Positive Partial Transpose criterion in Symplectic geometry

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Partial Transpose criterion

Background: The Positive

Quantum Entanglement

Consider a bipartite system consists of subsystems A and B.

Definition

A bipartite state $\hat{\rho}$ is called **separable** if it can be written as

$$\hat{\rho} = \sum_{i} p_{i} \hat{\rho}_{A,i} \otimes \hat{\rho}_{B,i} \tag{1}$$

for some sets of density operators $\{\hat{\rho}_{A,i}\}$ and $\{\hat{\rho}_{B,i}\}$ and positive real numbers $\{p_i\}$ satisfying $\sum_i p_i = 1$.

Otherwise, $\hat{\rho}$ is called **entangled**.

e.g.
$$\frac{|00\rangle+|11\rangle}{\sqrt{2}}\frac{\langle 00|+\langle 11|}{\sqrt{2}}$$
 is entangled, but $\frac{|00\rangle\langle 00|+|11\rangle\langle 11|}{2}$ is separable.

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Given $\hat{\rho}$, how to test if it is entangled?

$$\hat{\rho} = \sum_{ijkl} \rho_{ij,kl} (|i\rangle_A \otimes |j\rangle_B) ({}_A \langle k| \otimes {}_B \langle l|)$$

 $^{^{1}\}mathrm{A.~Peres,~Phys.~Rev.~Lett.~77,~1413-1415}$ (1996).

$$\hat{\rho} = \sum_{ijkl} \rho_{ij,kl}(|i\rangle_A \otimes |j\rangle_B)({}_A\langle k| \otimes {}_B\langle l|)$$

$$\hat{\rho}^T = \sum_{ijkl} \rho_{kl,ij}(|i\rangle_A \otimes |j\rangle_B)({}_A\langle k| \otimes {}_B\langle l|)$$

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$$\begin{split} \hat{\rho} &= \sum_{ijkl} \rho_{i\pmb{j},kl}(|i\rangle_A \otimes |j\rangle_B)({}_A\langle k| \otimes {}_B\langle l|) \\ \hat{\rho}^T &= \sum_{ijkl} \rho_{kl,ij}(|i\rangle_A \otimes |j\rangle_B)({}_A\langle k| \otimes {}_B\langle l|) \\ \hat{\rho}^{T_B} &= \sum_{ijkl} \rho_{i\pmb{l},k\pmb{j}}(|i\rangle_A \otimes |j\rangle_B)({}_A\langle k| \otimes {}_B\langle l|) \end{split}$$

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Theorem

If $\hat{\rho}$ is separable, then

$$\hat{\rho}^{T_B} \ge 0. \tag{2}$$

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If $\hat{\rho}$ is separable, then

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If $\hat{\rho}^{T_B}$ is not a valid state, then $\hat{\rho}$ is entangled.

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Motivation: PPT in

Continuous variable systems

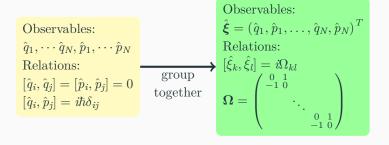
Observables:

$$\hat{q}_1, \cdots \hat{q}_N, \hat{p}_1, \cdots \hat{p}_N$$

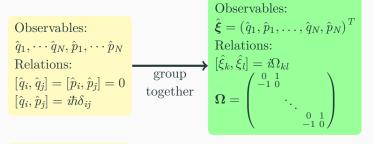
Relations:

$$[\hat{q}_i, \hat{q}_j] = [\hat{p}_i, \hat{p}_j] = 0$$

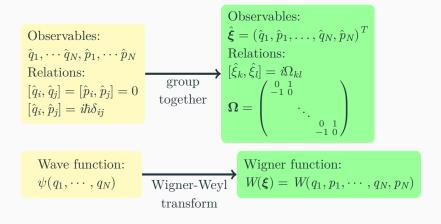
$$[\hat{q}_i,\hat{p}_j]=i\hbar\delta_{ij}$$



4



Wave function: $\psi(q_1, \dots, q_N)$



4

Examples of Wigner function

Coherent states
 coherent.gif
 (image source:
 https://commons.wikimedia.org/wiki/File:
 SmallDisplacedGaussianWF.gif)

```
    Fock states
        fock.jpg
        (image source: https://en.wikipedia.org/wiki/File:
        Wigner_functions.jpg)
```

PPT: If a state is separable, then its partial transpose is a valid state.

