

Adjacency Matrix

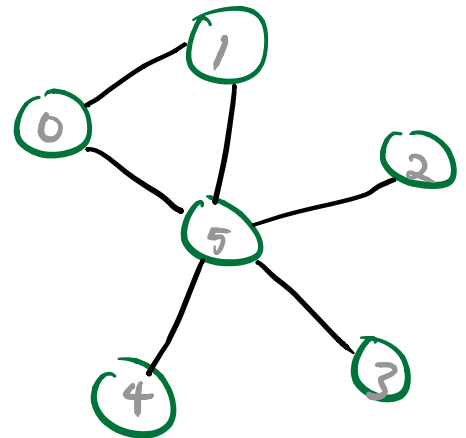
Checking if there exists an edge between two nodes? $O(1)$.

Iterating through all neighbours? $O(|V|)$

space? $O(|V|^2)$

Adding an edge between vertices v and w ? $connections[v][w]=1$

	0	1	2	3	4	5
0	0	1	0	0	0	1
1	1	0	0	0	0	1
2	0	0	0	0	0	1
3	0	0	0	0	0	1
4	0	0	0	0	0	1
5	1	1	1	1	1	0

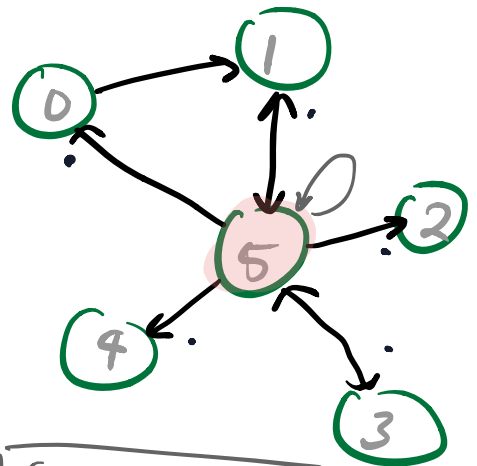


Undirected!

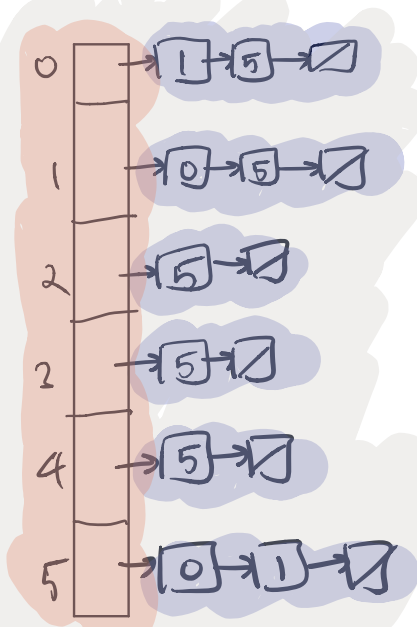
(if connected v
 \Rightarrow v connected
 to u)
 "symmetric".

	0	1	2	3	4	5
0	0	1	0	0	0	0
1	0	0	0	0	0	1
2						
3						
4						
5	1	1	1	1	1	1

directed!

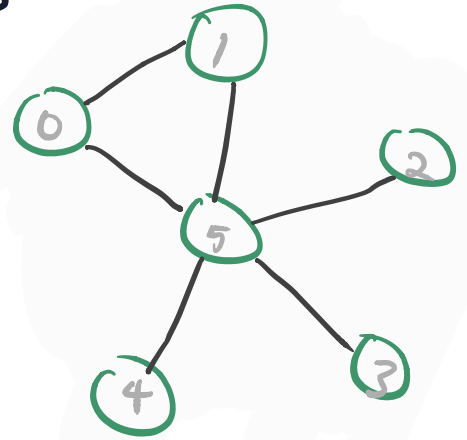


Adjacency List



Only store neighbours
for a given vertex.
Space?

