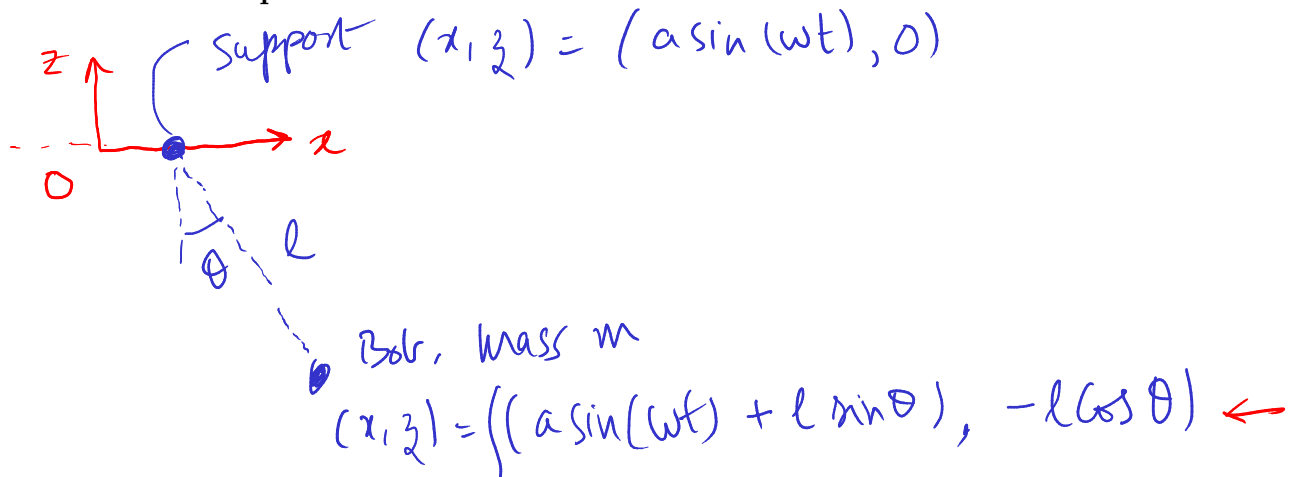


1. (5 points) A simple pendulum of mass m and length l has its point of support moving horizontally given by $x(t) = a \sin(\omega t)$ (assume that string remains "straight" at all times). Find the equation of motion of the bob, and then for small oscillations, comment on the expected solution.



Generalized Coordinates (l, θ)

KE of bob $= \frac{1}{2} m (\dot{x}^2 + \dot{z}^2) =$

$$= \frac{1}{2} m \left[(-a\omega \cos \omega t + l \cos \theta \dot{\theta})^2 + (l \sin \theta \dot{\theta})^2 \right]$$

$$= \frac{1}{2} m \left[a^2 \omega^2 \cos^2 \omega t - 2a\omega l \cos \omega t \cos \theta \dot{\theta} + l^2 \dot{\theta}^2 \right]$$

PE $= mgz = -mgl \cos \theta$

$L = KE - PE = \frac{1}{2} m \left[a^2 \omega^2 \cos^2 \omega t - 2a\omega l \cos \omega t \cos \theta \dot{\theta} + l^2 \dot{\theta}^2 \right] + mgl \cos \theta$

$L(\theta, \dot{\theta}, t)$ $\frac{\partial L}{\partial \theta} = \frac{1}{2} m \left[+2a\omega l \cos \omega t \sin \theta \dot{\theta} \right] - mgl \sin \theta$

$\frac{\partial L}{\partial \dot{\theta}} = \frac{1}{2} m \left[-2a\omega l \cos \omega t \cos \theta + l^2 2\dot{\theta} \right]$

$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = \frac{1}{2} m \left[2a\omega l (\cos \omega t \sin \theta \dot{\theta} - \omega \sin \omega t \cos \theta) + l^2 2\ddot{\theta} \right] - mgl \sin \theta$

$= \frac{\partial L}{\partial \theta} = \frac{1}{2} m \left[2a\omega l \cos \omega t \sin \theta \dot{\theta} \right] - mgl \sin \theta$

$\Rightarrow l^2 \ddot{\theta} = a\omega^2 l \sin \omega t \cos \theta - g l \sin \theta$

$\ddot{\theta} = -\frac{g}{l} \theta + \frac{a\omega^2}{l} \sin \omega t$

2. (5 points) On a particle the force is the following form $\vec{F}(\vec{r}) = (-ze^{-x}, \ln z, e^{-x} + y/z)$, where position vector $\vec{r} = (x, y, z)$. Does the work done when particle is moved from $(1, 1, 1)$ to $(2, 2, 2)$ depend on the path taken? Why or why not? Find the work for at least one such path by doing the line integral for the work done.

