Dimensionality reduction

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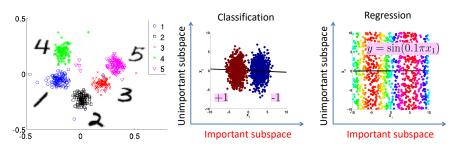
Review of the last lecture (Feature selection and sparsity)

- Feature selection: Wrapper method, Filter method, and Embedded method
- Wrapper method (Selecting features that maximize prediction accuracy. Computationally expensive.)
- Filter method (Use mutual information to select features, e.g., MR, mRMR, QPFS, etc.)
- Embedded method (Selecting features during training. e.g., Lasso)
- Alternating Direction Method of Multipliers (ADMM).
- Advanced method: HSIC Lasso

Dimensionality and Feature selection

Dimensionality reduction is a method to reduce the dimensionality of data.

- Feature selection is a dimensionality reduction method. Select a set of m features among d features (m < d).
- We tend to use feature selection if we want to interpret features.
- In dimensionality reduction, we may not need to interpret each feature.
- We tend to use dimensionality reduction to compress data, to visualize data, etc.



Dimensionality Reduction

Dimension reduction is to find a low-dimensional mapping $f: \mathbb{R}^d \to \mathbb{R}^m \ (d > m)$.

- It is useful for data visualization, computational/space efficiency, etc.
- Compression: keep the original information as much as possible
- The feature selection selects a set of features, while the dimensionality reduction outputs the combination of features.

Typically, dimensionality reduction can be categorized as

• Linear dimension reduction $z = U^{\top}x$ ($U \in \mathbb{R}^{d \times m}$).

$$m\begin{bmatrix} \mathbf{z} \end{bmatrix} = m\begin{bmatrix} \mathbf{U}^{\top} \\ d \end{bmatrix} \mathbf{x} d$$

• Nonlinear dimension reduction z = g(x). For example, deep learning model: $g(x) = \sigma(W_1(\sigma(W_2)))$

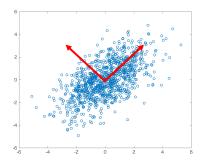
Dimensionality Reduction (Principal Component Analysis)

The principal component analysis (PCA) is a popular method:

$$\max_{\boldsymbol{U}^{\top}\boldsymbol{U}=\boldsymbol{I}.} \ \operatorname{tr}(\boldsymbol{U}^{\top}\boldsymbol{R}\boldsymbol{U}),$$

where $\mathbf{R} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i \mathbf{x}_i^{\top} \in \mathbb{R}^{d \times d}$ (we assume $\mathbb{E}[\mathbf{x}] = \mathbf{0}$) is the covariance matrix.

Idea: Find a direction that maximizes the variance



Obtain the first principal component

To obtain the first principal component:

$$\max_{\boldsymbol{u}^\top \boldsymbol{u} = 1.} \ \boldsymbol{u}^\top \boldsymbol{R} \boldsymbol{u} = \max_{\boldsymbol{u}} \frac{\boldsymbol{u}^\top \boldsymbol{R} \boldsymbol{u}}{\|\boldsymbol{u}\|_2^2},$$

where $\frac{\pmb{u}}{\|\pmb{u}\|_2}$ is a unit vector and $\frac{\pmb{u}^\top \pmb{R} \pmb{u}}{\|\pmb{u}\|_2^2}$ is called as the Rayleigh quotient.

Using the Lagrange multiplier (λ) to find a critical point:

$$L(\boldsymbol{u}) = \boldsymbol{u}^{\top} \boldsymbol{R} \boldsymbol{u} - \lambda (\boldsymbol{u}^{\top} \boldsymbol{u} - 1)$$

To take the derivative with respect to \boldsymbol{u} , we have

$$\frac{\partial L(\boldsymbol{u})}{\partial \boldsymbol{u}} = 2\boldsymbol{R}\boldsymbol{u} - 2\lambda\boldsymbol{u} = \boldsymbol{0} \to \boldsymbol{R}\boldsymbol{u} = \lambda\boldsymbol{u}.$$

This is an eigenvalue decomposition problem where λ is the eigenvalue and ${\pmb u}$ is the eigenvector.

