

Extra Homework – Optional

Due date: April 4, 2024

This homework is optional. You can receive a full grade for the course without completing this homework.

If you choose to submit a report for this homework, you will receive a grade. If superior to any of the grades you have obtained for HW1-4, it will replace the lowest of these grades.

In HW3, you have developed a general purpose solver for systems of ODEs of the form

$$\begin{cases}
\frac{d\mathbf{U}(t)}{dt} = \mathbf{F}(t, \mathbf{U}(t)) \\
\mathbf{U}(0) = \mathbf{U}_0
\end{cases}$$
(1)

and applied it to the solution of the semi-discrete problem

$$\begin{cases}
\frac{d\mathbf{U}(t)}{dt} = \mathbf{A}\mathbf{U}(t) \\
\mathbf{U}(0) = \mathbf{U}_0
\end{cases}$$
(2)

with $\mathbf{A} = -a\mathbf{D}$ a constant-coefficient matrix and with \mathbf{D} a discrete differential operator. This semi-discrete problem produces an approximate solution to the linear 1D advection problem

$$\begin{cases}
\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0 \\
u(x,0) = u_0(x)
\end{cases}$$
(3)

In your code from HW3, the system of equations (2) is solved using a ready-made Initial Value Problem (IVP) solver (e.g., SciPy's solve_ivp, or Matlab's ode45 function). An example of such code is provided at the end of this document.

In this assignment, you will be asked to write your own implementation of an IVP solver that is an explicit discrete time integrator. This function, in effect, will discretize the temporal space [0,T] into M time instances separated by a timestep Δt , and compute $\mathbf{U}(t+\Delta t)$ as

$$\mathbf{U}(t + \Delta t) = \mathbf{U}(t) + \mathbf{G}(t, \Delta t, \mathbf{U}(t)) \tag{4}$$

where $\mathbf{G}(t, \Delta t, \mathbf{U}(t))$ is the approximation of $\mathbf{F}(t, \mathbf{U}(t))$ integrated from t to $t + \Delta t$,

$$\mathbf{G}(t, \Delta t, \mathbf{U}(t)) \simeq \int_{t}^{t+\Delta t} \mathbf{F}(t, \mathbf{U}(t)) dt$$
(5)

hence the name "discrete time integrator". For instance, the trivial approximation

$$\mathbf{G}(t, \Delta t, \mathbf{U}(t)) = \mathbf{F}(t, \mathbf{U}(t)) \, \Delta t \tag{6}$$

leads to the first-order (forward) Euler method.

Problem 1 · In your code from HW3, replace the IVP solver by your own implementation of an explicit time integrator. This explicit time integrator must be able to consider the following schemes:

• Euler:

$$\mathbf{G}(t, \Delta t, \mathbf{U}(t)) = \mathbf{F}(t, \mathbf{U}(t)) \Delta t$$

• Runge-Kutta 2 (RK2):

$$k_1 = \mathbf{F}(t, \mathbf{U}(t))$$

$$k_2 = \mathbf{F}(t + \Delta t, \mathbf{U}(t) + k_1 \Delta t)$$

$$\mathbf{G}(t, \Delta t, \mathbf{U}(t)) = \left(\frac{k_1 + k_2}{2}\right) \Delta t$$

• Runge-Kutta 3 (RK3):

$$\begin{aligned} k_1 &= \mathbf{F}\left(t, \mathbf{U}(t)\right) \\ k_2 &= \mathbf{F}\left(t + \Delta t, \mathbf{U}(t) + k_1 \Delta t\right) \\ k_3 &= \mathbf{F}\left(t + \Delta t/2, \mathbf{U}(t) + (k_1 + k_2) \Delta t/4\right) \\ \mathbf{G}\left(t, \Delta t, \mathbf{U}(t)\right) &= \left(\frac{k_1 + k_2 + 4k_3}{6}\right) \Delta t \end{aligned}$$

• Runge-Kutta 4 (RK4): (this scheme is only required for 4 credit-hours students)

$$k_1 = \mathbf{F}(t, \mathbf{U}(t))$$

$$k_2 = \mathbf{F}(t + \Delta t/2, \mathbf{U}(t) + k_1 \Delta t/2)$$

$$k_3 = \mathbf{F}(t + \Delta t/2, \mathbf{U}(t) + k_2 \Delta t/2)$$

$$k_4 = \mathbf{F}(t + \Delta t, \mathbf{U}(t) + k_3 \Delta t)$$

$$\mathbf{G}(t, \Delta t, \mathbf{U}(t)) = \left(\frac{k_1 + 2k_2 + 2k_3 + k_4}{6}\right) \Delta t$$

<u>Solution</u>: See code attached in the appendix.

Problem 2 · For each of the schemes listed in Problem 1:

Q2.1 \rightarrow Derive the stability condition for the explicit time integration of the system of ODEs (2), i.e., when $\mathbf{F}(t, \mathbf{U}(t)) = \mathbf{A}\mathbf{U}(t)$. This stability condition will be a function of $\Delta t \lambda_n$, with λ_n the *n*th eigenvalue of \mathbf{A} .

 $Q2.2 \to Plot$ the corresponding stability region in the $(\Delta t \mathbb{R}e(\lambda_n), \Delta t \mathbb{I}m(\lambda_n))$ plane.

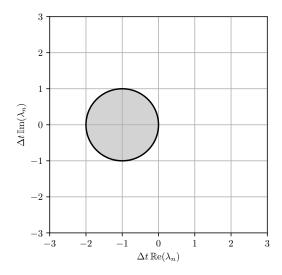
For instance: the stability condition for the first-order forward Euler scheme reads as

$$|1 + \Delta t \lambda_n| \le 1, \quad \forall n$$

and its corresponding stability region can be plotted with the Python code

```
import matplotlib.pyplot as plt
import numpy as np
s = np.linspace(-3,3,100,endpoint=True); re, im = np.meshgrid(s, s)
dt_lambda = re+im*1j
plt.contourf(re,im,np.abs(1+dt_lambda), [0,1], colors='lightgray')
plt.contour(re,im,np.abs(1+dt_lambda), [1], colors='k')
plt.xlabel(r'$\Delta t\,\mathrm{Re}(\lambda_n)$')
plt.ylabel(r'$\Delta t\,\mathrm{Im}(\lambda_n)$')
plt.grid()
plt.show()
```

which produces the following figure:



Solution:

Euler

$$w_n^{m+1} = w_n^m + \Delta t \lambda_n w_n^m = w_n^m (1 + \lambda_n \Delta t)$$
$$\sigma_n = 1 + \lambda_n \Delta t \quad \text{and} \quad |\sigma_n| \le 1$$
$$|1 + \lambda_n \Delta t| \le 1$$

Runge-Kutta 2

$$k_1 = \lambda_n w_n^m$$

$$k_2 = \lambda_n \left(w_n^m + k_1 \Delta t \right) = w_n^m \left(\lambda_n + \lambda_n^2 \Delta t \right)$$

$$w_n^{m+1} = w_n^m + \frac{\Delta t}{2} \left(\lambda_n w_n^m + w_n^m \left(\lambda_n + \lambda_n^2 \Delta t \right) \right)$$

$$= w_n^m \left(1 + \lambda_n \Delta t + \frac{1}{2} \left(\lambda_n \Delta t \right)^2 \right)$$

$$1 \ge |\sigma_n| = |1 + \lambda_n \Delta t + \frac{1}{2} \left(\lambda_n \Delta t \right)^2 |$$

