Meeting

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Progress report

1. Fix all the bugs of the code(rewrite by OOP)
   List of Errors
   a The control vector define not match
   b The velocity and angular velocity do not been set to zero.
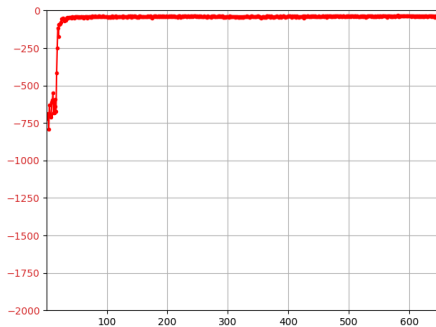   c Change the neural of hidden layer from 64 to 100

Progress report
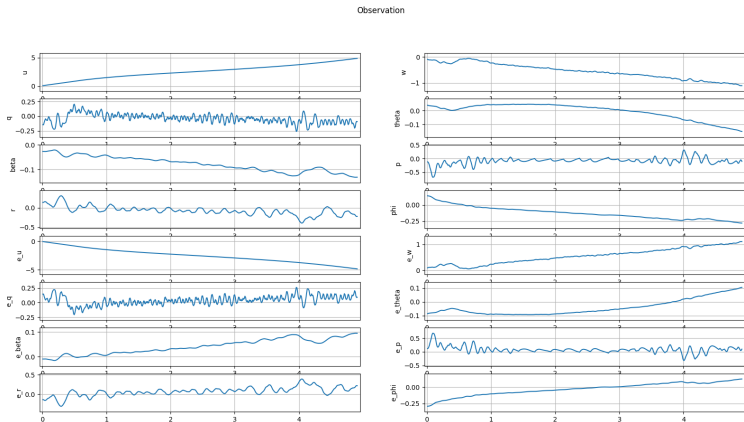

Figure 1: Mean trajectory reward

Progress report

Figure 2: Observation