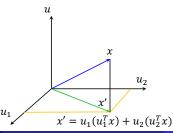
Obtain the k-th principal component

To obtain the k-th principal component, we extract the k-1 principal components from \boldsymbol{x}_i :

$$\boldsymbol{x}_i^{(k)} = \boldsymbol{x}_i - \sum_{s=1}^{k-1} (\boldsymbol{x}_i^\top \boldsymbol{u}_s) \boldsymbol{u}_s,$$

and compute the covariance matrix with the subtracted vectors \mathbf{R}_k . Then we obtain the k-th principal component as

$$\mathbf{u}_k = \underset{\mathbf{u}^\top \mathbf{u} = 1.}{\operatorname{argmax}} \quad \mathbf{u}^\top \mathbf{R}_k \mathbf{u}.$$



PCA with eigenvalue decomposition of symmetric matrix

PCA can be solved by simply do eigenvalue decomposition of R!

The eigenvalue decomposition of covariance matrix $\mathbf{R} \in \mathbb{R}^{d \times d}$:

$$R = U \Lambda U^{\top}$$

where

- $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_d) \in \mathbb{R}^{d \times d}$, where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_d$. If R is a positive definite matrix $\lambda_d \geq 0$.
- $m{U} \in \mathbb{R}^{d imes d}$ is an orthogonal matrix $m{U}^ op m{U} = m{U} m{U}^ op = m{I}_d$
- $\operatorname{tr}(\boldsymbol{R}) = \operatorname{tr}(\boldsymbol{U}\boldsymbol{\Lambda}\boldsymbol{U}^{\top}) = \operatorname{tr}(\boldsymbol{U}^{\top}\boldsymbol{U}\boldsymbol{\Lambda}) = \sum_{i=1}^{d} \lambda_{i}$.

Relationship to the Linear Auto-encoder (1/2)

Assume that $\mathbb{E}[x] = 0$. Then, consider the following linear Auto-encoder problem:

$$\min_{\mathbf{U}^{\top}\mathbf{U}=\mathbf{I}} \frac{1}{n} \sum_{i=1}^{n} \|\mathbf{x}_{i} - \mathbf{U}\mathbf{U}^{\top}\mathbf{x}_{i}\|_{2}^{2},$$

The loss function term can be written as

$$\frac{1}{n} \sum_{i=1}^{n} \|\mathbf{x}_{i} - \mathbf{U}\mathbf{U}^{\top}\mathbf{x}_{i}\|_{2}^{2} = \frac{1}{n} \sum_{i=1}^{n} \left(\mathbf{x}_{i}^{\top}\mathbf{x}_{i} - 2\mathbf{x}_{i}^{\top}\mathbf{U}\mathbf{U}^{\top}\mathbf{x}_{i} + \mathbf{x}_{i}^{\top}\mathbf{U}\mathbf{U}^{\top}\mathbf{U}^{\top}\mathbf{x}_{i}\right)
\propto -\frac{1}{n} \sum_{i=1}^{n} \left(\mathbf{x}_{i}^{\top}\mathbf{U}\mathbf{U}^{\top}\mathbf{x}_{i}\right) \quad \left(\mathbf{U}^{\top}\mathbf{U} = \mathbf{I}\right)
= -\frac{1}{n} \sum_{i=1}^{n} \left(\operatorname{tr}(\mathbf{U}^{\top}\mathbf{x}_{i}\mathbf{x}_{i}^{\top}\mathbf{U})\right) \quad \left(\operatorname{tr}(\mathbf{A}\mathbf{B}) = \operatorname{tr}(\mathbf{B}\mathbf{A})\right)
= -\operatorname{tr}(\mathbf{U}^{\top}\mathbf{R}\mathbf{U}), \quad \left(\mathbf{R} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i}\mathbf{x}_{i}^{\top}\right)$$

