

UNIT-1
GROUPS - SEM3
LONGS

Theorem No.: 1

Prove that the set of all +ve rational numbers forms an abelian group with respect to the binary operation "o" defined as $a \circ b = \frac{ab}{3} \forall a, b \in \mathbb{Q}^+$.

Proof:

Let \mathbb{Q}^+ is set of all +ve rational numbers

For $a, b \in \mathbb{Q}^+ \Rightarrow a \circ b = \frac{ab}{3}$

* Closure law:

For $a, b \in \mathbb{Q}^+$

$$\Rightarrow a \circ b = \frac{ab}{3}$$

\therefore "o" satisfies closure law.

* Associative law:

For $a, b, c \in \mathbb{Q}^+$

$$\Rightarrow a \circ (b \circ c) = (a \circ b) \circ c \in \mathbb{Q}^+$$

$$\text{L.H.S} = a \circ (b \circ c)$$

$$= a \circ \left(\frac{bc}{3}\right)$$

$$= \frac{a \cdot \frac{bc}{3}}{3}$$

$$= \frac{\frac{abc}{3}}{3}$$

$$= \frac{(a \circ b) \cdot c}{3}$$

$$= (a \circ b) \circ c$$

$$= \text{R.H.S}$$

$$\therefore \text{L.H.S} = \text{R.H.S}$$

\therefore "o" satisfies associative law.

* Existence of Identity law:

For $a \in \mathbb{Q}^+$

$\exists e \in \mathbb{Q}^+$ Such that $a \circ e = e \circ a = a$

$$\Rightarrow a \circ e = a$$

$$\Rightarrow \frac{ae}{3} = a$$

$$\Rightarrow ae = 3a$$

$$\Rightarrow e = 3$$

$$\text{L.H.S.} = aoe$$

$$= \frac{ae}{3}$$

$$= \frac{a \cdot 3}{3}$$

$$= a$$

$$= \text{R.H.S.}$$

Similarly, we can prove that $ea = a$.

" $e=3$ " is the identity element of a in \mathbb{Q}^+ .
 \therefore " 0 " satisfies existence of identity law in \mathbb{Q}^+ .

* Existence of Inverse law:

For $a \in \mathbb{Q}^+$

$\exists b \in \mathbb{Q}^+$ such that $ao b = bo a = e$

$$\Rightarrow aob = e$$

$$\Rightarrow \frac{ab}{3} = 3$$

$$\Rightarrow ab = 9$$

$$\Rightarrow b = \frac{9}{a}$$

$$\text{L.H.S.} = aob$$

$$= \frac{ab}{3} a o \frac{9}{a}$$

$$= \frac{a \frac{9}{a}}{3}$$

$$= \frac{9}{3}$$

$$= 3$$

$$= e$$

$$= \text{R.H.S.}$$

Similarly, we can prove that $boa = e$.

" $b = \frac{9}{a}$ " is Inverse element of a in \mathbb{Q}^+ .

\therefore " 0 " satisfies existence of Inverse in \mathbb{Q}^+ .

*Abelian law:

For $a, b \in \mathbb{Q}^+$

$$\Rightarrow a \circ b = b \circ a$$

$$\text{L.H.S} = a \circ b$$

$$= \frac{ab}{3}$$

$$= \frac{ba}{3}$$

$$= b \circ a$$

$$= \text{R.H.S}$$

\therefore "0" satisfies abelian law in \mathbb{Q}^+ .

$(\mathbb{Q}^+, 0)$ forms an abelian group.

Theorem: 2

Prove that the Set of integers \mathbb{Z} forms an abelian group w.r.t the operation $*$ defined by $a * b = a + b + 2$, for all $a, b \in \mathbb{Z}$.

Proof:

Let " \mathbb{Z} " be the set of all Integers.

For $a, b \in \mathbb{Z} \Rightarrow a * b = a + b + 2$.

* Closure law:

For $a, b \in \mathbb{Z}$

$$a * b = a + b + 2.$$

\therefore " $*$ " Satisfies closure law.

