

## ARMA series . Additional elements

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## Long memory time series

So far we were dealing with stationary processes where, when  $h \rightarrow \infty$   $\rho(h)$  were going fastly to zero, typically  $|\rho(h)| \leq c|a|^h$ , with  $|a| < 1$ , that is at an exponential rate.

This, in particular ensures that  $\sum \rho(h) < \infty$  and the sum converges fastly.

However some stationary processes, see fig \*\*\* exhibit correlations  $\sum \rho(h)$  such that the series converges slowly or even doesn't converge.

A class of such processes is obtained by considering a generalization of ARIMA(p,d,q) series unused till now with integer values for  $d$ , the most often  $d = 1, 2$ , or  $3$ . Recall that these processes were not stationary, but the  $d$ -difference do were.

Now we consider fractional differences with  $d < 1$ . That is, we extend the definition of the difference operator to give a sens to  $(1 - B)^d$  when  $d < 1$ . This will give a stationary processes satisfying

$$\phi(B)(1 - B)^d Y_t = \theta(B)\varepsilon_t, \quad d < 1$$

where  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$ .

Without loss of generality we consider

$$(1 - B)^d Y_t = \varepsilon_t$$

For stationarity of  $Y_t$  we need linearity:  $Y_t = (1 - B)^{-d} \varepsilon_t = \sum_{j=0}^{\infty} \psi_j \varepsilon_{t-j}$  By binomial expansion of  $(1 - x)^{-d}$  when  $d < 1$  we get

$$\psi_j = \frac{\Gamma(j+d)}{\Gamma(j+1)\Gamma(d)}$$

where  $\Gamma$  is the usual gamma function, generalizing the factorial ( $\Gamma(\alpha) = (\alpha-1)\Gamma(\alpha-1)$ ).

Asymptotically we have

$$\psi_j = \frac{1}{\Gamma(d)} \frac{1}{j^{1-d}} \quad (1)$$

Similarly for  $Y_t$  to be invertible, we need to write

$\varepsilon_t = (1-B)^d Y_t = Y_t - \sum_{j=1}^{\infty} \pi_j Y_{t-j}$ . When  $d > -1$  we get

$$\pi_j = -\frac{\Gamma(j-d)}{\Gamma(j+1)\Gamma(-d)}$$

Note the recursion  $\pi_{j+1} = \pi_j \frac{(j-d)}{(j+1)}$ , and that asymptotically

$$\pi_j = -\frac{1}{\Gamma(-d)} \frac{1}{j^{1+d}} \quad (2)$$

Hence from (1) and (2), we see that, to ensure  $\sum \pi_j^2 < \infty$  and  $\sum \psi_j^2 < \infty$  we need  $-0.5 < d < 0.5$ .

## Definition

We say that  $(Y_t)$  is an ARFIMA process, that is a fractionally integrated autoregressive moving average process when for  $-0.5 < d < 0.5$ , we have

$$\phi(B)(1-B)^d Y_t = \theta(B)\varepsilon_t$$

where  $\phi(B)$  and  $\theta(B)$  satisfy the usual conditions.

It can be proved that asymptotically

$$\rho(h) \sim c \cdot h^{2d-1}$$

and it follows that

$$\begin{aligned} 0 < d < 0.5 & \quad \sum_{h=0}^{\infty} |\rho(h)| = \infty \\ -0.5 < d < 0 & \quad \sum_{h=0}^{\infty} |\rho(h)| < \infty \end{aligned}$$

In the first case, the series is said *persistent* and *anti-persistent* in the second one.

Several methods can be used to estimate  $d$ , compute the fitted values, the residuals and their sample variance. Among others, a MLE method consists in maximizing the likelihood of the errors  $\varepsilon_t(d)$  under normality. In R the [fracdiff](#) and [arfima](#) libraries provides a MLE computed by Gauss-Newton method. Methods based on the density spectral have also been proposed.