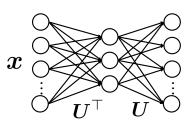
Relationship to the Linear Auto-encoder (2/2)

The minimization problem can be written as the maximization problem:

$$\min_{\boldsymbol{U}^{\top}\boldsymbol{U}=\boldsymbol{I}} \frac{1}{n} \sum_{i=1}^{n} \|\boldsymbol{x}_{i} - \boldsymbol{U}\boldsymbol{U}^{\top}\boldsymbol{x}_{i}\|_{2}^{2}, \leftrightarrow \max_{\boldsymbol{U}^{\top}\boldsymbol{U}=\boldsymbol{I}} \operatorname{tr}(\boldsymbol{U}^{\top}\boldsymbol{R}\boldsymbol{U})$$

Thus, PCA is related to the linear Auto-encoder.

Idea: Find a direction that maximizes the variance

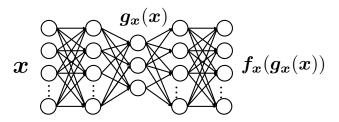


Nonlinear Auto-encoder (Deep auto-encoder)

We consider the following Auto-encoder problem:

$$\min_{\Theta} \ \frac{1}{n} \sum_{i=1}^{n} \| \mathbf{x}_{i} - \mathbf{f}_{\mathbf{x}}(\mathbf{g}_{\mathbf{x}}(\mathbf{x}_{i})) \|_{2}^{2},$$

Idea: Find a direction that maximizes the variance



Stochastic Neighbor Embedding (SNE)

Stochastic Neighbor Embedding (SNE):

The asymmetric probability p_{ij} that i-th sample would pick j-th sample as its neighbor:

$$p_{ij} = rac{\exp(-d_{ij}^2)}{\sum_{k
eq i} \exp(-d_{ki}^2)}, \quad d_{ij}^2 = rac{\|\mathbf{x}_i - \mathbf{x}_j\|_2^2}{2\sigma_i^2},$$

where σ_i is a tuning parameter.

The model:

$$q_{ij} = \frac{\exp(-\|\boldsymbol{y}_i - \boldsymbol{y}_j\|_2^2)}{\sum_{k \neq i} \exp(-\|\boldsymbol{y}_k - \boldsymbol{y}_i\|_2^2)}$$

Optimization:

$$\min_{\mathbf{y}_1, \dots, \mathbf{y}_n} \sum_{i=1}^n \sum_{i=1}^n p_{ij} \log \frac{p_{ij}}{q_{ij}}$$

Symmetric Stochastic Neighbor Embedding (SNE)

Stochastic Neighbor Embedding (SNE):

The symmetric probability p_{ij} that i-th sample would pick j-th sample as its neighbor:

$$p_{ij} = \frac{\exp(-d_{ij}^2)}{\sum_{k \neq l} \exp(-d_{kl}^2)}, \quad d_{ij}^2 = \frac{\|\mathbf{x}_i - \mathbf{x}_j\|_2^2}{2\sigma^2},$$

where σ is a tuning parameter.

The model:

$$q_{ij} = \frac{\exp(-\|\boldsymbol{y}_i - \boldsymbol{y}_j\|_2^2)}{\sum_{k \neq I} \exp(-\|\boldsymbol{y}_k - \boldsymbol{y}_I\|_2^2)}$$

Optimization:

$$\min_{\mathbf{y}_1, \dots, \mathbf{y}_n} \sum_{i=1}^n \sum_{i=1}^n p_{ij} \log \frac{p_{ij}}{q_{ij}}$$

t-Stochastic Neighbor Embedding (SNE)

The asymmetric probability p_{ij} that i-th sample would pick j-th sample as its neighbor:

$$p_{ij} = \frac{\exp(-d_{ij}^2)}{\sum_{k \neq l} \exp(-d_{ik}^2)}, \quad d_{ij}^2 = \frac{\|\mathbf{x}_i - \mathbf{x}_j\|_2^2}{2\sigma^2},$$

where σ is a tuning parameter.

