	Story	Estimate(hours)	
1	Set up DB in docker container		1
2	Design DB Schema		5
3	Set up SQLAlchemy		1
4	Implement database structure and make it accessible		5
5	FastAPI install on docker container		1
6	Basic get and post request		3
7	FastAPI calls to get and set drone data		3
8	Backend integration with db		2
9	MavLink installed and drone control research		3
10	MavProxy setup and flight controller emulator		2
11	Mavlink standalone script that flies to waypoint in sim		2
12	Mavlink integrated with backend		4
13	React app base created and functioning		1
14	Drone select drop down screen #1		2
15	Map api selected and component implemented		3
16	Map svg overlay to display position of selected vehicle		3
17	React app gauges for altitude and velocity		2
18	React app "nav ball" for roll, pitch, yaw of vehicle		2
19	Front end screen 1 integration with backend and db		2
20	Mavlink test on hardware		6
21	Front end screen 2 drone list		1
22	Front end screen 2 Path design component		8
23	Front end screen 2 save/load paths for selected vehicle		3
24	Front end screen 2 swarm paths component		4
25	Backend support for screen 2 implemented		3
26	Backend integrated with screen 2		3
27	Emergency land procedure		4
28	Teleop control of vehicles		5
29	Screen 3 connection manager		6
30	Screen 3 live data streaming component		8
31	Test swarm planning in simulation		6
32	Full shakedown in simulation		10
33	Full shakedown on hardware		15

ID

Priority (1-5)	Sprint When Finished	Completed
1 Hority (1 0)		Done
1		Done
1		Done
- 1		Done
- 1		Done
1		Done
1		Done
2		In Progress
1		Done
1		Done
1	. 1	Done
1	. 1	In Progress
1		Done
1	. 1	Done
1	. 1	Done
2	2 1	In Progress
1	. 1	Done
2	2 1	In Progress
2	2 1	In Progress
1	. 1	In Progress
1	. 2	
1	. 2	
1	. 2	
2	2 2	
2	2 2	
2		
1		
1	. 2	
2		
2		
2		
1		
1	3	