The spectral density exists and is well defined and given by:

$$\begin{aligned} f_Y(\omega) &= \sigma_\varepsilon^2 |1 - e^{-2\pi i \omega}|^{-2d} \\ &= \sigma_\varepsilon^2 [4 \sin^2(\pi \omega)]^{-d} \end{aligned}$$

The spectrum approaches  $\infty$  when  $\omega \rightarrow 0$

Forecasts in the fractional model are done the same way as for ARMA models: use the truncated  $\text{AR}(\infty)$  representation with  $\pi_j(\hat{d})$  calculated from the estimated parameters and control the standard errors by the way of the  $\text{MA}(\infty)$  representation.

$$\tilde{Y}_{t+m}^t = \sum_{j=1}^{m-1} \pi_j(\hat{d}) \tilde{Y}_{t+m-j}^t + \sum_{j=m}^{t+m-1} \pi_j(\hat{d}) Y_{t+m-j}$$

## Example

We use the file “varve”. Take the log, say  $\text{lvarve} = \log(\text{varve})$ . Plot the series lvarve and the ACF/PACF. Use `arfima` to fit a  $d$  value:

```
fr_lvarve<-arfima(lvarve)
```

Interpret the results and examine residuals.

## Exercise

Differentiate the `lvarve` series.

Plot the differentiated series and the ACF/PACF.

Fit an ARIMA model clearly suggested by these plots.

Get the residuals and compare with the residuals of the fractional fit.

## Example

```
.....
lvarve<- log(varve)
plot(lvarve,type="l")
acf2(lvarve) # ACF appears slow decreasing
fr_lvarve<-arfima(lvarve)
fr_lvarve
res<- residuals(fr_lvarve)[[1]]
plot(res,type="l")
acf2(res)
.....
```

## Exercise

```
.....
dflvarve<- diff(lvarve)
plot(dflvarve,type="l")
acf2(dflvarve) #
# could let think that arima(0,1,1) would be convenient
# adjust ,see residuals and compare with long memory
.....
```





Let's note that long-range dependence has undesirable effects: in particular the variance of  $\bar{X}_n$  can be heavily increased with respect to the i.i.d. case (with same theoretical variance), also with respect to a short dependence series. For instance for an AR(1) with  $\phi = 0.5$ ,  $n = 100$ , the variance is 3.041 times the one of the corresponding i.i.d.. For data with long dependence  $\rho(h) = 0.5 \cdot |h|^{-0.2}$ , this factor is 27.91. And the difference is increasing with  $n$ .

Note also that the forecast of short memory time series converge fastly to the mean of the past observations  $\bar{X}_n$ . The forecast based on a process with slowly decaying correlation converges rather slowly to  $\bar{X}_n$ : this means that the past observations influence the forecasts even far in the future.

Table 1.2. Comparison of  $v_o = \sigma n^{-\frac{1}{2}}$  with  $v_1 = \text{var}(\bar{X}_n)^{-\frac{1}{2}}$  for  $\rho(k) = a^{|k|}$  and for  $\rho(k) = \gamma \cdot |k|^{-0.2}$  ( $\gamma = 0.1, 0.5, 0.9$ ). Listed are the ratios  $q_n = v_1/v_o$ . Also given are the maximal correlations  $\rho_{max} = \max_k \rho(k)$ .

	$\rho_{max}$	$n = 50$	$n = 100$	$n = 400$	$n = 1000$
$\rho(k) = a^{ k }$					
$a = 0.1$	0.1	1.108	1.107	1.106	1.106
$a = 0.5$	0.5	1.755	1.744	1.735	1.733
$a = 0.9$	0.9	4.752	4.561	4.410	4.380
$\rho(k) = 0.1 \cdot  k ^{-0.2}$	0.1	2.007	2.526	4.197	5.978
$\rho(k) = 0.5 \cdot  k ^{-0.2}$	0.5	4.018	5.283	9.169	13.218
$\rho(k) = 0.9 \cdot  k ^{-0.2}$	0.9	5.316	7.032	12.269	17.711

Figure 1: Multiplicative factor with respect to the i.i.d. empirical variance of  $\bar{X}_n$