The model (Cauchy distribution):

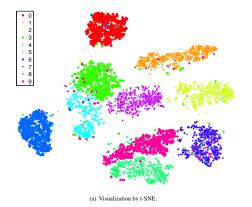
$$q_{ij} = \frac{(1 + \|\boldsymbol{y}_i - \boldsymbol{y}_j\|_2^2)^{-1}}{\sum_{k \neq l} (1 + \|\boldsymbol{y}_k - \boldsymbol{y}_l\|_2^2)^{-1}}$$

Optimization:

$$\min_{\mathbf{y}_1,\dots,\mathbf{y}_n} \sum_{i=1}^n \sum_{i=1}^n p_{ij} \log \frac{p_{ij}}{q_{ij}}$$

t-SNE illustration

Image taken from [1]



t-SNE is heavily used in biology data such as the expression data.

Multi-modal Dimensionality Reduction Methods

PCA and auto-encoders are for uni-modal input (i.e., only image or only text).

How to do dimensionality reduction for multi-modal data (i.e., image and text)?

We have (x, y), where $x \in \mathbb{R}^{d_x}$ and $y \in \mathbb{R}^{d_y}$.

- Linear dimension reduction $\mathbf{z}_x = \mathbf{U}^{\top} \mathbf{x}$ and $\mathbf{z}_y = \mathbf{V}^{\top} \mathbf{y}$. $\mathbf{U} \in \mathbb{R}^{d_x \times m}$ and $\mathbf{U} \in \mathbb{R}^{d_y \times m}$.
- Nonlinear dimension reduction $z_x = g_x(x)$ and $z_y = g_y(y)$.

Canonical Correlation Analysis (1/3)

Canonical Correlation Analysis (CCA) is to find dimensionality reduction that maximize the similarity between $z_x = U^T x$ and $z_y = V^T y$.

Let us assume that $\mathbb{E}[x] = 0$ and $\mathbb{E}[y] = 0$. We want to maximize the correlation:

$$\frac{1}{n} \sum_{i=1}^{n} \mathbf{z}_{x,i}^{\top} \mathbf{z}_{y,i} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i}^{\top} \mathbf{U} \mathbf{V}^{\top} \mathbf{y}_{i}$$

$$= \operatorname{tr}(\mathbf{U}^{\top} \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i} \mathbf{y}_{i}^{\top} \mathbf{V})$$

$$= \operatorname{tr}(\mathbf{U}^{\top} \mathbf{R}_{xy} \mathbf{V})$$

where $\mathbf{R}_{xy} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i \mathbf{y}_i^{\top} \in \mathbb{R}^{d_x \times d_y}$.

Canonical Correlation Analysis (CCA) (2/3)

The optimization problem of CCA is given as

$$\begin{aligned} & \max_{\boldsymbol{U},\boldsymbol{V}} & \operatorname{tr}(\boldsymbol{U}^{\top}\boldsymbol{R}_{xy}\boldsymbol{V}), \\ & \text{s.t.} & \boldsymbol{U}^{\top}\boldsymbol{R}_{xx}\boldsymbol{U} = \boldsymbol{I}, \boldsymbol{V}^{\top}\boldsymbol{R}_{yy}\boldsymbol{V} = \boldsymbol{I}, \end{aligned}$$

where $\mathbf{R}_{xx} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i} \mathbf{x}_{i}^{\top}$ and $\mathbf{R}_{yy} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{y}_{i} \mathbf{y}_{i}^{\top}$. Then, CCA can be written as

$$\max_{\boldsymbol{U},\boldsymbol{V}} \operatorname{tr} \left(\begin{bmatrix} \boldsymbol{U}^{\top} & \boldsymbol{V}^{\top} \end{bmatrix} \begin{bmatrix} \boldsymbol{O} & \boldsymbol{R}_{xy} \\ \boldsymbol{R}_{xy}^{\top} & \boldsymbol{O} \end{bmatrix} \begin{bmatrix} \boldsymbol{U} \\ \boldsymbol{V} \end{bmatrix} \right),$$
s.t.
$$\begin{bmatrix} \boldsymbol{U}^{\top} & \boldsymbol{V}^{\top} \end{bmatrix} \begin{bmatrix} \boldsymbol{R}_{xx} & \boldsymbol{O} \\ \boldsymbol{O} & \boldsymbol{R}_{yy} \end{bmatrix} \begin{bmatrix} \boldsymbol{U} \\ \boldsymbol{V} \end{bmatrix} = \boldsymbol{I},$$

This is a generalized eigenvalue decomposition (GEV) problem.

