Messages

Messages for Communication & Concurrency Control

IPC

Our Message Protocol

Mutexes & Signaling

Messages

 Interprocess communication (IPC): A system that allows processes to talk to each other

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What are some useful applications of IPC?

- IPC can denote communication between processes on the same computer
- However, IPC can also be used for distributed processes
 - Processes run on different computers
 - Connected through network
 - Sockets or messaging most common

- Interprocess communication (IPC): A system that allows processes to talk to each other
 - Messages/mailboxes (phase 2)
 - Signals
 - Pipes, files
 - Semaphores (phase 3)
 - Shared memory

- Mailboxes allow processes to send messages to other processes
 - Atomic messages, small payload
 - Buffering (often)
 - Blocking vs Non-blocking

- A signal is a software interrupt, sent from one process to another
 - OS must deliver, forces receiver into a signal handler function
 - Processes can block signals temporarily (analogous to disabling interrupts)
 - Typically no payload
 - "Default" behavior if no handler
 - Ignore, terminate, core dump, etc.

See \$ man 7 signal

Why would one choose to use a message/mailbox over a signal for IPC?

- A pipe is a file-like mechanism which handles a stream of bytes, but is never stored on disk
 - stdin, stdout, stderr
 - -cmd1 | cmd2
 - Usually only one reader, but many writers OK
 - Block writers when buffer fills

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- Semaphores are integers used for counting events, block processes when insufficient resources
 - No payload
 - P() decrements, blocks if insufficient
 - V () increments, releases blocked procs
 - Useful for mutexes, resource control, buffering
 - Slide deck later!

- Shared memory is any time that two processes map the same writable virtual page
 - Probably map to different virtual addresses
 - Instantaneous data flow
 - Need additional mechanism if want to coordinate via blocking
 - Hard to dynamically resize
 - Example: critical.c and critical_lock.c

Activity: IPC

Two processes A and B need to achieve mutual exclusion in a critical section via a lock (mutex).

Which form of IPC should be used?

Activity: IPC

Two processes A and B need to both send and receive strings between each-other to coordinate a computation.

Which form of IPC should be used?

- Non-blocking functions allow a program to ask if something is available, but refuse to block if not
 - Mostly used for IPC & dist. communication
 - Great for handling multiple simultaneous connections
 - Often, confusing to use
 - Can hurt performance if you don't have some way to sleep (spinning or polling)

Messages

Phase 2 Messaging Protocol

- In our simulation (Phase 2), we will implement mailboxes and messages
- Mailboxes are created with MboxCreate(), and identified by integer IDs
- Each mailbox will have two limits:
 - Max bytes per message (can be 0)
 - Max buffered messages (can be 0)

- In our simulation (Phase 2), we will implement mailboxes and messages
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Why would we ever want either or both of these to be zero?

- MboxSend() will "buffer" a message when there is no receiver ready to receive it
 - Each mailbox has a max (can be 0)
 - Sender will block if can't buffer
- Buffered messages must be delivered in order!!
- Blocked senders must be kept in order, too
 - Must buffer in same order they blocked
 - Beware priority problems!

- MboxRecv() will receive one message
 - Block if nothing buffered

- Messages must be received in order
- Blocked receivers must be kept in order
 - Beware priority problems here, too!

Process X (Priority 5)

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```
ID=MboxCreate()
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ID is 1

Process X (Priority 5)

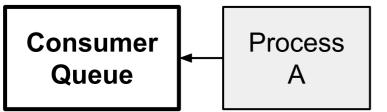
ID=MboxCreate()

ID is 1

fork1(pr=4) # A

Process A (Priority 4)

MboxRecv(1)
Block!



Process X (Priority 5)

ID=MboxCreate()

ID is 1

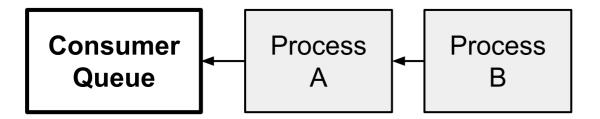
fork1(pr=4) # A fork1(pr=3) # B

Process A (Priority 4)

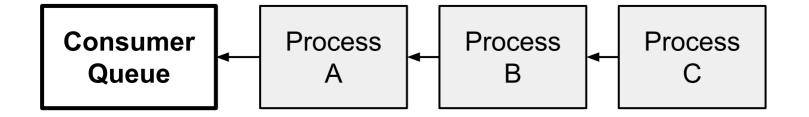
MboxRecv(1)
Block!