Table 1.3. *Comparison of the coverage probability of (1.2) with (incorrect) nominal coverage probability 0.95. Observations are assumed to be normal with correlations as in Table 1.2. Also listed are the maximal correlations  $\rho_{\max} = \max_k \rho(k)$ .*

	$\rho_{\max}$	$n = 50$	$n = 100$	$n = 400$	$n = 1000$
$\rho(k) = a^{ k }$					
$a = 0.1$	0.1	0.923	0.924	0.924	0.924
$a = 0.5$	0.5	0.756	0.739	0.741	0.742
$a = 0.9$	0.9	0.320	0.333	0.343	0.346
$\rho(k) = 0.1 \cdot  k ^{-0.2}$	0.1	0.671	0.562	0.359	0.257
$\rho(k) = 0.5 \cdot  k ^{-0.2}$	0.5	0.374	0.289	0.169	0.118
$\rho(k) = 0.9 \cdot  k ^{-0.2}$	0.9	0.288	0.220	0.127	0.088

Figure 2: Coverage probabilities

## Transfert function. Lagged regression.

Consider a model where:

$$Y_t = \sum_{j=0}^{\infty} \alpha_j X_{t-j} + \eta_t = \alpha(B)X_t + \eta_t \quad (3)$$

where  $\sum |\alpha_j| < \infty$  and  $\alpha(B) = \sum \alpha_j B^j$ .

$(X_t)$  and  $(\eta_t)$  are both stationary and mutually independent. We usually assume that they are ARMA processes.

The  $\alpha(B)$  is often proposed in the form:

$$\alpha(B) = \frac{\delta(B)}{\omega(B)} B^d$$

where

$$\omega(B) = 1 - \omega_1 B - \omega_2 B^2 - \dots - \omega_r B^r$$

and

$$\delta(B) = \delta_0 + \delta_1 B - \delta_2 B^2 + \dots + \delta_s B^s$$

We search for a simple form for  $\alpha(B)$ .

Assume that  $\phi(B)X_t = \theta(B)\varepsilon_t$  where  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$ .

Applying  $\phi(B)/\theta(B)$  on (3) yields:

$$\tilde{Y}_t = \frac{\phi(B)}{\theta(B)} Y_t = \alpha(B) \frac{\phi(B)}{\theta(B)} X_t + \frac{\phi(B)}{\theta(B)} \eta_t = \alpha(B) \varepsilon_t + \tilde{\eta}_t$$

$(\varepsilon_t)$  is a prewhitened version of  $(X_t)$ ; its cross-correlation with  $\tilde{Y}_t$  is

$$\gamma_{\tilde{Y}\varepsilon}(h) = \mathbb{E}[\tilde{Y}_{t+h} \varepsilon_t] = \sigma_\varepsilon^2 \alpha_h$$

Hence, up to a multiplicative constant, the CCF of  $\tilde{Y}_t$  and the prewhitened input series is an estimate of  $\alpha(B)$ .

## Exercise

Consider the SOI and Recruitment series (soi and rec):  $X_t = \text{soi}$ , and  $Y_t = \text{rec}$ .

- Detrend the SOI series by subtraction the linear regression on time. This result is named soi.d
- Plot the ACF and PACF of the residuals. This should give evidence for an ARMA(p,q).
- Get soi.pw the prewhitened version of soi.d
- Get rec.fil, the version  $\tilde{Y}_t$  of rec by using `filter(rec,...)`
- Plot the CCF of soi.pw and rec.fil and propose an interpretation.

It may happen that we are able to know the forms of  $\delta(B)$  and  $\omega(B)$  such that

$$Y_t = \frac{\delta(B)}{\omega(B)} B^d X_t + \eta_t \quad (4)$$

$$\omega(B)Y_t = \delta(B)B^d X_t + \omega(B)\eta_t \quad (5)$$

That is

$$Y_t = \sum_{k=1}^r \omega_k Y_{t-k} + \sum_{k=0}^s \delta_k X_{t-d-k} + u_t$$

where  $u_t = \omega(B)\eta_t$  and we assume  $(u_t) \sim \text{ARMA}$ .

