

Question 1: Reinforcement Learning - Q-Learning

a. $Q[s, a] = r + \gamma \max_{a'} (Q[s', a'])$

i. $Q[s17, \text{right}] = 2 + 0.9 * \max_{a'} (Q[s18, a']) = 2 + 0.9 * 0 = 2$

ii. $Q[s18, \text{up}] = 8 + 0.9 * \max_{a'} (Q[s14, a']) = 8 + 0.9 * 0 = 8$

iii. $Q[s14, \text{right}] = -6 + 0.9 * \max_{a'} (Q[s15, a']) = -6 + 0.9 * 0 = -6$

b. $Q^i[s, a] = Q^{i-1}[s, a] + \alpha_k ((r + \gamma \max_{a'} Q^{i-1}[s', a']) - Q^{i-1}[s, a])$

i. $Q[s23, \text{up}] = 0 + 0.9 * \max_{a'} (Q[s18, a']) = 0 + 0.9 * 8 = 7.2$

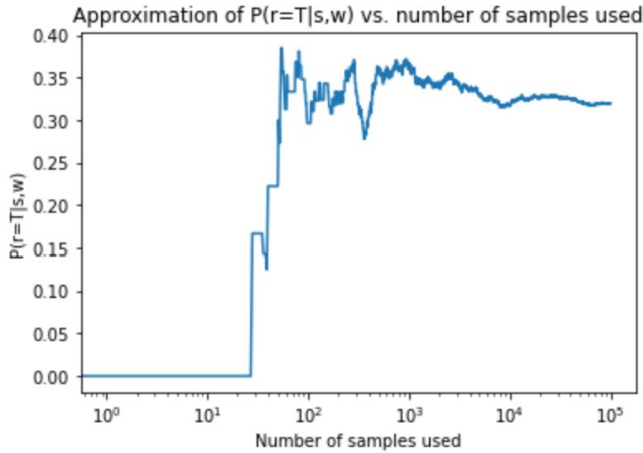
ii. $Q[s18, \text{up}] = Q^{i-1}[s18, \text{up}] + (1/k) * ((r + 0.9 * \max_{a'} Q^{i-1}[s14, a']) - Q^{i-1}[s18, a'])$
 $= Q^{i-1}[s18, \text{up}] + (1/2) * ((0 + 0.9 * 0) - Q^{i-1}[s18, a'])$
 $= 8 + 0.5 * (-8) = 4$

iii. $Q[s14, \text{right}] = Q^{i-1}[s14, \text{right}] + 0.5 * ((10 + 0.9 * \max_{a'} Q^{i-1}[s14, a']) - Q^{i-1}[s14, a'])$
 $= -6 + 0.5 * ((10 + 0.9 * 0) - (-6))$
 $= -6 + 0.5 * (16) = 2$

- c. Only the second update in part b would change, because SARSA would choose the action with value -6. Q-learning chooses the action greedily, meaning the action with value 0 is chosen, because $0 > -6$. SARSA, instead, only evaluates the actions suggested by the current policy, and therefore chooses the action with value -6.

Question 2: Approximate Reasoning in Belief Networks

a.

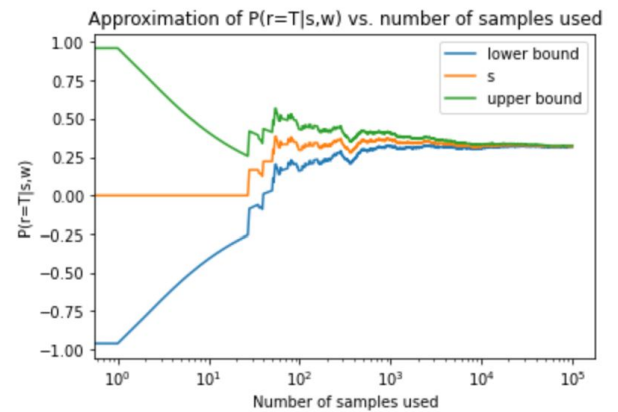


Approx. of $P(r=T|s,w)$ w/ 100000 samples: 0.3198136868505912

- b. Hoeffding's inequality: $P(|s - p| > \epsilon) \leq 2e^{-2n\epsilon^2}$
 $2e^{-2n\epsilon^2} < 0.05 \Rightarrow \ln e^{-2n\epsilon^2} < \ln(0.025) \Rightarrow$
 $n\epsilon^2 > -0.5\ln(0.025) \Rightarrow \epsilon^2 > \frac{\ln(40)}{2n}$

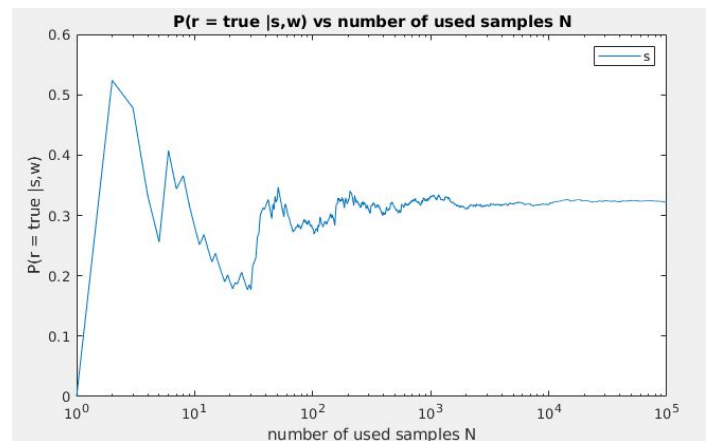
Tightest bound: $\epsilon > \sqrt{\frac{\ln(40)}{2n}}$

