
```

function[M, K, lambda] = MIE597VP2_Ngo(n, L, P)
    %Richie Ngo MIE 597V 27413591 Project 2
    %This function is supposed to solve Project 2 for the cantilever
    beam
    %using the given information and through the Galerkin method.
    E = 195*10^9;           %Young's Modulus (Pa)
    d = .01;                %Diameter (m)
    I = pi*(d/2)^4/2;       %Area moment of inertia (m^4)
    cross_A = pi*(d/2)^2;   %Cross-sectional area (m^2)
    rho = 8000;             %Density (kg/m^3)
    m = rho*cross_A*L;      %Mass (kg)
    zeta = .01;
    beta = [1.875 4.694 7.855 10.996 14.137]'; %Beta for cantilever
    and n <= 5
    %Could not figure out how to do anything in this problem without
    the
    %symbolic toolbox
    syms x
    if n > 5
        for j = 6:n
            beta(j) = (2*j - 1)*pi/(2*L); %Beta for cantilever and n
> 5
        end
    end
    phi = sym(zeros(1, n));
    phi_2 = phi;
    phi_4 = phi;
    for j = 1:n
        sigma = (sinh(beta(j)*L) - sin(beta(j)*L))/... %Sigma
            (cosh(beta(j)*L) + cos(beta(j)*L));
        phi(j) = cosh(beta(j)*x) - cos(beta(j)*x) -... %Phi
            sigma*(sinh(beta(j)*x) - sin(beta(j)*x));
        phi_2(j) = diff(phi(j), x, 2); %Second derivative of phi
        phi_4(j) = diff(phi(j), x, 4); %Fourth derivative of phi
    end
    F1 = sym(zeros(n));
    F2 = F1;
    F3 = F1;
    for i = 1:n
        for j = 1:n
            F1(i, j) = phi(i)*phi_4(j);
            F2(i, j) = phi(i)*phi_2(j);
            F3(i, j) = phi(i)*phi(j);
        end
    end
    A = double(int(F1, 0, L));
    B = double(int(F2, 0, L));
    G = double(int(F3, 0, L));
    K = E*I*A + P*B; %Stiffness matrix
    M = m*G; %Mass matrix
    %Do not have notes for how to find damping matrix
    D = inv(M)*K;

```

```
lambda = sqrt(eig(D)); %Eigenvalues
%I do not know how to proceed
end
```

$M =$

```
0.6283    0.0000
0.0000    0.6283
```

$K =$

```
1.0e+04 *
0.2367    -0.0011
0.0002     9.2926
```

$lambda =$

```
61.3774
384.5762
```

Published with MATLAB® R2015b