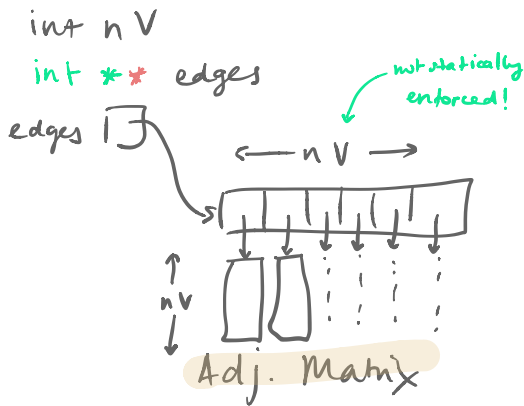
$$O(|V| + |E|)$$



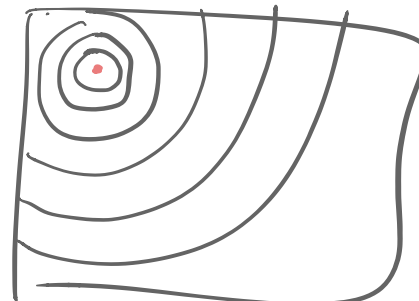
int n V
AdjList #edges

struct adjList :
Vertex node
AdjList next

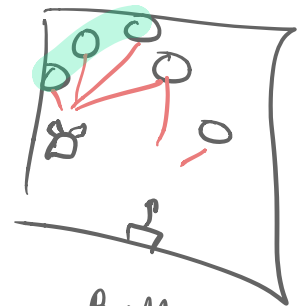
C Representation



Adj. List



ripple
(BFS)



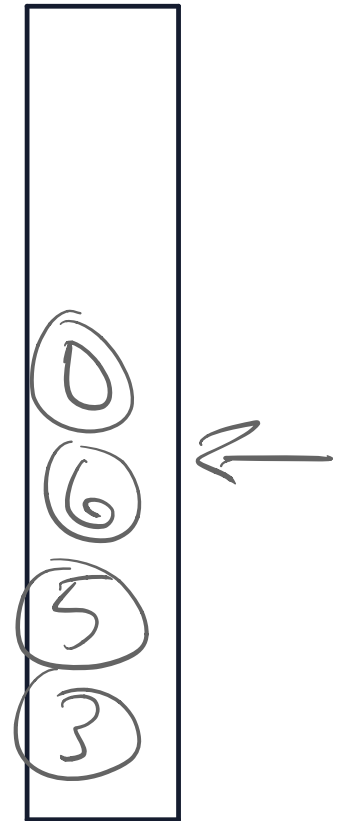
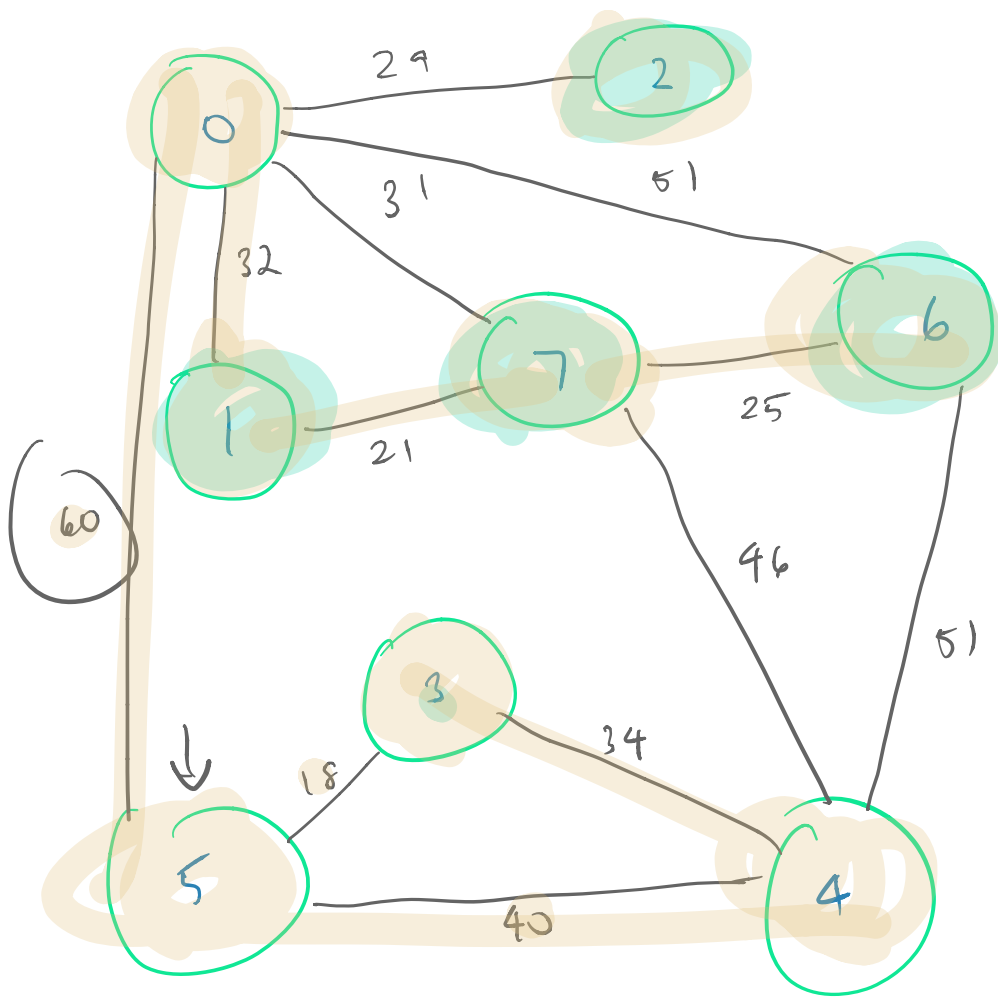
BFS.
(DFS)

Questions.

- (a) Time complexity to check if two vertices are neighbours? Adding an edge?
- (1) When is it appropriate to use an adj. matrix? similarly for adj list.

Extension : There is another representation of graphs that is useful in Functional Programming. Introduced in Erwig (2001) it's called an inductive graph. Inductive because it's defined in terms of itself.

Try and design an inductive graph.



STACK

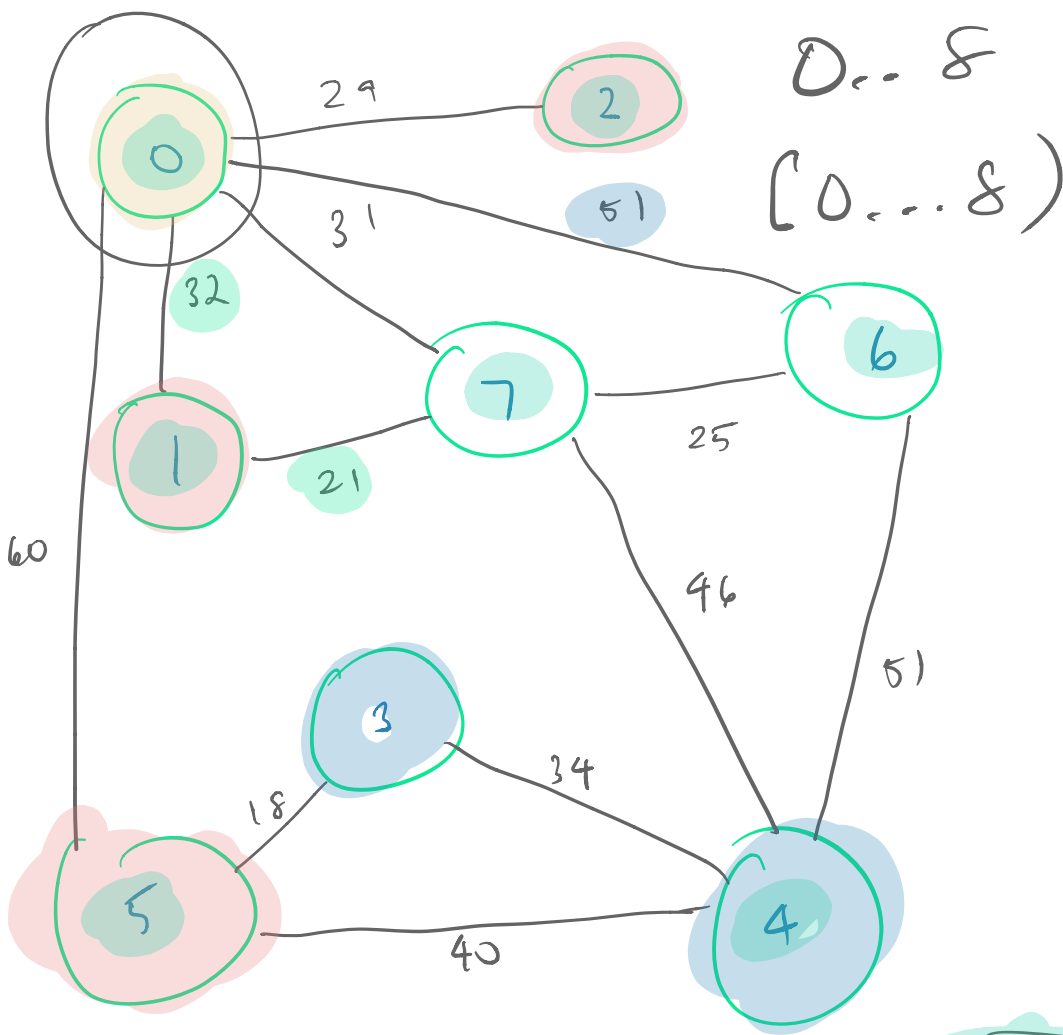
DFS

visited :

{ 3 : visited
4 : visited

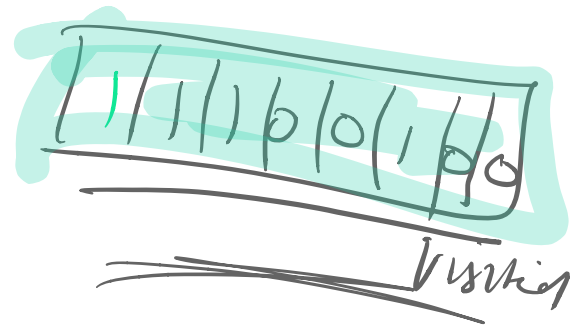