* Associative law:

For $a, b, c \in \mathbb{Z}$

$$a * (b * c) = (a * b) * c$$

$$\text{L.H.S} = a * (b * c)$$

$$= a * (b + c + 2)$$

$$= a + b + c + 2 + 2$$

$$= a + b + c + 4.$$

$$\text{R.H.S} = (a * b) * c$$

$$(a+b+2)*c$$

$$= a+b+c+2$$

$$= a+b+c+4$$

$$\therefore L.H.S = R.H.S$$

$\therefore *$ Satisfies associative law.

* Existence of Identity law:

For $a \in \mathbb{Z}$

$\exists e \in \mathbb{Z}$ Such that $a*e = e*a = a$

$$L.H.S = a*e = a$$

$$a+e+2 = a$$

$$e = -2$$

$$R.H.S = e*a = a$$

$$e+a+2 = a$$

$$e = -2$$

" $e = -2$ " is the identity element of a in \mathbb{Z}

$\therefore *$ Satisfies the existence of Identity law in \mathbb{Z} .

* Existence of Inverse law:

For $a \in \mathbb{Z}$

$\exists b \in \mathbb{Z}$ Such that $a*b = b*a = e$

$$\Rightarrow a*b = e$$

$$\Rightarrow a+b+2 = -2$$

$$\Rightarrow b = -4-a$$

$$L.H.S = a*b$$

$$= a+b+2$$

$$= a-4-a+2$$

$$= -2$$

$$= e$$

$$= R.H.S$$

$$\therefore L.H.S = R.H.S$$

Similarly, we can prove that $b*a = e$.

$b = -4 - a$ is the inverse of a in \mathbb{Z}

$\therefore "$ $*$ $"$ Satisfies the existence of Inverse law.

* Abelian law:

For $a, b \in \mathbb{Z}$

$$\Rightarrow a * b = b * a$$

$$\text{L.H.S} = a * b$$

$$= a + b + 2$$

$$= b + a + 2$$

$$= b * a$$

$$= \text{R.H.S}$$

$$\text{L.H.S} = \text{R.H.S}$$

$\therefore "$ $*$ $"$ Satisfies abelian law.

$\therefore (\mathbb{Z}, *)$ forms an abelian group.

[$\because a, b \in \mathbb{Z}, a + b = b + a$
By using abelian w.r.t to $+$]

③ Prove that the set of matrices $A_\alpha = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$

$\alpha \in \mathbb{R}$ forms a group w.r.t matrix multiplication
-on if $\cos \theta = \cos \phi \Rightarrow \theta = \phi$.

Proof:

For all $\alpha, \beta, \gamma \in \mathbb{R}$

$$G = \{ A_\alpha \mid \alpha \in \mathbb{R} \}$$

$$\therefore A_\alpha = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$$

$$A_\beta = \begin{bmatrix} \cos \beta & -\sin \beta \\ \sin \beta & \cos \beta \end{bmatrix}$$

$$A_\gamma = \begin{bmatrix} \cos \gamma & -\sin \gamma \\ \sin \gamma & \cos \gamma \end{bmatrix}$$

* closure law:

For $A_\alpha, A_\beta \in G$.

$$A_\alpha \cdot A_\beta = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{bmatrix} \cos \beta & -\sin \beta \\ \sin \beta & \cos \beta \end{bmatrix}$$

$$\begin{bmatrix} \sin \alpha \cos \beta + \cos \alpha \sin \beta & -\cos \alpha \sin \beta + \sin \alpha \cos \beta \\ \cos \alpha \sin \beta + \sin \alpha \cos \beta & -\sin \alpha \sin \beta + \cos \alpha \cos \beta \end{bmatrix}$$

$$= \begin{bmatrix} \cos(\alpha+\beta) & -\sin(\alpha+\beta) \\ \sin(\alpha+\beta) & \cos(\alpha+\beta) \end{bmatrix} \in G \quad \left[\because \alpha, \beta \in \mathbb{R}; \text{By using closure law wrt '+'} \right. \\ \left. \alpha+\beta \in \mathbb{R} \right]$$

\therefore " " Satisfies closure law in G .

