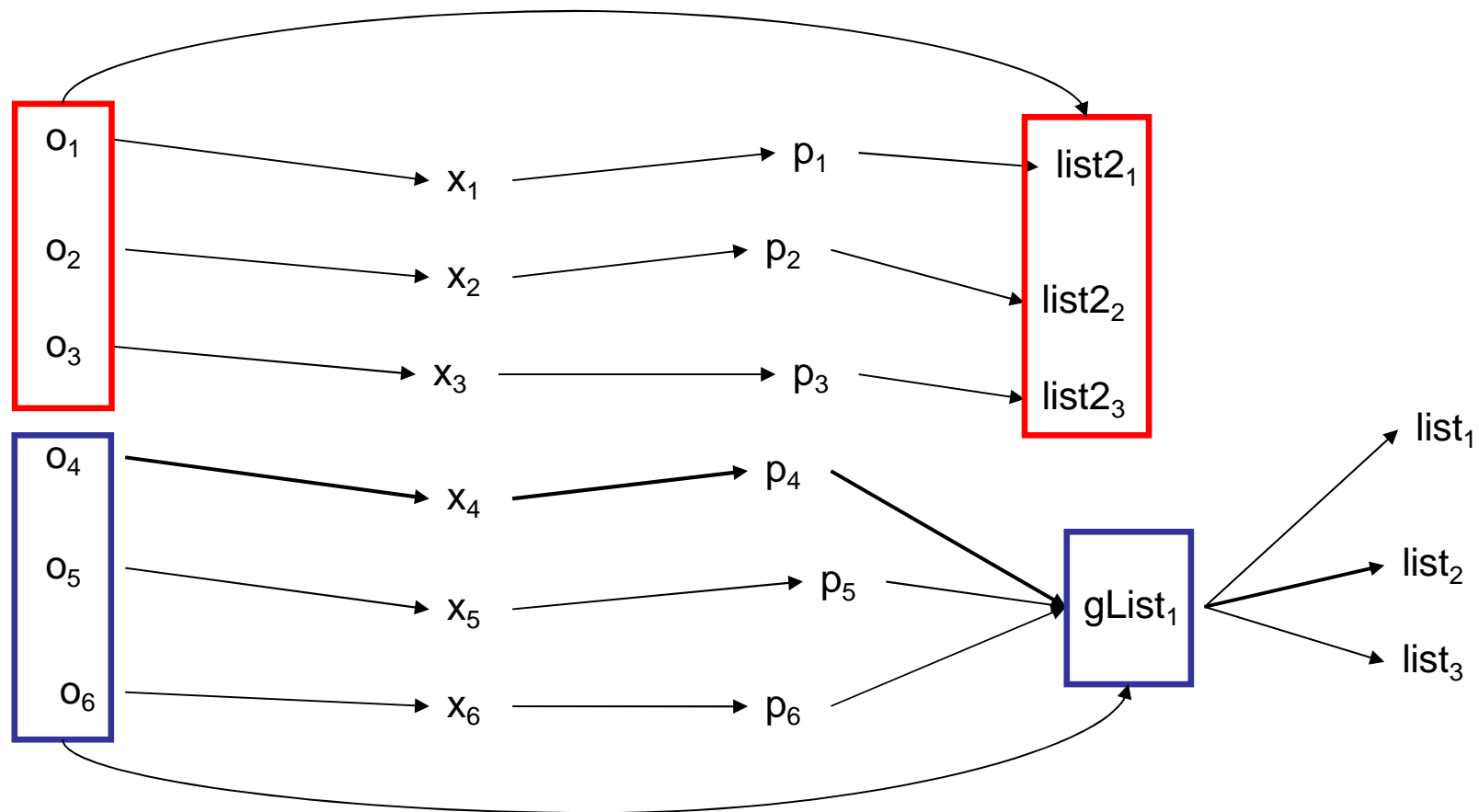
# Context Sensitive Flow Graph



# Context Sensitive Flow Graph

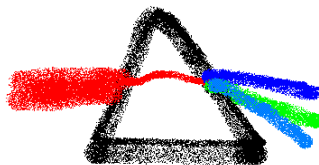


# Context Sensitive Flow Graph



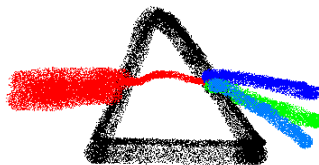
# Context Sensitive Points-to Analysis

- How can we do reachability analysis with the context sensitive flow graph efficiently?



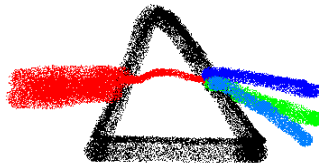
# Challenge

- The flow graph is extremely large!
- Handling a graph with billions of nodes is not an easy job.



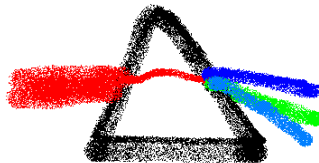
# bddbddb [PLDI04]

- Store the initial assigns-to relations into the BDD;
- Store the initial points-to relations into another BDD;
- Iteratively apply the BDD join operator until the points-to relations fixed;



# bddbddb [PLDI04]

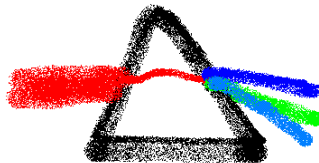
- Advantages:
  - A very large flow-to graph can be handled within 1GB memory;
  - Programming with BDD is not so difficult.





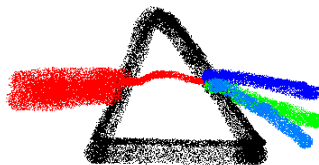
# bddbddb [PLDI04]

- Problems:
  - Multi-dimensional sensitivity (both pointer and heap) support are inefficient;
  - Although consider the pointer sensitivity only, the time efficiency is still not satisfiable;



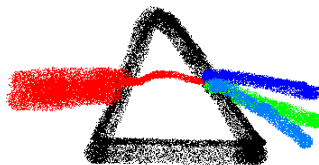
# EPA [ISSTA08]

- High level idea:
  - Do not number the contexts to 1, 2, 3... but use callsite string to represent contexts;
  - Extract the shared prefix of the context string to achieve compression.



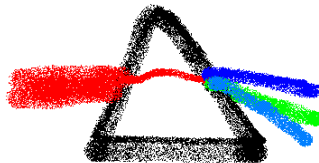
# EPA [ISSTA08]

- Problems:
  - Procedure summary based design: less efficient compared to whole program analysis because of more actions (e.g. method escape analysis, symbolic placeholder instantiation, etc.).

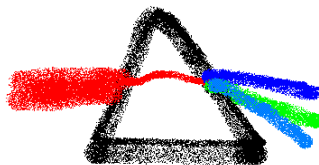
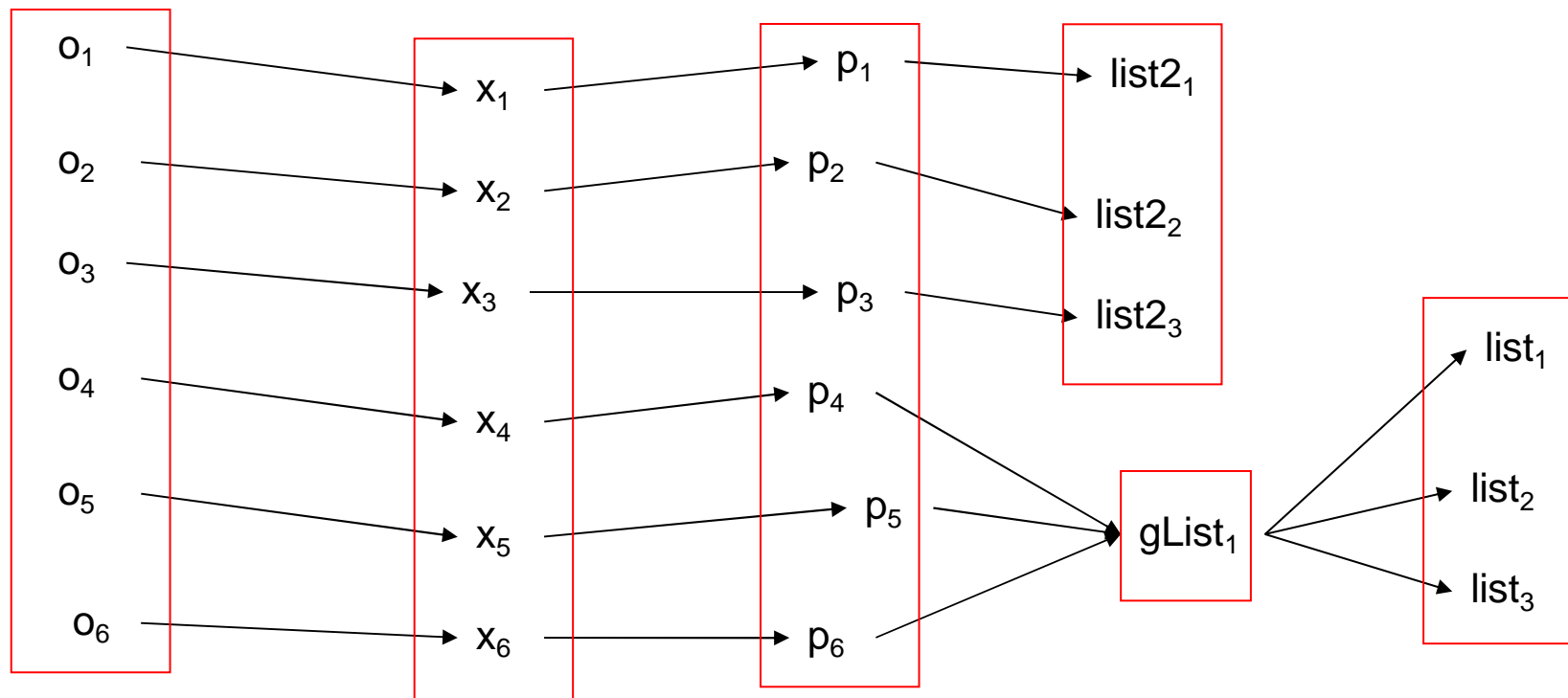


# Context Sensitive Flow Graph

- Let's see the flow graph again.....

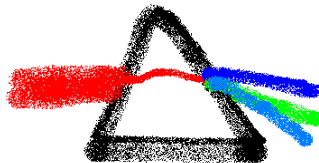


# Context Sensitive Flow Graph



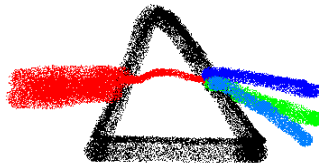
# Context Sensitive Flow Graph

- Can you find anything interesting from the *group view* of the flow graph?

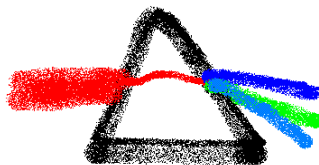
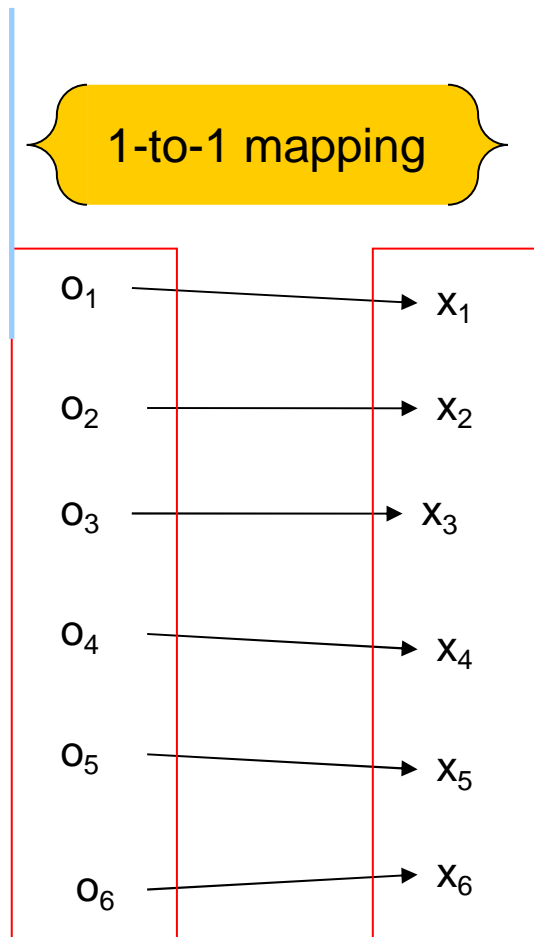


# Context Sensitive Flow Graph

- Yes, the flow graph is constructed by many mapping structures.

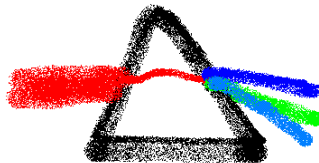
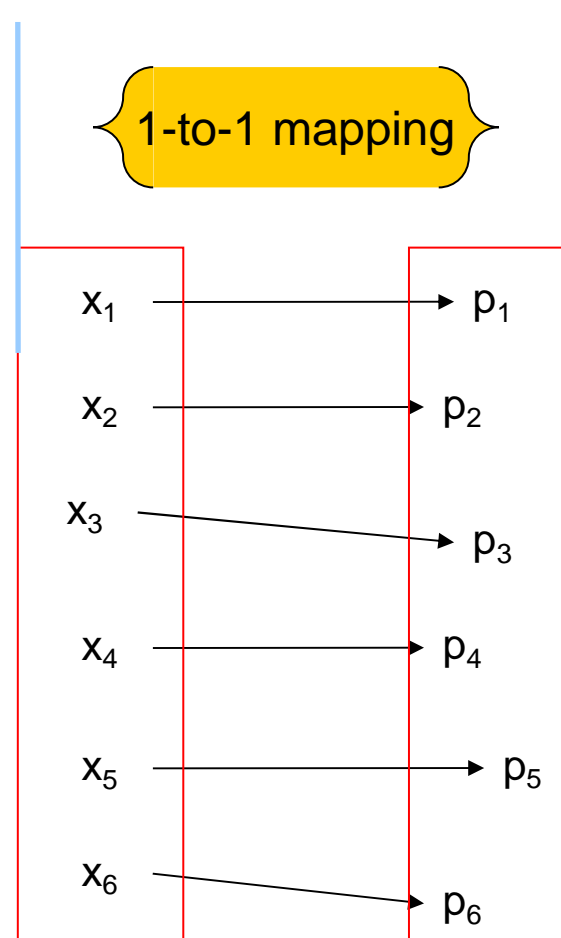