 $^{^2{\}rm R.}$ Simon, Phys. Rev. Lett. 84, 2726–2729 (2000).

PPT: If a state $W_{\hat{\rho}}(\xi)$ is separable, then its partial transpose $W_{\hat{\rho}^{T_B}}(\xi)$ is a valid state.

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Theorem

$$W_{\hat{\rho}^{T_B}}(q_A, p_A, q_B, p_B) = W_{\hat{\rho}}(q_A, p_A, q_B, -p_B)$$
 (3)

in both the position and Fock basis.

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in both the position and Fock basis.

Theorem

If $W(\xi)$ is a Gaussian function, then it is a valid state iff

$$\sigma + i\Omega \ge 0, \tag{4}$$

where $\sigma_{ij} = \langle \xi_i \xi_j + \xi_j \xi_i \rangle - 2 \langle \xi_i \rangle \langle \xi_j \rangle$.

It is a form of the uncertainty principle.

²R. Simon, Phys. Rev. Lett. 84, 2726–2729 (2000).

PPT criterion for Gaussian states

Theorem

A bipartite Gaussian function $W(\xi)$ is a valid state iff

$$\sigma + i \begin{pmatrix} \Omega_A & 0 \\ 0 & \Omega_B \end{pmatrix} \ge 0, \tag{5}$$

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A change from $\Omega_A \oplus \Omega_B$ to $\Omega_A \oplus -\Omega_B$.

$$\boldsymbol{\xi} = (\mathbf{q}, \mathbf{p}) \xrightarrow{\text{canonical}} \boldsymbol{\Xi} = (\mathbf{Q}, \mathbf{P})$$

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 Ω is actually a matrix representation of a bilinear form ω :

$$\omega(\xi_i, \xi_j) = \Omega_{ij} \tag{7}$$

$$\begin{split} \boldsymbol{\xi} &= (\mathbf{q}, \mathbf{p}) & \xrightarrow{\text{canonical}} \boldsymbol{\Xi} &= (\mathbf{Q}, \mathbf{P}) \\ & \Omega_{ij} & \xrightarrow{\partial \xi_i} \frac{\partial \xi_j}{\partial \Xi_k} \Omega_{kl} &= \Omega_{ij} \end{split}$$

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Definition

A symplectic vector space (E, ω) is a vector space E together with a nondegenerate, antisymmetric bilinear form ω , called the symplectic form.

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Can we formulate PPT with geometry?

Result: PPT criterion in Symplectic geometry (CV

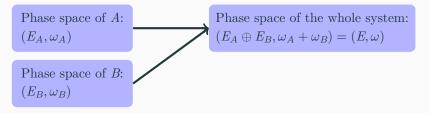
systems)

Partial transpose in symplectic geometry

Phase space of A: (E_A, ω_A)

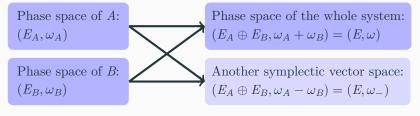
Phase space of B: (E_B, ω_B)

Partial transpose in symplectic geometry



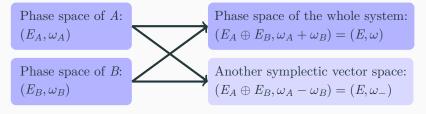
Let A, B has n, m modes respectively, then the whole system has N = n + m modes and $E_A \cong \mathbb{R}^{2n}$, $E_B \cong \mathbb{R}^{2m}$, $E \cong \mathbb{R}^{2N}$.