Accepted samples at $N=100000$: 27910
 epsilon for $n=27910$: 0.008129284366775905



Approx. of $P(r=T|s,w)$ w/ 100000 samples: 0.3198136868505912

- c. It is evident that approximating $P(r|s,w)$ using the likelihood weighting converges faster (we can see from the plot that the algorithm converges between 100-1000 samples). The convergence is also much more stable. With rejection sampling, the algorithm doesn't converge until more than 10000 samples are used.



Question 3: Temporal Reasoning in Belief Networks

a. $P(X_i = t|e), P(X_0 = \text{true}) = P(X_0 = \text{false}) = 0.5, e = (t, f, t)$

i. $P(X_1|e) = \alpha P(X_1|e_{0:1})P(e_{2:3}|X_1) = \alpha * [0.765, 0.235] * [0.196, 0.262] \propto [0.709, 0.291]$

- $P(X_1|e_{0:1}) = \alpha P(e_1|X_1) \sum_{X_0} P(X_1|X_0)P(X_0|e_0)$
 - $= \alpha * [0.8, 0.3] * (0.5[0.7, 0.3] + 0.5[0.4, 0.6])$
 - $= \alpha * [0.44, 0.135] \propto [0.765, 0.235]$

- $P(e_{2:3}|X_1) = (0.2 * 0.65[0.7, 0.4]) + (0.7 * 0.5[0.3, 0.6]) = [0.196, 0.262]$

- $P(X_1 = t|e) = 0.709$

ii. $P(X_2|e) = \alpha P(X_2|e_{0:2})P(e_{3:3}|X_2) = \alpha * [0.389, 0.611] * [0.65, 0.5] \propto [0.454, 0.546]$

- $P(X_2|e_{0:2}) = \alpha P(e_2|X_2) \sum_{X_1} P(X_2|X_1)P(X_1|e_{0:1})$
 - $= \alpha * [0.3, 0.8] * (0.765[0.7, 0.3] + 0.235[0.4, 0.6])$
 - $= \alpha * [0.18885, 0.2964] \propto [0.389, 0.611]$

- $P(e_{3:3}|X_2) = (0.8 * 1[0.7, 0.4]) + (0.3 * 1[0.3, 0.6]) = [0.65, 0.5]$

- $P(X_2 = t|e) = 0.454$

iii. $P(X_3|e) = \alpha P(X_3|e_{0:3})P(e_{4:3}|X_3) = \alpha * [0.74, 0.26] * [1, 1] \propto [0.74, 0.26]$

- $P(X_3|e_{0:3}) = \alpha P(e_3|X_3) \sum_{X_2} P(X_3|X_2)P(X_2|e_{0:2})$
 - $= \alpha * [0.8, 0.3] * (0.389[0.7, 0.3] + 0.611[0.4, 0.6])$
 - $= \alpha * [0.4136, 0.1449] \propto [0.741, 0.259]$

- $P(e_{4:3}|X_3) = [1, 1]$

- $P(X_3 = t|e) = 0.741$

b. Most likely sequence with Viterbi algorithm: $[s_1, s_2, s_3] = [true, true, true]$

i. $m_{1:1} = P(X_1|e) = [0.709, 0.291]$

ii. $m_{1:2} = P(e_2|X_2) * [\max[0.8P(X_2|X_1), 0.2P(X_2|\neg X_1)], \max[0.8P(\neg X_2|X_1), 0.2P(\neg X_2|\neg X_1)]]$

■ $= [0.2, 0.7] * [\max[0.709 * 0.7, 0.291 * 0.4], \max[0.709 * 0.3, 0.291 * 0.6]]$

■ $= [0.2, 0.7] * [\max[0.4963, 0.1164], \max[0.2127, 0.1746]]$

■ $= [0.2, 0.7] * [0.4963, 0.2127] = [0.09926, 0.14889]$

The previous state that maximized the probability of being in the true state is: $X_1 = t$

The previous state that maximized the probability of being in the false state is: $X_1 = f$

iii. $m_{1:3} = P(e_3|X_3) * [\max[0.099P(X_3|X_2), 0.149P(X_3|\neg X_2)], \max[0.099P(\neg X_3|X_2), 0.149P(\neg X_3|\neg X_2)]]$

■ $= [0.8, 0.3] * [\max[0.099 * 0.7, 0.149 * 0.4], \max[0.099 * 0.3, 0.149 * 0.6]]$

■ $= [0.8, 0.3] * [\max[0.0695, 0.0596], \max[0.0298, 0.0893]]$

■ $= [0.8, 0.3] * [0.0695, 0.0893] = [0.0556, 0.0268]$

The previous state that maximized the probability of being in the true state is: $X_2 = t$

The previous state that maximized the probability of being in the false state is: $X_2 = f$