Canonical Correlation Analysis (CCA) (3/3)

Let us transform the variables as

$$\left[\begin{array}{c} \bar{\boldsymbol{U}} \\ \bar{\boldsymbol{V}} \end{array}\right] = \left[\begin{array}{cc} \boldsymbol{R}_{xx}^{1/2} & \boldsymbol{O} \\ \boldsymbol{O} & \boldsymbol{R}_{yy}^{1/2} \end{array}\right] \left[\begin{array}{c} \boldsymbol{U} \\ \boldsymbol{V} \end{array}\right]$$

we can rewrite the CCA optimization problem as

$$\max_{\bar{\boldsymbol{U}},\bar{\boldsymbol{V}}} \ \frac{1}{2} \mathrm{tr} \left(\left[\begin{array}{cc} \bar{\boldsymbol{U}}^{\top} & \bar{\boldsymbol{V}}^{\top} \end{array} \right] \left[\begin{array}{cc} \boldsymbol{O} & \boldsymbol{R}_{xx}^{-1/2} \boldsymbol{R}_{xy} \boldsymbol{R}_{yy}^{-1/2} \\ (\boldsymbol{R}_{xx}^{-1/2} \boldsymbol{R}_{xy} \boldsymbol{R}_{yy}^{-1/2})^{\top} & \boldsymbol{O} \end{array} \right] \left[\begin{array}{c} \bar{\boldsymbol{U}} \\ \bar{\boldsymbol{V}} \end{array} \right]$$
 s.t.
$$\left[\begin{array}{cc} \bar{\boldsymbol{U}}^{\top} & \bar{\boldsymbol{V}}^{\top} \end{array} \right] \left[\begin{array}{cc} \bar{\boldsymbol{U}} \\ \bar{\boldsymbol{V}} \end{array} \right] = \boldsymbol{I},$$

Thus, we can solve the CCA problem by using eigenvalue decomposition!

Multivariate Regression

Multivariate regression is a regression problem to predict multiple output variables $\mathbf{f}: \mathbb{R}^d \to \mathbb{R}^m \pmod{m > 1}$. If m = 1, it is a uni-variate regression.

Training dataset $\{(\boldsymbol{x}_i, \boldsymbol{y}_i)\}_{i=1}^n$

- ullet $oldsymbol{x}_i \in \mathbb{R}^d$: feature vector
- $\mathbf{y}_i \in \mathbb{R}^m$: real-valued target vector

Multivariate linear regression model:

$$\mathbf{y} = \mathbf{W}^{\top} \mathbf{x},$$

where $\boldsymbol{W} \in \mathbb{R}^{d \times m}$ and $^{\top}$ is matrix transpose.

Solution of the multivariate regression

The optimization problem can be written as

$$\min_{\boldsymbol{W} \in \mathbb{R}^{d \times m}} \sum_{i=1}^{n} \|\boldsymbol{y}_i - \boldsymbol{W}^{\top} \boldsymbol{x}_i\|_2^2,$$

where $\| {m x} \|_2 = \sqrt{\sum_{k=1}^d (x^{(k)})^2}$ is the ℓ_2 norm.

Let us denote $\mathbf{Y} = [\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n] \in \mathbb{R}^{m \times n}$ and

 $\pmb{X} = [\pmb{x}_1, \pmb{x}_2, \dots, \pmb{x}_n] \in \mathbb{R}^{d \times n}$. Then, the optimization problem can be written as

$$\min_{\boldsymbol{W}} \|\boldsymbol{Y} - \boldsymbol{W}^{\top} \boldsymbol{X} \|_F^2,$$

where $\|\boldsymbol{W}\|_F^2 = \sum_{(i,j)} [\boldsymbol{W}]_{ij}^2$: Frobenius norm.

