

# 3CNN, AvgPool, Sigmoid, Batch, SGD

March 25, 2024

```
[1]: %matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import torch
import torchvision
import torchvision.transforms as transforms
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
```

## Prepare for Dataset

```
[2]: transform = transforms.Compose(
    [#transforms.RandomHorizontalFlip(),
     #transforms.RandomRotation(10),
     transforms.ToTensor(),
     transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4, #Increase ↴
                                         ↪batch size
                                         shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                         shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified

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```
[3]: def imshow(img):
    img = img / 2 + 0.5
    npimg = img.numpy()
```

```
plt.imshow(np.transpose(npimg, (1, 2, 0)))
plt.show()

dataiter = iter(trainloader)
images, labels = next(dataiter)
imshow(torchvision.utils.make_grid(images))
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



truck truck horse ship

### Choose a Device

```
[4]: device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
print(device)
```

cuda:0

### Network Definition

```
[25]: class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()

        self.conv1 = nn.Conv2d(3, 32, 3, 1, 1)
        self.batch1 = nn.BatchNorm2d(32)
        self.activation1 = nn.Sigmoid()
        self.apool1 = nn.AvgPool2d(kernel_size = (2, 2))

        self.conv2 = nn.Conv2d(32, 16, 3, 1, 1)
        self.batch3 = nn.BatchNorm2d(16)
        self.activation2 = nn.Sigmoid()
        self.apool2 = nn.AvgPool2d(kernel_size = (2, 2))

        self.conv3 = nn.Conv2d(16, 64, 3, 1, 1)
        self.batch3 = nn.BatchNorm2d(64)
        self.activation3 = nn.Sigmoid()
        self.apool3 = nn.AvgPool2d(kernel_size = (2, 2))
```

```

        self.flat = nn.Flatten()

        self.fc1 = nn.Linear(1024,100)
        self.activation3 = nn.Sigmoid()
        self.fc2 = nn.Linear(100,10)

    def forward(self, x):

        x = self.activation1(self.conv1(x))
        x = self.apool1(x)
        x = self.activation2(self.conv2(x))
        x = self.apool2(x)
        x = self.activation3(self.conv3(x))
        x = self.apool3(x)
        x = self.flat(x)
        x = self.fc1(self.activation3(x))
        x = self.fc2(x)

    return x

net = Net()
net.to(device)

```

```

[25]: Net(
  (conv1): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (batch1): BatchNorm2d(32, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
  (activation1): ReLU()
  (apool1): AvgPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0)
  (conv2): Conv2d(32, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (batch3): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
  (activation2): ReLU()
  (apool2): AvgPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0)
  (conv3): Conv2d(16, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (activation3): ReLU()
  (apool3): AvgPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0)
  (flat): Flatten(start_dim=1, end_dim=-1)
  (fc1): Linear(in_features=1024, out_features=100, bias=True)
  (fc2): Linear(in_features=100, out_features=10, bias=True)
)

```

## Optimizer and Loss Function

```
[26]: loss_func = nn.CrossEntropyLoss()

      opt = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

### Training Procedure

```
[20]: avg_losses = []
      epochs = 15
      print_freq = 1500

      for epoch in range(epochs):
          running_loss = 0.0
          for i, data in enumerate(trainloader, 0):

              inputs, labels = data
              inputs, labels = inputs.to(device), labels.to(device)
              opt.zero_grad()
              outputs = net(inputs)
              loss = loss_func(outputs, labels)
              loss.backward()
              opt.step()

              running_loss += loss.item()
              if i % print_freq == print_freq - 1:
                  avg_loss = running_loss / print_freq
                  print('[epoch: {}], i: {:5d}] avg mini-batch loss: {:.3f}'.format(
                      epoch, i, avg_loss))
                  avg_losses.append(avg_loss)
                  running_loss = 0.0

      print('Finished Training.')
```

```
[epoch: 0, i: 1499] avg mini-batch loss: 2.346
[epoch: 0, i: 2999] avg mini-batch loss: 2.313
[epoch: 0, i: 4499] avg mini-batch loss: 2.307
[epoch: 0, i: 5999] avg mini-batch loss: 2.306
[epoch: 0, i: 7499] avg mini-batch loss: 2.303
[epoch: 0, i: 8999] avg mini-batch loss: 2.304
[epoch: 0, i: 10499] avg mini-batch loss: 2.304
[epoch: 0, i: 11999] avg mini-batch loss: 2.304
[epoch: 1, i: 1499] avg mini-batch loss: 2.304
[epoch: 1, i: 2999] avg mini-batch loss: 2.303
[epoch: 1, i: 4499] avg mini-batch loss: 2.303
[epoch: 1, i: 5999] avg mini-batch loss: 2.304
[epoch: 1, i: 7499] avg mini-batch loss: 2.303
[epoch: 1, i: 8999] avg mini-batch loss: 2.304
[epoch: 1, i: 10499] avg mini-batch loss: 2.303
[epoch: 1, i: 11999] avg mini-batch loss: 2.304
```

