Al drones to track suspect vehicles

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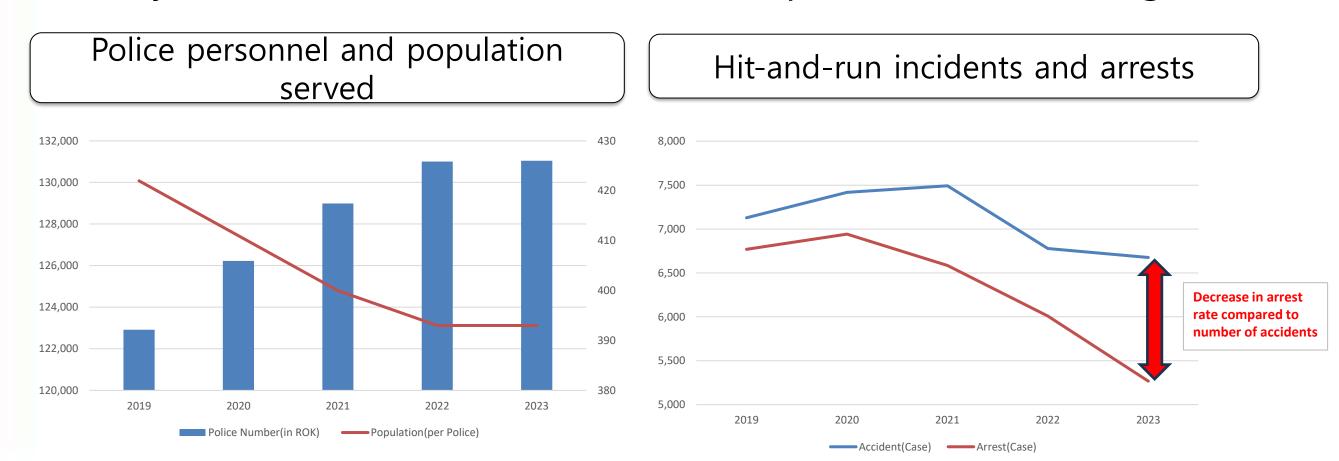
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Purpose

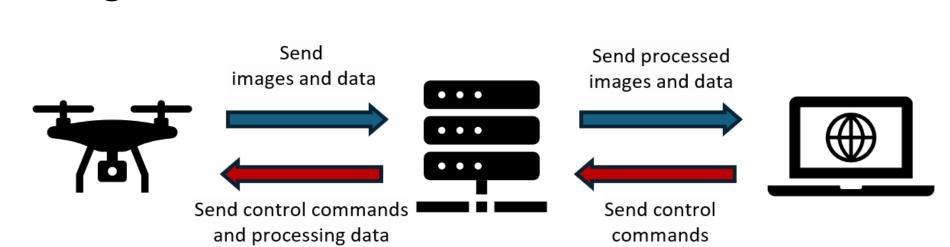
- Criminals sometimes use cars as a means of transportation and get away at high speeds.
- Tracking suspicious vehicles is expensive and can lead to **safety** incidents.
- Drones will be developed for widespread exploration and low-cost tracking of stolen vehicles.
- It will utilize stereo cameras to **track** the vehicle, recognize nearby obstacles, and use YOLO to improve vehicle recognition





What are deliverables?

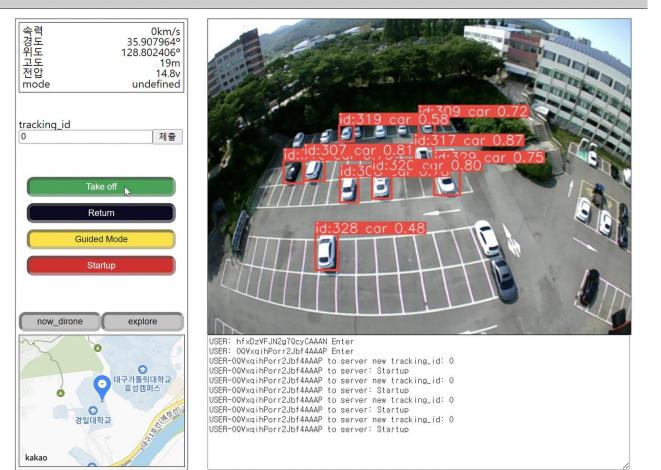
- Use a fixed camera mounted on the drone to send footage to the server.
- Tracking is done by using AI to enter the number of the object in question on a webpage, which then sends the coordinates of the drone.
- The drone uses the data it receives to track objects based on video footage





How dose it work?

