DSP HW2-1 Report

b08902045 資工四 袁紹奇

Result

I use the following parameters and get the following result. The final accuracy is 97.01%.

Train

Test

```
1 opt_acwt=0.2
2 test_beam=20.0
```

topo.proto

```
1 <Topology>
   <TopologyEntry>
    <ForPhones>
   NONSILENCEPHONES
    </ForPhones>
 6 <State> 0 <PdfClass> 0 <Transition> 0 0.50 <Transition> 1 0.25 <Transition>
    2 0.25 </state>
    <State> 1 <PdfClass> 1 <Transition> 1 0.50 <Transition> 2 0.25 <Transition>
    3 0.25 </state>
   <State> 2 <PdfClass> 2 <Transition> 2 0.50 <Transition> 3 0.25 <Transition>
    4 0.25 </state>
    <State> 3 <PdfClass> 3 <Transition> 3 0.50 <Transition> 4 0.25 <Transition>
    5 0.25 </state>
    <State> 4 <PdfClass> 4 <Transition> 3 0.25 <Transition> 4 0.25 <Transition>
10
    5 0.50 </state>
    <State> 5 </State>
11
12
    </TopologyEntry>
    <TopologyEntry>
13
    <ForPhones>
14
    SILENCEPHONES
15
16
    </ForPhones>
```

I tried several settings to increase the performance. By increasing the initial and total number of Gaussian, it improves to 94-96%. Also, adding more states and giving enough iteration of training can have better performance. As for the testing stage, setting opt_acwt to 0.2-0.3 would have better performance.

Challenge

Building the docker environment takes me a lot of time since I wrote this homework on the workstation, for which I don't have root permission. After solving the environmental issues, finding the correct parameters also takes me some time. It took a while until I got an acceptable result.