3CNN, AvgPool, ReLU, No Batch, SGD

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```
[1]: %matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import torch
import torchvision
import torchvision.transforms as transforms
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
```

Prepare for Dataset

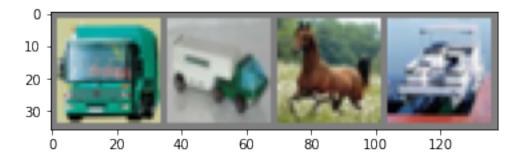
```
[2]: transform = transforms.Compose(
         [#transforms.RandomHorizontalFlip(),
          #transforms.RandomRotation(10),
          transforms.ToTensor(),
          transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
     trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                             download=True, transform=transform)
     trainloader = torch.utils.data.DataLoader(trainset, batch_size=4, #Increase_
      ⇔batch size
                                               shuffle=True, num_workers=2)
     testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                            download=True, transform=transform)
     testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                              shuffle=False, num_workers=2)
     classes = ('plane', 'car', 'bird', 'cat',
                'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified Files already downloaded and verified

```
[3]: def imshow(img):
    img = img / 2 + 0.5
    npimg = img.numpy()
```

```
plt.imshow(np.transpose(npimg, (1, 2, 0)))
   plt.show()

dataiter = iter(trainloader)
images, labels = next(dataiter)
imshow(torchvision.utils.make_grid(images))
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



truck truck horse ship

Choose a Device

```
[4]: device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu") print(device)
```

cuda:0

Network Definition

```
class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()

    self.convo1 = nn.Conv2d(3,32,3,1,1)
    self.activation1 = nn.ReLU()
    self.apool1 = nn.AvgPool2d(kernel_size = (2,2))

    self.convo2 = nn.Conv2d(32,16,3,1,1)
    self.activation2 = nn.ReLU()
    self.apool2 = nn.AvgPool2d(kernel_size = (2,2))

    self.convo3 = nn.Conv2d(16,64,3,1,1)
    self.activation3 = nn.ReLU()
    self.apool3 = nn.AvgPool2d(kernel_size = (2,2))

    self.flat = nn.Flatten()
```

```
self.fc1 = nn.Linear(1024,100)
              self.activation3 = nn.ReLU()
              self.fc2 = nn.Linear(100,10)
          def forward(self, x):
              x = self.activation1(self.convo1(x))
              x = self.apool1(x)
              x = self.activation2(self.convo2(x))
              x = self.apool2(x)
              x = self.activation3(self.convo3(x))
              x = self.apool3(x)
              x = self.flat(x)
              x = self.fc1(self.activation3(x))
              x = self.fc2(x)
              return x
      net = Net()
      net.to(device)
[27]: Net(
        (convo1): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (activation1): ReLU()
        (apool1): AvgPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0)
        (convo2): Conv2d(32, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (activation2): ReLU()
        (apool2): AvgPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0)
        (convo3): Conv2d(16, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (activation3): ReLU()
        (apool3): AvgPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0)
        (flat): Flatten(start_dim=1, end_dim=-1)
        (fc1): Linear(in_features=1024, out_features=100, bias=True)
        (fc2): Linear(in_features=100, out_features=10, bias=True)
      )
     Optimizer and Loss Function
[28]: loss_func = nn.CrossEntropyLoss()
      opt = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

Training Procedure

```
[29]: avg_losses = []
      epochs = 15
      print_freq = 1500
      for epoch in range(epochs):
          running_loss = 0.0
          for i, data in enumerate(trainloader, 0):
              inputs, labels = data
              inputs, labels = inputs.to(device), labels.to(device)
              opt.zero grad()
              outputs = net(inputs)
              loss = loss_func(outputs, labels)
              loss.backward()
              opt.step()
              running_loss += loss.item()
              if i % print_freq == print_freq - 1:
                  avg_loss = running_loss / print_freq
                  print('[epoch: {}, i: {:5d}] avg mini-batch loss: {:.3f}'.format(
                      epoch, i, avg_loss))
                  avg losses.append(avg loss)
                  running_loss = 0.0
      print('Finished Training.')
```

```
[epoch: 0, i: 1499] avg mini-batch loss: 2.218
[epoch: 0, i: 2999] avg mini-batch loss: 1.995
[epoch: 0, i: 4499] avg mini-batch loss: 1.796
[epoch: 0, i: 5999] avg mini-batch loss: 1.684
[epoch: 0, i: 7499] avg mini-batch loss: 1.579
[epoch: 0, i: 8999] avg mini-batch loss: 1.504
[epoch: 0, i: 10499] avg mini-batch loss: 1.449
[epoch: 0, i: 11999] avg mini-batch loss: 1.418
[epoch: 1, i: 1499] avg mini-batch loss: 1.371
[epoch: 1, i: 2999] avg mini-batch loss: 1.347
[epoch: 1, i: 4499] avg mini-batch loss: 1.318
[epoch: 1, i: 5999] avg mini-batch loss: 1.303
[epoch: 1, i: 7499] avg mini-batch loss: 1.250
[epoch: 1, i: 8999] avg mini-batch loss: 1.232
[epoch: 1, i: 10499] avg mini-batch loss: 1.215
[epoch: 1, i: 11999] avg mini-batch loss: 1.186
[epoch: 2, i: 1499] avg mini-batch loss: 1.140
[epoch: 2, i: 2999] avg mini-batch loss: 1.144
[epoch: 2, i: 4499] avg mini-batch loss: 1.134
[epoch: 2, i: 5999] avg mini-batch loss: 1.133
[epoch: 2, i: 7499] avg mini-batch loss: 1.122
```