Server
Web Client
Server log



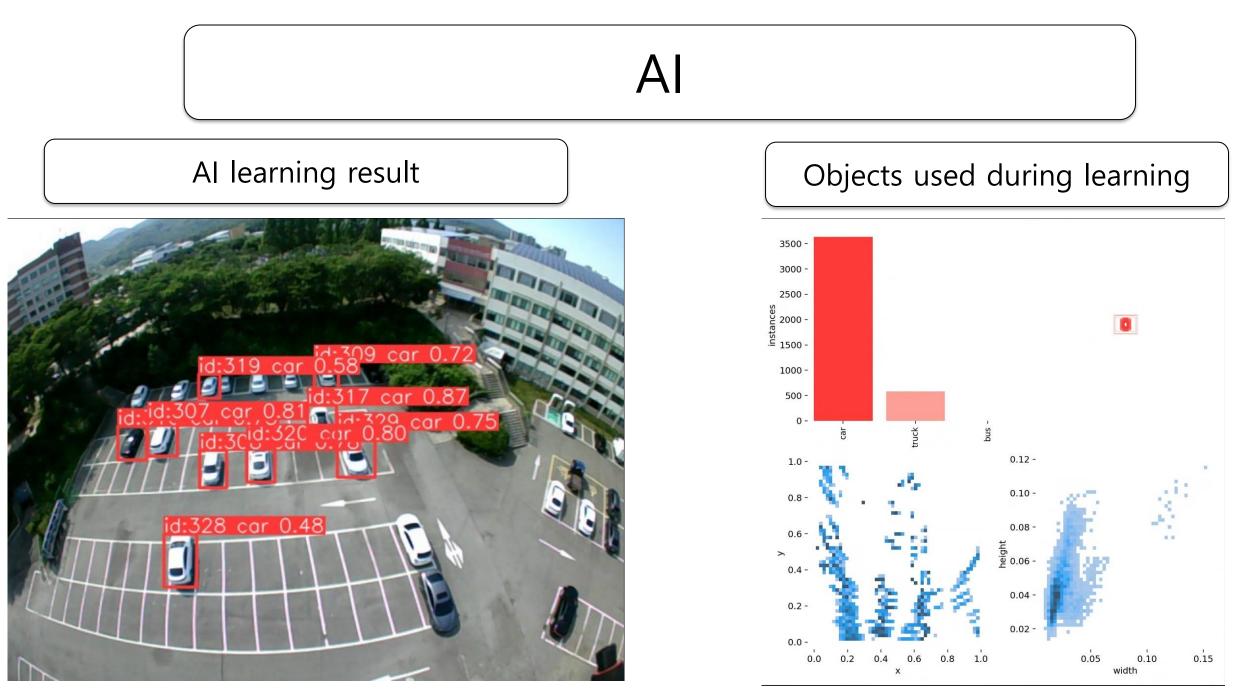
- listening on *:80
 server listen { address: '192.168.0.3', family: 'IPv4', port: 8484 }
 클라이언트 접속 ltnDkZWgp_jmdmmwAAAB
 [object Object] client connection
 USER-ltnDkZWgp_jmdmmwAAAB to server new tracking_id: 0
 Guide Mode:

 La 124.84848842774221

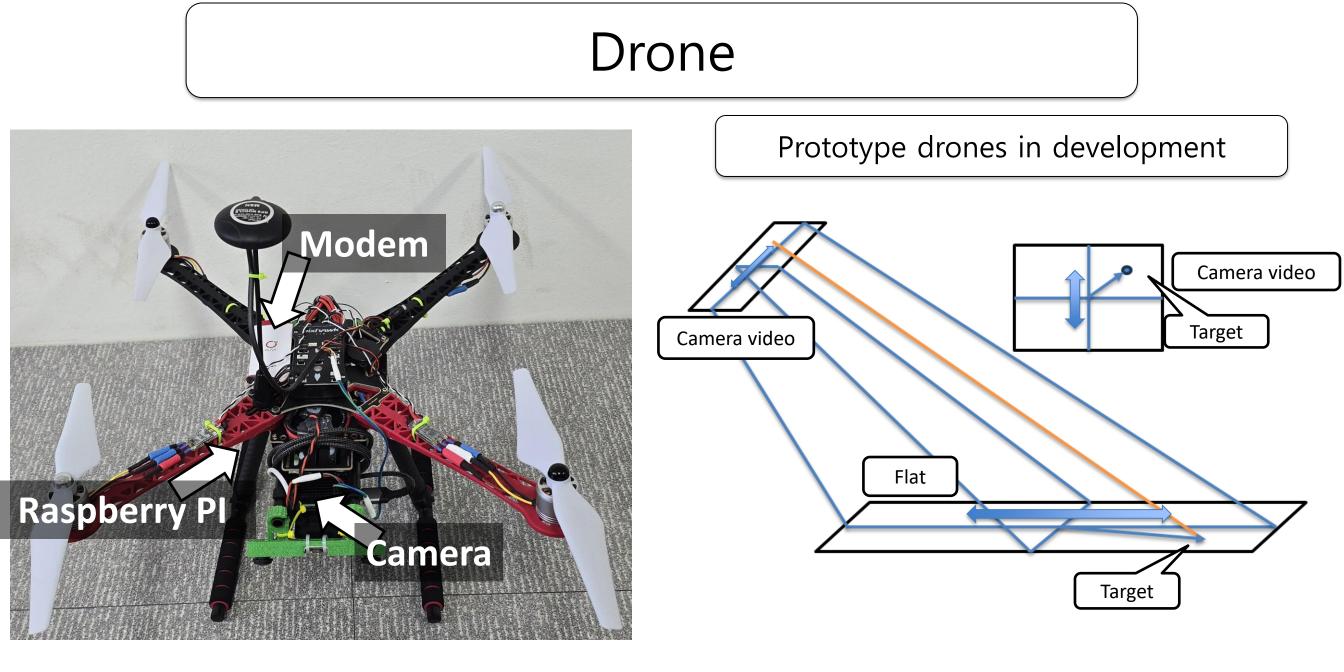
 Ma 33.474968908881905

 USER-ltnDkZWgp_jmdmmwAAAB to server: Guide Mode
 USER-ltnDkZWgp_jmdmmwAAAB to server new tracking_id: 0
 USER-ltnDkZWgp_jmdmmwAAAB to server: Startup
 USER-ltnDkZWgp_jmdmmwAAAB to server: Take off
 USER-ltnDkZWgp_jmdmmwAAAB to server: Take off
 USER-ltnDkZWgp_jmdmmwAAAB to server new tracking_id: 7
 USER-ltnDkZWgp_jmdmmwAAAB to server new tracking_id: 9
 USER-ltnDkZWgp_jmdmmwAAAB to server: Move
 USER-ltnDkZWgp_jmdmmwAAAB to server: Move
 USER-ltnDkZWgp_jmdmmwAAAB to server: Move
 USER-ltnDkZWgp_jmdmmwAAAB to server: Move
 USER-ltnDkZWgp_jmdmmwAAAB to server: Return

 BCP-ltnDkZWgp_jmdmmwAAAB to server: Return
- It communicates with the drone to receive drone status data and real-time video, and uses the Al module on the server to send the results to the drone and web client.
- Get the drone control commands from the web client and pass them to the drone.



- We collected about 200 aerial photos to train AI deep learning (about 3500 total differential car objects and 500 truck objects)
- Use YOLO to train on data to create a model.
- Recognize and track vehicle images and send data to the server.



- It uses TCP sockets to communicate between the drone and the server to autonomously drive and track objects.
- Receives the object coordinates and calculates the difference between the camera image center coordinates and the object coordinates.
- Distance and horizontal distance are calculated from the object's coordinate values, from which the object's GPS value is derived.



Application plan

- If the police are tracking a suspect rather than a vehicle, they can change the target to identify and track the suspect.
- Drones can also be used for rescue efforts, such as quickly identifying the scene of a fire or accident to reduce the risk of loss of life.
- With so many people with disabilities, dementia, or children going missing, police can use data to collect, track, and locate missing persons.



Expected effect

- Using drones to help police track suspects to maximize arrest rates
- Reduce the cost of suspect vehicle tracking
- Developed drones can be scaled up for a variety of uses, including rescue.