The solution is given as

$$\widehat{\boldsymbol{W}} = (\boldsymbol{X}\boldsymbol{X}^{\top} + \lambda \boldsymbol{I})^{-1}\boldsymbol{X}\boldsymbol{Y}.$$

We can use
$$\frac{\partial \operatorname{tr}(\boldsymbol{A}\boldsymbol{B})}{\partial \boldsymbol{A}} = \boldsymbol{B}^{\top}$$

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Reduced rank regression

Using the dimensionality reduction, we can compress the information and use the information for regression.

Low-rank assumption

$$\boldsymbol{W} = \boldsymbol{U} \boldsymbol{V}^{\top}$$

 $\boldsymbol{U} \in \mathbb{R}^{d \times k}, \boldsymbol{V} \in \mathbb{R}^{m \times k}$ (i.e., rank of \boldsymbol{W} is K and $k < \min(d, m)$) m output variables share K-dimensional latent space If we use the low-rank assumption (i.e., $\boldsymbol{W} = \boldsymbol{U} \boldsymbol{V}^{\top}$), we have

$$\mathbf{y} = (\mathbf{U}\mathbf{V}^{\top})^{\top}\mathbf{x} = \mathbf{V}^{\top}(\mathbf{U}^{\top}\mathbf{x}),$$

where $\boldsymbol{U}^{\top}\boldsymbol{x} \in \mathbb{R}^{k}$.

Reduced rank regression: Sparsity in the dim of latent space

$$\min_{\boldsymbol{W}} \|\boldsymbol{Y} - \boldsymbol{W}^{\top} \boldsymbol{X} \|_F^2$$

s.t. $\operatorname{rank}(\boldsymbol{W}) \leq k$.

Sparsity in reduced rank regression

Parameter W in the reduced rank regression $y = W^{\top}x$ is dense in terms of matrix elements.

 $m{W}$ is sparse in terms of singular values $\rightarrow m{W} = m{U} m{V}^{\top}$ is low-rank. $m{U} \in \mathbb{R}^{d \times k}$, $m{V} \in \mathbb{R}^{m \times k}$, $k < \min(d, m)$

Rank is the number of non-zero singular values. That is, Rank is the ℓ_0 norm of singular values:

$$\operatorname{rank}(\boldsymbol{W}) = \|\boldsymbol{\sigma}(\boldsymbol{W})\|_0,$$

where $\sigma(\mathbf{W}) = [\sigma_1(\mathbf{W}), \sigma_2(\mathbf{W}), \dots, \sigma_{\min(d,m)}(\mathbf{W})]^{\top} \in \mathbb{R}^{\min(d,m)}$ and $\sigma_i(\mathbf{W})$ is the *i*-th singular value of \mathbf{W} .

$$\|\boldsymbol{\sigma}\|_0 = \sum_{\ell=1}^d \delta(\sigma_i), \quad \delta(\sigma) = \left\{ \begin{array}{ll} 1 & (\sigma \neq 0) \\ 0 & (\sigma = 0) \end{array} \right.$$

Solution of reduced rank regression

The objective function to be minimized:

$$\|\mathbf{Y} - \mathbf{W}^{\top} \mathbf{X}\|_{F}^{2} = \operatorname{tr}[(\mathbf{Y} - \mathbf{W}^{\top} \mathbf{X})^{\top} (\mathbf{Y} - \mathbf{W}^{\top} \mathbf{X})]$$

$$= \operatorname{tr}(\mathbf{Y}^{\top} \mathbf{Y} - 2\mathbf{Y}^{\top} \mathbf{W}^{\top} \mathbf{X} + \mathbf{X}^{\top} \mathbf{W} \mathbf{W}^{\top} \mathbf{X})$$

