

Meeting

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Future

1. Train controller on XPlane.

$$\begin{bmatrix} \beta \\ p \\ r \\ \phi \end{bmatrix} \Rightarrow \begin{bmatrix} \mathbf{r}_\beta \\ \mathbf{r}_p \\ \mathbf{r}_r \\ \mathbf{r}_\phi \\ e_\beta \\ e_p \\ e_r \\ e_\phi \end{bmatrix} \quad (1)$$

2. Rewrite PPO algorithm.