Partial transpose in symplectic geometry



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Proposition

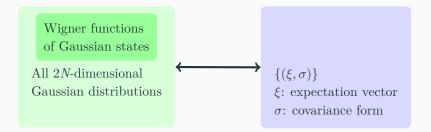
The partial transposition map (with respect to a quadrature basis) corresponds to a separable linear symplectomorphism from (E, ω) to (E, ω) .

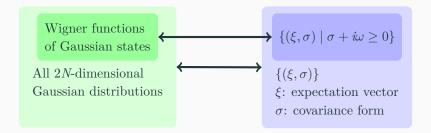
Moreover, any such symplectomorphisms correspond to the partial transposition map up to a local unitary transformation.

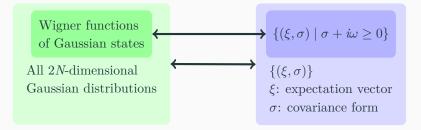
Wigner functions of Gaussian states

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All 2N-dimensional Gaussian distributions

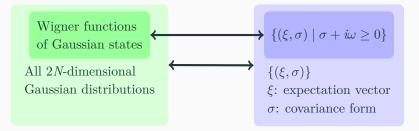






Generalization:

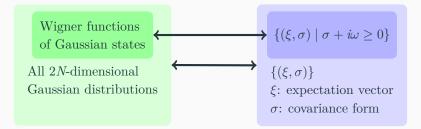
Wigner functions of certain type of states



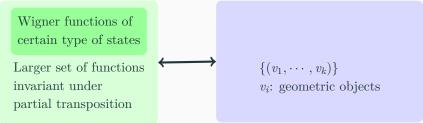
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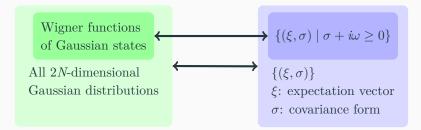
Wigner functions of certain type of states

Larger set of functions invariant under partial transposition

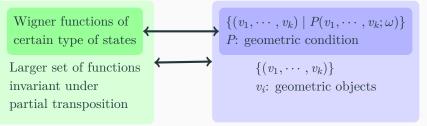


Generalization:





Generalization:



PPT in symplectic geometry³

Summary of our framework:

- 1. Extend the set of Wigner functions to a larger set invariant under partial transposition.
- 2. Parametrize this set with geometric objects v_1, \dots, v_k .
- 3. Find a geometric condition $P(v_1, \dots, v_k; \omega)$ that the parameters correspond to a valid state.

Definition

An element (v_1, \dots, v_k) of the above parametrization is called **valid** with respect to a symplectic form ω' if the condition $P(v_1, \dots, v_k; \omega')$ is true.

 $^{^3\}mathrm{Yi}\text{-}\mathrm{Ting}$ Tu and Ray-Kuang Lee, in preparation

PPT in symplectic geometry³

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Proposition

A state satisfies PPT iff it is valid with respect to ω_{-} .

³Yi-Ting Tu and Ray-Kuang Lee, in preparation

A cat state is a superposition of two coherent states at opposite positions.

$$|\text{cat}\rangle \propto |\alpha\rangle \pm |-\alpha\rangle,$$
 (8)

cat-ani.gif

(image source:

https://commons.wikimedia.org/wiki/File:Wigner_ function_of_a_Schr%C3%B6dinger_cat_state.gif)

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We consider the following type of bipartite cat states:

$$|\text{cat}_{\xi}\rangle \propto |\xi\rangle - |-\xi\rangle,$$
 (9)

where $\boldsymbol{\xi}$ is a vector in the phase space $E \cong \mathbb{R}^{2N}$.