$$= \operatorname{tr}(\mathbf{Y} \mathbf{Y}^{\top} - 2\mathbf{W}^{\top} \mathbf{X} \mathbf{Y}^{\top} + \mathbf{W}^{\top} \mathbf{X} \mathbf{X}^{\top} \mathbf{W}),$$

where we used tr(AB) = tr(BA). We further decompose XX^{\top} as

$$XX^{\top} = U\Lambda U^{\top}.$$

Let us denote $\widetilde{\boldsymbol{W}} = \boldsymbol{\Lambda}^{1/2} \boldsymbol{U}^{\top} \boldsymbol{W}$. Then, we have

$$\|\mathbf{Y} - \mathbf{W}^{\top} \mathbf{X}\|_{F}^{2} = \operatorname{tr}(\mathbf{Y} \mathbf{Y}^{\top} - 2\mathbf{W}^{\top} \mathbf{X} \mathbf{Y}^{\top} + \mathbf{W}^{\top} \mathbf{X} \mathbf{X}^{\top} \mathbf{W})$$

$$= \operatorname{tr}(\mathbf{Y} \mathbf{Y}^{\top} - 2\widetilde{\mathbf{W}}^{\top} \mathbf{\Lambda}^{-1/2} \mathbf{U}^{\top} \mathbf{X} \mathbf{Y}^{\top} + \widetilde{\mathbf{W}}^{\top} \widetilde{\mathbf{W}})$$

$$= \|\widetilde{\mathbf{W}} - \mathbf{\Lambda}^{-1/2} \mathbf{U}^{\top} \mathbf{X} \mathbf{Y}^{\top}\|_{F}^{2} + \operatorname{Const.}$$

Best rank-K approximation

Best rank-k approximation problem of matrix \boldsymbol{B} :

$$\min_{\widehat{\boldsymbol{B}}} \ \|\boldsymbol{B} - \widehat{\boldsymbol{B}}\|_F^2, \text{ s.t. } \mathrm{rank}(\widehat{\boldsymbol{B}}) \leq k$$

The optimal solution is given as

$$\widehat{\boldsymbol{B}} = \boldsymbol{U}_k \boldsymbol{\Sigma}_k \boldsymbol{V}_k^{\top}.$$

If $\hat{\boldsymbol{B}} = \boldsymbol{O}$, we have

$$\|\boldsymbol{B}\|_F^2 = \sum_{i=1}^{\min(m,n)} \sigma_i^2$$

Since $\sigma_1 \geq \sigma_2 \geq \ldots \geq \sigma_q \geq 0$, the rank-k solution that minimizes the loss function is given as

$$\|oldsymbol{B} - \widehat{oldsymbol{B}}\|_F^2 = \|oldsymbol{U}oldsymbol{\Sigma}oldsymbol{V}^ op - oldsymbol{U}oldsymbol{\Sigma}_koldsymbol{V}^ op\|_F^2 = \sum_{i=k+1}^{\min(m,q)} \sigma_i^2$$

Review of Singular value decomposition (SVD)

A matrix $\mathbf{B} \in \mathbb{R}^{m \times n}$ can be decomposed by

$$\boldsymbol{B} = \boldsymbol{U} \bar{\boldsymbol{\Sigma}} \boldsymbol{V}^{\top}$$

where $\boldsymbol{U} \in \mathbb{R}^{m \times m}$, $\boldsymbol{V} \in \mathbb{R}^{n \times n}$,

$$ar{oldsymbol{\Sigma}} = \left\{ egin{array}{ccc} oldsymbol{\Sigma} & oldsymbol{O} & oldsymbol{(m < n)} \ oldsymbol{\Sigma} & (m = n) \ oldsymbol{\delta} & oldsymbol{(m > n)} \end{array}
ight., \quad oldsymbol{\Sigma} = \operatorname{diag}(\sigma_1, \sigma_2, \dots, \sigma_q) \in \mathbb{R}^{q \times q},$$

and $q = \min(m, n)$ and $\sigma_1 \ge \sigma_2 \ge \cdots \ge \sigma_q \ge 0$ are singular values.

