# GUST Sprint #3

GROUND CONTROL STATION FOR UNCREWED SWARMS AND TEAMS









Nick Warren

Jacob Stock

Ricardo R-C

James Montgomery

Cameron Acree

GitHub: https://github.com/rickyrc123/GUSTv2/Website: https://rickyrc123.github.io/GUSTv2/

#### What is GUST?

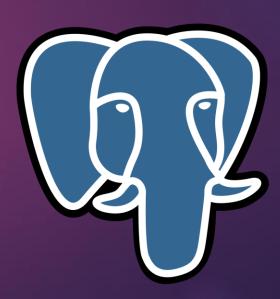
- Multiplatform ground control station for autonomous aerial vehicles
- Written in React + Python FastAPI + PostgreSQL
- Runs on Docker container
- Designed as an open-source alternative to Mission Planner that supports large groups of vehicles
- Path Design, Live Telemetry, Flight Controls

## Major Functionality

- Live telemetry streaming, including air speed, altitude, heading, and GPS position
- Individual path design
- Swarm maneuver design
- Flight command and execution
- Return to home functionality

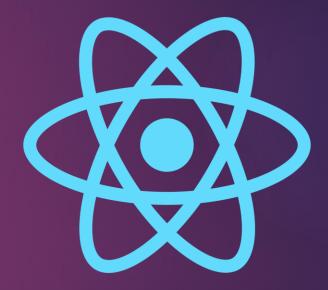
## James Montgomery

- Initial database design (swarm, drone, program)
- Database helper functions to modify and access database
- Partial integration with FastAPI
- Functionality improvements



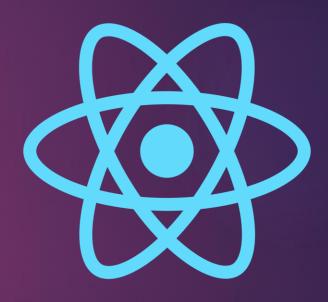
#### Jacob Stock

- ► Telemetry screen implementation
- React App design
- FastAPI integration
- Docker Work



#### Ricardo RC

- Planning screen implementation
- Connection screen implementation
- React App design
- Drone Tests
- FastAPI integration



#### Nick Warren

- Fast API Server and Endpoints
- Database and API Integrations
- Drone hardware testing



#### Cameron Acree

- Background code and sim testing
- Help with drone flight



# Sprint 3 Backlog

ID	Story
34	Dragon Link hardware testing
35	Connection Screen Implementation
36	Telemetry page refactor
37	Telemetry page maneuver list
38	Telemetry page ARM functionality
39	Dragon Link takeoff/land
40	Dragon Link seek to waypoint
41	Doodle Labs takeoff/land
42	Doodle Labs seek to Waypoint
43	Planning Screen Point table
	Planning screen maneuver
44	integration
45	Connection enumeration
46	Connection configuration + refresh
47	Direct connect w/ connection string
48	Saved connections
49	Telemetry screen flight controls
50	Telemetry screen E-Land
51	Telemetry screen return to home

# Live Demo