# Context Sensitive Flow Graph

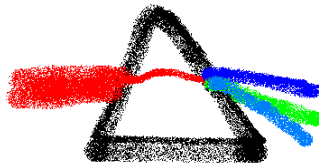
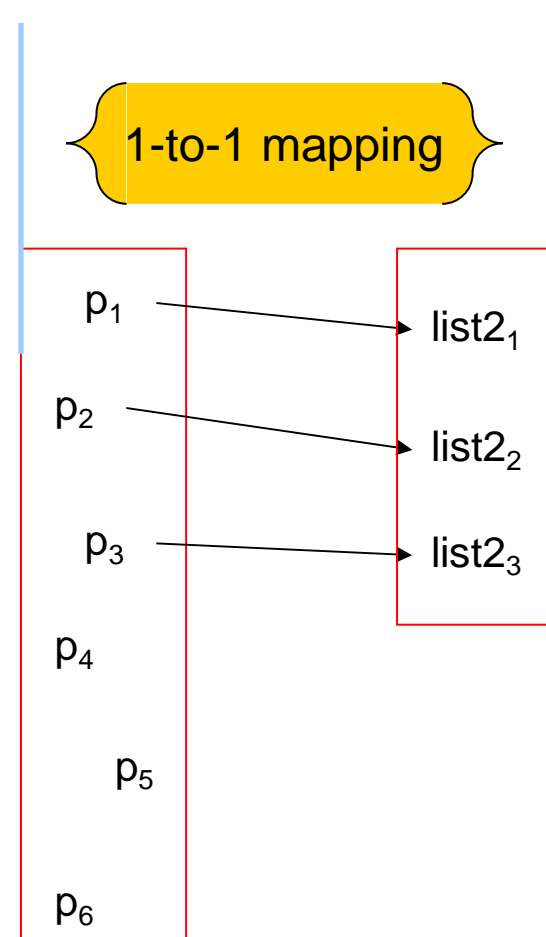




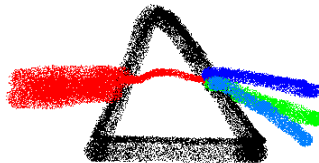
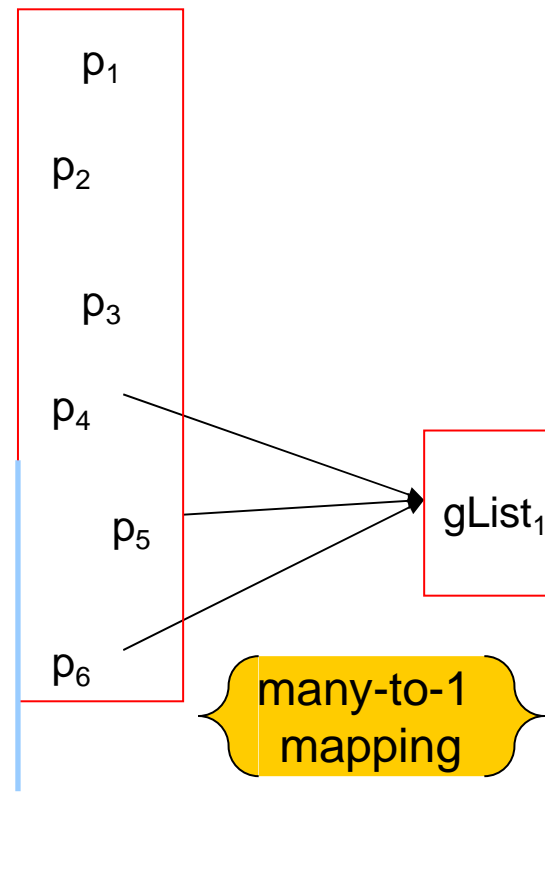
# Context Sensitive Flow Graph



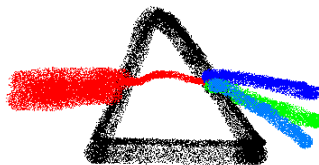
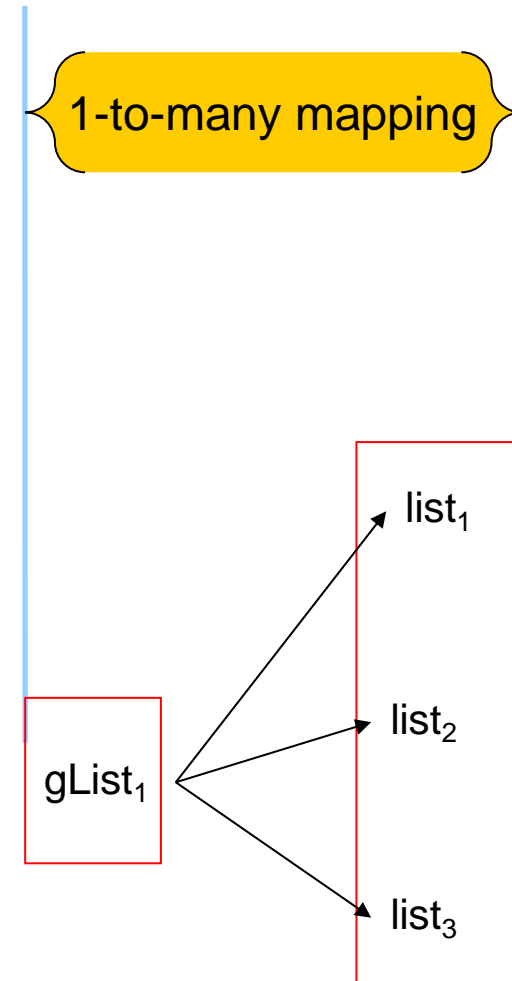
# Context Sensitive Flow Graph



# Context Sensitive Flow Graph

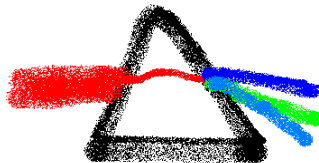


# Context Sensitive Flow Graph

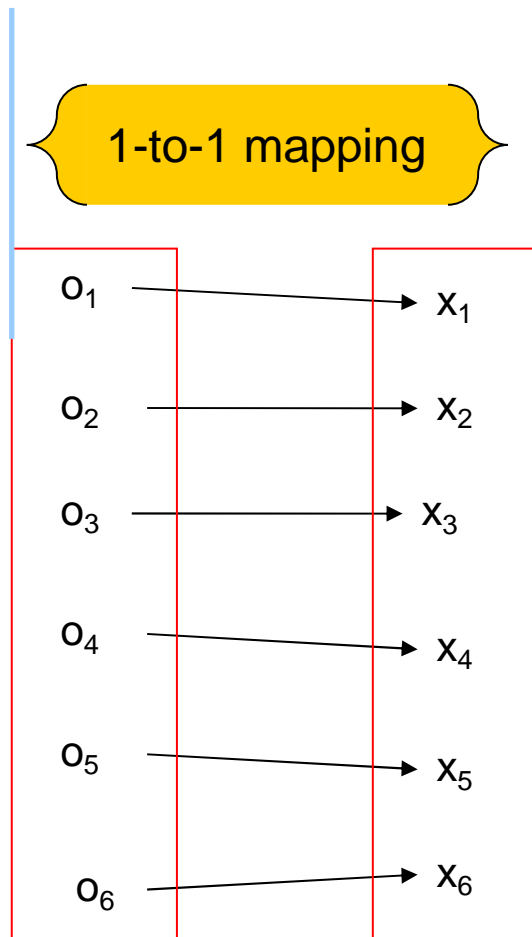


# Context Sensitive Flow Graph

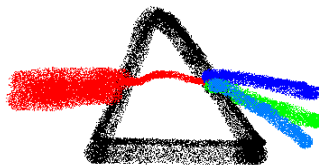
- Any other observations?



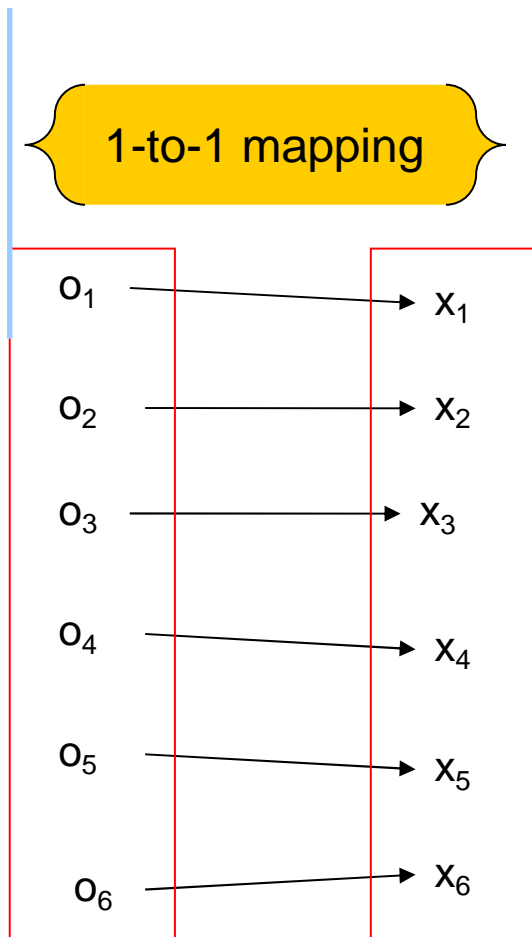
# Context Sensitive Flow Graph



Please look at the subscripts....



# Context Sensitive Flow Graph

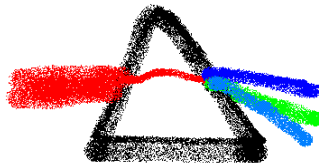


Please look at the  
subscripts....

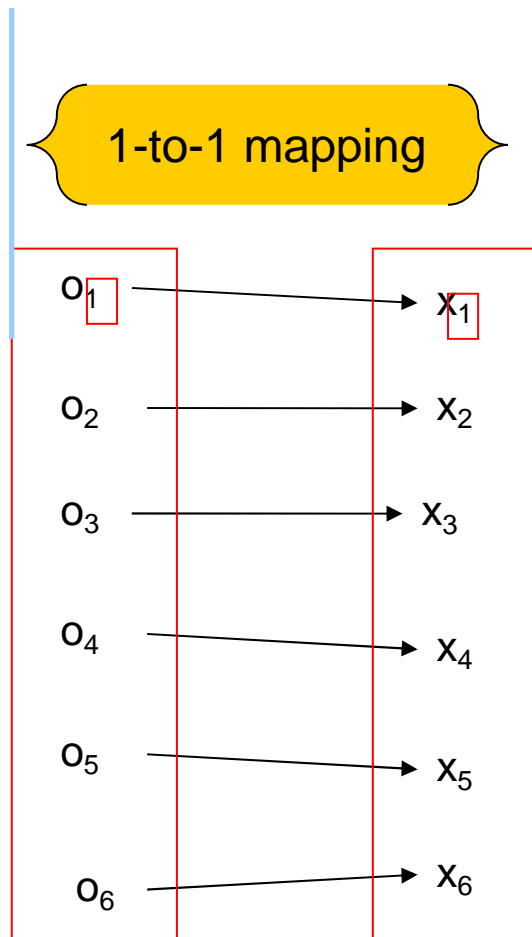
$o : [1, 6]$

$x : [1, 6]$

Consecutive numbers

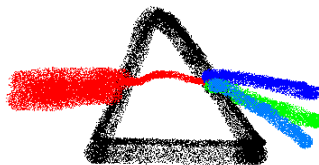


# Context Sensitive Flow Graph



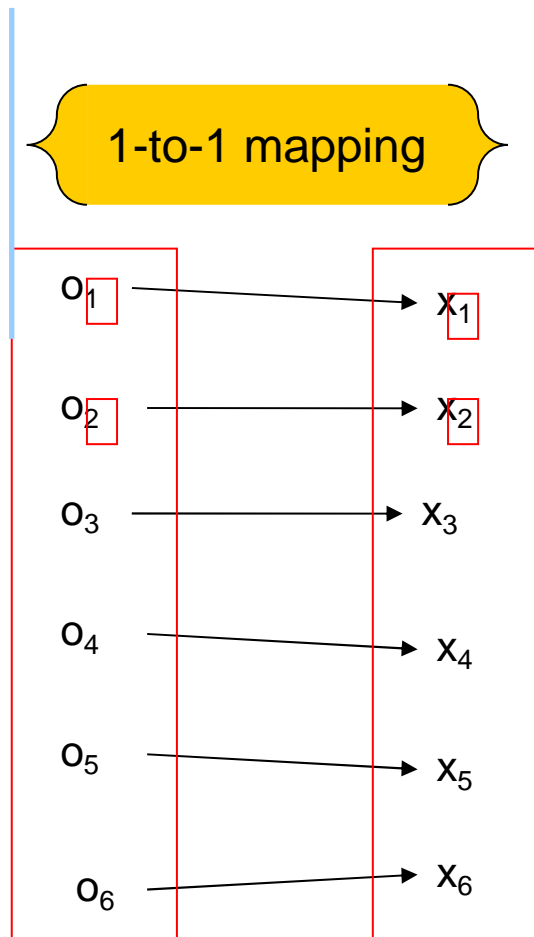
Please look at the subscripts....

1 -> 1





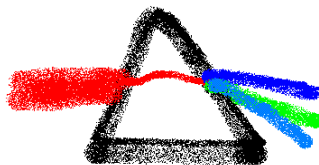
# Context Sensitive Flow Graph



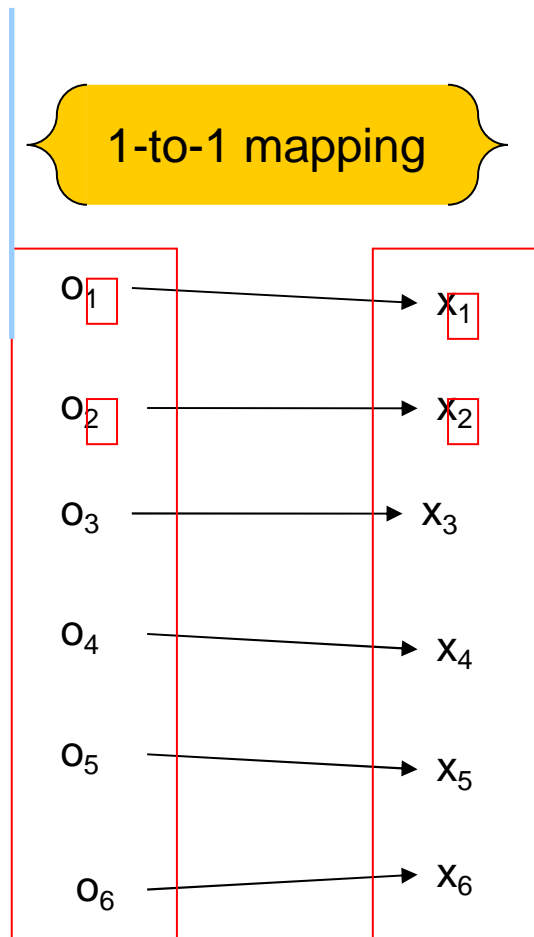
Please look at the subscripts....

1 -> 1

2 -> 2



# Context Sensitive Flow Graph

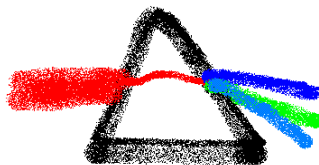


Please look at the subscripts....

1 -> 1

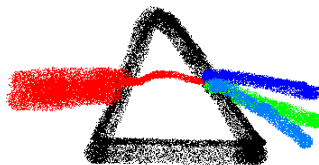
2 -> 2

.....



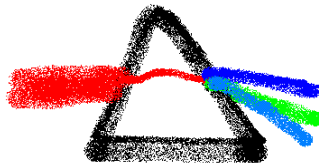
# Context Sensitive Flow Graph

- We call this *ordering law*:
  - $Y = \text{map}(X)$ ;
  - Elements in  $X$  are numbered consecutively;
  - Elements in  $Y$  are numbered consecutively;
  - $a < b$  in  $X \Rightarrow \text{map}(a) < \text{map}(b)$ .