$$\left\{ \begin{array}{l} \frac{\partial F_x}{\partial y} = 0 \\ \frac{\partial F_y}{\partial x} = 0 \\ \frac{\partial F_z}{\partial x} = -e^{-x} \end{array} \right\} \left\{ \begin{array}{l} \frac{\partial F_x}{\partial z} = -e^{-x} \\ \frac{\partial F_y}{\partial z} = \frac{1}{z} \\ \frac{\partial F_z}{\partial y} = \frac{1}{z} \end{array} \right\} \left\{ \begin{array}{l} \text{Clearly } \frac{\partial F_x}{\partial y} = \frac{\partial F_y}{\partial x}, \frac{\partial F_x}{\partial z} = \frac{\partial F_z}{\partial x} \\ \text{and similarly for other} \\ \text{cross derivatives.} \end{array} \right.$$

So F is conservative.

PATH INDEPENDENT WORK!

$$F(x, y, z) = -\left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z}\right)$$

$$\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z}$$

$$\begin{aligned} -\frac{\partial u}{\partial x} &= F_x = -ze^{-x} \Rightarrow -u = ze^{-x} + C_1(y, z) \\ F_y &= \ln z \Rightarrow -u = y \ln z + C_2(z) \\ F_z &= \frac{y}{z} \Rightarrow -u = y \ln z + C_3(x, y) \end{aligned} \left\{ \begin{array}{l} -u = ze^{-x} + y \ln z + C \\ \rightarrow u(x, y, z) = -ze^{-x} - y \ln z + C_2 \end{array} \right.$$

$$W = \int_A^B d\vec{r} \cdot \vec{F} = \int_A^B dx(-ze^{-x}) + dy(\ln z) + dz(e^{-x} + y/z)$$

$$\begin{aligned} A &= (1, 1, 1) \rightarrow B = (2, 2, 2) \\ dx &= dy = dz \\ dx &= dy = dz = 1 \end{aligned}$$

$$W = -(u_2 - u_1)$$

For conservative

3. (5 points) A rod of length L_0 in its rest frame is lying at an angle θ with respect to x-axis. What is the length and orientation of this rod as measured by an observer moving along x-axis with speed v ?

Length contraction along x-axis; gives length $\Delta x' = \sqrt{1 - \frac{v^2}{c^2}} \cdot (L_0 \cos \theta)$

Looking

 $L_0 \cos \theta$

$$\Delta y' = L_0 \sin \theta$$

so length of rod will be $\sqrt{\Delta x'^2 + \Delta y'^2} = \sqrt{1 - \frac{v^2}{c^2}} \cdot L_0 \cos^2 \theta + L_0^2 \sin^2 \theta$

$$L = L_0 \sqrt{1 - \frac{v^2}{c^2} \cos^2 \theta}$$

Angle will be $\theta' = \tan^{-1} \left(\frac{\Delta y'}{\Delta x'} \right) = \tan^{-1} \left(\frac{L_0 \sin \theta}{L_0 \cos \theta \sqrt{1 - \frac{v^2}{c^2}}} \right)$

i.e. $\tan \theta' = \frac{\tan \theta}{\sqrt{1 - \frac{v^2}{c^2}}}$

4. (5 points) Rest mass energy of electron is 0.5 MeV, and of proton is 938 MeV. Anti-particles has same mass but opposite charge. In a particular nuclear reaction, electron and its anti-particle positron collide to give proton and its antiparticle anti-proton. What is the minimum kinetic energy of each particle to produce this reaction?



Energy Conservation $E(\text{React}) = E(\text{Prod.})$

$$\gamma_e m_e c^2 + \gamma_{e^+} m_{e^+} c^2 = \gamma_p m_p c^2 + \gamma_{p^+} m_{p^+} c^2$$

$$m_e c^2 [\gamma_e + \gamma_{e^+}] = m_p c^2 (\gamma_p + \gamma_{p^+})$$

clearly for minimum KE, γ has to be minimum.

"obviously": $\gamma_p = \gamma_{p^+} = 1$ (ie $v_p = v_{p^+} = 0$)

This gives $v_e = -v_{e^+}$ (by conservation of momentum)

and hence $(0.5 \text{ MeV}) 2\gamma_e = (938 \text{ MeV})(1+1)$

$$\Rightarrow \gamma_e = 2 \times 938 \text{ MeV} / 0.5 \text{ MeV} = 3752$$

and hence $\left\{ \begin{array}{l} KE_e = KE_{e^+} = (\gamma - 1) m_e c^2 \\ \quad = 1875 \times 0.5 \text{ MeV} \\ \quad = 937.5 \text{ MeV} \\ KE_p = KE_{p^+} = 0. \end{array} \right.$

ROUGH WORK