

Benefits



- Even if one thread is blocked other threads can continue execution
- Resource sharing
 - Sharing memory & other resources of the process it belongs to
- Economy
 - It is more economical to create & context switch threads
- Scalability: Utilization of multiprocessor architectures
 - Increases multi threading (threads can run parallel)
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- Takes less time to
 - Create a new thread than a process
 - Terminate a thread than a process
 - Switch between two threads within the same process
- Since threads within the same process share memory and files, they can communicate with each other without invoking the kernel





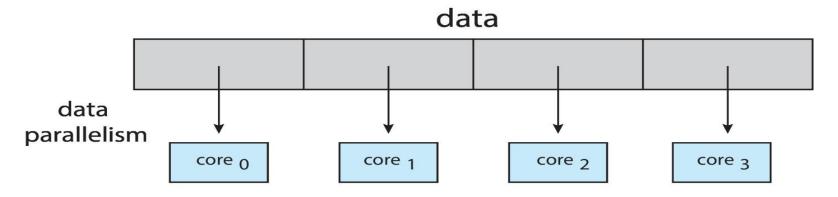
- Multicore or multiprocessor systems putting pressure on programmers, challenges include:
 - Dividing activities, Balance, Data splitting, Data dependency, Testing and debugging
- Parallelism implies a system can perform more than one task simultaneously
- Concurrency supports more than one task making progress
 - Single processor / core, scheduler providing concurrency

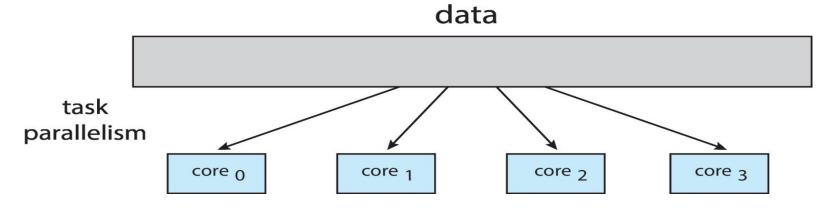


Multi-core programming

- Types of parallelism
 - Data parallelism distributes subsets of the same data across multiple cores, same operation on each
 - Task parallelism distributing threads across cores, each thread performing unique operation

Data and Task Parallelism







- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS



- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- API specifies behavior of the thread library, implementation is up to development of the library
 - Only Specification NOT the Implementation
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)



Thread Example Program

```
#include<pthread.h>
#include<stdio.h>
int sum;
void *runner(void *param);
int main(int argc,char *argv[])
   printf("Main Thread:The pid is
          %d\n",getpid());
   printf("Main thread:The tid is
          %u\n",pthread self());
   pthread t tid;
   pthread attr tattr;
   pthread attr init(&attr);
   pthread create(&tid,&attr, runner,
argv[1]);
   pthread join(tid, NULL);
   printf("Main: sum= %d\n",sum);
```

```
void *runner ( void *param )
 int upper=atoi(param);
  int i; sum=0;
  printf("New Thread: The pid is
          %d\n",getpid());
  printf("New Thread: The tid is
          %u\n",pthread self());
  if (upper>0)
  { for ( i=1; i <= upper; i++ )</pre>
         sum = sum + i; } }
  printf("New Thread: sum = %d
          n",sum);
  pthread exit(0);
```

Thread Example Program

```
#include<pthread.h>
#include<stdio.h>
#include<asm/unistd.h>
int sum;
void *runner(void *param);
nt main(int argc,char *argv[])
 printf("Main Thread: TID self =%u,
TID=%d,PID=%d\n",pthread self(),
syscall(__NR_gettid),getpid());
  pthread t tid;
  pthread attr tattr;
  pthread attr init(&attr);
  pthread create(&tid,&attr, runner,
argv[1]);
  pthread join(tid, NULL);
  printf("Main: sum= %d\n",sum);
```

```
void *runner ( void *param )
{ int upper=atoi(param);
  int i; sum=0;
   printf("New Thread: TID self=
%u,TID=%d, PID=%d\n",
pthread_self(), syscall(__NR_gettid),
getpid());
  if (upper>0)
  { for ( i=1; i <= upper; i++ )</pre>
          sum = sum + i; } }
  printf("New Thread: sum = %d
          n'',sum);
  pthread exit(0);
```

```
#include<pthread.h>
#include<stdio.h>
int sum;
void *runner ( void *param );
int main (int argc, char *argv[])
   pthread t tid1, tid2;
   pthread attr tattr;
   pthread attr init(&attr);
   pthread create(&tid1, &attr,
          runner, argv[1]);
   pthread create(&tid2, &attr,
          runner, argv[2]);
   pthread join(tid1, NULL);
   pthread join(tid2, NULL);
   printf( "sum = %d \n", sum);
```

```
void *runner ( void *param )
   int upper = atoi (param);
  int i; sum=0;
   if (upper > 0)
         for ( i=1; i <= upper; i++ )
            sum = sum + i; }
  printf(" The i value is %d and
         the sum value is %d\n",i,
         sum);
   pthread exit(0);
```