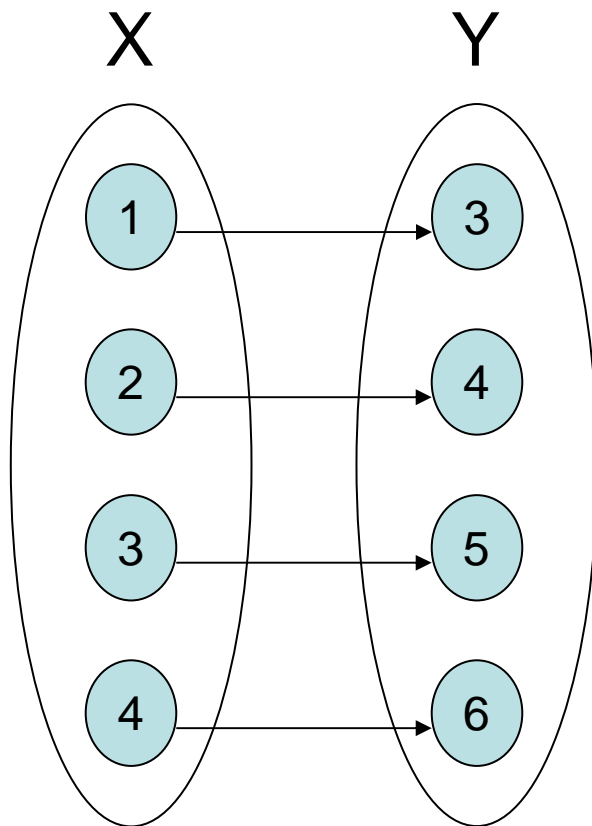


# Context Sensitive Flow Graph

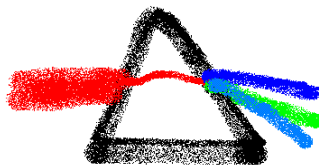
- Is it useful for our points-to analysis?



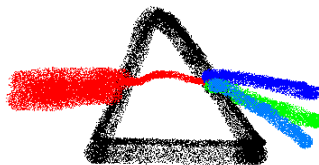
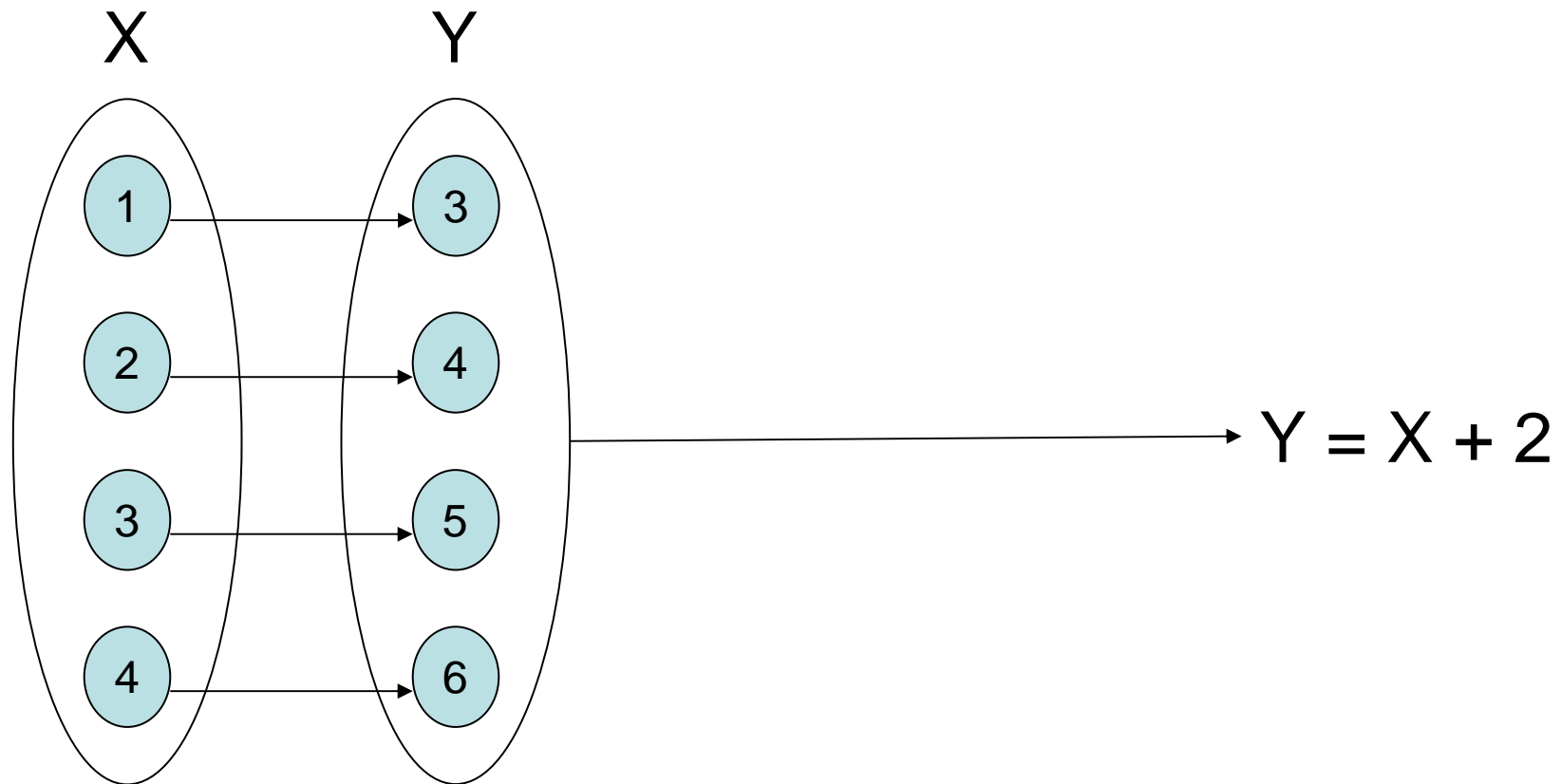
# Geometric Encoding



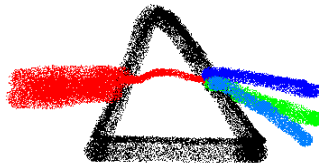
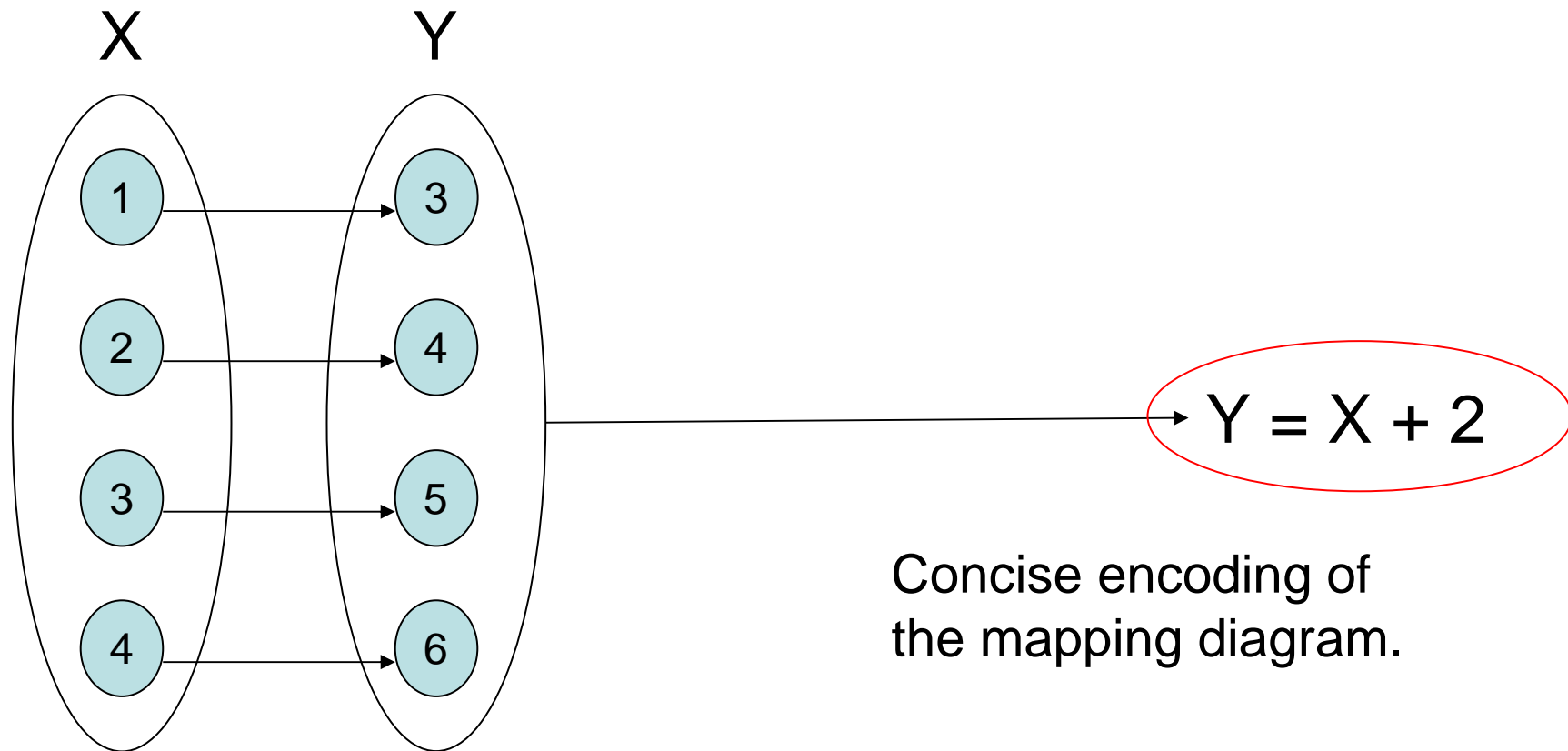
1-to-1 mapping with  
ordering law.....



# Geometric Encoding

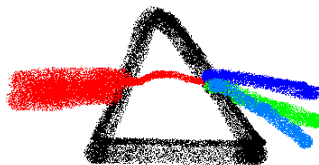


# Geometric Encoding



# Geometric Encoding

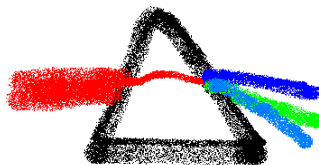
- Next, we visualize all the mapping relations that conform to the ordering law.





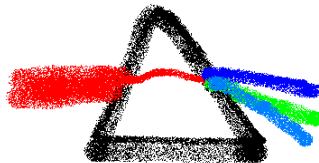
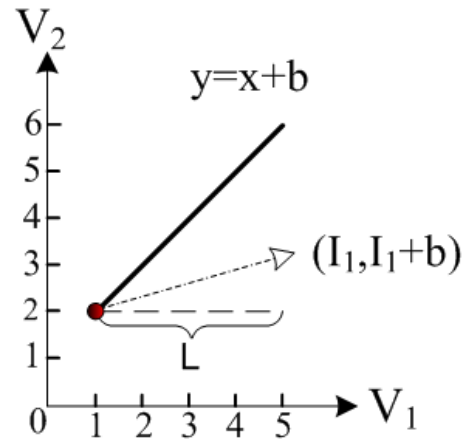
# Geometric Encoding

1-to-1 mapping



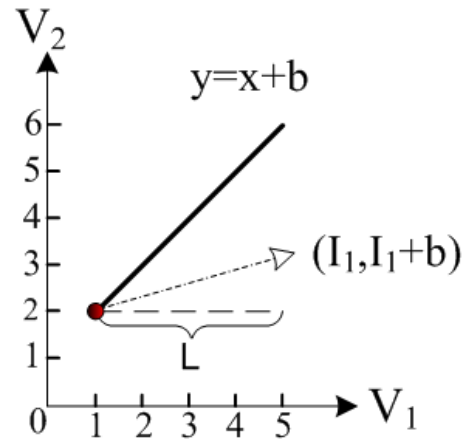
# Geometric Encoding

1-to-1 mapping

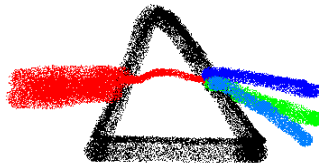


# Geometric Encoding

1-to-1 mapping

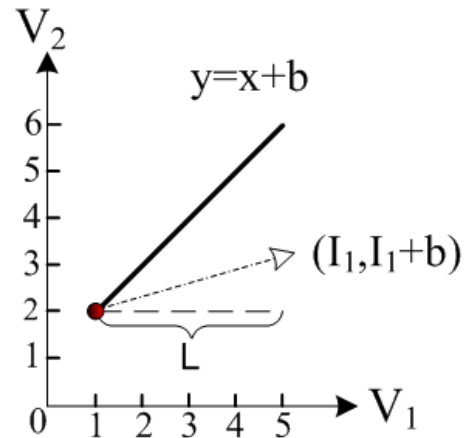


$(I_1, I_1 + b, L)$



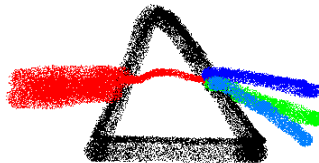
# Geometric Encoding

1-to-1 mapping



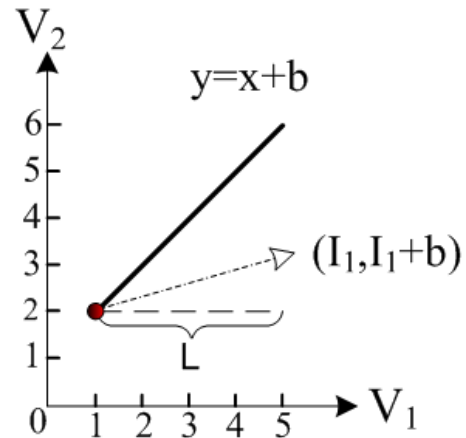
$$(l_1, l_1 + b, L)$$

many-to-many  
(1-to-many,  
many-to-1)



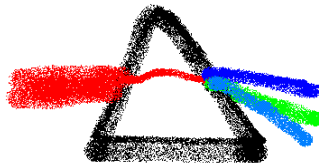
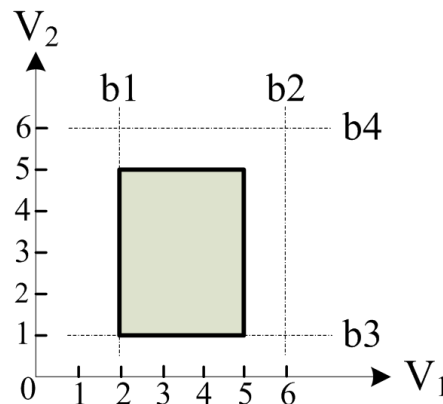
# Geometric Encoding