Process B (Priority 3)

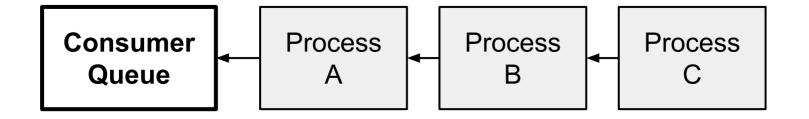
MboxRecv(1)
Block!

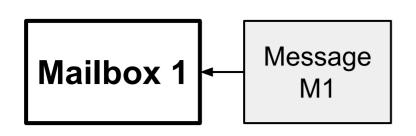


Process X Process A Process B Process C (Priority 5) (Priority 4) (Priority 3) (Priority 2) MboxRecv(1) MboxRecv(1) MboxRecv(1) ID=MboxCreate() # Block! # Block! # Block! # ID is 1 fork1(pr=4) # Afork1(pr=3) # Bfork1(pr=2) # C

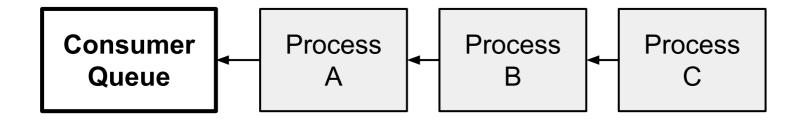


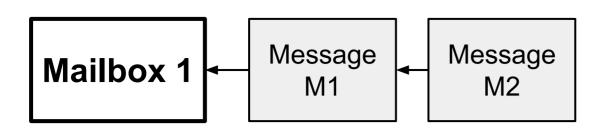
Process X (Priority 5)	Process A (Priority 4)	Process B (Priority 3)	Process C (Priority 2)	Process D (Priority 1)
ID=MboxCreate() # ID is 1	MboxRecv(1) # Block!	MboxRecv(1) # Block!	MboxRecv(1) # Block!	
fork1(pr=4) # A fork1(pr=3) # B fork1(pr=2) # C fork1(pr=1) # D				
••••				



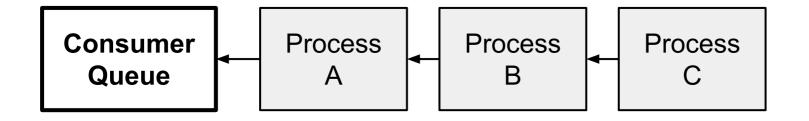


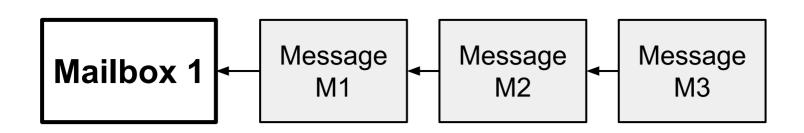
Process X (Priority 5)	Process A (Priority 4)	Process B (Priority 3)	Process C (Priority 2)	Process D (Priority 1)
ID=MboxCreate() # ID is 1	MboxRecv(1) # Block!	MboxRecv(1) # Block!	MboxRecv(1) # Block!	MboxSend(1, M1)
fork1(pr=4) # A fork1(pr=3) # B fork1(pr=2) # C fork1(pr=1) # D				