### Example

Based on the exercise above, we may propose the model

$$Y_t = \alpha + \omega_1 Y_{t-1} + \delta_0 X_{t-5} + u_t$$

The model is fitted using [sarima](#) along the code given below.

```

.....
soi.d  = resid(lm(soi~time(soi), na.action=NULL)) # detrended SOI
acf2(soi.d)
fit     = arima(soi.d, order=c(1,0,0))
ar1     = as.numeric(coef(fit)[1]) # = 0.5875
soi.pw  = resid(fit)
rec.fil = filter(rec, filter=c(1, -ar1), sides=1)
ccf2(soi.pw, rec.fil, na.action=na.omit)
.....

.....
fish   = ts.intersect(rec, RL1=lag(rec,-1), SL5=lag(soi.d,-5))
(u     = lm(fish[,1]~fish[,2:3], na.action=NULL))
acf2(resid(u)) # suggests ar1
(arx   = sarima(fish[,1], 1, 0, 0, xreg=fish[,2:3])) # final model
pred   = rec - resid(arx$fit) # 1-step-ahead predictions
ts.plot(pred, rec, col=c('gray90',1), lwd=c(7,1))
.....

```

# Univariate ARMAX

ARMAX models can be seen as linear regression models with autocorrelated noise (generally as an ARMA model).

## Regression with correlated errors

Consider a generic model

$$Y_t = \beta_0 + \beta_1 x_{t1} + \dots + \beta_r x_{tr} + u_t \quad (6)$$

where  $(u_t)$  is a correlated noise.

Given observations  $(x_t, y_t)$ ,  $t = 1, \dots, n$ , we can use a matrix representation (as in ch.0)

$$\underline{y} = \underline{X}\underline{\beta} + \underline{u} \quad (7)$$

$$\begin{aligned} \underline{y} &= (y_1, \dots, y_n)' \\ \underline{u} &= (u_1, \dots, u_n)' \end{aligned}$$

and  $t = 1, \dots, n$ ,  $\underline{x}_t = (1, x_{t1}, \dots, x_{tr})'$ , that is  $\underline{x}_t$  is the value of all the independent variables for the  $t$ -th observation.

$\underline{\beta} = (\beta_0, \beta_1, \dots, \beta_r)'$  and the design matrix is  $\underline{X} = (\underline{x}'_1, \dots, \underline{x}'_n)'$ . Hence  $\underline{X}$  is a  $n \times (r + 1)$  matrix with generic term  $X_{tj} = x_{tj}$ .



Here we assume  $\text{Var}(\underline{u}) = \Sigma$ , with  $\Sigma_{ij} = \text{Cov}(u_i, u_j)$ . Applying  $\Sigma^{-1/2}$  on both parts of equation (7) yields

$$\begin{aligned}\Sigma^{-1/2}\underline{y} &= \Sigma^{-1/2}X\underline{\beta} + \Sigma^{-1/2}\underline{u} \\ \underline{y}^* &= X^*\underline{\beta} + \underline{\varepsilon}\end{aligned}\tag{8}$$

where  $\text{Var}(\underline{\varepsilon}) = I$ . It follows:

$$\hat{\underline{\beta}} = (X^{*'}X^*)^{-1}X^{*'}\underline{y}\tag{9}$$

$$= (X'\Sigma^{-1}X)^{-1}X'\Sigma^{-1}\underline{y}\tag{10}$$

and  $\text{Var}(\hat{\underline{\beta}}) = (X'\Sigma^{-1}X)^{-1}$ .

### When observations are ts.

When observations are time series it can be assumed that  $(u_t)$  is a 2nd order stationary process which we could model as an ARMA process. In the simplest case  $(u_t)$  could be an AR(p) process, that is

$$\phi(B)u_t = \varepsilon_t.$$

where  $\varepsilon_t \sim WN(0, \sigma^2)$  and  $\phi(B) = I - \phi_1 B - \phi_2 B^2 - \dots - \phi_p B^p$ .

Applying  $\phi(B)$  on both sides of equation (6) yields:

$$\begin{aligned}\phi(B)y_t &= \sum_{j=0}^r \beta_j \phi(B)x_{tj} + \phi(B)u_t \\ y_t^* &= \sum_{j=0}^r \beta_j x_{tj}^* + \varepsilon_t\end{aligned}$$

Consequently, to estimate  $\phi = \{\phi_1, \dots, \phi_p\}$  and  $\beta = \{\beta_0, \dots, \beta_r\}$  we can use the least squares method and minimize:

$$\begin{aligned}S(\phi, \beta) &= \sum_{t=1}^n (y_t^* - \sum_{j=0}^r \beta_j x_{tj}^*)^2 \\ &= \sum_{t=1}^n (\phi(B)y_t - \sum_{j=0}^r \beta_j \phi(B)x_{tj})^2\end{aligned}$$

When  $(u_t) \sim \text{ARMA}$ ,  $\phi(B)u_t = \theta(B)\varepsilon_t$ ,  $\varepsilon_t = \theta(B)^{-1}\phi(B)u_t = \pi(B)u_t$  and we have to minimize:

$$S(\phi, \theta, \beta) = \sum_{t=1}^n (\pi(B)y_t - \sum_{j=0}^r \beta_j \pi(B)x_{tj})^2 \quad (11)$$

In practice the following algorithm could be applied:

- 1 Perform the ordinary regression of  $(y_t)$  on  $(x_t)$  and get the residuals  $\hat{u}_t = y_t - \hat{y}_t$ .
- 2 Fit an ARMA model on  $(\hat{u}_t)$ .
- 3 Run the least squares method to minimize (11) from the autocorrelation structure deduced from step2
- 4 Examine the residuals  $(\hat{\varepsilon}_t)$  and possibly modify the model of step2

### Exercise

Apply the principle of this algorithm to the LA cardiovascular data with  $Y_t = cmort$  and independent regression variables  $trend = time(cmort)$ ,  $temp = tempr - mean(tempr)$ ,  $temp2 = temp^2$  and  $part$ . Plot the acf/pacf of the residuals. When the ARMA (p,0,q) model for  $(u_t)$  has been chosen, use the [sarima](#) function:

```
.....  
sarima(cmort, p,0,q, xreg=cbind(trend,temp,temp2,part) )  
.....
```

Analyze the residuals.

## Multivariate ARMAX

### Regression with k-dimensional response variable

Consider a linear regression where the response variable is k-dimensional:

$$y_t = (y_{t1}, \dots, y_{tk})'$$

and for  $j = 1, 2, \dots, k$

$$y_{tj} = \beta_{j0} + \beta_{j1}x_{t1} + \dots + \beta_{jr}x_{tr} + u_{tj}$$

for fixed  $t$ ,  $u_{t1}, \dots, u_{tk}$  are correlated, but the errors related to two different observations are uncorrelated, that is  $\text{Cov}(u_{si}, u_{tj}) = 0$ .

We can write:

$$y_t = \mathfrak{B}x_t + u_t \quad (12)$$

where  $y_t$  is a  $k \times 1$  vector, as well as  $u_t$ . The matrix  $\mathfrak{B}$  is  $k \times (r + 1)$  and  $x_t$  a  $(r + 1) \times 1$  vector.

When we are given  $n$  observations, the l.s.e. of  $\mathfrak{B}$  is given by:

$$\hat{\mathfrak{B}} = \left( \sum_{t=1}^n y_t x_t' \right) \left( \sum_{t=1}^n x_t x_t' \right)^{-1} \quad (13)$$

The covariance matrix of the residuals is estimated by:

$$\hat{\Sigma}_u = \frac{1}{n-r} \sum_{t=1}^n (y_t - \hat{\mathfrak{B}}x_t)(y_t - \hat{\mathfrak{B}}x_t)' \quad (14)$$

and the estimate of the standard error of  $\hat{\mathfrak{B}}$  :

$$s(\hat{\mathfrak{B}}_{ij}) = (c_{jj}\hat{\sigma}_{ii}^2)^{1/2}$$

for  $i = 1, \dots, k$  and  $j = 1, \dots, r+1$ .  $\hat{\sigma}_{ii}^2$  is the  $i$ -th diagonal term of  $\hat{\Sigma}_u$  and  $c_{jj}$  is the  $j$ -th diagonal term of  $\left(\sum_{t=1}^n x_t x_t'\right)^{-1}$ .