Interference



Gaussian



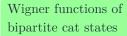
Wigner functions of bipartite cat states



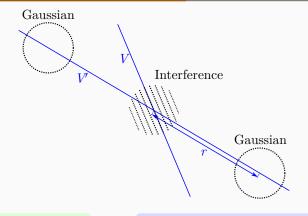
Interference



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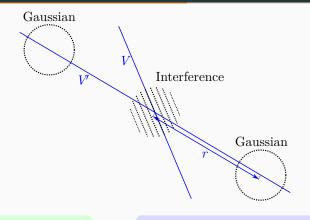


Same functions but interference may be in wrong direction



Wigner functions of bipartite cat states Same functions but

interference may be in wrong direction $\{(V, V', r)\}\$ V: a (2N-1)-dim subsp, V: a 1-dim subsp, r: a scalar



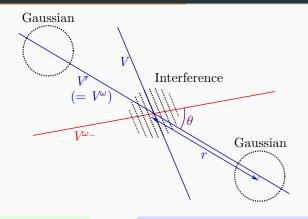
Wigner functions of bipartite cat states

Same functions but interference may be in wrong direction

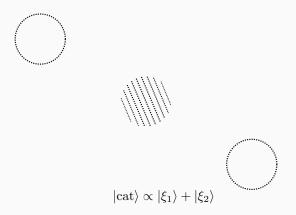
 $\{(V, V', r) \mid V' = V^{\omega}\}, \text{ where}$ $V^{\omega} := \{u \in E \mid \omega(u, v) = 0 \,\forall v \in V\}$

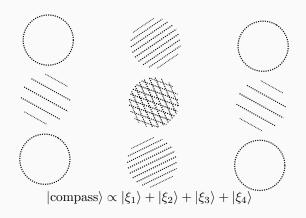
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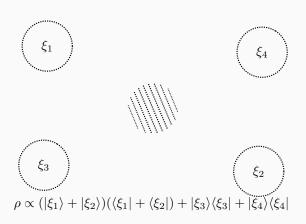
 $\{(V, V', r)\}$

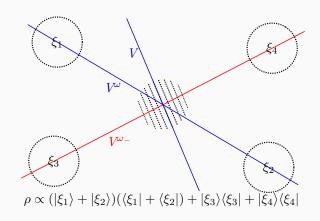


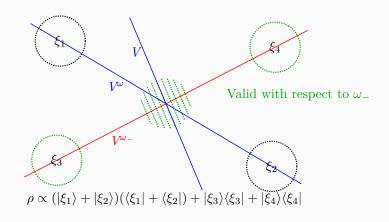
Wigner functions of bipartite cat states $\{(V,V',r)\mid V'=V^\omega\}, \text{ where } \\ V^\omega:=\{u\in E\mid \omega(u,v)=0\,\forall v\in V\} \\ \\ \text{Same functions but } \\ \text{interference may be } \\ \text{in wrong direction} \\ V': \text{ a } (2N-1)\text{-dim subsp, } \\ V': \text{ a } 1\text{-dim subsp, } r\text{: a scalar} \\ \\ \text{otherwise functions of the properties of the prope$











Consider the simultaneous zero eigenstates of N compatible quadrature operators.

(For example, the $p_1 + p_2 = 0$, $x_1 - x_2 = 0$ eigenstate.)

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The Wigner functions of these states are N-dimensional delta functions with support on a Lagrangian subspace $(L = L^{\omega})$.

Wigner functions of zero eigenstates of quadratures

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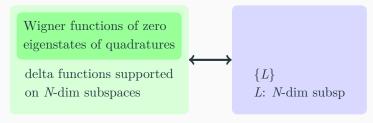
Wigner functions of zero eigenstates of quadratures

delta functions supported on N-dim subspaces

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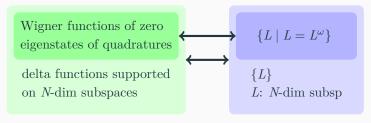
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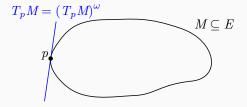
Relationship with classical integrable system

Let M be the Lagrangian torus of a bipartite classical system.