* Associative law:-

For $A_\alpha, A_\beta, A_\gamma \in G$.

$$\Rightarrow (A_\alpha \cdot A_\beta) \cdot A_\gamma = A_\alpha \cdot (A_\beta \cdot A_\gamma) \in G.$$

$$\text{L.H.S} = (A_\alpha \cdot A_\beta) A_\gamma$$

$$= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{bmatrix} \cos \beta & -\sin \beta \\ \sin \beta & \cos \beta \end{bmatrix} \begin{bmatrix} \cos \gamma & -\sin \gamma \\ \sin \gamma & \cos \gamma \end{bmatrix}$$

$$= \begin{bmatrix} \cos \alpha \cos \beta - \sin \alpha \sin \beta & -\sin \beta \cos \alpha - \sin \alpha \cos \beta \\ \sin \alpha \cos \beta + \sin \beta \cos \alpha & -\sin \alpha \sin \beta + \cos \alpha \cos \beta \end{bmatrix} \begin{bmatrix} \cos \gamma & -\sin \gamma \\ \sin \gamma & \cos \gamma \end{bmatrix}$$

$$= \begin{bmatrix} \cos(\alpha+\beta) & -\sin(\alpha+\beta) \\ \sin(\alpha+\beta) & \cos(\alpha+\beta) \end{bmatrix} \begin{bmatrix} \cos \gamma & -\sin \gamma \\ \sin \gamma & \cos \gamma \end{bmatrix}$$

$$= \begin{bmatrix} \cos[(\alpha+\beta)+\gamma] & -\sin[(\alpha+\beta)+\gamma] \\ \sin[(\alpha+\beta)+\gamma] & \cos[(\alpha+\beta)+\gamma] \end{bmatrix} \quad \left[\because \alpha, \beta, \gamma \in \mathbb{R} \right. \\ \left. \text{By using Associative law wrt '+'} \right]$$

$$= \begin{bmatrix} \cos[\alpha+(\beta+\gamma)] & -\sin[\alpha+(\beta+\gamma)] \\ \sin[\alpha+(\beta+\gamma)] & \cos[\alpha+(\beta+\gamma)] \end{bmatrix} \quad (\alpha+\beta)+\gamma = \alpha+(\beta+\gamma)$$

$$= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{bmatrix} \cos(\beta+\gamma) & -\sin(\beta+\gamma) \\ \sin(\beta+\gamma) & \cos(\beta+\gamma) \end{bmatrix}$$

$$= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \left(\begin{bmatrix} \cos \beta & -\sin \beta \\ \sin \beta & \cos \beta \end{bmatrix} \begin{bmatrix} \cos \gamma & -\sin \gamma \\ \sin \gamma & \cos \gamma \end{bmatrix} \right)$$

$$= A_\alpha \cdot (A_\beta \cdot A_\gamma)$$

$$= \text{R.H.S}$$

$$\text{L.H.S} = \text{R.H.S}$$

\therefore " " Satisfies Associative law in G .

* Existence of Identity law:

For $A_\alpha \in G$

$$\exists I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \cos 0 & -\sin 0 \\ \sin 0 & \cos 0 \end{bmatrix}, A_0 \in G \forall 0 \in \mathbb{R} \text{ such}$$

$$\text{that } A_\alpha \cdot A_0 = A_0 \cdot A_\alpha = A_\alpha.$$

$$L.H.S = A_\alpha \cdot A_0$$

$$= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{bmatrix} \cos 0 & -\sin 0 \\ \sin 0 & \cos 0 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \alpha \cos 0 + \sin \alpha \sin 0 & -\sin \alpha \cos 0 - \sin \alpha \cos 0 \\ \sin \alpha \cos 0 + \sin 0 \cos \alpha & -\sin 0 \sin \alpha + \cos \alpha \cos 0 \end{bmatrix}$$

$$= \begin{bmatrix} \cos(\alpha+0) & -\sin(\alpha+0) \\ \sin(\alpha+0) & \cos(\alpha+0) \end{bmatrix} \left[\because 0, \alpha \in \mathbb{R} \text{ By using closure law w.r.t to } +, \alpha+0 \in \mathbb{R} \right]$$

$$= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$$

$$= A_\alpha$$

$$= R.H.S$$

$$L.H.S = R.H.S$$

Similarly, we can prove that $A_0 \cdot A_\alpha = A_\alpha$

$\therefore A_0$ is the multiplicative identity.