[epoch: 2, i: 1499] avg mini-batch loss: 2.303  
[epoch: 2, i: 2999] avg mini-batch loss: 2.304  
[epoch: 2, i: 4499] avg mini-batch loss: 2.303  
[epoch: 2, i: 5999] avg mini-batch loss: 2.304  
[epoch: 2, i: 7499] avg mini-batch loss: 2.304  
[epoch: 2, i: 8999] avg mini-batch loss: 2.303  
[epoch: 2, i: 10499] avg mini-batch loss: 2.303  
[epoch: 2, i: 11999] avg mini-batch loss: 2.304  
[epoch: 3, i: 1499] avg mini-batch loss: 2.303  
[epoch: 3, i: 2999] avg mini-batch loss: 2.303  
[epoch: 3, i: 4499] avg mini-batch loss: 2.303  
[epoch: 3, i: 5999] avg mini-batch loss: 2.304  
[epoch: 3, i: 7499] avg mini-batch loss: 2.304  
[epoch: 3, i: 8999] avg mini-batch loss: 2.304  
[epoch: 3, i: 10499] avg mini-batch loss: 2.303  
[epoch: 3, i: 11999] avg mini-batch loss: 2.303  
[epoch: 4, i: 1499] avg mini-batch loss: 2.304  
[epoch: 4, i: 2999] avg mini-batch loss: 2.304  
[epoch: 4, i: 4499] avg mini-batch loss: 2.303  
[epoch: 4, i: 5999] avg mini-batch loss: 2.304  
[epoch: 4, i: 7499] avg mini-batch loss: 2.303  
[epoch: 4, i: 8999] avg mini-batch loss: 2.304  
[epoch: 4, i: 10499] avg mini-batch loss: 2.304  
[epoch: 4, i: 11999] avg mini-batch loss: 2.303  
[epoch: 5, i: 1499] avg mini-batch loss: 2.304  
[epoch: 5, i: 2999] avg mini-batch loss: 2.303  
[epoch: 5, i: 4499] avg mini-batch loss: 2.304  
[epoch: 5, i: 5999] avg mini-batch loss: 2.303  
[epoch: 5, i: 7499] avg mini-batch loss: 2.304  
[epoch: 5, i: 8999] avg mini-batch loss: 2.304  
[epoch: 5, i: 10499] avg mini-batch loss: 2.304  
[epoch: 5, i: 11999] avg mini-batch loss: 2.304  
[epoch: 6, i: 1499] avg mini-batch loss: 2.304  
[epoch: 6, i: 2999] avg mini-batch loss: 2.304  
[epoch: 6, i: 4499] avg mini-batch loss: 2.303  
[epoch: 6, i: 5999] avg mini-batch loss: 2.304  
[epoch: 6, i: 7499] avg mini-batch loss: 2.304  
[epoch: 6, i: 8999] avg mini-batch loss: 2.303  
[epoch: 6, i: 10499] avg mini-batch loss: 2.304  
[epoch: 6, i: 11999] avg mini-batch loss: 2.303  
[epoch: 7, i: 1499] avg mini-batch loss: 2.304  
[epoch: 7, i: 2999] avg mini-batch loss: 2.304  
[epoch: 7, i: 4499] avg mini-batch loss: 2.303  
[epoch: 7, i: 5999] avg mini-batch loss: 2.303  
[epoch: 7, i: 7499] avg mini-batch loss: 2.304  
[epoch: 7, i: 8999] avg mini-batch loss: 2.304  
[epoch: 7, i: 10499] avg mini-batch loss: 2.303  
[epoch: 7, i: 11999] avg mini-batch loss: 2.304