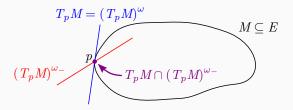
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Relationship with classical integrable system

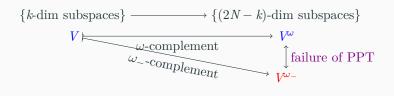
Let M be the Lagrangian torus of a bipartite classical system.



$$\{k\text{-dim subspaces}\} \longrightarrow \{(2N-k)\text{-dim subspaces}\}$$

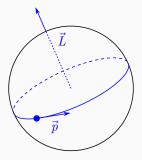
$$V \longmapsto \omega\text{-complement}$$

$$\omega_-\text{-complement} \longrightarrow V^\omega$$



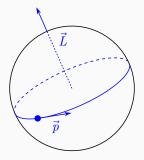
Result: PPT criterion in Symplectic geometry (general systems)

Consider a classical system of a free particle on a sphere.



The phase space is 4-dimensional.

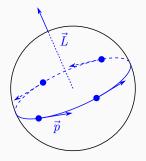
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• Restrict $|\vec{L}|$ to a fixed value L.

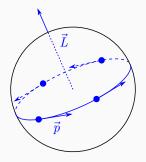
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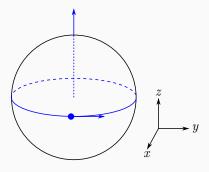


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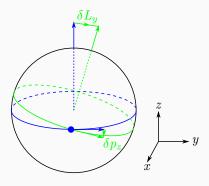
- Restrict $|\vec{L}|$ to a fixed value L.
- Identify all states related by time evolution as a single state.

Then the reduced phase space is 2-dimensional and identified with the sphere of all possible \vec{L} 's. (Large spin limit of spin phase spaces.)

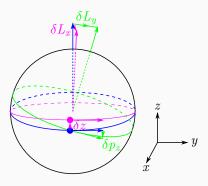
Consider two perturbations of this classical state:



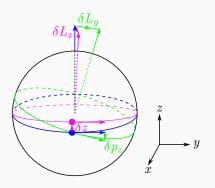
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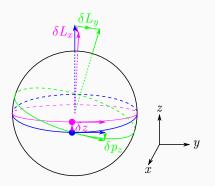
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From this we can see that:

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From this we can see that:

- The symplectic form is reduced as $\omega(\cdots) = \delta z \delta p_z = -\frac{1}{L} \delta L_x \delta L_y$.
- The reduced phase space locally looks like that of a one-dimensional particle with $q \propto \delta L_x$, $p \propto \delta L_y$.

$\overline{ ext{SW correspondence}^4}$ and the KKS symplectic form⁵

⁴Brif, C. and Mann, A. Phys. Rev. A 59, 971-987 (1999)

 $^{^5\}mathrm{E}.$ Meinrenken, Lecture notes on Symplectic Geometry

We use the framework of **Stratonovich-Weyl correspondence**:

• Let the dynamical symmetry group G acting on the Hilbert space. (A set of ways to move around the phase space)

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We assume that the phase space can be identified with a coadjoint orbit of G, so its symplectic form can be given by the

Kirillov-Kostant-Souriau form.

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SW correspondence and the KKS symplectic form

	CV systems	
Hilbert space H	$L^2(\mathbb{R}^N)$	
$\begin{array}{c} \text{Dynamical} \\ \text{group } G \end{array}$	Heisenberg group H_{2N+1}	
Reference state $ \psi_0\rangle$	SHO ground state $ 0\rangle$	
Phase space X	\mathbb{R}^{2N}	
SW kernel $\hat{\Delta}(\xi)$	$ \int \frac{d^{2N}\boldsymbol{\xi}'}{\pi^2} \cdot e^{i\boldsymbol{\xi}' \hat{T} \mathbf{\Omega} \boldsymbol{\xi}} \hat{D}(\boldsymbol{\xi}) $	
Symplectic form ω	$\sum_{i} dq_i \wedge dp_i$	