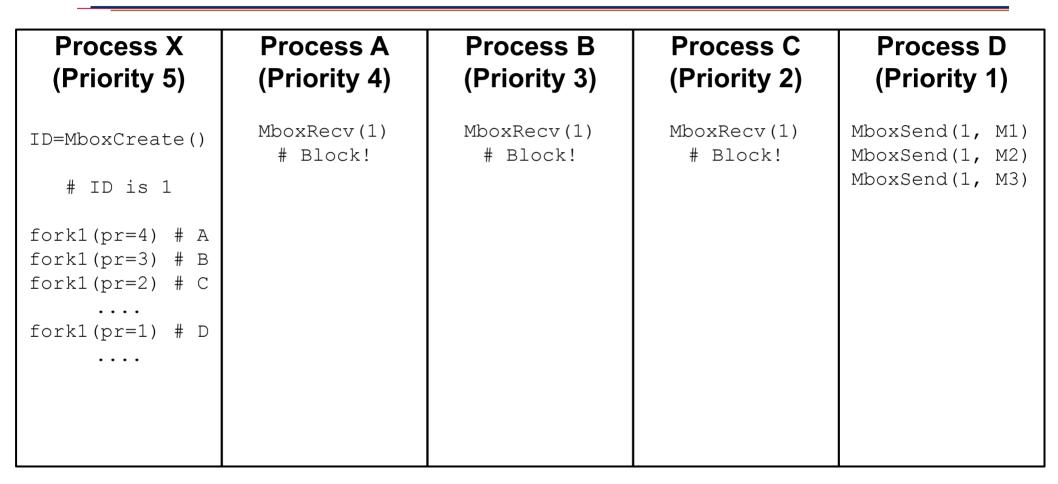


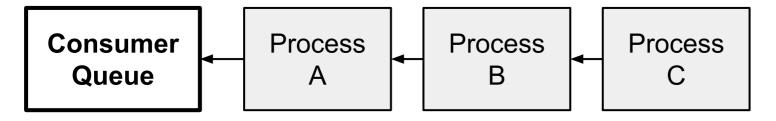


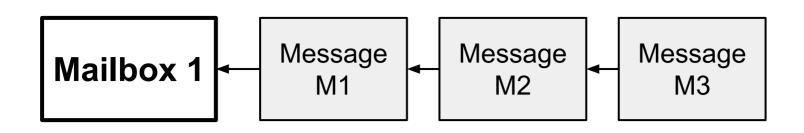
Process X (Priority 5)	Process A (Priority 4)	Process B (Priority 3)	Process C (Priority 2)	Process D (Priority 1)
ID=MboxCreate() # ID is 1	MboxRecv(1) # Block!	MboxRecv(1) # Block!	MboxRecv(1) # Block!	MboxSend(1, M1) MboxSend(1, M2)
fork1(pr=4) # A fork1(pr=3) # B fork1(pr=2) # C				
fork1(pr=1) # D				

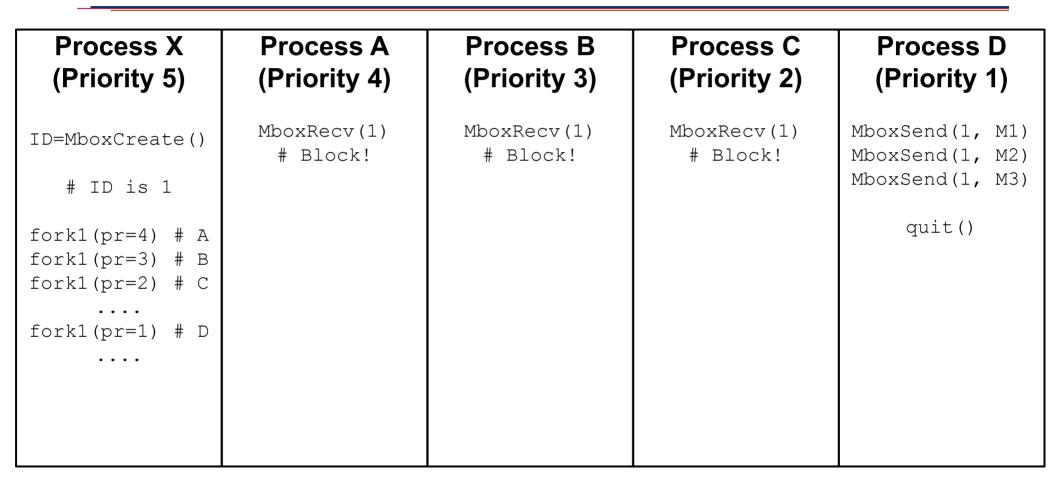


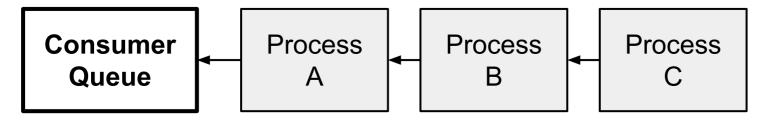


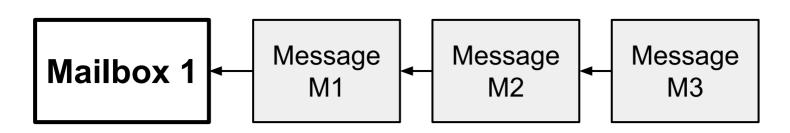


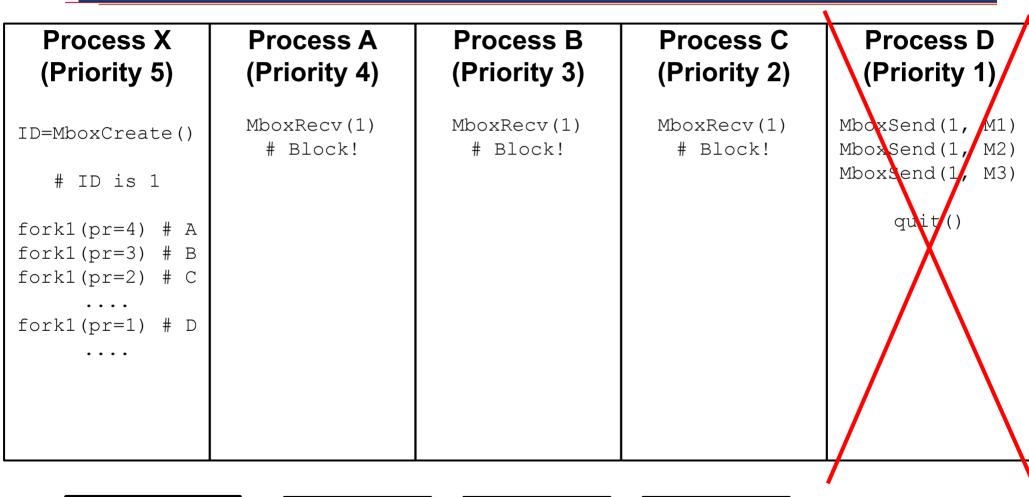




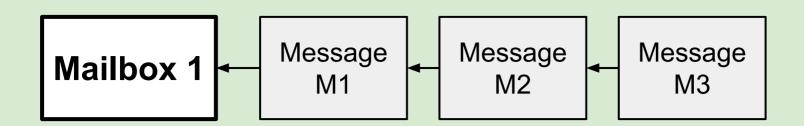












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ID is 1

fork1(pr=4) # A fork1(pr=3) # B fork1(pr=2) # C

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fork1(pr=1) # D

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Process A (Priority 4)

MboxRecv(1)
Block!

Process B (Priority 3)

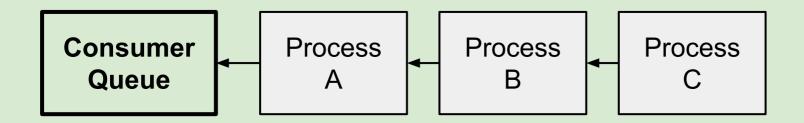
MboxRecv(1)
Block!

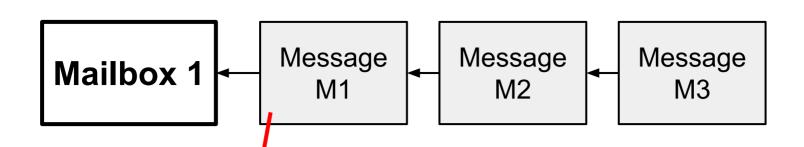
Process C (Priority 2)

MboxRecv(1)
Block!

Who should be woken up next?

> Who should receive M1?





Process X (Priority 5)

ID=MboxCreate()

ID is 1

fork1(pr=4) # A fork1(pr=3) # B

fork1(pr=2) # C

fork1(pr=1) # D

. . .

Process A (Priority 4)

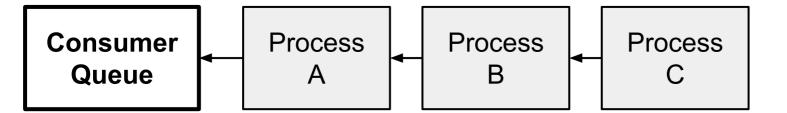
MboxRecv(1)

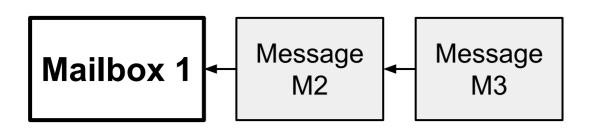
Process B (Priority 3)

MboxRecv(1)
Block!

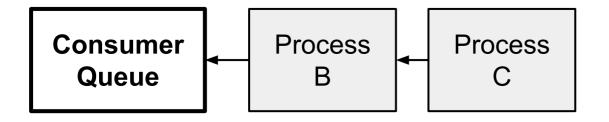
Process C (Priority 2)

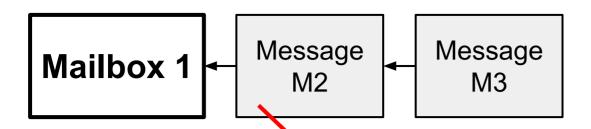
MboxRecv(1)
Block!



