Meeting

Po Hsun Wu

November 28, 2022

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Progress report

Table 1: Step performance

	Tracker		Regulator	
	β	ϕ	β	ϕ
Rise time(sec)	μ =0.3605 σ =0.2923	μ =0.3285 σ =0.3213	μ =0.5887 σ =0.3575	μ =0.4132 σ =0.4636
2% Settling time(sec)	μ =7.2089 σ =3.6041	μ =6.1229 σ =4.0108	μ =4.6819 σ =3.3599	μ=4.3516 σ=3.3567
5% Settling time(sec)	μ =3.8233 σ =4.0600	μ =3.1465 σ =3.9023	μ =2.4018 σ =2.8485	μ =2.2058 σ =2.7957
Overshoot(%)	μ = 10.0160 σ =20.1131	μ = 9.5844 σ =22.0348	μ = 9.0915 σ =21.5718	μ = 8.9186 σ =21.3232
Undershoot(%)	μ = 4.9523 σ =18.8622	μ = 4.1673 σ =17.7305	μ = 6.3101 σ =23.0001	μ = 4.6244 σ =17.7231

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Normalize

$$y_{\text{norm}} = \frac{y(t) - y_{\text{init}}}{y_{\text{final}} - y_{\text{init}}}$$

 y_{init} is 0, y_{final} is the end point.

• TransientTime tolerance:

$$\max(|y(t)-y_{\rm final}|)\times 0.02\%$$

• SettlingTime tolerance:

$$|y_{\rm final} - y_{\rm init}| \times 0.02\%$$

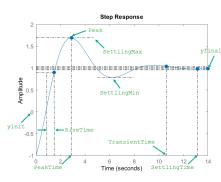


Figure 1: MATLAB stepinfo function

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- Determine the y_{init} and y_{final} .
- Have some problems when calculating the rise time.

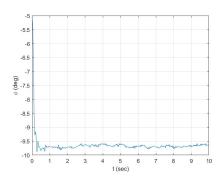


Figure 2: ϕ response