1-to-1 mapping



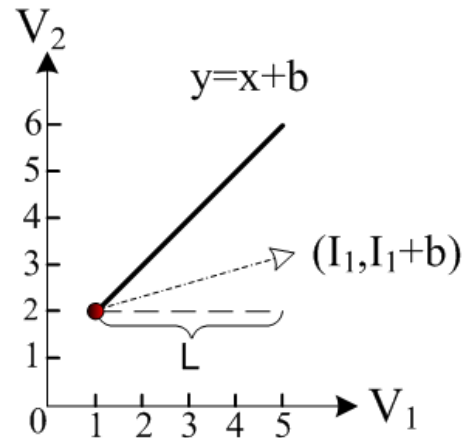
$$(I_1, I_1 + b, L)$$

many-to-many  
(1-to-many,  
many-to-1)



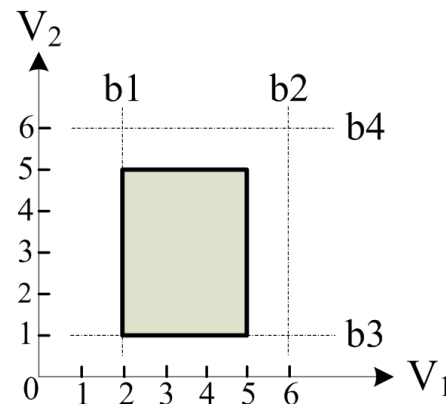
# Geometric Encoding

1-to-1 mapping

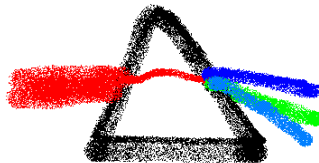


$$(I_1, I_1 + b, L)$$

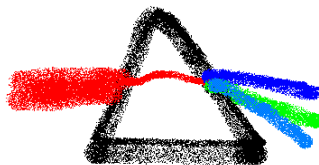
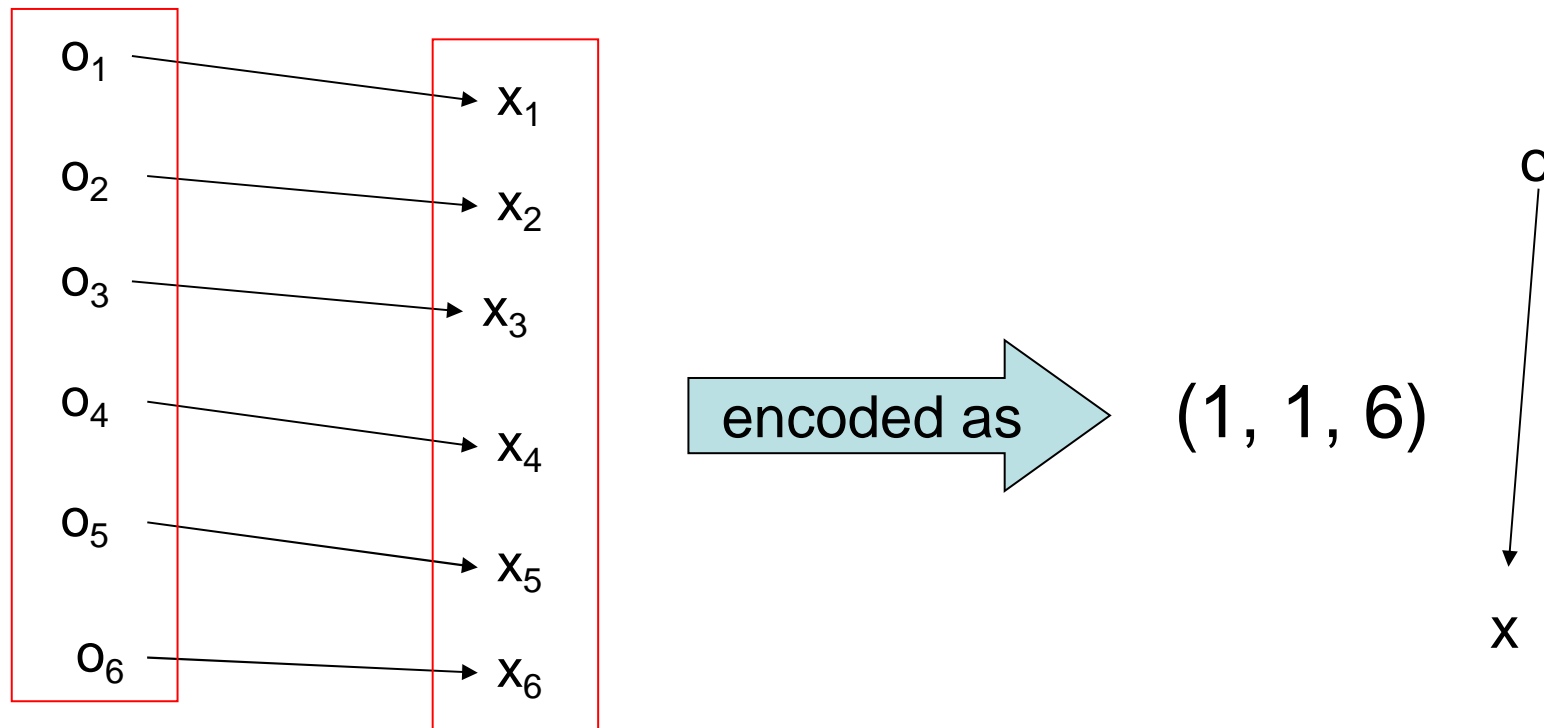
many-to-many  
(1-to-many,  
many-to-1)



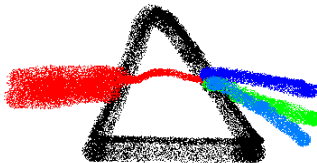
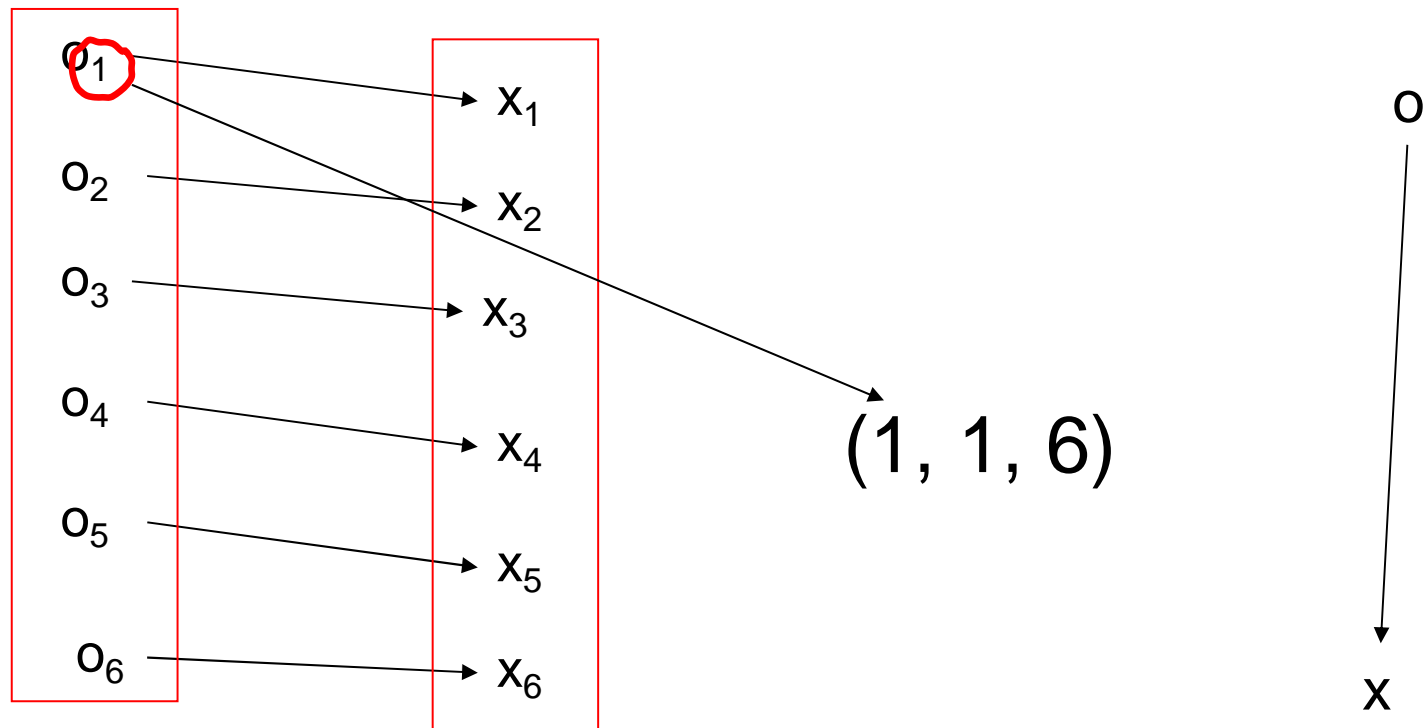
$$(b_1, b_3, b_2 - b_1, b_4 - b_3)$$



# Geometric Encoding

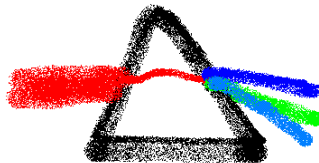
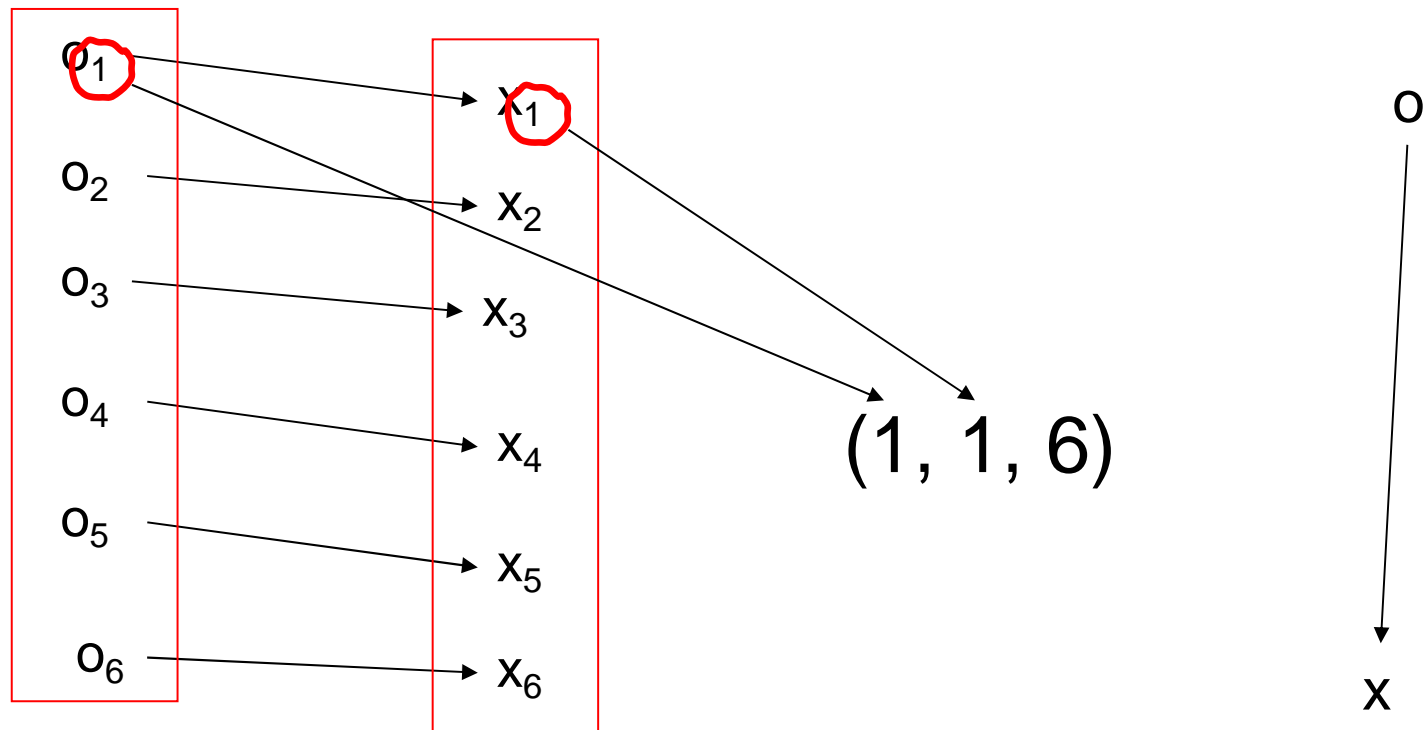


# Geometric Encoding

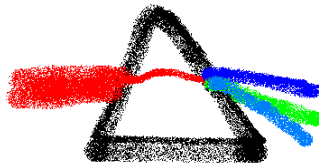
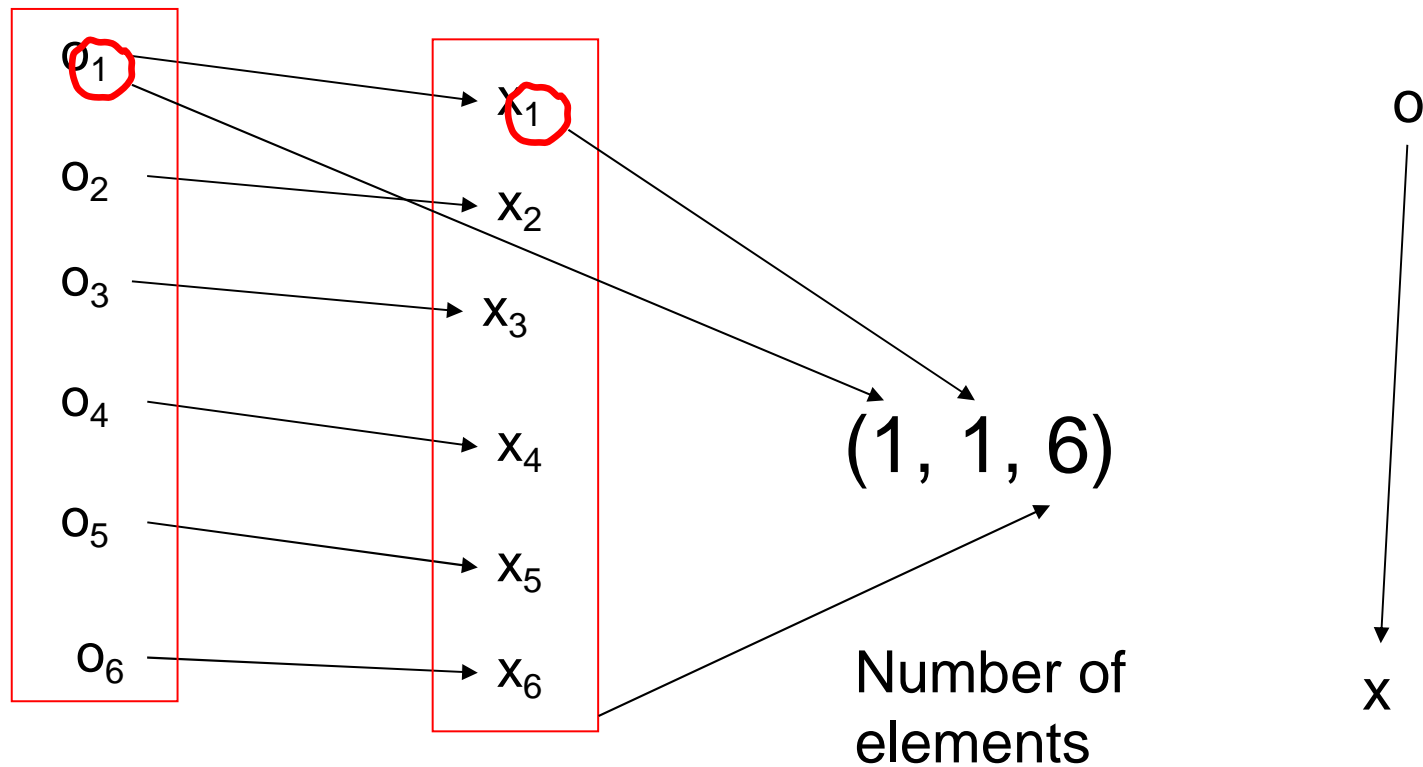




# Geometric Encoding



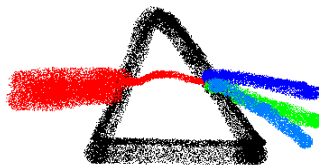
# Geometric Encoding



# Geometric Encoding

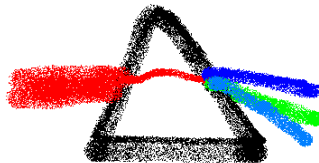


How can we do reachability analysis with the flow graph compressed by geometric encoding?