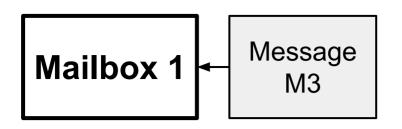


Process X Process A Process B Process C (Priority 5) (Priority 4) (Priority 3) (Priority 2) MboxRecv(1) MboxRecv(1) MboxRecv(1) ID=MboxCreate() # Block! # Block! # ID is 1 fork1(pr=4) # Afork1(pr=3) # Bfork1(pr=2) # Cfork1(pr=1) # D

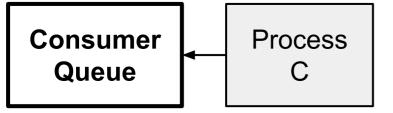


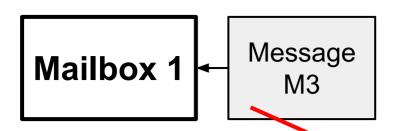


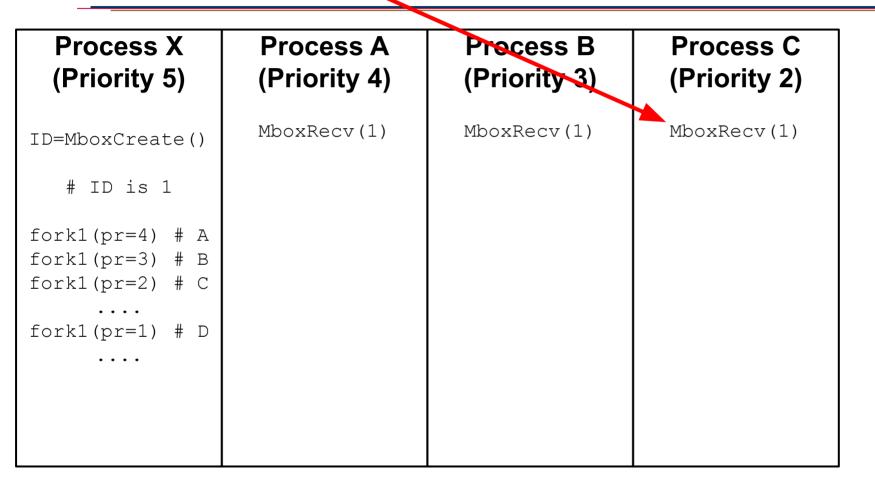
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fork1(pr=4) # A fork1(pr=3) # B fork1(pr=2) # C			
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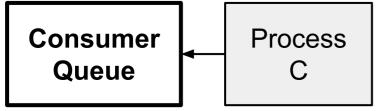


Process X (Priority 5)	Process A (Priority 4)	Process B (Priority 3)	Process C (Priority 2)
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fork1(pr=4) # A fork1(pr=3) # B fork1(pr=2) # C fork1(pr=1) # D			









Process A (Priority 4)	Process B (Priority 3)	Process C (Priority 2)
MboxRecv(1)	MboxRecv(1)	MboxRecv(1)
	(Priority 4)	(Priority 4) (Priority 3)

Consumer Queue

- We have a large pool of "message buffers"
 - Global pool, shared by all mailboxes
 - Allocate when you have a message
 - In MboxSend(), not MboxCreate()
 - Over-allocation is allowed
 - Buffering can fail if no free slots
 - Free in MboxRecv()

- MboxCondSend(), MboxCondRecv() are non-blocking versions
 - Send or recv if possible
 - Return special value if you would have blocked

Messages

Mutexes & Signaling

Mutexes & Signaling

- A mailbox can be used (abused?) as a mutex
 - Initialize with size 1
 - Send() to lock, Recv() to unlock
 - Process A calls Send() while in CS
 Process B calls Send() and blocks until A
 calls Recv()

ICA: Mutexes & Signaling

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Can it be reversed? Use Recv() to gain lock and Send() to release it? Discuss!

Mutexes & Signaling

- Soon, we'll be implementing syscalls
 - For example, call to fopen should block after the call until the the device responds
 - In-General: Block current process until something happens

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How to use mailboxes for sleep & wakeup?

Nicer interface than calling Phase 1 code How to do it? When to allocate mailboxes? What can be shared, or not?