Runge-Kutta 3

$$k_1 = \lambda_n w_n^m$$

$$k_2 = \lambda_n \left(w_n^m + k_1 \Delta t \right) = w_n^m \left(\lambda_n + \lambda_n^2 \Delta t \right)$$

$$k_3 = \lambda_n \left(w_n^m + \frac{k_1 + k_2}{4} \Delta t \right)$$

$$= w_n^m \left(\lambda_n + \frac{1}{2} \lambda_n^2 \Delta t + \frac{1}{4} \lambda_n^3 \Delta t^2 \right)$$

$$w_n^{m+1} = w_n^m + \frac{k_1 + k_2 + 4k_3}{6} \Delta t$$

$$= w_n^m \left(1 + \lambda_n \Delta + \frac{1}{2} \left(\lambda_n \Delta t \right)^2 + \frac{1}{6} \left(\lambda_n \Delta t \right)^3 \right)$$

$$1 \le |\sigma_n| = |1 + \lambda_n \Delta + \frac{1}{2} \left(\lambda_n \Delta t \right)^2 + \frac{1}{6} \left(\lambda_n \Delta t \right)^3 |$$

Runge-Kutta 4

$$k_{1} = \lambda_{n} w_{n}^{m}$$

$$k_{2} = \lambda_{n} \left(w_{n}^{m} + \frac{k_{1}}{2} \Delta t \right)$$

$$= w_{n}^{m} \left(\lambda_{n} + \frac{1}{2} \lambda_{n}^{2} \Delta t \right)$$

$$k_{3} = \lambda_{n} \left(w_{n}^{m} + \frac{k_{2}}{2} \Delta t \right)$$

$$= w_{n}^{m} \left(\lambda_{n} + \frac{1}{2} \lambda_{n}^{2} \Delta t + \frac{1}{4} \lambda_{n}^{3} \Delta t^{2} \right)$$

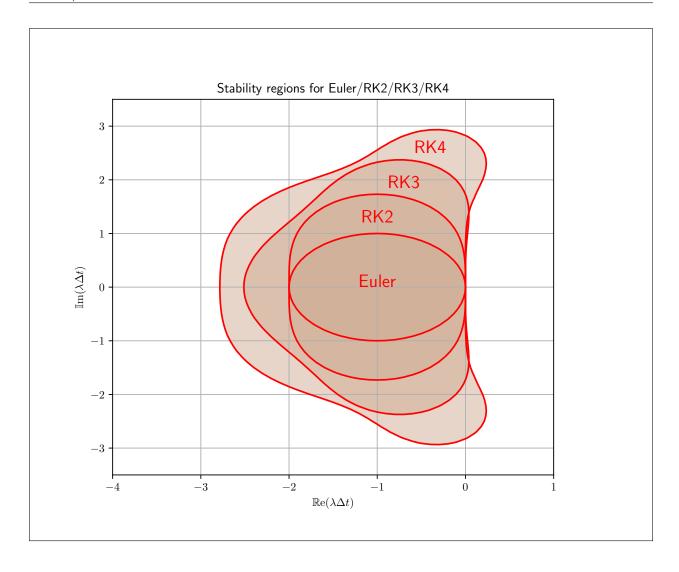
$$k_{4} = \lambda_{n} \left(w_{n}^{m} + k_{3} \Delta \right)$$

$$= w_{n}^{m} \left(\lambda_{n} + \lambda_{n}^{2} \Delta t + \frac{1}{2} \lambda_{n}^{3} \Delta t^{2} + \frac{1}{4} \lambda_{n}^{4} \Delta t^{3} \right)$$

$$w_{n}^{m+1} = w_{n}^{m} + \frac{k_{1} + 2k_{2} + 2k_{3} + k_{4}}{6} \Delta t$$

$$= w_{n}^{m} \left(1 + \lambda_{n} \Delta t + \frac{1}{2} \left(\lambda_{n} \Delta t \right)^{2} + \frac{1}{6} \left(\lambda_{n} \Delta t \right)^{3} + \frac{1}{24} \left(\lambda_{n} \Delta t \right)^{4} \right)$$

$$1 \leq |\sigma_{n}| = |1 + \lambda_{n} \Delta t + \frac{1}{2} \left(\lambda_{n} \Delta t \right)^{2} \frac{1}{6} \left(\lambda_{n} \Delta t \right)^{3} + \frac{1}{24} \left(\lambda_{n} \Delta t \right)^{4} |$$



Problem 3 · Consider the periodic advection of a Gaussian pulse with the constant wavespeed a = 1, domain length L = 1, final time T = 30, $N_x = 50$ discrete grid points, and the initial condition

$$u_0(x) = \exp\left(\frac{-\left(x - \frac{L}{2}\right)^2}{2\sigma^2}\right), \quad \sigma = \frac{3}{40}$$

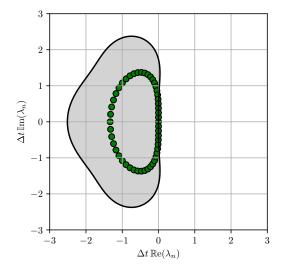
For the explicit time integration, consider the RK3 scheme with a CFL number

$$CFL = \frac{|a|\Delta t}{\Delta x} = 1$$

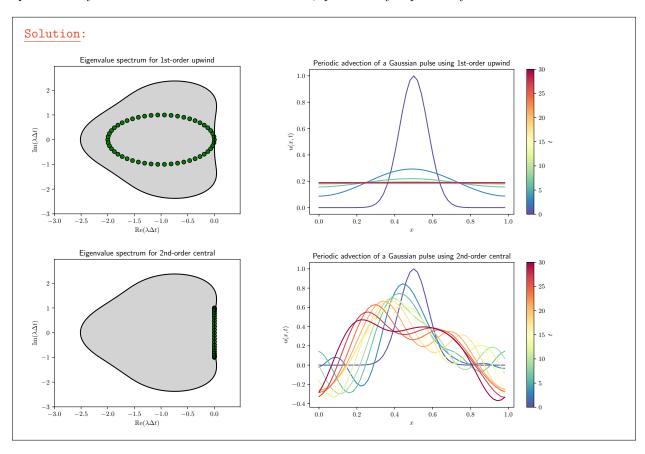
For each of the spatial schemes implemented in HW3 (i.e., first-order and third-order upwind, second-order and fourth-order central, and sixth-order Padé):

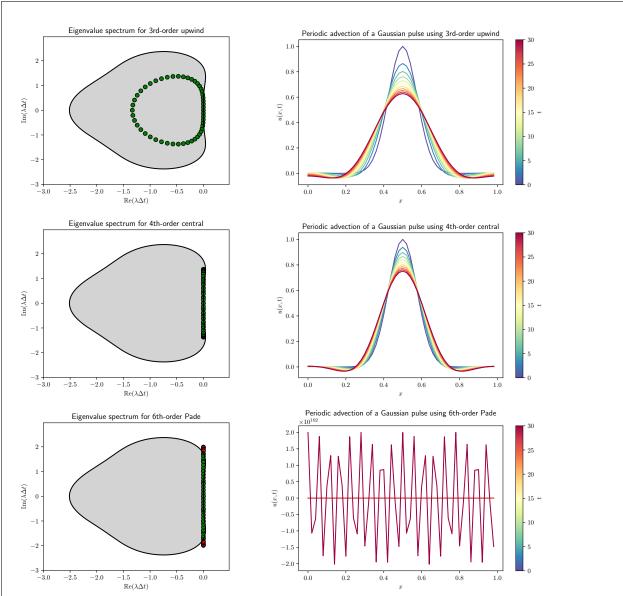
Q3.1 \rightarrow Plot the eigenvalue spectrum of the matrix $\mathbf{A} = -a\mathbf{D}$ in the $(\Delta t \mathbb{R}e(\lambda_n), \Delta t \mathbb{I}m(\lambda_n))$ plane, on top of the RK3 stability region.

 $\underline{\text{For instance:}}$ The eigenvalue spectrum of **A** for the third-order upwind scheme, plotted on top of the RK3 stability region, looks as follows:



Q3.2 \rightarrow Compare your numerical solution to the exact expected solution at the times $t_m, m \in \{3, 6, \dots, 30\}$. Q3.3 \rightarrow Are your numerical solutions stable? If not, qualitatively explain why.