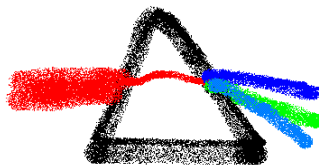
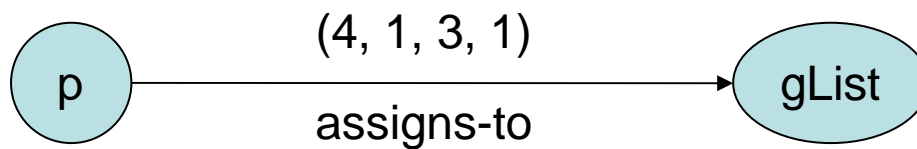
# Inference Rules

- Pointer assignment:



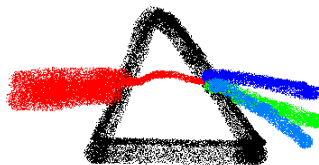
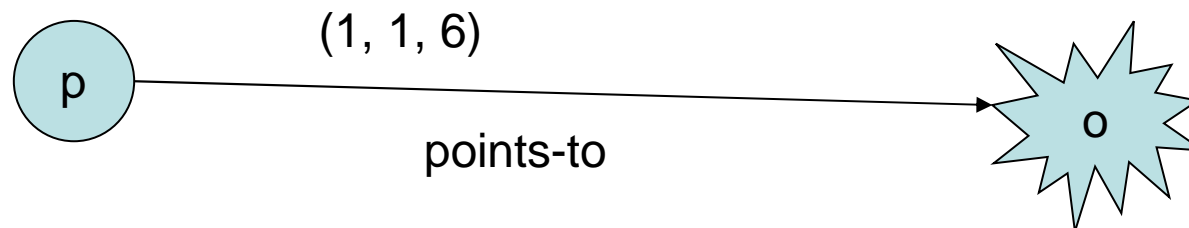
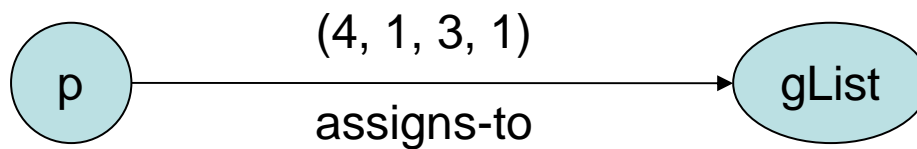
# Inference Rules

- Pointer assignment:



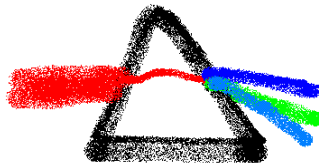
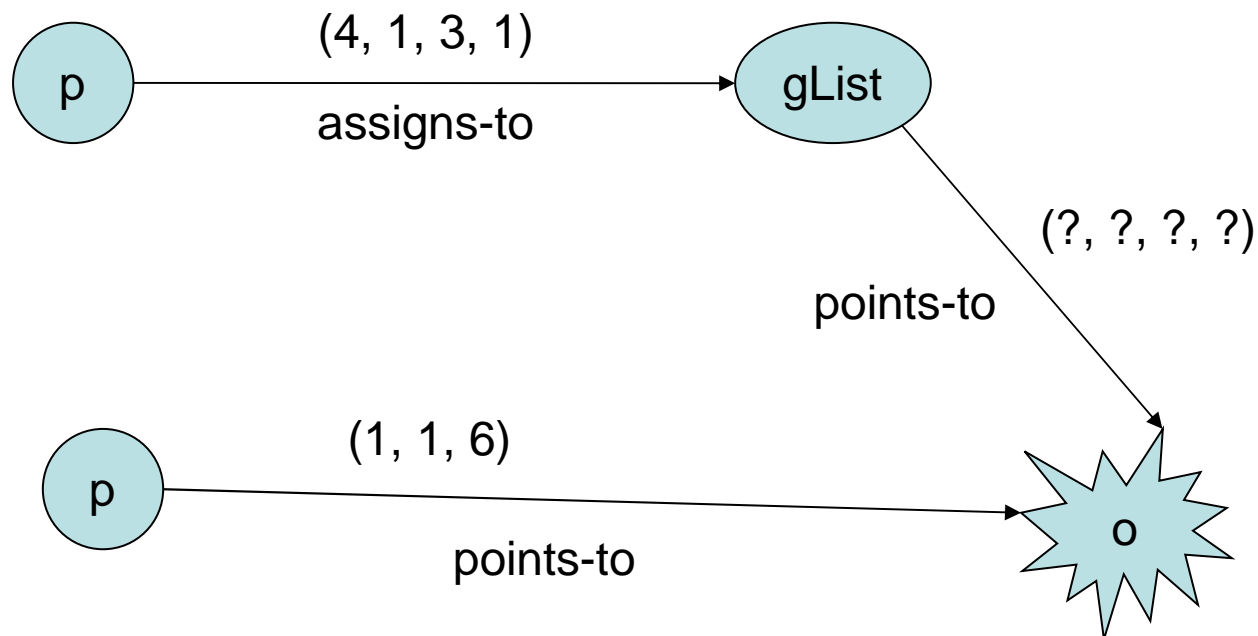
# Inference Rules

- Pointer assignment:

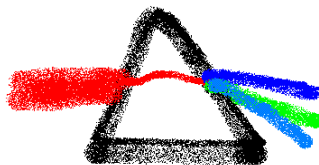
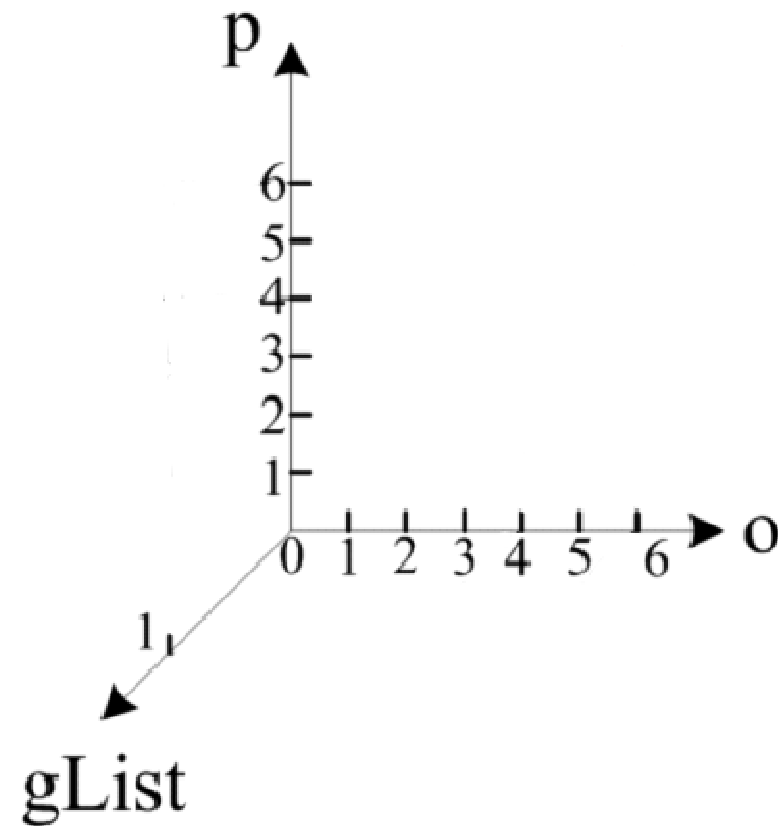


# Inference Rules

- Pointer assignment:

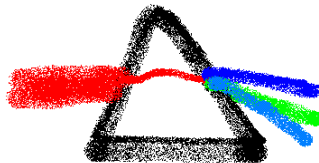
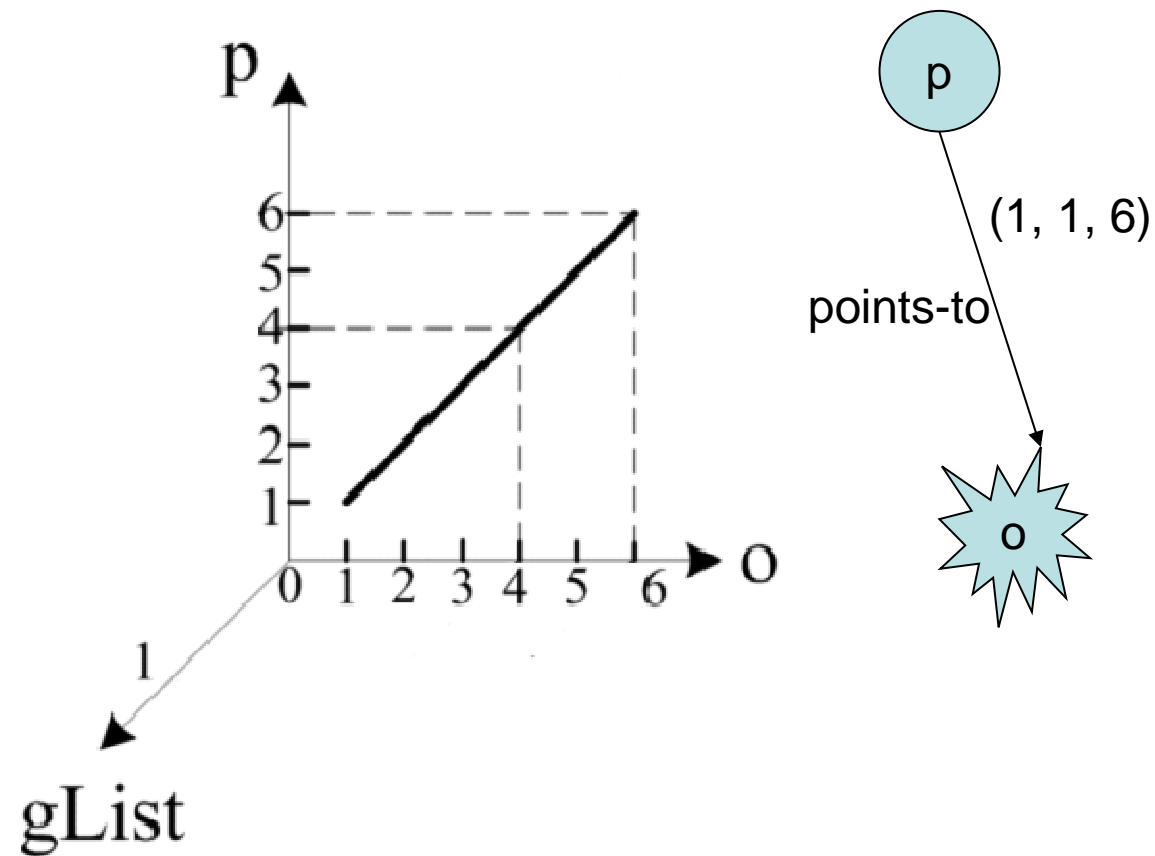


# Inference Rules

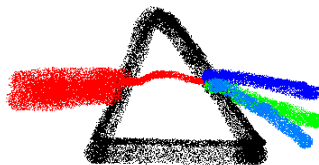
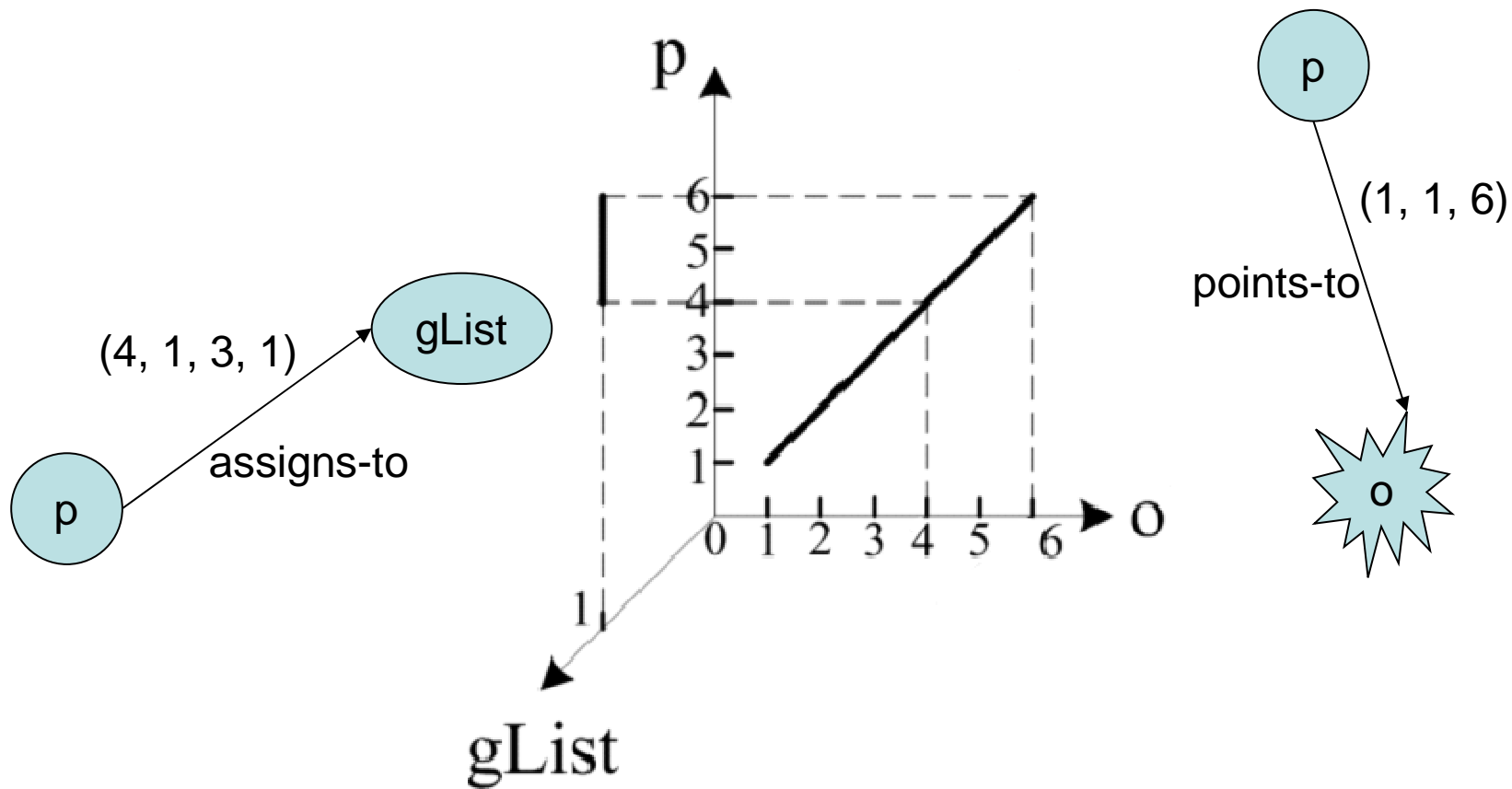




