

Meeting

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July 25, 2022

Progress report

- Fixed the simulation.

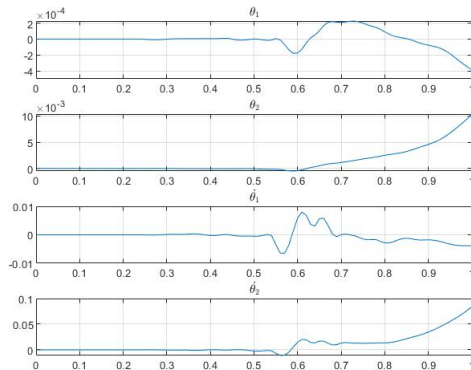


Figure 1: Error between python and ODE45

Progress report

- Train the controller using Q-learning method.

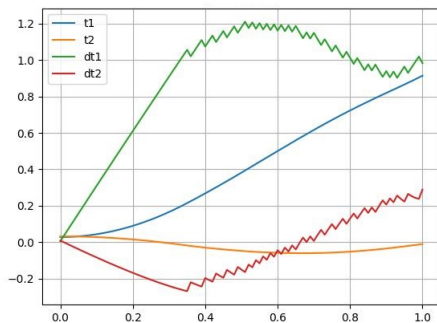


Figure 2: Training result

Future

- Fix the reward system.

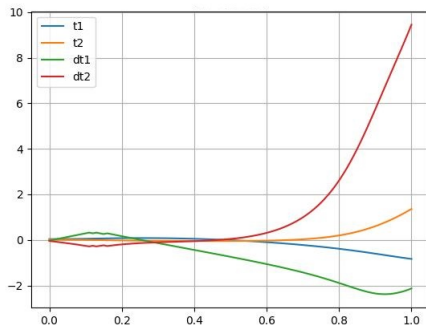


Figure 3: Training result