[epoch: 8, i: 1499] avg mini-batch loss: 2.303  
[epoch: 8, i: 2999] avg mini-batch loss: 2.304  
[epoch: 8, i: 4499] avg mini-batch loss: 2.303  
[epoch: 8, i: 5999] avg mini-batch loss: 2.303  
[epoch: 8, i: 7499] avg mini-batch loss: 2.304  
[epoch: 8, i: 8999] avg mini-batch loss: 2.303  
[epoch: 8, i: 10499] avg mini-batch loss: 2.303  
[epoch: 8, i: 11999] avg mini-batch loss: 2.304  
[epoch: 9, i: 1499] avg mini-batch loss: 2.303  
[epoch: 9, i: 2999] avg mini-batch loss: 2.304  
[epoch: 9, i: 4499] avg mini-batch loss: 2.304  
[epoch: 9, i: 5999] avg mini-batch loss: 2.304  
[epoch: 9, i: 7499] avg mini-batch loss: 2.303  
[epoch: 9, i: 8999] avg mini-batch loss: 2.304  
[epoch: 9, i: 10499] avg mini-batch loss: 2.304  
[epoch: 9, i: 11999] avg mini-batch loss: 2.304  
[epoch: 10, i: 1499] avg mini-batch loss: 2.303  
[epoch: 10, i: 2999] avg mini-batch loss: 2.303  
[epoch: 10, i: 4499] avg mini-batch loss: 2.303  
[epoch: 10, i: 5999] avg mini-batch loss: 2.304  
[epoch: 10, i: 7499] avg mini-batch loss: 2.303  
[epoch: 10, i: 8999] avg mini-batch loss: 2.304  
[epoch: 10, i: 10499] avg mini-batch loss: 2.303  
[epoch: 10, i: 11999] avg mini-batch loss: 2.304  
[epoch: 11, i: 1499] avg mini-batch loss: 2.303  
[epoch: 11, i: 2999] avg mini-batch loss: 2.304  
[epoch: 11, i: 4499] avg mini-batch loss: 2.303  
[epoch: 11, i: 5999] avg mini-batch loss: 2.304  
[epoch: 11, i: 7499] avg mini-batch loss: 2.303  
[epoch: 11, i: 8999] avg mini-batch loss: 2.303  
[epoch: 11, i: 10499] avg mini-batch loss: 2.304  
[epoch: 11, i: 11999] avg mini-batch loss: 2.303  
[epoch: 12, i: 1499] avg mini-batch loss: 2.304  
[epoch: 12, i: 2999] avg mini-batch loss: 2.303  
[epoch: 12, i: 4499] avg mini-batch loss: 2.304  
[epoch: 12, i: 5999] avg mini-batch loss: 2.304  
[epoch: 12, i: 7499] avg mini-batch loss: 2.304  
[epoch: 12, i: 8999] avg mini-batch loss: 2.304  
[epoch: 12, i: 10499] avg mini-batch loss: 2.303  
[epoch: 12, i: 11999] avg mini-batch loss: 2.304  
[epoch: 13, i: 1499] avg mini-batch loss: 2.304  
[epoch: 13, i: 2999] avg mini-batch loss: 2.303  
[epoch: 13, i: 4499] avg mini-batch loss: 2.304  