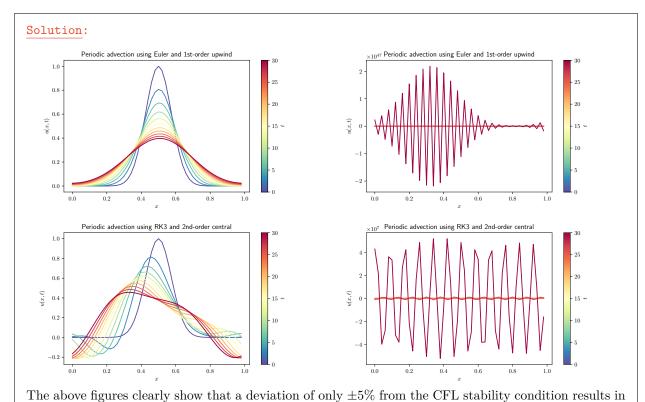
As can be seen in above figures, all spatial discretization schemes whose eigenvalues are exclusively within the stability region of the time integration scheme (here Runge-Kutta 3) are unconditionally stable, as can be seen in the unsteady solution. Only the Padé scheme has eigenvalues that lie outside the stability region and consequently grow out of bounds, which can be seen in the unsteady solution.

Problem $4 \cdot \text{In class}$, we have derived several stability conditions in the form CFL $\leq \text{CFL}_{\text{max}}$ for combinations of discrete temporal and spatial differential operators applied to the numerical solution of (2).

For instance:

- For the combination of explicit Euler (time) and 1st-order upwind (space), $CFL_{max} = 1$.
- For the combination of RK3 (time) and 2nd-order central differences (space), $CFL_{max} = \sqrt{3}$.

 $Q4 \rightarrow Solve$ the periodic advection problem described in Problem 3 with these two combinations of schemes, at $CFL = (1 \pm 0.05) \times CFL_{max}$. Are the results consistent with your expectations?



either stable or unstable simulations.

Problem $5 \cdot$ This problem is required for all students taking AE 410/CSE 461 for four credit hours. It is not required for students taking AE 410/CSE 461 for three credit hours.

 $Q5.2 \rightarrow Derive$ the expression of the stability limit CFL_{max} for the combination of RK4 (time) and 2nd-order central differences (space) applied to the system of equations (2).

 $Q5.2 \rightarrow Solve$ the periodic advection problem described in Problem 3 with this combination of schemes, at $CFL = (1 \pm 0.05) \times CFL_{max}$. Are the results consistent with your expectations?

Solution:

For central finite differences, where the eigenvalues are purely imaginary, we can write $\Delta t \lambda_n = \alpha i$ with $\alpha \in \mathbb{R}$, and the stability condition for Runge-Kutta 4 becomes

$$\begin{aligned} 1 &\leq \left| 1 + \alpha i - \frac{1}{2}\alpha^2 - \frac{1}{6}\alpha^3 i + \frac{1}{24}\alpha^4 \right| \\ &\leq \left| 1 - \frac{1}{2}\alpha^2 + \frac{1}{24}\alpha^4 + i\left(\alpha - \frac{1}{6}\alpha^3\right) \right| \\ &\leq \sqrt{\left(1 - \frac{1}{2}\alpha^2 + \frac{1}{24}\alpha^4\right)^2 + \left(\alpha - \frac{1}{6}\alpha^3\right)^2} \\ &\cdots \\ &8 &\leq \alpha^2 \\ -2\sqrt{2} &\leq \alpha \leq 2\sqrt{2} \end{aligned}$$

In other terms, if the chosen spatial discretization is neutrally stable, then the discrete time integration with Runge-Kutta 4 is stable if

$$\left| \mathbb{I}m\left(\lambda_n\right) \right| \leq \frac{2\sqrt{2}}{\Delta t}$$

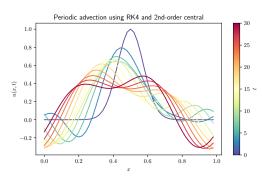
For the specific case of the second order central difference scheme, we know the analytical eigenvalues to be

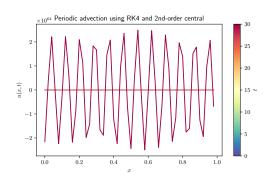
$$\lambda_n = -\frac{ai}{\Delta x} \sin\left(\frac{2\pi n}{N}\right)$$

therefore the stability condition fore the RK4 scheme becomes

$$\frac{|a|}{\Delta x} \le \frac{2\sqrt{2}}{\Delta t}$$

$$\Rightarrow \text{CFL} = \frac{|a|\Delta t}{\Delta x} \le 2\sqrt{2}$$





As can bee seen in above pictures (CFL = $0.95 \cdot \text{CFL}_{\text{crit}}$ (left), CFL = $1.05 \cdot \text{CFL}_{\text{crit}}$ (right)), the unsteady solution is only stable when the CFL number is below its critical value, as expected.

Submission guidelines · Instructions on how to prepare and submit your report are available on the course's Canvas page at https://canvas.illinois.edu/courses/43781/assignments/syllabus

Appendix · Full codes:

Python (0-based indexing)

```
# %% [markdown]
# Problem 2: Stability regions

# %%
import matplotlib.pyplot as plt
import matplotlib.lines as mlines
import matplotlib as mpl
import numpy as np
plt.rcParams['text.usetex'] = True
plt.rcParams['figure.dpi'] = 300
plt.rcParams['savefig.dpi'] = 300
plt.rcCarams['savefig.dpi'] = 300
```

```
15 VS = XS
16 X, Y = np.meshgrid(xs, ys)
17 lambda_dt = X+Y*1j
fig, ax = plt.subplots(1, 1, figsize=(7, 6))
20 plt.title('Stability regions for Euler/RK2/RK3/RK4')
   plt.xlabel(r'$\mathbb{R}\mathrm{e}(\lambda \Delta t)$');
22 plt.ylabel(r'$\mathbb{I}\mathrm{m}(\lambda \Delta t)$');
plt.contourf(X,Y,np.abs(1+lambda_dt+1/2*lambda_dt**2+1/6*lambda_dt**3+1/24*lambda_dt**4),
       [0,1], cmap='pink', alpha=.5)
24 plt.contour(X,Y,np.abs(1+lambda_dt+1/2*lambda_dt**2+1/6*lambda_dt**3+1/24*lambda_dt**4), [1],
       colors='r')
plt.contourf(X,Y,np.abs(1+lambda_dt+1/2*lambda_dt**2+1/6*lambda_dt**3), [0,1], cmap='pink',
26 plt.contour(X,Y,np.abs(1+lambda_dt+1/2*lambda_dt**2+1/6*lambda_dt**3), [1], colors='r')
   plt.contourf(X,Y,np.abs(1+lambda_dt+1/2*lambda_dt**2), [0,1], cmap='pink', alpha=.5)
  plt.contour(X,Y,np.abs(1+lambda_dt+1/2*lambda_dt**2), [1], colors='r')
29 plt.contourf(X,Y,np.abs(1+lambda_dt), [0,1], cmap='pink', alpha=.5)
plt.contour(X,Y,np.abs(1+lambda_dt), [1], colors='r')
31 plt.grid()
33 plt.text(-1,0, 'Euler', dict(size=16), horizontalalignment='center', color='r')
34 plt.text(-1,1.2, 'RK2', dict(size=16), horizontalalignment='center', color='r')
35 plt.text(-0.7,1.85, 'RK3', dict(size=16), horizontalalignment='center', color='r')
36 plt.text(-0.4,2.5, 'RK4', dict(size=16), horizontalalignment='center', color='r')
   ax.set_xlim([-4, 1])
38 ax.set_ylim([-3.5, 3.5])
39 plt.savefig('stabregions.pdf')
40 plt.show()
   # %% [markdown]
42
   # Problem 3: Explicit time integration of the 1D linear advection
43
45 # %%
   from scipy.linalg import circulant
46
47
   from scipy.integrate import solve_ivp
48
   # Operator from HW1
   def D_operator_periodic(N,L,R,a):
50
51
     first_row = np.zeros(N); first_row[0:L+R+1] = a; first_row = np.roll(first_row,-L)
     return np.array(circulant(first_row)).transpose()
52
54 # Functor for the 1D advection equation
55 def LinearAdv1D(t,U,D):
    # Initialize velocity
    a = 1
57
    # Return F(t,U)
58
     return (-a*D)@U
59
60
   # Time integrator
   def TimeIntegration(functor, scheme, time_limits, dt, U0, D, t_eval):
     # Use Python's IVP solver; see documentation at:
63
64
     # https://docs.scipy.org/doc/scipy/reference/generated/scipy.integrate.solve_ivp.html
     if scheme == 'Exact':
65
       sol = solve_ivp(functor, time_limits, U0, args=(D,), t_eval=t_eval, rtol=1.0e-6, atol=1.0e
           -6, first_step=dt)
       return sol.y.transpose()
     # Use in-house IVP solver
68
69
       # Number of timesteps
70
       Nt = int(np.ceil((time_limits[1] - time_limits[0]))/dt)+1
71
       Uold = U0
72
       \# Vector of stored solutions -- add initial condition
73
       sol = []; keval = 0
74
75
       if t_eval[keval] == time_limits[0]:
         sol.append(U0)
76
         keval = 1
77
       # Loop over all timesteps
78
```

```
for k in range(Nt):
79
         told = time_limits[0] + dt * k
         tnew = told + dt
81
         # Compute RHS at told
         rhs = functor(told, Uold, D)
83
         # Update new solution with explicit scheme
84
         match scheme:
85
          case 'Euler':
86
             Unew = Uold + dt * rhs
           case 'RK2':
88
             K1 = functor(told, Uold, D)
89
             K2 = functor(told+dt, Uold+dt*K1, D)
90
             Unew = Uold + dt*(K1+K2)/2
91
           case 'RK3':
            K1 = functor(told, Uold, D)
93
             K2 = functor(told+dt, Uold+dt*K1, D)
94
             K3 = functor(told+0.5*dt, Uold+0.5*dt*0.5*(K1+K2), D)
95
             Unew = Uold + dt*(K1+K2+4*K3)/6
96
           case 'RK4':
97
             K1 = functor(told, Uold, D)
98
             K2 = functor(told+0.5*dt, Uold+0.5*dt*K1, D)
             K3 = functor(told+0.5*dt, Uold+0.5*dt*K2, D)
100
             K4 = functor(told+dt, Uold+dt*K3, D)
101
             Unew = Uold + dt*(K1+2*K2+2*K3+K4)/6
102
         # Update stored solution vector
103
         if (keval < len(t_eval) and t_eval[keval] >= told and t_eval[keval] <= tnew):</pre>
           sol.append(Uold + (Unew - Uold) * (t_eval[keval] - told) / dt)
105
           keval += 1
106
107
         # Move to next timestep
         Uold = Unew
108
       return sol
109
110
111 # General integrator function
112
   def Integrator(periodic, operator, temporalscheme, problem, L, T, Nx, Nt, U0, dt):
     113
114
     # periodic : boolean flag to select periodicity (options: True of False)
115
     \mbox{\tt\#} operator : string to select the spatial derivative operator
     # problem : string to select the governing equations
117
             L: length of the physical domain, x runs from 0 to L
118
             T : length of the temporal domain, t runs from 0 to T
119
             Nx : number of points to use in x
120
             Nt : number of points to use in t (for reporting the solutions)
             U0 : initial condition
122
     #
123
     124
125
              t : the discrete time levels (in a vector of size Nt)
                                                                                       #
126
              U : the solutions (in a matrix of size Nt x Nx)
127
     129
130
131
     # Initialize spatial domain
     x = np.linspace(0, L, Nx, endpoint=(not periodic))
132
133
     dx = x[1] - x[0]
134
     # Initialize temporal domain
135
136
     t = np.linspace(0, T, Nt, endpoint=True)
137
     # Construct spatial matrix operator
138
     match (operator,periodic):
139
       #### All periodic cases
       case ('1st-order upwind',True):
                                          # Periodic 1st-order upwind
141
          D = D_{operator\_periodic}(Nx, 1, 0, [-1/dx, 1/dx])
142
143
       case ('2nd-order central',True):
                                           # Periodic 2nd-order central differences
          D = D_{operator_periodic(Nx,1,1,[-1/(2*dx),0,1/(2*dx)])}
144
       case ('3rd-order upwind',True):
                                           # Periodic 3rd-order upwind
           D = D_{operator\_periodic(Nx,2,1,[1/(6*dx),-1/dx,1/(2*dx),1/(3*dx)])
146
```

```
case ('4th-order central',True):
                                                                                       # Periodic 4th-order central differences
147
                      D = D_{operator\_periodic(Nx,2,2,[1/(12*dx),-8/(12*dx),0,8/(12*dx),-1/(12*dx)])
               case ('6th-order Pade',True):
                                                                                       # Periodic 6th-order Pade
149
                       DR = D_{\text{operator}} = D_{\text{
                      DL = D_{operator\_periodic(Nx,1,1,[1/3,1,1/3])}
151
                      D = np.linalg.inv(DL)@DR
152
153
           # Solve and return solutions!
154
           U = TimeIntegration(LinearAdv1D, temporalscheme, [0,T], dt, U0, D, t)
           return t, U, D
156
157
158 # %%
159 import cmath
160 from numpy import linalg as LA
161 plt.rcParams['text.usetex'] = True
162 plt.rcParams['figure.dpi'] = 300
plt.rcParams['savefig.dpi'] = 300
plt.rc('text.latex', preamble=r'\usepackage{amsmath} \usepackage{amssymb}')
166 ############ Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
       temporalscheme = 'RK3'
168 ############ Choose CFL = a*dt/dx
169 CFL = 1
171 # Initialize case parameters
172 L = 1; T = 30; Nx = 50; Nt = 11; a = 1
dx = L/Nx
_{174} dt = CFL * dx / a
^{175} # Initialize solution at t=0
x = \text{np.linspace}(0, L, Nx, \text{endpoint=False}); dx = x[1] - x[0]
sigma = 3/40; U0 = np.exp(-(x-0.5)**2/(2*sigma**2))
       # Initialize list of schemes that will be tested:
179 listofspatialschemes = ['1st-order upwind', '2nd-order central', '3rd-order upwind', '4th-
               order central', '6th-order Pade']
180
181 # Plotting the eigenvalue spectra and numerical solutions for each scheme
_{182} A = []
       for scheme in listofspatialschemes:
           # Run solver and plot solution
184
           t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0,dt)
185
           A.append(-a*D)
186
           fig, ax = plt.subplots(1, 1, figsize=(7, 4))
187
            ax.plot(x,U0,color=plt.cm.Spectral_r(0))
           for j in range(1,len(U)):
189
               ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
190
           plt.title('Periodic advection of a Gaussian pulse using %s' % scheme)
191
           plt.xlabel(r'$x$');plt.ylabel(r'$u(x,t)$');
192
           fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
           , orientation='vertical', label=r'$t$')
plt.savefig('solution-%s.pdf' % scheme)
195
           plt.show()
196
197
            # Plot stability region
           fig, ax = plt.subplots(1, 1, figsize=(5, 4))
198
199
            Ngrid = 200; xs = np.arange(-3,0.5,3.5/Ngrid); ys = np.arange(-3,3,6/Ngrid); X, Y = np.
                   meshgrid(xs, ys)
           lambda_dt = X+Y*1j
200
           match temporalscheme:
201
               case 'Euler':
202
                   ax.contourf(X,Y,np.abs(1+lambda_dt), [0,1], colors='lightgray')
203
                  ax.contour(X,Y,np.abs(1+lambda_dt), [1], colors='k')
204
               case 'RK2':
                  ax.contourf(X,Y,np.abs(1+lambda_dt+0.5*lambda_dt**2), [0,1], colors='lightgray')
206
                  ax.contour(X,Y,np.abs(1+lambda_dt+0.5*lambda_dt**2), [1], colors='k')
207
               case 'RK3':
208
                  ax.contourf(X,Y,np.abs(1+lambda_dt+0.5*lambda_dt**2+(1/6)*lambda_dt**3), [0,1], colors=1
209
                           lightgray')
                   ax.contour(X,Y,np.abs(1+lambda_dt+0.5*lambda_dt**2+(1/6)*lambda_dt**3), [1], colors='k')
210
```

```
case 'RK4':
211
                               ax.contourf(X,Y,np.abs(1+lambda_dt+0.5*lambda_dt**2+(1/6)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda_dt**3+(1/24)*lambda
212
                                            **4), [0,1], colors='lightgray')
                               ax.contour(X,Y,np.abs(1+lambda_dt+0.5*lambda_dt**2+(1/6)*lambda_dt**3+(1/24)*lambda_dt
                                           **4), [1], colors='k')
214
                   # Plot eigenvalue spectrum
215
                   evalsdt, evecs = LA.eig(-a*D*dt)
216
                   relambdadt = [ele.real for ele in evalsdt]
                   imlambdadt = [ele.imag for ele in evalsdt]
218
                   cmap = mpl.colors.ListedColormap(['green', 'red'])
219
                  match temporalscheme:
220
                       case 'Euler':
221
                              ax.scatter(relambdadt, imlambdadt, c=np.abs(1+evalsdt), edgecolors='black', vmin=1e-6,
                                           vmax=2. cmap=cmap)
                        case 'RK2':
223
                              ax.scatter(relambdadt, imlambdadt, c=np.abs(1+evalsdt+0.5*evalsdt**2), edgecolors='black
224
                                             ', vmin=1e-6, vmax=2, cmap=cmap)
                        case 'RK3':
225
                              {\tt ax.scatter(relambdadt, imlambdadt, c=np.abs(1+evalsdt+0.5*evalsdt**2+(1/6)*evalsdt**3), and the action of the control of 
226
                                            edgecolors='black', vmin=1e-6, vmax=2, cmap=cmap)
                        case 'RK4':
227
                              ax.scatter(relambdadt, imlambdadt, c=np.abs(1+evalsdt+0.5*evalsdt**2+(1/6)*evalsdt
228
                                            **3+(1/24)*evalsdt**4), edgecolors='black', vmin=1e-6, vmax=2, cmap=cmap)
                        case :
229
                               ax.scatter(relambdadt, imlambdadt, color='w', edgecolors='black')
231
                   plt.title('Eigenvalue spectrum for %s' % scheme)
232
                  plt.xlabel(r'\$\mathbb{R}\mathbb{L}^{e}(\lambda t)$'); plt.ylabel(r'\$\mathbb{I}\mathbb{I}^{m}(\lambda t)$'); plt.ylabel(r'\$\mathbb{I}^{m}(\lambda t)$'); plt.ylabel(r'$\mathbb{I}^{m}(\lambda t)$'); plt.ylabel(r'$\mathbb{I}^{m}(\lambda t))$'); plt.ylabel(r'$\mathbb{I}^{m}(\lambda t))
233
                                lambda \Delta t)$');
                   plt.savefig('eigenvalues-%s.pdf' % scheme)
234
                  plt.show()
235
237 # %% [markdown]
238 # Problem 4: Testing the stability of Euler and RK3
239
240 # %%
241 ########### Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
242 temporalscheme = 'Euler'
            ############ Choose CFL = a*dt/dx
244 CFL = 0.95 * 1
245 dt = CFL * dx / a
246 listofspatialschemes = ['1st-order upwind']
247
            # Plotting the eigenvalue spectra and numerical solutions for each scheme
249 for scheme in listofspatialschemes:
                  # Run solver and plot solution
250
                  t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0,dt)
                  fig, ax = plt.subplots(1, 1, figsize=(7, 4))
252
                   ax.plot(x,U0,color=plt.cm.Spectral_r(0))
254
                  for j in range(1,len(U)):
                        ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
255
256
                   plt.title('Periodic advection using Euler and %s' % scheme)
                   plt.xlabel(r'$x$');plt.ylabel(r'$u(x,t)$');
257
258
                   fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
                                 , orientation='vertical', label=r'$t$')
                  plt.savefig('solution-P4_Euler_095.pdf')
260
                  plt.show()
261
262 ############ Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
263 temporalscheme = 'Euler'
264 ############ Choose CFL = a*dt/dx
265 CFL = 1.05 * 1
            dt = CFL * dx / a
266
267 listofspatialschemes = ['1st-order upwind']
268
269 # Plotting the eigenvalue spectra and numerical solutions for each scheme
270 for scheme in listofspatialschemes:
```

```
# Run solver and plot solution
271
      t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0,dt)
272
      fig, ax = plt.subplots(1, 1, figsize=(7, 4))
273
      ax.plot(x,U0,color=plt.cm.Spectral_r(0))
275
      for j in range(1,len(U)):
        ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
276
277
      plt.title('Periodic advection using Euler and %s' % scheme)
      plt.xlabel(r'$x$'); plt.ylabel(r'$u(x,t)$');
278
      fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
          , orientation='vertical', label=r'$t$')
      plt.savefig('solution-P4_Euler_105.pdf')
280
281
      plt.show()
282
283 ########### Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
284 temporalscheme = 'RK3'
    ############ Choose CFL = a*dt/dx
286 CFL = 0.95 * np.sqrt(3)
_{287} dt = CFL * dx / a
    listofspatialschemes = ['2nd-order central']
289
    # Plotting the eigenvalue spectra and numerical solutions for each scheme
    for scheme in listofspatialschemes:
291
      # Run solver and plot solution
292
      t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0,dt)
293
      fig, ax = plt.subplots(1, 1, figsize=(7, 4))
294
      ax.plot(x,U0,color=plt.cm.Spectral_r(0))
      for j in range(1,len(U)):
296
        ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
297
      plt.title('Periodic advection using RK3 and %s' % scheme)
298
      plt.xlabel(r'$x$');plt.ylabel(r'$u(x,t)$');
299
      fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
          , orientation='vertical', label=r'$t$')
      plt.savefig('solution-P4_RK3_095.pdf')
302
      plt.show()
303
304 ########### Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
305 temporalscheme = 'RK3'
306 ########### Choose CFL = a*dt/dx
307 CFL = 1.05 * np.sqrt(3)
    dt = CFL * dx / a
308
309 listofspatialschemes = ['2nd-order central']
310
_{311} # Plotting the eigenvalue spectra and numerical solutions for each scheme
312 for scheme in listofspatialschemes:
      # Run solver and plot solution
      t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0, dt)
314
      fig, ax = plt.subplots(1, 1, figsize=(7, 4))
315
      ax.plot(x,U0,color=plt.cm.Spectral_r(0))
316
      for j in range(1,len(U)):
317
        ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
      plt.title('Periodic advection using RK3 and %s' % scheme)
319
      plt.xlabel(r'$x$'); plt.ylabel(r'$u(x,t)$');
320
      fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
          , orientation='vertical', label=r'$t$')
322
      plt.savefig('solution-P4_RK3_105.pdf')
     plt.show()
323
324
325 # %% [markdown]
    # Problem 5: Testing the stability of RK4
326
327
328 # %%
329 ########## Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
330 temporalscheme = 'RK4'
    ########### Choose CFL = a*dt/dx
331
332 CFL = 0.95 * 2 * np.sqrt(2)
333 dt = CFL * dx / a
334 listofspatialschemes = ['2nd-order central']
335
```

```
336 # Plotting the eigenvalue spectra and numerical solutions for each scheme
   for scheme in listofspatialschemes:
      # Run solver and plot solution
338
      t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0,dt)
340
     fig, ax = plt.subplots(1, 1, figsize=(7, 4))
      ax.plot(x,U0,color=plt.cm.Spectral_r(0))
341
      for j in range(1,len(U)):
342
       ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
343
      plt.title('Periodic advection using RK4 and %s' % scheme)
      345
      fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
346
          , orientation='vertical', label=r'$t$')
     plt.savefig('solution-P5_095.pdf')
347
     plt.show()
349
350 ############ Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
351 temporalscheme = 'RK4'
352 ############ Choose CFL = a*dt/dx
_{353} CFL = 1.05 * 2 * np.sqrt(2)
   dt = CFL * dx / a
354
   listofspatialschemes = ['2nd-order central']
357 # Plotting the eigenvalue spectra and numerical solutions for each scheme
358 for scheme in listofspatialschemes:
     # Run solver and plot solution
359
     t, U, D = Integrator(True, scheme, temporalscheme, 'LinearAdv1D',L, T, Nx, Nt, U0,dt)
     fig, ax = plt.subplots(1, 1, figsize=(7, 4))
361
      ax.plot(x,U0,color=plt.cm.Spectral_r(0))
362
363
     for j in range(1,len(U)):
        ax.plot(x,U[j],color=plt.cm.Spectral_r(t[j]/T))
364
      plt.title('Periodic advection using RK4 and %s' % scheme)
      plt.xlabel(r'$x$');plt.ylabel(r'$u(x,t)$');
366
      fig.colorbar(mpl.cm.ScalarMappable(norm=mpl.colors.Normalize(0, T), cmap='Spectral_r'),ax=ax
          , orientation='vertical', label=r'$t$')
      plt.savefig('solution-P5_105.pdf')
368
369
      plt.show()
 Matlab (1-based indexing)
 clear all; close all; clc
 3 \text{ xs} = -3.2:0.1:3.2;
 4 ys = xs;
   [X, Y] = meshgrid(xs, ys);
 5
 6 lambda_dt = X + Y*1i;
 8 figure(1); clf
 9 contourf(X, Y, abs(1 + lambda_dt),[-1,0,1], 'EdgeColor', 'none', 'LineWidth', 2); hold on;
10 contour(X, Y, abs(1 + lambda_dt), [1,1.001], 'LineColor', 'r', 'LineWidth', 3);
11 caxis([-1,1])
title('Stability Diagram for Euler');
13 xlabel('Re(\lambda \Delta t)');
ylabel('Im(\lambda \Delta t)');
15 xlim([-4, 2]);
16 ylim([-3.1, 3.1]);
17 colormap pink;
18 %saveas(gcf, 'stabDiagsEuler.pdf');
19
20 %%
   figure(2), clf;
21
22 contourf(X, Y, abs(1 + lambda_dt + lambda_dt.^2/2), [-1,0,1], 'EdgeColor', 'none', 'LineWidth'
        , 2); hold on
   contour(X, Y, abs(1 + lambda_dt + lambda_dt.^2/2), [1,1.001], 'LineColor', 'r', 'LineWidth',
23
24 caxis([-1,1])
25 title('Stability Diagram for Runge-Kutta 2');
26 xlabel('Re(\lambda \Delta t)');
27 ylabel('Im(\lambda \Delta t)');
   xlim([-4, 2]);
```

```
29 ylim([-3.1, 3.1]);
   colormap pink;
31 %saveas(gcf, 'stabDiagsRK2.pdf');
33 %%
34 figure(3), clf;
35 contourf(X, Y, abs(1 + lambda_dt + 1/2*lambda_dt.^2 + 1/6*lambda_dt.^3), [-1,0,1], 'EdgeColor'
       , 'none', 'LineWidth', 2); hold on
   contour(X, Y, abs(1 + lambda_dt + 1/2*lambda_dt.^2 + 1/6*lambda_dt.^3), [1,1.001], 'LineColor'
       , 'r', 'LineWidth', 2);
  caxis([-1,1])
37
38 title('Stability Diagram for Runge-Kutta 3');
39 xlabel('Re(\lambda \Delta t)');
40 ylabel('Im(\lambda \Delta t)');
41 xlim([-4, 1]);
42 ylim([-3.1, 3.1]);
43 colormap pink;
44 %saveas(gcf, 'stabDiagsRK3.pdf');
46 %%
   figure(4), clf;
   \texttt{contourf(X, Y, abs(1 + lambda_dt + 1/2*lambda_dt.^2 + 1/6*lambda_dt.^3 + 1/2*lambda_dt.^4),}
       [-1,0,1], 'EdgeColor', 'none', 'LineWidth', 2); hold on
   contour(X, Y, abs(1 + lambda_dt + 1/2*lambda_dt.^2 + 1/6*lambda_dt.^3 + 1/24*lambda_dt.^4),
       [1,1.001], 'LineColor', 'r', 'LineWidth', 2);
   caxis([-1,1])
51 title('Stability Diagram for Runge-Kutta 4');
52 xlabel('Re(\lambda \Delta t)');
53 ylabel('Im(\lambda \Delta t)');
54 xlim([-4, 1]);
55 ylim([-3.1, 3.1]);
56 colormap pink;
%saveas(gcf, 'stabDiagsRK4.pdf');
clear all; close all; clc
4 % Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
5 temporalscheme = 'RK3';
6 % Choose CFL = a*dt/dx
7 CFL = 1; % 1.05 * sqrt(3)
9 % Initialize case parameters
_{10} L = 1; T = 30.6; Nx = 50; Nt = 11;
11 a = 1;
12 % Initialize solution at t=0
13 x = linspace(0, L, Nx);
14 dx = x(2) - x(1);
15 dt = CFL * dx / a;
sigma = 3 / 40; U0 = exp(-(x - 0.5).^2 / (2 * sigma^2)); U0=U0';
_{\rm 17} % Initialize list of schemes that will be tested:
   listofspatialschemes = {'1st-order upwind', '2nd-order central', '3rd-order upwind', '4th-
       order central', '6th-order Pade'};
19
20 % Plotting the eigenvalue spectra and numerical solutions for each scheme
21 \quad A = [];
   for idx = 1:length(listofspatialschemes)
22
       scheme = listofspatialschemes{idx};
23
       % Run solver and plot solution
24
       [t, U, D] = Integrator(true, scheme, temporalscheme, 'LinearAdv1D', L, T, Nx, Nt, U0, dt);
25
       %A = [A; -a * D];
26
       fig = figure('Position', [100, 100, 500, 400]); hold on
       colors = [linspace(0,1,length(t))',zeros(length(t),2)];
28
       plot(x, U0, 'color', colors(1,:), 'LineWidth',2); hold on
29
30
       for j = 2:length(t)