- U is the eigenvectors of BB^{\top} and V is the eigenvectors of $B^{\top}B$, respectively.
- $\bullet \ \ \bar{\boldsymbol{\Sigma}}\bar{\boldsymbol{\Sigma}}^\top = \mathsf{diag}(\sigma_1^2, \sigma_2^2, \dots, \sigma_q^2, 0, \dots, 0) \in \mathbb{R}^{m \times m}$

Convex reduced rank regression

The optimization problem can be written as

$$\min_{\boldsymbol{W} \in \mathbb{R}^{d \times m}} \sum_{i=1}^{n} \|\boldsymbol{y}_{i} - \boldsymbol{W}^{\top} \boldsymbol{x}_{i}\|_{2}^{2} + \lambda \|\boldsymbol{W}\|_{p},$$

where $\|\boldsymbol{W}\|_p$ is the Schatten *p*-norm (all norm is convex).

$$\|oldsymbol{w}\|_{oldsymbol{
ho}} = \left(\sum_{i=1}^{\min\{n,m\}} \sigma_i^{oldsymbol{
ho}}(oldsymbol{w})
ight)^{1/oldsymbol{
ho}}.$$

To make \boldsymbol{W} low-rank, the Schatten 1-norm is useful (Sum of singular values).

$$\|oldsymbol{\mathcal{W}}\|_1 = \sum_{i=1}^{\min\{n,m\}} \sigma_i(oldsymbol{\mathcal{W}})$$

Optimization with ADMM

The optimization problem can be written as

$$\min_{\boldsymbol{W},\boldsymbol{M}\in\mathbb{R}^{d\times m}} \quad \sum_{i=1}^{n} \|\boldsymbol{y}_{i} - \boldsymbol{W}^{\top}\boldsymbol{x}_{i}\|_{2}^{2} + \lambda \|\boldsymbol{M}\|_{1},$$
s.t. $\boldsymbol{W} = \boldsymbol{M}$.

The augumented Laglangian function is defined

$$L(\boldsymbol{W}, \boldsymbol{M}, \boldsymbol{\Gamma}) = \sum_{i=1}^{n} \|\boldsymbol{y}_{i} - \boldsymbol{W}^{\top} \boldsymbol{x}_{i}\|_{2}^{2} + \lambda \|\boldsymbol{M}\|_{1} + \frac{\rho}{2} \|\boldsymbol{W} - \boldsymbol{M}\|_{F}^{2} + \operatorname{tr}(\boldsymbol{\Gamma}(\boldsymbol{W} - \boldsymbol{M})),$$

where Γ is the Laglange multipliers. To solve this, we can use the following soft thresholding function:

$$S_{\lambda/
ho}(oldsymbol{M}) = \operatorname*{argmin}_{oldsymbol{M}} \left(rac{1}{2} \| oldsymbol{W} - oldsymbol{M} \|_F^2 + rac{\lambda}{
ho} \| oldsymbol{M} \|_1
ight) = oldsymbol{U} \max(oldsymbol{\Sigma} - \lambda/
ho, 0) oldsymbol{V}^{ op},$$

where $\boldsymbol{W} = \boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^{\top}$.

Other dimensionality reduction methods

- Fisher Discriminant Analysis (FDA)
- Independent Component Analysis (ICA)
- Sufficient Dimensionality Reduction (SDR)
- Locally Linear Embedding (LLE)
- etc.

Summary of today's lecture

- Dimensionality reduction (Reduce the dimensionality of features).
- Feature selection is to interpret features, while dimensionality reduction is to reduce the dimensionality (for compression and visualization).
- Multi-variate Regression and reduced-rank regression
- Convex reduced-rank regression with ADMM
- Principal Component Analysis (PCA)
- Canonical Correlation Analysis (Multi-modal data)



Laurens van der Maaten and Geoffrey Hinton.

Visualizing data using t-sne.

Journal of machine learning research, 9(Nov):2579–2605, 2008.