$\therefore "$ " Satisfies existence of Identity law in G .

* Existence of Inverse law:

For $A_\alpha \in G$

$$A_\alpha = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$$

$$|A_\alpha| = \cos^2 \alpha + \sin^2 \alpha = 1 \neq 0$$

A_α is non singular matrix.

A_α^{-1} exists.

$$A_\alpha^{-1} = \frac{\text{Adj } A}{|A|}$$

$$\text{Adj } A = \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix}$$

$\exists A_\alpha^{-1} \in G$ such that $A_\alpha \cdot A_\alpha^{-1} = A_\alpha^{-1} \cdot A_\alpha = A_0$

$$\text{L.H.S} = A_\alpha \cdot A_\alpha^{-1}$$

$$= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix}$$

$$= \begin{bmatrix} \cos^2 \alpha + \sin^2 \alpha & \sin \alpha \cos \alpha - \sin \alpha \cos \alpha \\ \sin \alpha \cos \alpha - \sin \alpha \cos \alpha & \cos^2 \alpha + \sin^2 \alpha \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= A_0$$

$$= \text{R.H.S}$$

$$\text{L.H.S} = \text{R.H.S}$$

\therefore Similarly, we can prove that $A_\alpha^{-1} \cdot A_\alpha = A_0$

$\therefore A_\alpha^{-1}$ is the multiplicative inverse of A_α in G .

\therefore " " Satisfies Existence of Inverse law in G .

$\therefore (G, \cdot)$ forms a Group.

Theorem. #4

In a group G , -for $a, b, x, y \in G$ prove that the equations $ax=b$; $ya=b$ have unique solutions.

Proof:

Let (G, \cdot) be a group.

Let 'e' be the identity element in G .

For $a \in G \Rightarrow a^{-1} \in G$ [\because By Inverse law.]

$a^{-1} \in G, b \in G \Rightarrow a^{-1}b \in G$ [\because By closure law]

Also, $ax=b$

Multiply with a^{-1} on both sides

$$a^{-1}(ax) = a^{-1}b$$

$$(a^{-1}a)x = a^{-1}b$$

$$ex = a^{-1}b$$

$$x = a^{-1}b$$

$$\text{L.H.S} = ax$$

$$= a(a^{-1}b)$$

$$= (aa^{-1})b$$

$$= e.b$$

$$= b$$

$$= \text{R.H.S}$$

$$\text{L.H.S} = \text{R.H.S}$$

$x = a^{-1}b$ is the solution of $ax=b$ Now

we have to prove that $x = a^{-1}b$ is the unique solution.

If possible, let x_1, x_2 are the solution sets of $ax=b$.

$$ax_1=b; ax_2=b$$

$$ax_1 = ax_2$$

By left cancellation law

$$x_1 = x_2$$

$\therefore x = a^{-1}b$ is the unique solution of
 $ax = b$

Similarly, we can prove that $y = ba^{-1}$ is
the solution of $ya = b$.

Now we have to prove that $y = ba^{-1}$ is
the unique solution sets of $ya = b$

If possible, let y_1, y_2 are the solution
sets of $ya = b$

$$y_1 a = b ; y_2 a = b$$

$$\Rightarrow y_1 a = y_2 a$$

By right cancellation law

$$y_1 = y_2$$

$\therefore y = ba^{-1}$ is the unique solution of
 $ya = b$.

Theorem : ⑤

Prove that n^{th} roots of unity forms an abelian group.