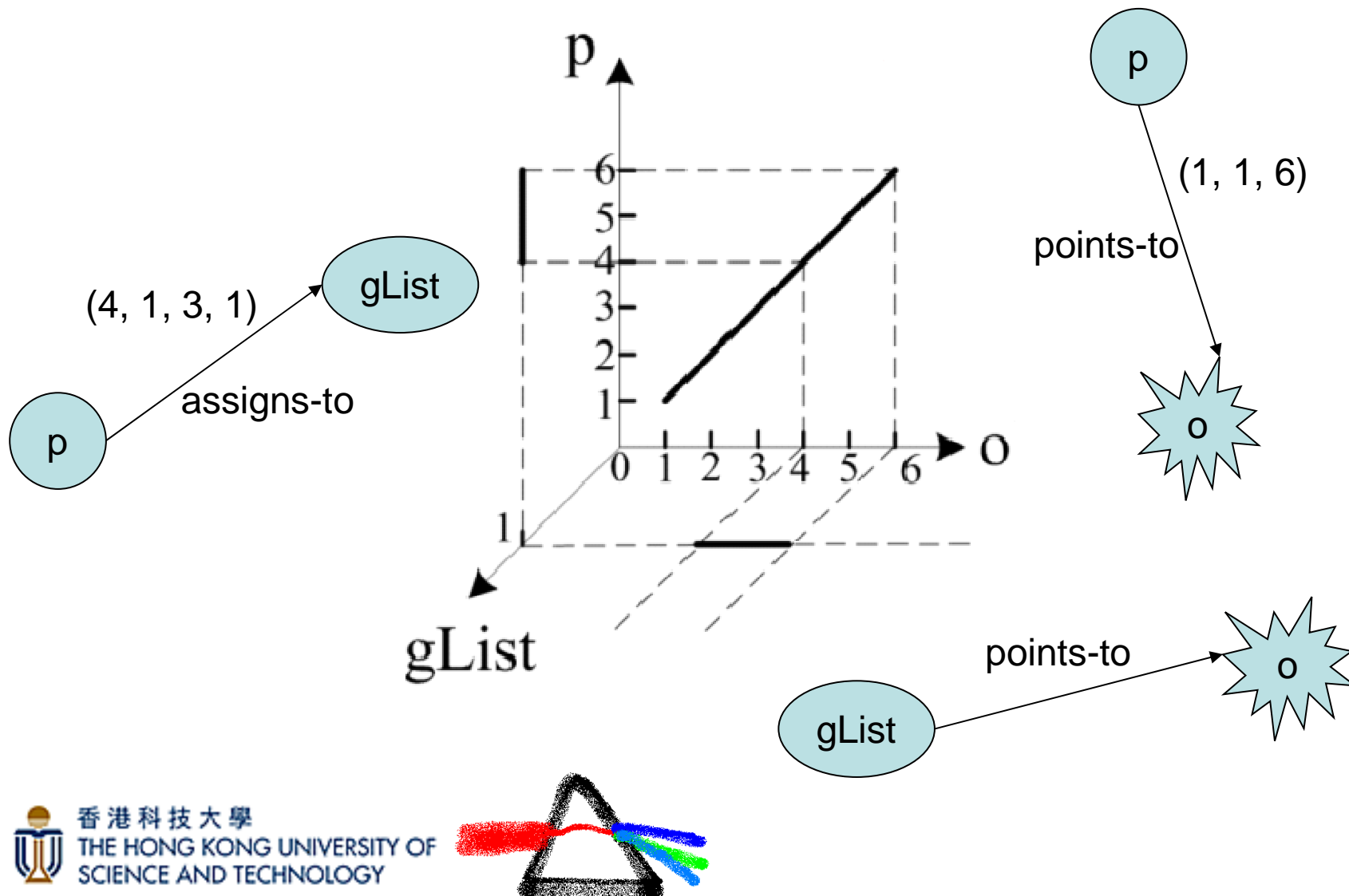
# Inference Rules



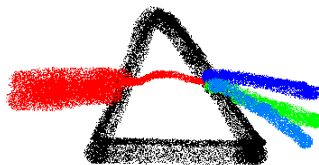
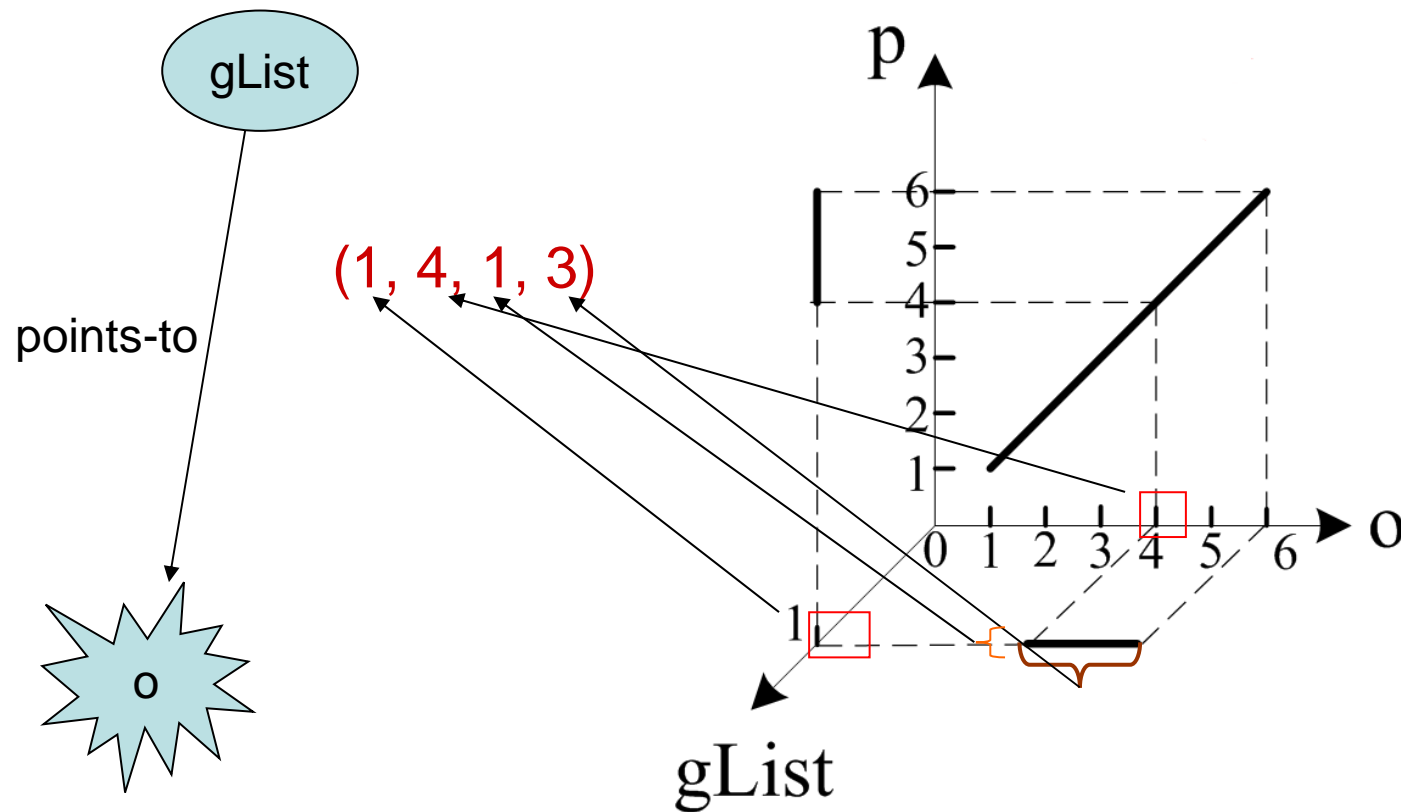
# Inference Rules



# Inference Rules

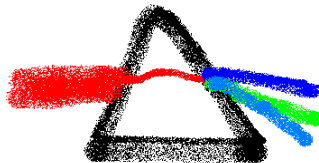


# Inference Rules

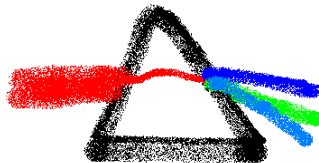
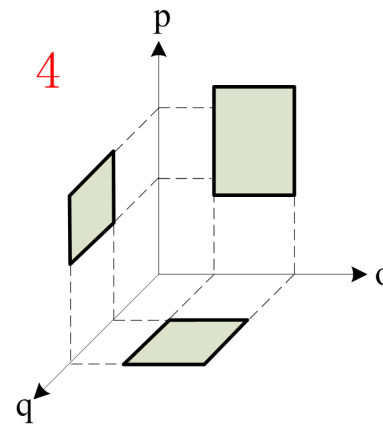
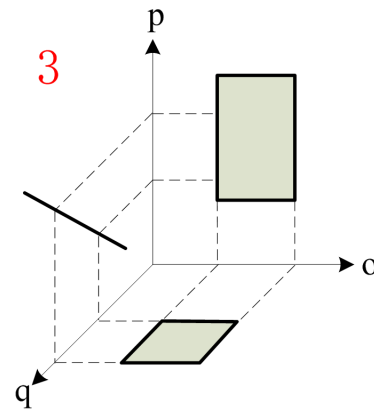
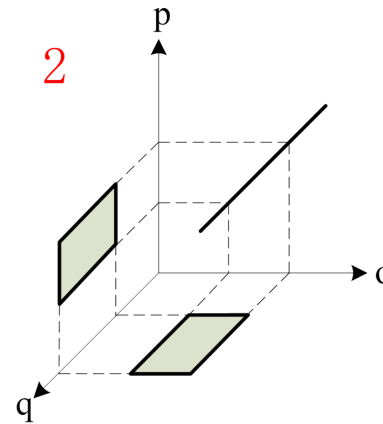
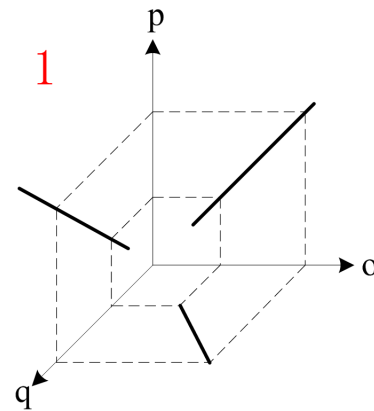


# Inference Rules

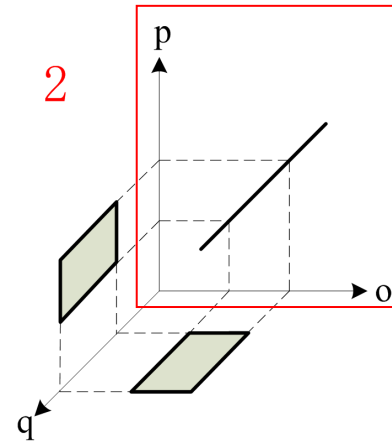
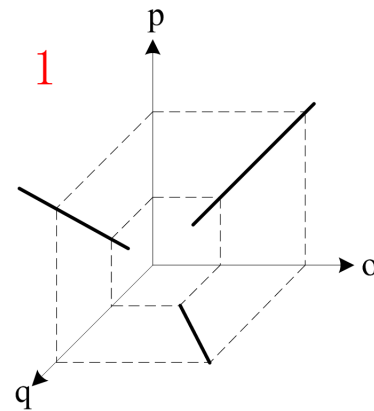
- Pointer assignment inference problem:
  - Input:  $p = q, p \rightarrow o$
  - Infer:  $q \rightarrow o$



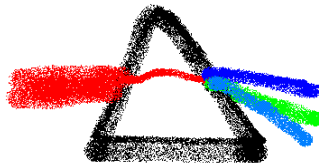
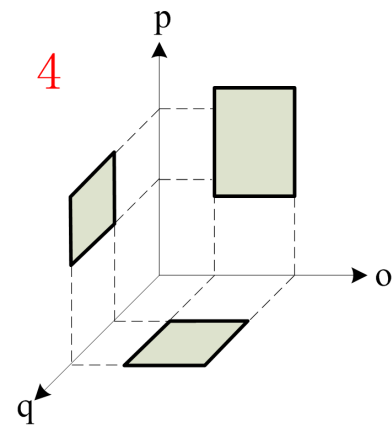
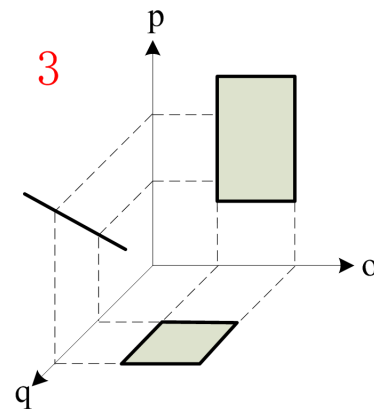
# Inference Rules



# Inference Rules

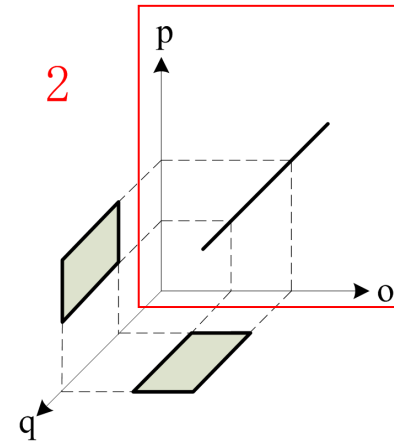
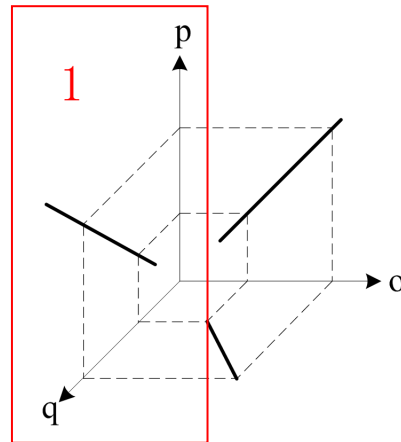


p points-to o

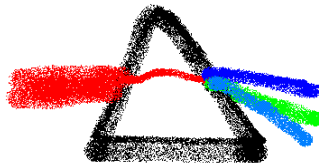
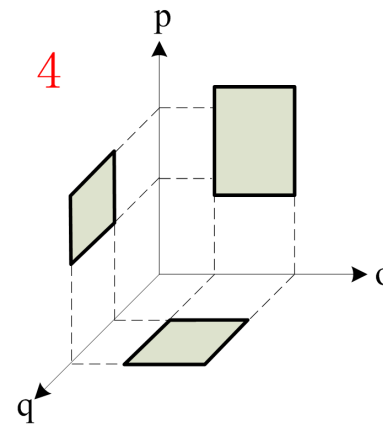
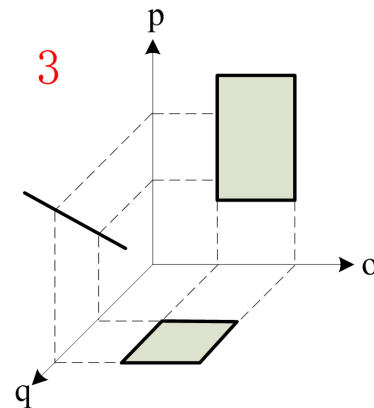


# Inference Rules

p assigns-to q



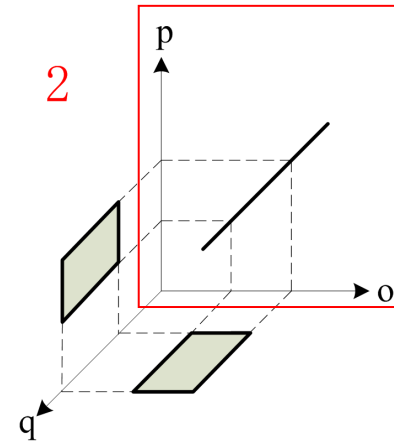
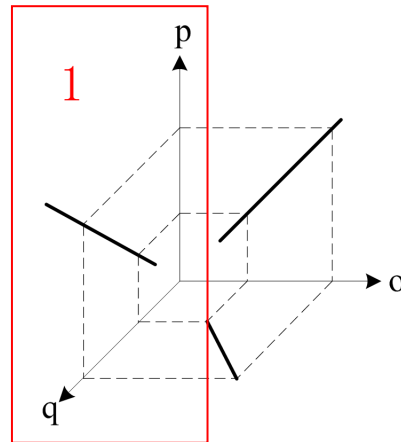
p points-to o



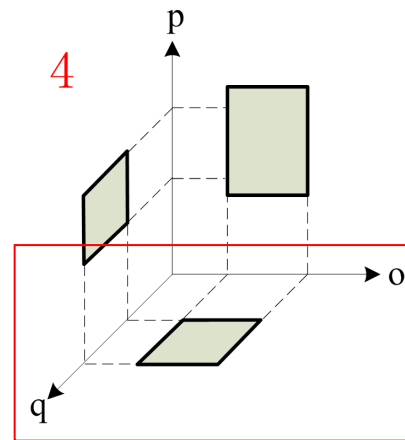
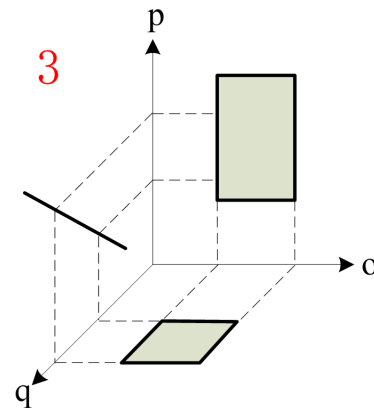


# Inference Rules

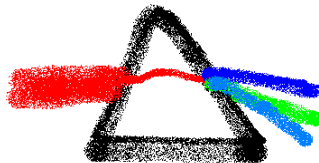
p assigns-to q



p points-to o

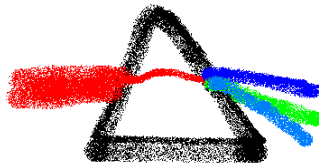


q points-to o



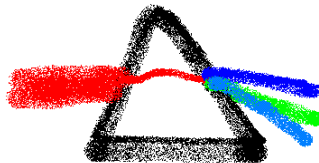
# Inference Rules

- Pointer Dereference:
  - a.k.a complex constraints instantiation
  - e.g.  $p = q.f$
- Please read our paper for details...



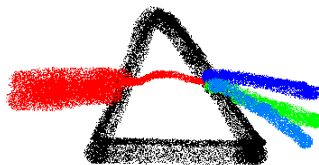
# Experiment

- Questions:
  - Performance?
  - Precision?



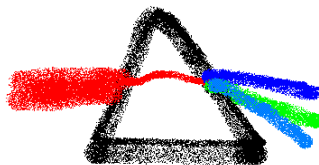
# Experimental Configuration

- Evaluated algorithm:
  - Two encoding instances: *Geom* and *HeapIns*
- State of the art:
  - Paddle 1-Object Sensitivity
  - Both BDD and worklist based
- Execution environment:
  - Soot 2.4.0
  - JDK 1.3.1\_20 (analysis library)
  - JRockit 28.1 (backbone our algorithms and Paddle)
  - Intel Xeon 3.0 G
  - 15G RAM



# Benchmark

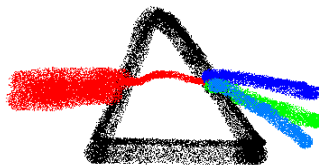
Program	#Contexts	#Methods	Max SCC
jetty	$1.1 \times 10^7$	2464	853
jlex	$2.6 \times 10^7$	2534	875
jasmin	$1.5 \times 10^7$	2695	854
polyglot	$1.1 \times 10^7$	2453	857
javacup	$3.3 \times 10^7$	2757	904
jflex	$3.9 \times 10^{11}$	4081	951
soot	$1.5 \times 10^{11}$	4697	965
sablecc	$1.0 \times 10^{11}$	9070	1572
antlr	$2.1 \times 10^{11}$	3141	910
bloat	$4.5 \times 10^{10}$	5696	1847
ps	$1.6 \times 10^{10}$	5660	1419
pmd	$> 9.2 \times 10^{18}$	3556	887
gython	$3.1 \times 10^{17}$	4231	1408
jedit	$8.3 \times 10^8$	10266	4965
megamek	$8.1 \times 10^{12}$	14330	1635



# Benchmark

- The number of contexts is very large!
- $9.2 \times 10^{18} = 2^{63}$

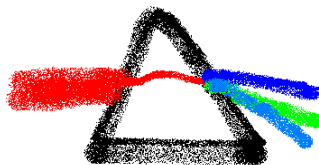
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# Benchmark

- The number of contexts is very large!
- $9.2 \times 10^{18} = 2^{63}$
- The benchmark size is also very large!

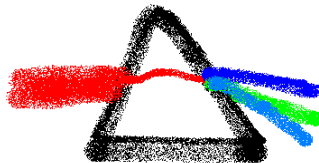
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# Performance Evaluation

Table 3: Summary of the time and memory usage for all evaluated algorithms.

Program	#Constraints	Time (s)					Memory (MB)				
		SPARK	1-obj-W	1-obj-B	HeapIns	Geom-1	SPARK	1-obj-W	1-obj-B	HeapIns	Geom-1
jetty	23447 ( $\times 1.44$ )	14.3	37.3	520.2	3.1	5.2	293	1486	460	99	115
jlex	26742 ( $\times 1.39$ )	10.8	44.8	550.5	3.8	6.6	299	1641	491	102	129
jasmin	27838 ( $\times 1.39$ )	11.8	43.3	584.5	4.6	5.5	343	1732	509	118	152
polyglot	23495 ( $\times 1.44$ )	15.5	37.9	524.2	3.0	5.3	298	1561	464	96	114
javacup	30279 ( $\times 1.35$ )	11.1	45.9	582.9	4.2	5.7	319	1792	500	220	292
jflex	41827 ( $\times 1.4$ )	19.5	95.3	1143.4	7.1	10.2	418	3928	738	241	444
soot	75209 ( $\times 1.2$ )	17.6	81.9	1226.3	12.9	18.7	410	2430	745	463	631
sablecc	117298 ( $\times 1.4$ )	36.8	119.9	1526.7	42.1	70.1	714	3588	845	1027	1561
antlr	35626 ( $\times 1.3$ )	12.6	54.4	720.0	4.4	7.4	335	1990	559	135	162
bloat	95863 ( $\times 1.15$ )	20.8	251.0	2276.1	46.0	126.7	481	5535	858	1450	2989
ps	82477 ( $\times 1.35$ )	25.0	86.4	1003.7	49.0	77.5	517	3215	676	933	1462
pmd	36120 ( $\times 1.3$ )	14.1	65.1	731.0	16.1	45.9	352	2119	579	1193	1886
pythn	52873 ( $\times 1.2$ )	17.5	150.9	1236.4	10.4	23.1	407	4139	710	242	631
jedit	119464 ( $\times 1.3$ )	43.0	7078.1	-	42.7	104.4	919	11487	-	1881	3617
megamek	207122 ( $\times 1.3$ )	77.0	14128.7	-	190.0	403.0	1799	9396	-	5807	10223

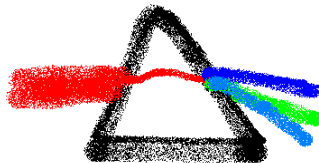




# Performance Evaluation

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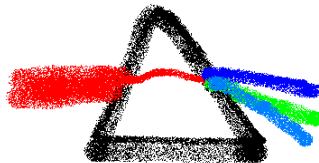
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jlex	26742 ( $\times 1.39$ )	10.8	44.8	550.5	3.8	6.6	299	1641	491	102	129
jasmin	27838 ( $\times 1.39$ )	11.8	43.3	584.5	4.6	5.5	343	1732	509	118	152
polyglot	23495 ( $\times 1.44$ )	15.5	37.9	524.2	3.0	5.3	298	1561	464	96	114
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sablecc	117298 ( $\times 1.4$ )	36.8	119.9	1526.7	42.1	70.1	714	3588	845	1027	1561
antlr	35626 ( $\times 1.3$ )	12.6	54.4	720.0	4.4	7.4	335	1990	559	135	162
bloat	95863 ( $\times 1.15$ )	20.8	251.0	2276.1	46.0	126.7	481	5535	858	1450	2989
ps	82477 ( $\times 1.35$ )	25.0	86.4	1003.7	49.0	77.5	517	3215	676	933	1462
pmd	36120 ( $\times 1.3$ )	14.1	65.1	731.0	16.1	45.9	352	2119	579	1193	1886
jython	52873 ( $\times 1.2$ )	17.5	150.9	1236.4	10.4	23.1	407	4139	710	242	631
jedit	119464 ( $\times 1.3$ )	43.0	7078.1	-	42.7	104.4	919	11487	-	1881	3617
megamek	207122 ( $\times 1.3$ )	77.0	14128.7	-	190.0	403.0	1799	9396	-	5807	10223



# Performance Evaluation

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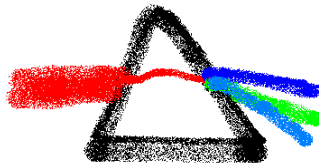
# Performance Evaluation

Table 3: Summary of the time and memory usage for all evaluated algorithms.

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HeapIns: points-to analysis with simplified geometric encoding;

Geom-1: points-to analysis with geometric encoding and context sensitive modeling for the recursive calls



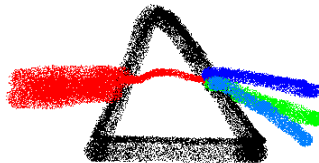
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HeapIns and Geom-1 are:

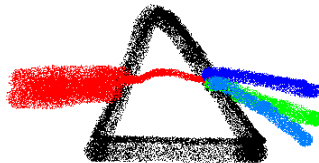
- 23.9x and 11.6x faster than 1-obj-W;
- 111x and 68.3x faster than 1-obj-B;



# Performance Evaluation

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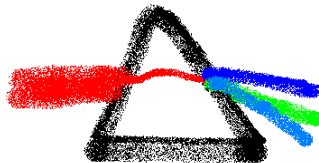
# Performance Evaluation

Table 3: Summary of the time and memory usage for all evaluated algorithms.

Program	#Constraints	Time (s)					Memory (MB)				
		SPARK	1-obj-W	1-obj-B	HeapIns	Geom-1	SPARK	1-obj-W	1-obj-B	HeapIns	Geom-1
jetty	23447 ( $\times 1.44$ )	14.3	37.3	520.2	3.1	5.2	293	1486	460	99	115
jlex	26742 ( $\times 1.39$ )	10.8	44.8	550.5	3.8	6.6	299	1641	491	102	129
jasmin	27838 ( $\times 1.39$ )	11.8	43.3	584.5	4.6	5.5	343	1732	509	118	152
polyglot	23495 ( $\times 1.44$ )	15.5	37.9	524.2	3.0	5.3	298	1561	464	96	114
javacup	30279 ( $\times 1.35$ )	11.1	45.9	582.9	4.2	5.7	319	1792	500	220	292
jflex	41827 ( $\times 1.4$ )	19.5	95.3	1143.4	7.1	10.2	418	3928	738	241	444
soot	75209 ( $\times 1.2$ )	17.6	81.9	1226.3	12.9	18.7	410	2430	745	463	631
sablecc	117298 ( $\times 1.4$ )	36.8	119.9	1526.7	42.1	70.1	714	3588	845	1027	1561
antlr	35626 ( $\times 1.3$ )	12.6	54.4	720.0	4.4	7.4	335	1990	559	135	162
bloat	95863 ( $\times 1.15$ )	20.8	251.0	2276.1	46.0	126.7	481	5535	858	1450	2989
ps	82477 ( $\times 1.35$ )	25.0	86.4	1003.7	49.0	77.5	517	3215	676	933	1462
pmd	36120 ( $\times 1.3$ )	14.1	65.1	731.0	16.1	45.9	352	2119	579	1193	1886
jython	52873 ( $\times 1.2$ )	17.5	150.9	1236.4	10.4	23.1	407	4139	710	242	631
jedit	119464 ( $\times 1.3$ )	43.0	7078.1	-	42.7	104.4	919	11487	-	1881	3617
megamek	207122 ( $\times 1.3$ )	77.0	14128.7	-	190.0	403.0	1799	9396	-	5807	10223

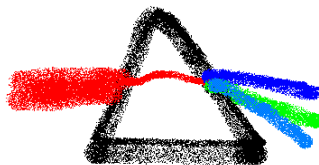
HeapIns and Geom-1 are:

- requires 9.6x and 6.7x memory than 1-obj-W.

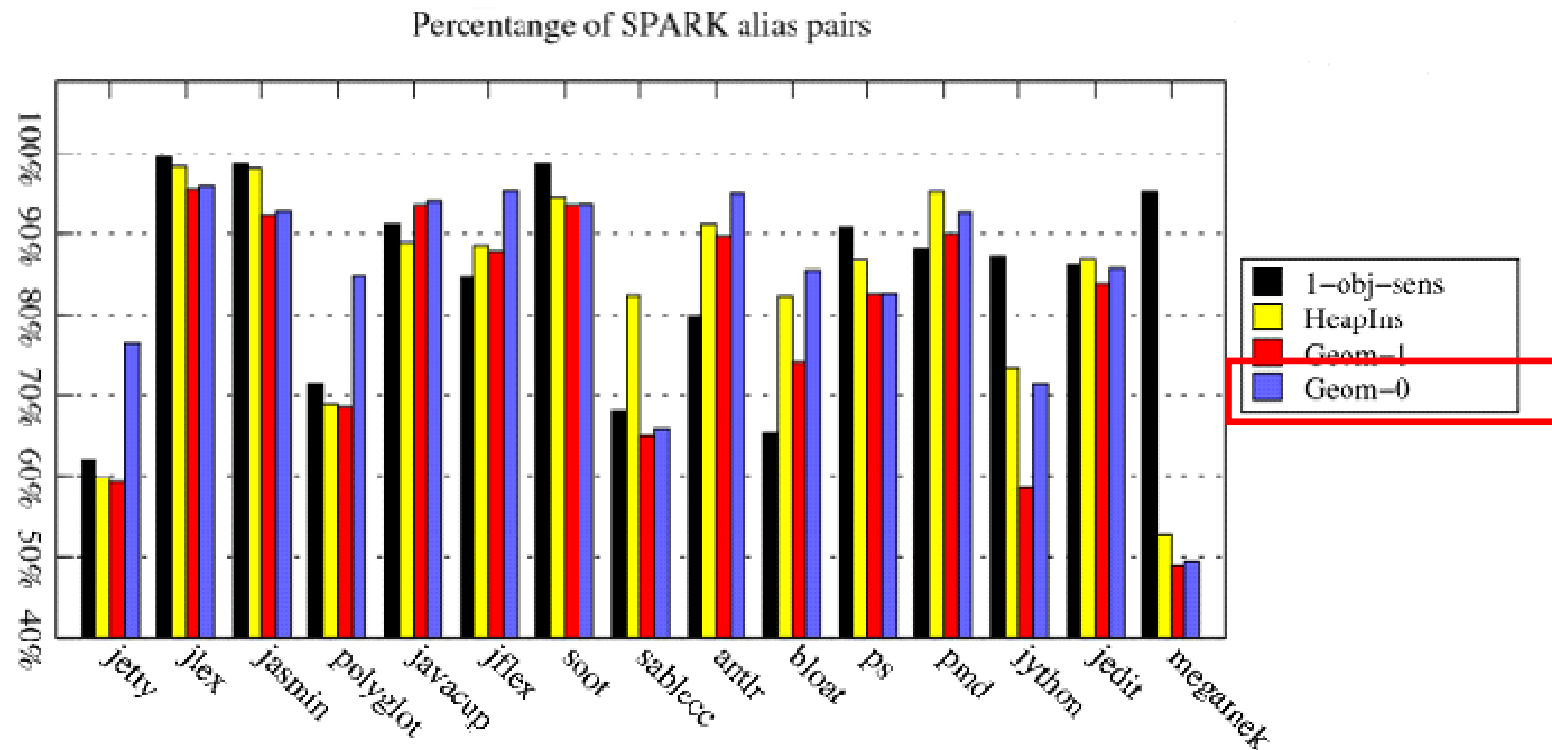


# Alias Analysis

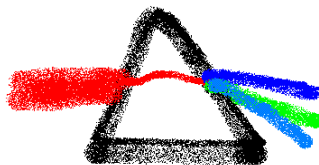
- Determine two pointers  $p$  and  $q$  may point to the same object or not;
- Improving the precision of the alias analysis is not easy.



# Alias Analysis

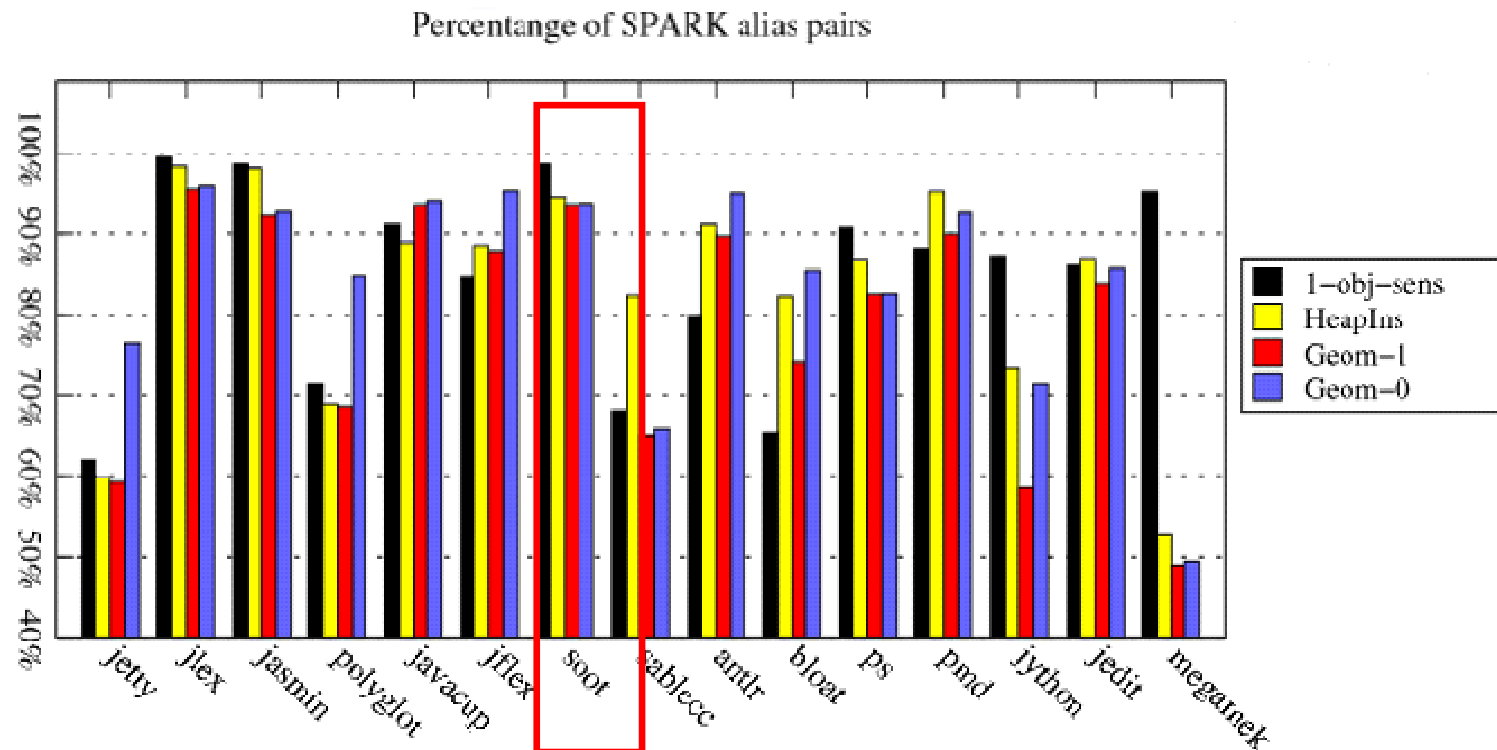


Geom-0 means the context insensitive modeling for the recursive calls.

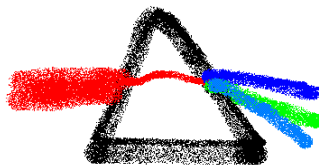




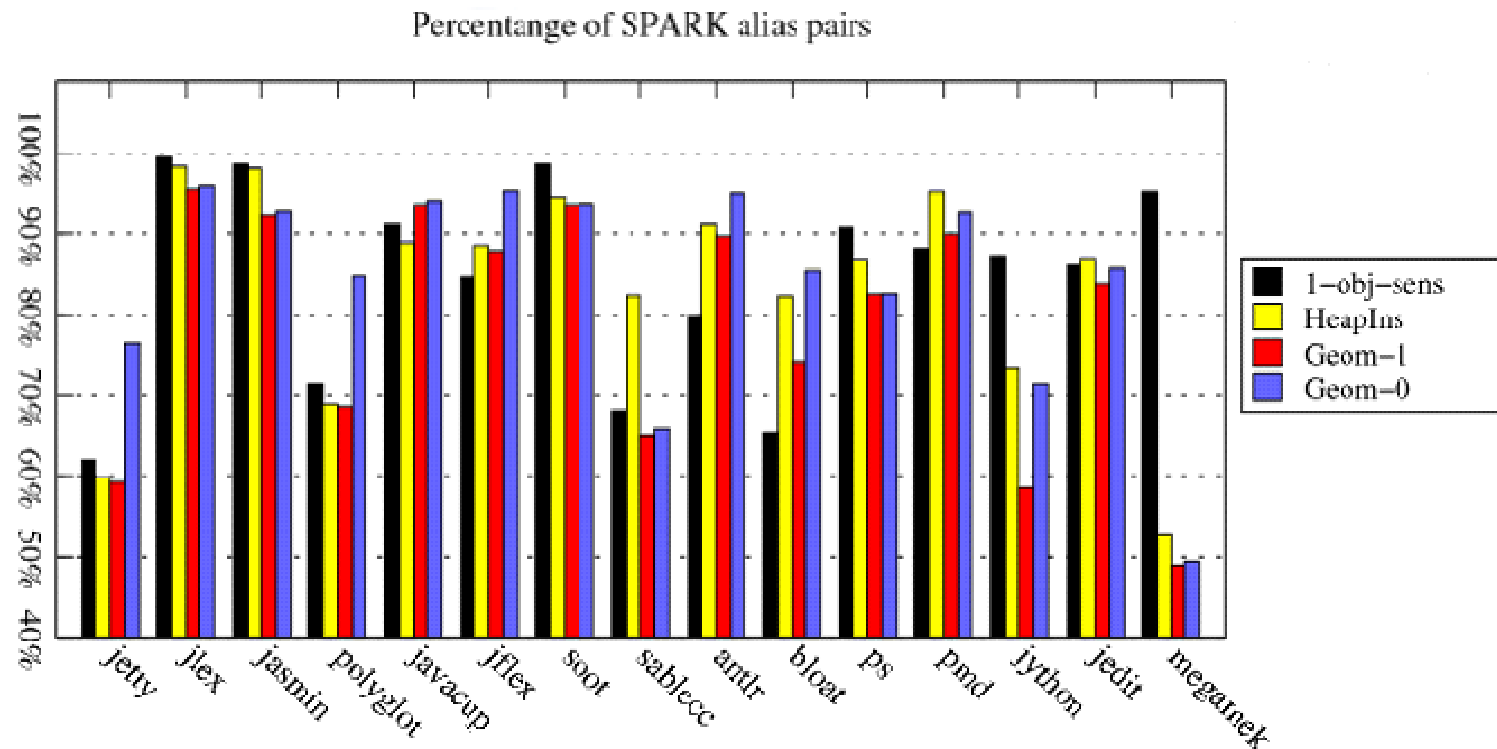
# Alias Analysis



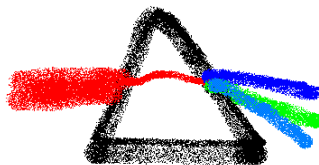
Percentage of the alias pairs computed by SPARK.  
The lower is better.



# Alias Analysis

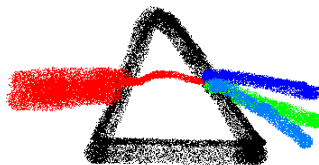


- 1-obj reduces 15.5%;
- HeapIns reduces 16.8%;
- Geom-1 reduces 21.2%.



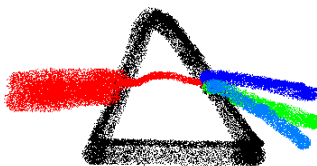
# Summary

- New data representation:
  - We develop the geometric encoding, it has good compression rate for the working data of the points-to analysis.



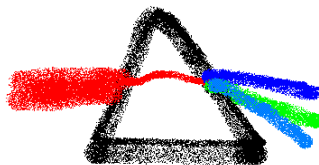
# Summary

- Soundness:
  - Geometric encoding has a sound calculating system for context sensitive points-to analysis.



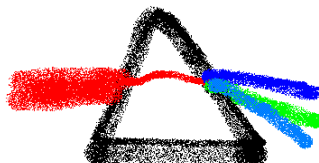
# Summary

- Easy to work with:
  - The complexity of writing a points-to analysis with geometric encoding is not too high.



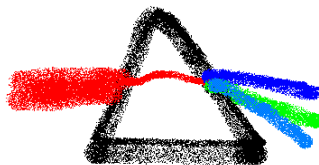
# Summary

- Good performance:
  - Geometric encoding based points-to analysis is 11.6x and 68.3x faster than 1-obj-W and 1-obj-B.



# Summary

- Good precision:
  - Geometric encoding based points-to analysis performs better than 1-obj-sens in alias analysis.

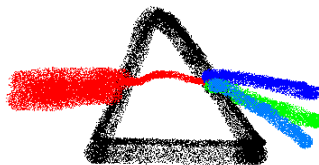


# Other Results

- More experimental results and analyses can be found in our paper;
- We are still improving our methodology. Please visit us at

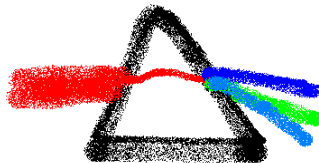
*[www.cse.ust.hk/prism](http://www.cse.ust.hk/prism)*

for up-to-date information.





# Thanks for your attention!



# Points-to Algorithm

Anderson's analysis

=

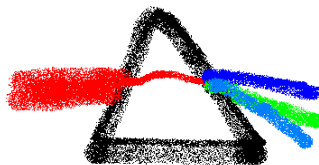
Worklist Selection

+

Points-to Propagation

+

Complex Constraints Instantiation



# Points-to Algorithm

Anderson's analysis

=

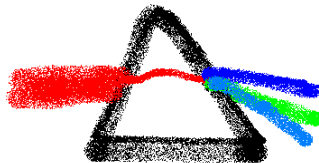
Worklist Selection

+

Points-to Propagation

+

Complex Constraints Instantiation



# Points-to Algorithm

Anderson's analysis

=

Worklist Selection

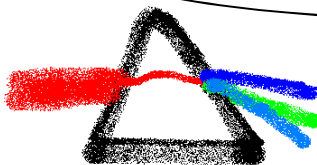
+

Points-to Propagation

+

Complex Constraints Instantiation

Geometric Encoding  
Based Inference Rules



# Points-to Algorithm

Anderson's analysis

=

Worklist Selection

+

Points-to Propagation

+

Complex Constraints Instantiation

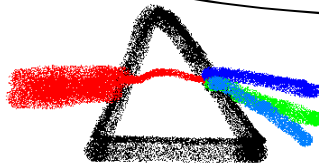
Our Context Sensitive Points-to  
Analysis

=

Worklist Selection

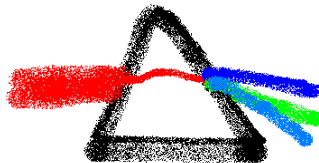
+

Geometric Encoding  
Based Inference Rules



# Other Characteristics

- With geometric encoding:
  - Context sensitive model for the recursive calls;
  - Simplified geometric encoding (HeapIns);
  - Parameters to control the analysis time.



# Other Characteristics

- Compared to EPA [ISSTA 08]:
  - We have the same compression capability with EPA;
  - We can handle global pointer correctly without trading-off precision.