### When observations are $k$ -dimensional ts

Assume now that  $Y_t$  is a  $k$ -dimensional process. We focus on the simplest situation of a VAR(1) model:

$$Y_t = \alpha + \Phi Y_{t-1} + \varepsilon_t$$

where  $\Phi$  is a  $k \times k$  matrix and  $\varepsilon_t$  a vectorial white noise  $\mathcal{N}(0, \Sigma_\varepsilon)$ , and if  $\mathbb{E}(Y_t) = \mu$ ,  $\alpha = (I - \Phi)\mu$ .

We can apply the just above regression method for estimating  $(\alpha, \Phi)$ , using  $\mathfrak{B} = (\alpha, \Phi)$  and  $x_t = (1, y_{t-1})'$ . We get  $\hat{\mathfrak{B}}$  by (14) and  $\hat{\Sigma}_\varepsilon$  by

$$\hat{\Sigma}_\varepsilon = \frac{1}{n-1} \sum_{t=2}^n \left( y_t - \hat{\alpha} - \hat{\Phi} y_{t-1} \right) \left( y_t - \hat{\alpha} - \hat{\Phi} y_{t-1} \right)'$$

More generally: the method can be extended to an AR(p), and to include a fixed vector of inputs,  $z_t$ , that is a model of the form

$$Y_t = \Gamma z_t + \sum_{j=1}^p \Phi_j Y_{t-j} + \varepsilon_t$$

where  $z_t$  is a  $r' \times 1$  vector of inputs and  $\Gamma$  a  $k \times r'$  matrix.  
 VARMA is also possible,... but more involved!

**Exercise** Consider the vector  $Y_t = (cmort, tempr, part)'$  from the dataset of cardiovascular mortality at LA.

- 1 Adjust a VAR(1) model with a linear trend (type = "both") and analyze the results.

```
library(vars)
x = cbind(cmort, tempr, part)
summary(VAR(x, p=1, type="both")) # "both" fits constant + trend
```

- 2 Use information criteria to choose the  $p$  order of a more general VAR( $p$ )  
`VARselect(x, lag.max=10, type="both")`
- 3 Fit a VAR(2) model with linear trend (type = "both") and analyze the results. Plot the ACF of the residual vector. Perform a test for a vectorial white noise.  
`summary(fit = VAR(x, p=2, type="both"))`
- 4 Plot the acf of the residuals vector and test the hypothesis of vectorial white noise.  
`par(mfrow=c(3,3))`  
`acf(resid(fit), 52)`  
`serial.test(fit, lags.pt=12, type="PT.adjusted")`

Additional: forecasting.

```
(fit.pr = predict(fit, n.ahead = 24, ci = 0.95)) 4 weeks ahead  
fanchart(fit.pr) plot prediction + error
```



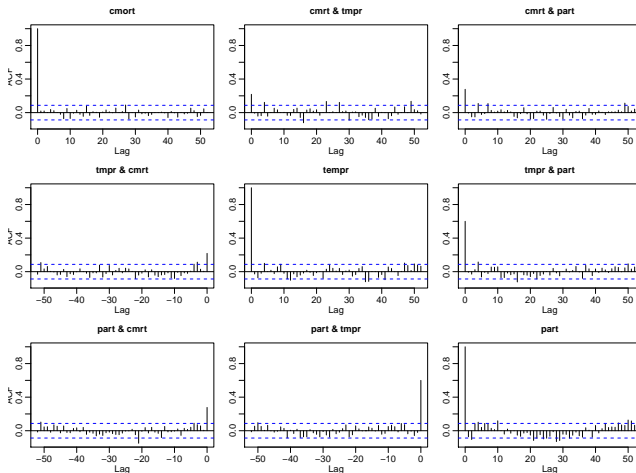


Figure 3: ACF of the residuals vector for VAR(2) model fit on LA cardiovascular mortality