SW correspondence and the KKS symplectic form

	CV systems	Spin systems	
$\begin{array}{c} \text{Hilbert} \\ \text{space } H \end{array}$	$L^2(\mathbb{R}^N)$	\mathbb{C}^{2j+1}	
$\begin{array}{c} \text{Dynamical} \\ \text{group } G \end{array}$	Heisenberg group H_{2N+1}	SU(2)	
Reference state $ \psi_0\rangle$	SHO ground state $ 0\rangle$	$ s,s\rangle$	
Phase space X	\mathbb{R}^{2N}	Sphere S^2	
SW kernel $\hat{\Delta}(\xi)$	$ \int \frac{d^{2N}\boldsymbol{\xi}'}{e^{i\boldsymbol{\xi}'}} \cdot e^{i\boldsymbol{\xi}'} \hat{D}(\boldsymbol{\xi}) $	$ \sqrt{\frac{4\pi}{2j+1}} \sum_{l=0}^{2j} \sum_{m=-l}^{l} \hat{D}_{lm} Y_{lm}^*(\theta, \phi) $	
Symplectic form ω		$j\sin\theta\ d\theta \wedge d\phi$	

SW correspondence and the KKS symplectic form

	CV systems	Spin systems	Bipartite systems
$\begin{array}{c} \text{Hilbert} \\ \text{space } H \end{array}$	$L^2(\mathbb{R}^N)$	\mathbb{C}^{2j+1}	$H_A \otimes H_B$
$\begin{array}{c} \text{Dynamical} \\ \text{group } G \end{array}$	Heisenberg group H_{2N+1}	SU(2)	$G_A imes G_B$
Reference state $ \psi_0\rangle$	SHO ground state $ 0\rangle$	$ s,s\rangle$	$ \psi_0 angle_A\otimes \psi_0 angle_B$
Phase space X	\mathbb{R}^{2N}	Sphere S^2	$X_A \times X_B$
SW kernel $\hat{\Delta}(\xi)$	$ \int \frac{d^{2N}\boldsymbol{\xi}'}{e^{i\boldsymbol{\xi}'}} \cdot e^{i\boldsymbol{\xi}'} \hat{T}^{2}_{\boldsymbol{\Omega}\boldsymbol{\xi}} \hat{D}(\boldsymbol{\xi}) $	$ \sqrt{\frac{4\pi}{2j+1}} \sum_{l=0}^{2j} \sum_{m=-l}^{l} \hat{D}_{lm} Y_{lm}^*(\theta, \phi) $	$\hat{\Delta}_A(\xi_A)\otimes\hat{\Delta}_B(\xi_B)$
Symplectic form ω	$\sum_{i} dq_i \wedge dp_i$	$j\sin\theta \ d\theta \wedge d\phi$	$\omega_A + \omega_B$

Partial transposition in Symplectic geometry⁶

Theorem

Assume that there is an equivariant diffeomorphism from $X_{A,B}$ to a coadjoint orbit $G_{A,B} \cdot \mu_{A,B}$ sending the class of $|\psi_{A,B}\rangle$ to $\mu_{A,B}$, and $\langle \mu_B, \eta \rangle = \langle \psi_B | i T_{B*} \eta | \psi_B \rangle$ for all ξ in the Lie algebra of G_B , and that the complex conjugation of T_B with respect to a basis containing $|\psi_B\rangle$ induces an involutive automorphism on G_B , then $W_{\hat{\rho}^{T_B}}(\xi) = W_{\hat{\rho}}(\varphi(\xi))$, where φ is a separable symplectomorphism from (X, ω) to (X, ω_-) .

 $^{^6\}mathrm{Yi}\text{-}\mathrm{Ting}$ Tu and Ray-Kuang Lee, in preparation

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And, using the same framework as in the CV case, we still has

Proposition

A state satisfies PPT iff it is valid with respect to ω_{-} .

⁶Yi-Ting Tu and Ray-Kuang Lee, in preparation

Summary

- PPT criterion: if $\hat{\rho}$ is separable, then $\hat{\rho}^{T_B}$ is positive (a valid quantum state).
- In our framework of describing states with geometric objects, PPT is equivalent to validity with respect to the symplectic form ω_{-} .
- Examples of this framework include Gaussian states, cat states, and the zero eigenstates of quadratures.
- Under some technical assumptions, this framework can be generalized to other quantum systems, including spin systems.