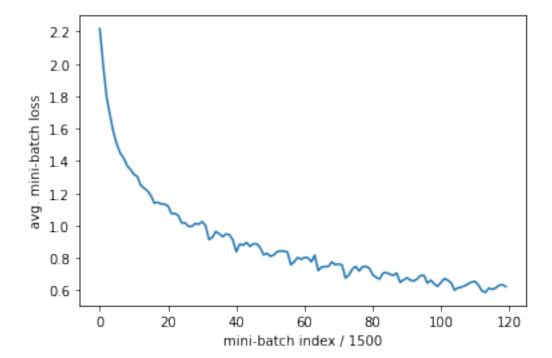
```
[epoch: 2, i: 8999] avg mini-batch loss: 1.075
[epoch: 2, i: 10499] avg mini-batch loss: 1.075
[epoch: 2, i: 11999] avg mini-batch loss: 1.063
[epoch: 3, i: 1499] avg mini-batch loss: 1.018
[epoch: 3, i: 2999] avg mini-batch loss: 1.017
[epoch: 3, i: 4499] avg mini-batch loss: 0.996
[epoch: 3, i:
              5999] avg mini-batch loss: 0.996
[epoch: 3, i: 7499] avg mini-batch loss: 1.013
[epoch: 3, i: 8999] avg mini-batch loss: 1.009
[epoch: 3, i: 10499] avg mini-batch loss: 1.025
[epoch: 3, i: 11999] avg mini-batch loss: 1.001
[epoch: 4, i: 1499] avg mini-batch loss: 0.915
[epoch: 4, i:
              2999] avg mini-batch loss: 0.928
[epoch: 4, i: 4499] avg mini-batch loss: 0.964
[epoch: 4, i: 5999] avg mini-batch loss: 0.950
[epoch: 4, i: 7499] avg mini-batch loss: 0.932
[epoch: 4, i: 8999] avg mini-batch loss: 0.949
[epoch: 4, i: 10499] avg mini-batch loss: 0.943
[epoch: 4, i: 11999] avg mini-batch loss: 0.912
[epoch: 5, i:
              1499] avg mini-batch loss: 0.839
[epoch: 5, i:
              2999] avg mini-batch loss: 0.886
[epoch: 5, i: 4499] avg mini-batch loss: 0.880
[epoch: 5, i: 5999] avg mini-batch loss: 0.896
[epoch: 5, i: 7499] avg mini-batch loss: 0.872
[epoch: 5, i:
              8999] avg mini-batch loss: 0.888
[epoch: 5, i: 10499] avg mini-batch loss: 0.888
[epoch: 5, i: 11999] avg mini-batch loss: 0.865
[epoch: 6, i: 1499] avg mini-batch loss: 0.819
[epoch: 6, i:
              2999] avg mini-batch loss: 0.829
[epoch: 6, i: 4499] avg mini-batch loss: 0.810
[epoch: 6, i: 5999] avg mini-batch loss: 0.819
[epoch: 6, i:
              7499] avg mini-batch loss: 0.839
[epoch: 6, i: 8999] avg mini-batch loss: 0.843
[epoch: 6, i: 10499] avg mini-batch loss: 0.843
[epoch: 6, i: 11999] avg mini-batch loss: 0.836
[epoch: 7, i: 1499] avg mini-batch loss: 0.758
[epoch: 7, i: 2999] avg mini-batch loss: 0.778
[epoch: 7, i: 4499] avg mini-batch loss: 0.803
[epoch: 7, i: 5999] avg mini-batch loss: 0.792
[epoch: 7, i: 7499] avg mini-batch loss: 0.803
[epoch: 7, i: 8999] avg mini-batch loss: 0.802
[epoch: 7, i: 10499] avg mini-batch loss: 0.777
[epoch: 7, i: 11999] avg mini-batch loss: 0.818
[epoch: 8, i: 1499] avg mini-batch loss: 0.723
[epoch: 8, i: 2999] avg mini-batch loss: 0.744
[epoch: 8, i: 4499] avg mini-batch loss: 0.748
[epoch: 8, i: 5999] avg mini-batch loss: 0.748
[epoch: 8, i: 7499] avg mini-batch loss: 0.776
```

```
[epoch: 8, i: 8999] avg mini-batch loss: 0.758
[epoch: 8, i: 10499] avg mini-batch loss: 0.763
[epoch: 8, i: 11999] avg mini-batch loss: 0.756
[epoch: 9, i:
              1499] avg mini-batch loss: 0.676
[epoch: 9, i:
              2999] avg mini-batch loss: 0.695
[epoch: 9, i: 4499] avg mini-batch loss: 0.732
[epoch: 9, i:
              5999] avg mini-batch loss: 0.748
[epoch: 9, i: 7499] avg mini-batch loss: 0.720
[epoch: 9, i: 8999] avg mini-batch loss: 0.746
[epoch: 9, i: 10499] avg mini-batch loss: 0.748
[epoch: 9, i: 11999] avg mini-batch loss: 0.737
[epoch: 10, i:
               1499] avg mini-batch loss: 0.696
[epoch: 10, i:
               2999] avg mini-batch loss: 0.680
[epoch: 10, i:
               4499] avg mini-batch loss: 0.670
[epoch: 10, i:
               5999] avg mini-batch loss: 0.707
[epoch: 10, i:
               7499] avg mini-batch loss: 0.710
[epoch: 10, i:
               8999] avg mini-batch loss: 0.700
[epoch: 10, i: 10499] avg mini-batch loss: 0.692
[epoch: 10, i: 11999] avg mini-batch loss: 0.707
[epoch: 11, i:
               1499] avg mini-batch loss: 0.650
               2999] avg mini-batch loss: 0.664
[epoch: 11, i:
[epoch: 11, i:
               4499] avg mini-batch loss: 0.678
[epoch: 11, i:
               5999] avg mini-batch loss: 0.663
[epoch: 11, i:
               7499] avg mini-batch loss: 0.658
[epoch: 11, i:
               8999] avg mini-batch loss: 0.671
[epoch: 11, i: 10499] avg mini-batch loss: 0.692
[epoch: 11, i: 11999] avg mini-batch loss: 0.693
[epoch: 12, i:
               1499] avg mini-batch loss: 0.645
[epoch: 12, i:
               2999] avg mini-batch loss: 0.663
[epoch: 12, i:
               4499] avg mini-batch loss: 0.641
[epoch: 12, i:
               5999] avg mini-batch loss: 0.626
               7499] avg mini-batch loss: 0.649
[epoch: 12, i:
[epoch: 12, i:
               8999] avg mini-batch loss: 0.673
[epoch: 12, i: 10499] avg mini-batch loss: 0.663
[epoch: 12, i: 11999] avg mini-batch loss: 0.646
[epoch: 13, i:
               1499] avg mini-batch loss: 0.601
[epoch: 13, i:
               2999] avg mini-batch loss: 0.616
[epoch: 13, i:
               4499] avg mini-batch loss: 0.620
[epoch: 13, i:
               5999] avg mini-batch loss: 0.629
               7499] avg mini-batch loss: 0.641
[epoch: 13, i:
[epoch: 13, i:
               8999] avg mini-batch loss: 0.652
[epoch: 13, i: 10499] avg mini-batch loss: 0.655
[epoch: 13, i: 11999] avg mini-batch loss: 0.632
[epoch: 14, i:
               1499] avg mini-batch loss: 0.597
[epoch: 14, i:
               2999] avg mini-batch loss: 0.588
[epoch: 14, i:
               4499] avg mini-batch loss: 0.614
[epoch: 14, i:
               5999] avg mini-batch loss: 0.607
[epoch: 14, i: 7499] avg mini-batch loss: 0.615
```

