#include <Servo.h>

int pos = 0;

Servo servo\_9;

Servo servo\_10;

Servo servo\_11;

void setup()

{

servo\_9.attach(9);

servo\_10.attach(10);

servo\_11.attach(11);

}

void loop()

{

// sweep the servo from 0 to 180 degrees in steps

// of 1 degrees

for (pos = 0; pos <= 180; pos += 1) {

// tell servo to go to position in variable 'pos'

servo\_9.write(pos);

// wait 15 ms for servo to reach the position

delay(15); // Wait for 15 millisecond(s)

servo\_10.write(pos);

delay(15);

servo\_11.write(pos);

delay(15);

}

for (pos = 180; pos >= 0; pos -= 1) {

// tell servo to go to position in variable 'pos'

servo\_9.write(pos);

// wait 15 ms for servo to reach the position

delay(15); // Wait for 15 millisecond(s)

servo\_10.write(pos);

delay(15);

servo\_11.write(pos);

delay(15);

}

}