

# Linear Systems

HW5

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#1 For  $\{Av_1, Av_2, \dots, Av_n\}$  is linearly independent.

$$\alpha_1 Av_1 + \alpha_2 Av_2 + \dots + \alpha_n Av_n = 0_W, \quad \alpha_1 = \alpha_2 = \dots = \alpha_n = 0$$

$\therefore A$  is a linear transformation.

$$\therefore A(\alpha_1 v_1) + A(\alpha_2 v_2) + \dots + A(\alpha_n v_n) = A(\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n) = 0_W$$

$$\Rightarrow \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = 0_V, \quad \alpha_1 = \alpha_2 = \dots = \alpha_n = 0$$

$\Rightarrow \{v_1, v_2, \dots, v_n\}$  is linearly independent. #

Let  $V, W \in \mathbb{R}^2$ ,  $A: V \rightarrow W$

$$V = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}, \quad A\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 3x_1 - 2x_2 \\ 3x_1 - 2x_2 \end{bmatrix} = W$$

$$w_1 = A(v_1) = \begin{bmatrix} 3 \cdot 1 - 2 \cdot 0 \\ 3 \cdot 1 - 2 \cdot 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

$$w_2 = A(v_2) = \begin{bmatrix} 3 \cdot 0 - 2 \cdot 1 \\ 3 \cdot 0 - 2 \cdot 1 \end{bmatrix} = \begin{bmatrix} -2 \\ -2 \end{bmatrix}$$

$$\Rightarrow W = \left\{ \begin{bmatrix} 3 \\ 3 \end{bmatrix}, \begin{bmatrix} -2 \\ -2 \end{bmatrix} \right\}$$

$$\alpha_1 \begin{bmatrix} 3 \\ 3 \end{bmatrix} + \alpha_2 \begin{bmatrix} -2 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \alpha_1 = \frac{1}{3}, \quad \alpha_2 = \frac{1}{2}$$

$$\therefore \alpha_1, \alpha_2 \neq 0$$

$\therefore W$  is NOT linear independent. #

#2. Let  $x \in \mathcal{N}(A)$ ,  $v \in V$ , but  $x \in V$ ,  $v \notin \mathcal{N}(A)$

$$\begin{aligned} A(x+v) &= A(x) + A(v) \\ &= A(v) \end{aligned}$$

If  $A$  is one-to-one mapping,

$$A(x+v) = A(v) \Rightarrow x+v = v$$

then  $\mathcal{X} = \mathcal{O}_v$

$$\Rightarrow \mathcal{N}(A) = \mathcal{O}_v \quad \#$$

#3.

$$\#4. \text{ Let } W = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}, V = \left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} \right\}$$

$$P(s) = a_4 s^4 + a_3 s^3 + a_2 s^2 + a_1 s + a_0 = (a_4, a_3, a_2, a_1, a_0) \text{ w.r.t. } W$$

$$\begin{aligned} \mathcal{A}(P(s)) &= \int_0^s a_4 s^4 + a_3 s^3 + a_2 s^2 + a_1 s + a_0 \, ds \\ &= \frac{a_4}{5} s^5 + \frac{a_3}{4} s^4 + \frac{a_2}{3} s^3 + \frac{a_1}{2} s^2 + a_0 s \Rightarrow A_W = \begin{bmatrix} \frac{1}{5} & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{4} & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{3} & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}_W \end{aligned}$$

(a) Let  $P_1, P_2$  w.r.t.  $W$

$$\begin{aligned} A(P_1(s) + P_2(s)) &= A(P_1 + P_2) = AP_1 + AP_2 \\ &= A(P_1(s)) + A(P_2(s)) \end{aligned}$$

$$A(\alpha P_1(s)) = A(\alpha P_1) = \alpha(AP_1) = \alpha A(P_1)$$

$\therefore A$  is a linear transformation #

(b) Let  $(b_1, b_2, b_3)$  w.r.t.  $V$

$$\begin{cases} v_1 = 1 \cdot w_1 + (-1) \cdot w_2 + \\ v_2 = 0 \cdot w_1 + 1 \cdot w_2 + (-1) w_3 \\ v_3 = \phantom{0 \cdot w_1 + 1 \cdot w_2 + (-1) w_3} + 1 \cdot w_4 + (-1) w_5 \end{cases}$$

$$T_{W \rightarrow V} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

$$A_V = A_W T_{W \rightarrow V} = \begin{bmatrix} \frac{1}{5} & 0 & 0 \\ -\frac{1}{4} & \frac{1}{4} & 0 \\ 0 & -\frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{2} \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} R(A) = A_V \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} &= \begin{bmatrix} \frac{1}{5} b_1 \\ -\frac{1}{4} b_1 + \frac{1}{4} b_2 \\ -\frac{1}{3} b_2 \\ \frac{1}{2} b_3 \\ -b_3 \\ 0 \end{bmatrix} = b_1 \begin{bmatrix} \frac{1}{5} \\ -\frac{1}{4} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + b_2 \begin{bmatrix} 0 \\ \frac{1}{4} \\ -\frac{1}{3} \\ 0 \\ 0 \\ 0 \end{bmatrix} + b_3 \begin{bmatrix} 0 \\ 0 \\ 0 \\ \frac{1}{2} \\ -1 \\ 0 \end{bmatrix} \end{aligned}$$

$$\mathcal{R}(A) = \text{sp} \left( \begin{bmatrix} \frac{1}{5} \\ -\frac{1}{4} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ \frac{1}{4} \\ -\frac{1}{3} \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ \frac{1}{2} \\ -1 \\ 0 \end{bmatrix} \right) \text{ w.r.t. } \{s^6, s^5, \dots, s, 1\}$$

$$(c) \quad A = \begin{bmatrix} \frac{1}{5} & 0 & 0 \\ -\frac{1}{4} & \frac{1}{4} & 0 \\ 0 & -\frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{2} \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} = A_V \quad \#$$

$$(d) \quad \text{Let } x = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \text{ w.r.t } V$$

$$A_V x = 0$$

$$\Rightarrow \begin{bmatrix} \frac{1}{5} & 0 & 0 \\ -\frac{1}{4} & \frac{1}{4} & 0 \\ 0 & -\frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{2} \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} \frac{1}{5} a_1 & = 0 \\ -\frac{1}{4} a_1 + \frac{1}{4} a_2 & = 0 \\ -\frac{1}{3} a_2 & = 0 \\ \frac{1}{2} a_3 & = 0 \\ -a_3 & = 0 \\ 0 & = 0 \end{cases}$$

$$\Rightarrow \begin{cases} a_1 = 0 \\ a_2 = 0 \\ a_3 = 0 \end{cases} \Rightarrow \mathcal{N}(A) = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\} \quad \#$$

$$(e) \quad \dim(\mathcal{R}(A)) + \dim(\mathcal{N}(A)) = 3 + 0 = 3 = \dim(V) \quad \#$$