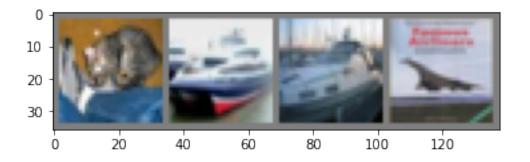
```
[epoch: 14, i: 8999] avg mini-batch loss: 0.631 [epoch: 14, i: 10499] avg mini-batch loss: 0.636 [epoch: 14, i: 11999] avg mini-batch loss: 0.623 Finished Training.
```

Training Loss Curve

```
[30]: plt.plot(avg_losses)
    plt.xlabel('mini-batch index / {}'.format(print_freq))
    plt.ylabel('avg. mini-batch loss')
    plt.show()
```



Evaluate on Test Dataset



GroundTruth: cat ship ship plane Predicted: dog ship ship plane

```
[32]: # Get test accuracy.
correct = 0
total = 0
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to(device), labels.to(device)
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()

print('Accuracy of the network on the 10000 test images: %d %%' % (
        100 * correct / total))
```

Accuracy of the network on the 10000 test images: 73 %

```
for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))

Accuracy of plane : 78 %
Accuracy of car : 83 %
Accuracy of bird : 68 %
Accuracy of cat : 50 %
Accuracy of deer : 69 %
Accuracy of dog : 67 %
Accuracy of frog : 78 %
Accuracy of horse : 74 %
Accuracy of ship : 86 %
Accuracy of truck : 80 %
```