Proof :

$$\sqrt[n]{1} = (1)^{\frac{1}{n}}$$

$$= [\cos 0 + i \sin 0]^{\frac{1}{n}}$$

$$= [\cos 2k\pi + i \sin 2k\pi]^{\frac{1}{n}} ; k = 0, 1, 2, \dots, n-1$$

$$= \cos \frac{2k\pi}{n} + i \sin \frac{2k\pi}{n} ; k = 0, 1, 2, \dots, n-1$$

[Euler's formula]

$$G = e^{\frac{2k\pi i}{n}} ; k = 0, 1, 2, \dots, n-1$$

$$\text{Let } G = e^{\frac{2k\pi i}{n}} ; k = 0, 1, 2, \dots, n-1$$

* Closure law :

For $a, b \in G$

$$a = (1)^{\frac{1}{n}}$$

$$a^n = 1$$

$$b = (1)^{\frac{1}{n}}$$

$$b^n = 1$$

Consider,

$$(ab)^n = a^n \cdot b^n$$

$$ab = (1)^{\frac{1}{n}}$$

For $a, b \in G \Rightarrow ab \in G$.

$\therefore "$ satisfies closure law in G .

* Associative Law :-

Since the elements of G are Complex $\leftarrow \begin{matrix} A.S \\ A.B \end{matrix}$
Complex.

We know that,

The complex no's are associative with respect to multiplication.

$\therefore "$ satisfies Associative law in G .

* Existence Of Identity law :-

For $e^{\frac{2k\pi i}{n}} \in G$.

$\exists 1 = e^{\frac{2(0)\pi i}{n}} \in G$ such that

$$e^{\frac{2k\pi i}{n}} \cdot e^{\frac{2(0)\pi i}{n}} = e^{\frac{2(0)\pi i}{n}} e^{\frac{2k\pi i}{n}} = e^{\frac{2k\pi i}{n}}$$

$$\text{L.H.S} = e^{\frac{2k\pi i}{n}} \cdot e^{\frac{2(0)\pi i}{n}}$$

$$= e^{\frac{2k\pi i + 2(0)\pi i}{n}}$$

$$= e^{\frac{2k\pi i + 2(0)\pi i}{n}}$$

$$= e^{\frac{2\pi i(k+0)}{n}}$$

$$= e^{\frac{2k\pi i}{n}}$$

$$= \text{R.H.S}$$

\therefore Similarly we can prove that $e^{\frac{2(0)\pi i}{n}} \cdot e^{\frac{2k\pi i}{n}} = e^{\frac{2k\pi i}{n}}$

$\therefore e^{\frac{2(0)\pi i}{n}}$ is the multiplicative identity of $e^{\frac{2k\pi i}{n}}$ in G

$\therefore "$ satisfies Existence of identity law.

* Existence of Inverse law:

For $e^{\frac{2r\pi i}{n}} \in G \quad \forall 0 \leq r \leq n-1$

$$e^{\frac{2(0)\pi i}{n}} \in G \quad \forall r=0$$

$$e^{\frac{2(n-r)\pi i}{n}} \in G \quad \forall 0 < r \leq n-1$$

$$\begin{aligned} e^{\frac{2r\pi i}{n}} \cdot e^{\frac{2(0)\pi i}{n}} &= e^{\frac{2(0)\pi i}{n} + \frac{2(0)\pi i}{n}} \\ &= e^{\frac{2(0)\pi i + 2(0)\pi i}{n}} \\ &= e^0 \end{aligned}$$

$$= 1$$

$$\begin{aligned} e^{\frac{2r\pi i}{n}} \cdot e^{\frac{2(n-r)\pi i}{n}} &= e^{\frac{2r\pi i}{n} + \frac{2(n-r)\pi i}{n}} \\ &= e^{\frac{2r\pi i + 2n\pi i - 2r\pi i}{n}} \\ &= e^{\frac{2n\pi i}{n}} \\ &= e^{2\pi i} \end{aligned}$$

$$= \cos 2\pi + i \sin 2\pi$$

$$= 1 + i(0)$$

$$= 1$$

\therefore Every element of G are invertible.

\therefore " satisfies existence of Inverse law in G .

* Abelian law:

Since the elements of G are complex.

We know that,

The complex no's are associative with respect to multiplication.

\therefore " satisfies Abelian law in G .