           plot( x, U(:,j), 'color', colors(j,:),'LineWidth',2);
31
32
       end
       hold off
33
```

```
title(sprintf('Periodic advection of a Gaussian pulse using %s', scheme));
34
        xlabel( 'x');
35
        ylabel( 'u(x,t)');
36
37
        %saveas(fig, sprintf('solution-%s.pdf', scheme));
38
        %close(fig);
39
        % Plot stability region
40
        fig = figure('Position', [600, 100, 500, 400]);
41
        Ngrid = 200; xs = (-3:3.5/Ngrid:0.5); ys = (-3:3.5/Ngrid:3);
42
        [X, Y] = meshgrid(xs, ys);
43
        lambda_dt = X + 1i * Y;
44
        eigvals = eig(-a*D);
45
        eigvals = diag(eigvals);
46
        switch temporalscheme
47
48
            case 'Euler'
                %contourf(X, Y, abs(1 + lambda_dt), [0, 1], 'LineColor', 'none');
49
50
                %hold on
                contour(X, Y, abs(1 + lambda_dt), [0.999,1], 'LineColor', 'k'); hold on
51
                plot(real(eigvals)*dt,imag(eigvals)*dt,'r.','MarkerSize',15)
52
            case 'RK2
53
                %contourf(X, Y, abs(1 + lambda_dt + 0.5 * lambda_dt.^2), [0, 1], 'LineColor', '
                     none'):
                %hold on
55
                contour(X, Y, abs(1 + lambda_dt + 0.5 * lambda_dt.^2), [0.999,1], 'LineColor', 'k'
56
                     ):hold on
                plot(real(eigvals)*dt,imag(eigvals)*dt,'r.','MarkerSize',15)
57
            case 'RK3'
58
                \contourf(X, Y, abs(1 + lambda_dt + 0.5 * lambda_dt.^2 + (1/6) * lambda_dt.^3),
59
                     [0, 1], 'LineColor', 'none');
                %hold on
60
                 \texttt{contour}(\texttt{X}, \texttt{Y}, \texttt{abs}(\texttt{1} + \texttt{lambda}_\texttt{dt} + \texttt{0.5} * \texttt{lambda}_\texttt{dt}.^2 + (1/6) * \texttt{lambda}_\texttt{dt}.^3),
                     [0.999,1], 'LineColor', 'k'); hold on
                plot(real(eigvals)*dt,imag(eigvals)*dt,'r.','MarkerSize',15)
63
            case 'RK4'
                64
                %hold on
65
                \texttt{contour}(\texttt{X}, \texttt{Y}, \texttt{abs}(\texttt{1} + \texttt{lambda\_dt} + \texttt{0.5} * \texttt{lambda\_dt}.^2 + (\texttt{1/6}) * \texttt{lambda\_dt}.^3 + \texttt{1.3})
                     (1/24) * lambda_dt.^4), [0.999,1], 'LineColor', 'k'); hold on
67
                plot(real(eigvals)*dt,imag(eigvals)*dt,'r.','MarkerSize',15)
68
        end
        title(sprintf('Eigenvalue spectrum for %s', scheme));
69
        xlabel('Re(\lambda \Delta t)');
        ylabel('Im(\lambda \Delta t)');
71
        %saveas(fig, sprintf('eigenvalues-%s.pdf', scheme));
72
        %close(fig);
73
   end
74
75
76
   return
78
   %% Problem 4: First Set of Schemes
79
80 % Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
   temporalscheme = 'Euler';
81
   % Choose CFL = a*dt/dx
83 CFL = 0.95 * 1; % sqrt(3)
85 % Initialize case parameters
   L = 1; T = 30; Nx = 50; Nt = 11; a = 1;
86
  dx = L / Nx;
88 dt = CFL * dx / a;
89 % Initialize solution at t=0
90 x = linspace(0, L, Nx); dx = x(2) - x(1);
   sigma = 3 / 40; U0 = exp(-(x - 0.5).^2 / (2 * sigma^2)); U0=U0';
   % Initialize list of schemes that will be tested:
93 listofspatialschemes = {'1st-order upwind'};
95 % Plotting the eigenvalue spectra and numerical solutions for each scheme
```

```
96 \quad A = [];
    for idx = 1:length(listofspatialschemes)
        scheme = listofspatialschemes{idx};
98
        % Run solver and plot solution
        [t, U, D] = Integrator(true, scheme, temporalscheme, 'LinearAdv1D', L, T, Nx, Nt, U0, dt);
100
        A = [A; -a * D];
101
        fig = figure('Position', [100, 100, 700, 400]);
102
        colors = [linspace(0,1,length(t))',zeros(length(t),2)];
103
        plot(x, U0, 'color', colors(1,:));
        hold on
105
        for j = 2:length(t)
106
            plot(x, U(:,j), 'color', colors(j,:));
107
108
        hold on
109
        title(sprintf('Periodic advection using Euler and %s', scheme));
110
        xlabel('x');
111
        ylabel('u(x,t)');
112
        colorbar;
113
        %saveas(fig, 'solution-P4_Euler_095.pdf');
114
        %close(fig);
115
116
117
118 % Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
temporalscheme = 'Euler';
_{120} % Choose CFL = a*dt/dx
121 CFL = 1.05 * 1; % sqrt(3)
122
_{123} % Initialize case parameters
124 L = 1; T = 30; Nx = 50; Nt = 11; a = 1;
125 dx = L / Nx;
126 dt = CFL * dx / a;
127 % Initialize solution at t=0
x = linspace(0, L, Nx); dx = x(2) - x(1);
sigma = 3 / 40; U0 = exp(-(x - 0.5).^2 / (2 * sigma^2)); U0 = U0';
    % Initialize list of schemes that will be tested:
130
131 listofspatialschemes = {'1st-order upwind'};
132
133 % Plotting the eigenvalue spectra and numerical solutions for each scheme
134 \quad A = [];
135
    for idx = 1:length(listofspatialschemes)
        scheme = listofspatialschemes{idx};
136
        % Run solver and plot solution
137
        [t, U, D] = Integrator(true, scheme, temporalscheme, 'LinearAdv1D', L, T, Nx, Nt, U0, dt);
        A = [A; -a * D];
139
        fig = figure('Position', [100, 100, 700, 400]);
140
        colors = [linspace(0,1,length(t))',zeros(length(t),2)];
141
        plot(x, U0, 'color', colors(1,:));
142
        hold on
143
        for j = 2:length(t)
144
            plot(x, U(:,j), 'color', colors(j,:));
146
        end
        hold('off'):
147
        title(sprintf('Periodic advection using Euler and %s', scheme));
148
        xlabel('x');
149
        ylabel('u(x,t)');
150
151
        colorbar
        %saveas(fig, 'solution-P4_Euler_105.pdf');
152
153
        %close(fig);
154
    %% Problem 4: Second Set of Schemes
156
^{158} % Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
    temporalscheme = 'RK3';
159
    % Choose CFL = a*dt/dx
_{161} CFL = 0.95 * sqrt(3);
163 % Initialize case parameters
```

```
_{164} L = 1; T = 30; Nx = 50; Nt = 11; a = 1;
165 	ext{ dx = L / Nx;}
166 dt = CFL * dx / a;
167 % Initialize solution at t=0
x = linspace(0, L, Nx); dx = x(2) - x(1);
sigma = 3 / 40; U0 = exp(-(x - 0.5).^2 / (2 * sigma^2)); U0 = U0';
170 % Initialize list of schemes that will be tested:
171 listofspatialschemes = {'2nd-order central'};
173 % Plotting the eigenvalue spectra and numerical solutions for each scheme
174 \quad A = [];
175  for idx = 1:length(listofspatialschemes)
        scheme = listofspatialschemes{idx};
176
        % Run solver and plot solution
        [t,\ U,\ D] \ = \ Integrator(true,\ scheme,\ temporal scheme,\ 'Linear Adv 1D',\ L,\ T,\ Nx,\ Nt,\ UO,\ dt);
178
        A = [A; -a * D];
179
        fig = figure('Position', [100, 100, 700, 400]);
180
        colors = [linspace(0,1,length(t))',zeros(length(t),2)];
181
        plot(x, U0, 'color', colors(1,:));
182
        hold on
183
184
        for j = 2:length(t)
            plot(x, U(:,j), 'color', colors(j,:));
185
186
        hold off
187
        title(sprintf('Periodic advection using RK3 and %s', scheme));
188
        xlabel('x');
        ylabel('u(x,t)');
190
        colorbar
191
        %saveas(fig, 'solution-P4_RK3_095.pdf');
192
        %close(fig);
193
    end
194
195
196 % Choose temporal scheme between: Exact, Euler, RK2, RK3, RK4
197 temporalscheme = 'RK3';
198 % Choose CFL = a*dt/dx
199 CFL = 1.05 * sqrt(3);
200
_{\rm 201} % Initialize case parameters
202 L = 1; T = 30; Nx = 50; Nt = 11; a = 1;
203 dx = L / Nx;
204 dt = CFL * dx / a;
_{205} % Initialize solution at t=0
x = linspace(0, L, Nx); dx = x(2) - x(1);
207 sigma = 3 / 40; U0 = exp(-(x - 0.5).^2 / (2 * sigma^2)); U0=U0';
    \% Initialize list of schemes that will be tested:
209 listofspatialschemes = {'2nd-order central'};
210
211 % Plotting the eigenvalue spectra and numerical solutions for each scheme
212 \quad A = [];
    for idx = 1:length(listofspatialschemes)
214
        scheme = listofspatialschemes{idx};
        % Run solver and plot solution
215
        [t, U, D] = Integrator(true, scheme, temporalscheme, 'LinearAdv1D', L, T, Nx, Nt, U0, dt);
216
        A = [A; -a * D];
217
        fig = figure('Position', [100, 100, 700, 400]);
218
        colors = [linspace(0,1,length(t))',zeros(length(t),2)];
219
        plot(x, U0, 'color', colors(1,:));
220
221
        hold on
222
        for j = 2:length(t)
            plot(x, U(:,j), 'color', colors(j,:));
223
        end
224
        hold off
        title(sprintf('Periodic advection using RK3 and %s', scheme));
226
        xlabel('x');
227
228
        ylabel('u(x,t)');
        colorbar
229
        %saveas(fig, 'solution-P4_RK3_105.pdf');
230
        %close(fig);
231
```

```
end
232
233
234
    %% Auxiliary Functions
    function [ D ] = D_operator_periodic( n,L,R,a )
236
        %computes a finite difference operator
237
           n = number of grid points
238
           dx = step size
239
           [R,L] = right/left bound of stencil
240
          a = stencils
241
242
        % initialize
243
        D = zeros(n);
244
        % fill interior domain
        for i=1+L:n+1-R-1
246
            D(i,i-L:i+R) = a;
247
248
        end
        % fill left boundary
249
250
        for i=1:L
            D(i,1:i+R)
                                  = a(L-i+2:end);
251
            D(i,end-L+i:end)
                                 = a(1:L-i+1);
253
        end
254
        % fill right boundary
255
        for i=n+1-R:n
256
            D(i, end-L+0+(i-n): end) = a(1:L+(n+2-i)-1);
257
            D(i,1:(i-n+R-0))
                                     = a(L+(n+2-i):end);
258
259
260
    end
261
    \% Functor for the 1D advection equation
262
    function dUdt = LinearAdv1D(t, U, D)
263
        % Initialize velocity
265
        a = 1;
        % Compute dU/dt
266
        dUdt = -a * (D * U);
267
268
    end
269
    % Time integrator
270
271
    function sol = TimeIntegration(scheme, time_limits, dt, U0, D, t_eval)
        % Exact solution using MATLAB's ODE solver
272
273
        if strcmp(scheme, 'Exact')
            options = odeset('RelTol', 1.0e-6, 'AbsTol', 1.0e-6);
            [~, sol] = ode45(@(t, U) LinearAdv1D(t, U, D), t_eval, U0, options);
275
            sol = sol';
276
            return;
277
278
        else
279
            % Number of timesteps
            Nt = ceil((time_limits(2) - time_limits(1)) / dt) + 1;
280
            Uold = U0;
282
            \% Vector of stored solutions -- add initial condition
            sol = [];
283
284
            keval = 1;
            if t_eval(keval) == time_limits(1)
285
286
                 sol(:, keval) = U0;
                 keval = keval + 1;
287
288
289
            % Loop over all timesteps
            for k = 1:Nt
290
                 told = time_limits(1) + dt * (k - 1);
291
                 tnew = told + dt;
292
                 % Compute RHS at told
                 rhs = LinearAdv1D(told, Uold, D);
294
                 % Update new solution with explicit scheme
295
296
                 switch scheme
                     case 'Euler'
297
                         Unew = Uold + dt * rhs;
298
                     case 'RK2'
299
```

```
K1 = dt*LinearAdv1D(told, Uold, D);
300
                                                  K2 = dt*LinearAdv1D(told+dt, Uold+K1,D);
                                                  Unew = Uold+1/2*(K1+K2);
302
303
                                          case 'RK3'
                                                 K1 = dt*LinearAdv1D(told, Uold, D);
304
                                                  K2 = dt*LinearAdv1D(told+dt/2, Uold+K1/2, D);
305
                                                  K3 = dt*LinearAdv1D(told+dt, Uold+2*K2-K1,D);
306
                                                  Unew = Uold+1/6*(K1+4*K2+K3);
307
                                          case 'RK4'
308
                                                  K1 = LinearAdv1D(told, Uold, D);
309
                                                  K2 = LinearAdv1D(told + 0.5 * dt, Uold + 0.5 * dt * K1, D);
310
                                                  K3 = LinearAdv1D(told + 0.5 * dt, Vold + 0.5 * dt * K2, D);
311
                                                  K4 = LinearAdv1D(told + dt, Uold + dt * K3, D);
312
                                                  Unew = Uold + dt * (K1 + 2 * K2 + 2 * K3 + K4) / 6;
313
314
                                  end
                                 %Update stored solution vector
315
                                  if keval <= length(t_eval) && t_eval(keval) >= told && t_eval(keval) <= tnew
316
                                          sol(:, keval) = Uold + (Unew - Uold) * (t_eval(keval) - told) / dt;
317
                                          keval = keval + 1;
318
                                 end
319
320
                                 % Move to next timestep
                                 Uold = Unew;
321
                         end
322
323
                 end
        end
324
325
        function [t, U, D] = Integrator(periodic, operator, temporalscheme, problem, L, T, Nx, Nt, UO,
326
327
                % Initialize spatial domain
                x = linspace(0, L, Nx);
328
                dx = x(2) - x(1);
329
330
                % Initialize temporal domain
332
                t = linspace(0, T, Nt);
333
334
                \% Construct spatial matrix operator
                 switch operator
335
336
                         \% All periodic cases
                         case '1st-order upwind'
337
                                 D = D_{operator_periodic(Nx, 1, 0, [-1/dx, 1/dx]);
338
339
                         case '2nd-order central
                                 D = D_{operator_periodic(Nx, 1, 1, [-1/(2*dx), 0, 1/(2*dx)]);
340
                         case '3rd-order upwind'
                                 D = D_{operator\_periodic(Nx, 2, 1, [1/(6*dx), -1/dx, 1/(2*dx), 1/(3*dx)]);
342
                         case '4th-order central
343
                                  D = D_{operator\_periodic(Nx, 2, 2, [1/(12*dx), -8/(12*dx), 0, 8/(12*dx), -1/(12*dx)) 
344
                                         ]);
                         case '6th-order Pade'
345
                                  DR = D\_operator\_periodic(Nx, 2, 2, [-1/(36*dx), -28/(36*dx), 0, 28/(36*dx), 1/(36*dx), 1/(36*dx)
346
347
                                 DL = D_{operator_periodic(Nx, 1, 1, [1/3, 1, 1/3]);
                                 D = inv(DL) * DR;
348
349
                         otherwise
                                 error("The %s operator '%s' is not yet implemented!", ...
350
351
                                          ifelse(periodic, 'periodic', 'non-periodic'), operator);
352
                 end
353
354
                U = TimeIntegration(temporalscheme, [0, T], dt, U0, D, t);
355
```