Meeting

PO-HSUN WU

May 31, 2021

Progress report

- Overview of quadcopter flight dynamic & RL.
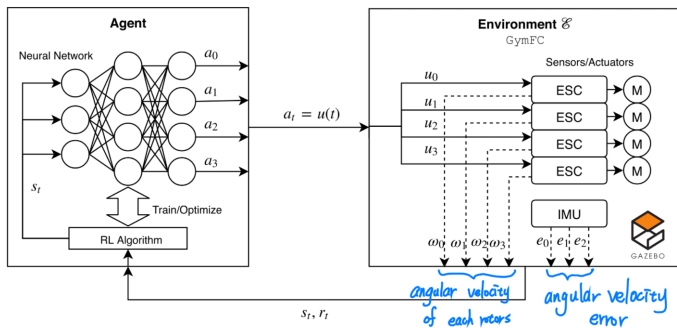- Introduction of training environment.

Fig. 2. RL architecture using the GYMFC environment for training intelligent attitude flight controllers.