std::cout <<

0 \n 1 \n 2 \n



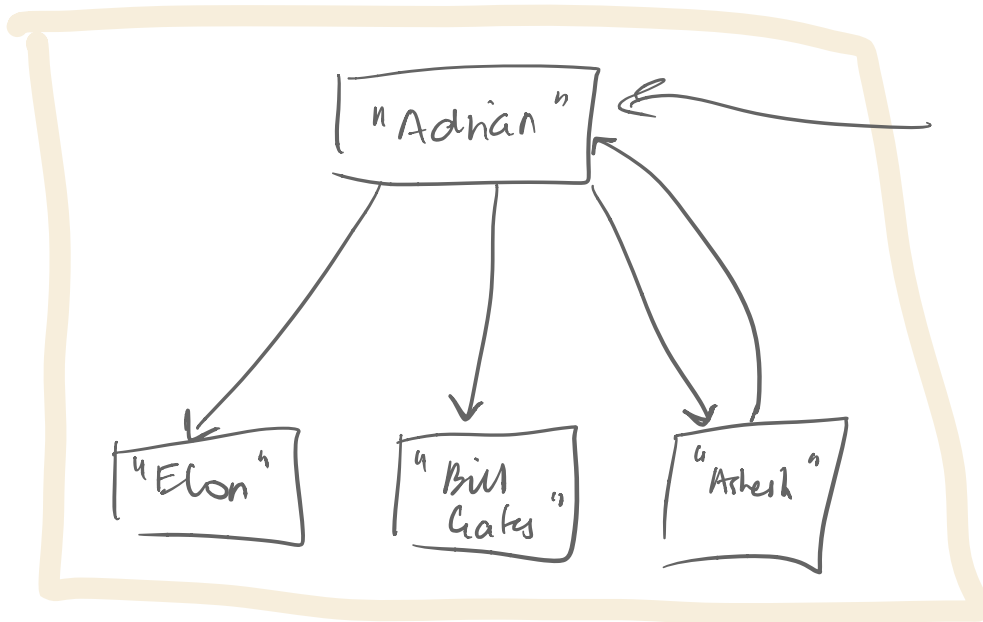
$x = 5$

BFS



VISITED?

We used assumption that all our vertices are labelled with tags from $O \dots nV$.
What if our graph represented a social network?



How would we implement a "visited" test during our DFS/BFS?

Implement function 'is visited' on graphs with string vertex names.

is visited :: Char * \rightarrow "Set" \rightarrow Bool.

① DIRECT MAP ARRAY. O(1) query.

② LINEAR STRUCTURES.

③ BALANCED TREES! lookup $O(\log n)$