[epoch: 13, i: 5999] avg mini-batch loss: 2.304  
[epoch: 13, i: 7499] avg mini-batch loss: 2.304  
[epoch: 13, i: 8999] avg mini-batch loss: 2.304  
[epoch: 13, i: 10499] avg mini-batch loss: 2.303  
[epoch: 13, i: 11999] avg mini-batch loss: 2.303

```

[epoch: 14, i: 1499] avg mini-batch loss: 2.303
[epoch: 14, i: 2999] avg mini-batch loss: 2.304
[epoch: 14, i: 4499] avg mini-batch loss: 2.303
[epoch: 14, i: 5999] avg mini-batch loss: 2.303
[epoch: 14, i: 7499] avg mini-batch loss: 2.303
[epoch: 14, i: 8999] avg mini-batch loss: 2.304
[epoch: 14, i: 10499] avg mini-batch loss: 2.303
[epoch: 14, i: 11999] avg mini-batch loss: 2.303
Finished Training.

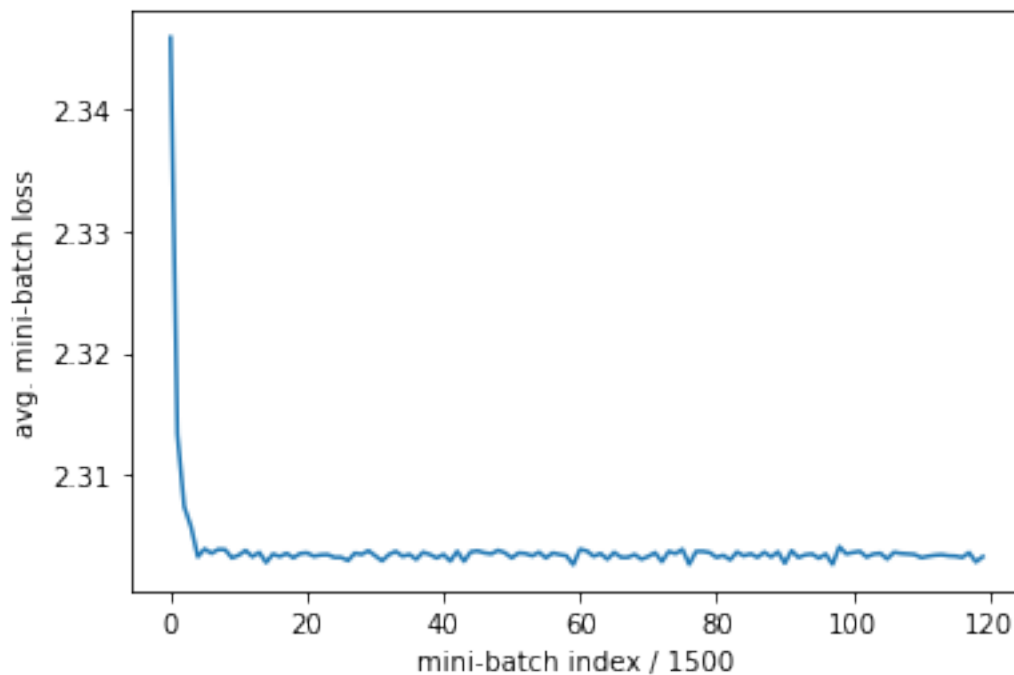
```

### Training Loss Curve

```

[21]: plt.plot(avg_losses)
plt.xlabel('mini-batch index / {}'.format(print_freq))
plt.ylabel('avg. mini-batch loss')
plt.show()

```



### Evaluate on Test Dataset

```

[22]: # Check several images.
dataiter = iter(testloader)
images, labels = next(dataiter)
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))
outputs = net(images.to(device))
_, predicted = torch.max(outputs, 1)

```

```
print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                                for j in range(4)))
```



```
GroundTruth:  cat  ship  ship plane
Predicted:   frog  frog  frog  frog
```

```
[23]: # Get test accuracy.
correct = 0
total = 0
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()

print('Accuracy of the network on the 10000 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 10000 test images: 10 %

```
[24]: # Get test accuracy for each class.
class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
```



```
        label = labels[i]
        class_correct[label] += c[i].item()
        class_total[label] += 1

for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))
```

```
Accuracy of plane :  0 %
Accuracy of  car :  0 %
Accuracy of bird :  0 %
Accuracy of  cat :  0 %
Accuracy of deer :  0 %
Accuracy of  dog :  0 %
Accuracy of frog : 100 %
Accuracy of horse :  0 %
Accuracy of ship :  0 %
Accuracy of truck :  0 %
```

[ ]: