Transfer Learning

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Review: Supervised Learning

Problem formulation of supervised learning.

- Input vector: $\mathbf{x} = [x_1, x_2, \dots, x_d]^{\top} \in \mathbb{R}^d$
- Output: $y \in \mathbb{R}$
- $(\mathbf{x}_i, y_i) \stackrel{\text{i.i.d.}}{\sim} p(\mathbf{x}, y)$
- Labeled data: $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
- Model: $f(x; w) = w^{\top}x$. (Linear model)

Risk:
$$R(\mathbf{w}) = \iint loss(y, f(\mathbf{x}; \mathbf{w})) p(\mathbf{x}, y) d\mathbf{x} dy$$

Empirical Risk:
$$R_{emp}(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^{n} loss(y_i, f(\mathbf{x}_i; \mathbf{w}))$$

Empirical Risk Minimization (ERM):
$$\hat{\boldsymbol{w}} = \operatorname{argmin}_{\boldsymbol{w}} R_{emp}(\boldsymbol{w})$$

Transfer Learning

Supervised Learning:

- Training $\{(\boldsymbol{x}_i, y_i)\}_{i=1}^n \overset{\text{i.i.d.}}{\sim} p_{\text{tr}}(\boldsymbol{x}, y)$
- Test $(x, y) \stackrel{\text{i.i.d.}}{\sim} p_{\text{te}}(x, y)$ (Not observed during training)
- $p_{\rm tr} = p_{\rm te}$ (Training and test distributions are same)

Semi-supervised Learning:

- Training $\{(\boldsymbol{x}_i,y_i)\}_{i=1}^n \overset{\text{i.i.d.}}{\sim} p_{\text{tr}}(\boldsymbol{x},y), \ \{\boldsymbol{x}_i\}_{i=n+1}^{n+m} \overset{\text{i.i.d.}}{\sim} p_{\text{tr}}(\boldsymbol{x}).$
- Test $(x, y) \stackrel{\text{i.i.d.}}{\sim} p_{\text{te}}(x, y)$ (Not observed during training)
- $p_{\rm tr} = p_{\rm te}$ (Training and test distributions are same)

If $p_{\rm tr} \neq p_{\rm te}$, supervised method and semi-supervised method do not perform well. A possible answer would be Transfer Learning!

Types of Transfer Learning

Key idea: Reduce generalization error in test data. (not in training data)

Unsupervised transfer learning

$$\bullet \{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y),$$

$$\bullet \ \{\mathbf{x}_{j}^{\text{te}}\}_{j=1}^{n_{\text{te}}} \overset{\text{i.i.d.}}{\sim} p_{\text{te}}(\mathbf{x}), \ n_{\text{tr}} \ll n_{\text{te}}$$

Supervised transfer learning

$$\bullet \{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y)$$

•
$$\{(x_j^{\text{te}}, y_j^{\text{te}})\}_{j=1}^{n_{\text{te}}} \overset{\text{i.i.d.}}{\sim} p_{\text{te}}(x, y), n_{\text{te}} \ll n_{\text{tr}}$$

Semi-supervised transfer learning

$$\bullet \{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y)$$

•
$$\{(x_i^{\text{te}}, y_i^{\text{te}})\}_{i=1}^{n_{\text{te}}} \overset{\text{i.i.d.}}{\sim} p_{\text{te}}(x), n_{\text{te}} \ll n_{\text{tr}}$$

•
$$\{\mathbf{x}_i^{\mathrm{te}}\}_{i=n_{\mathrm{te}}+1}^{n_{\mathrm{te}}+n_{\mathrm{te}}'} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{te}}(\mathbf{x}), n_{\mathrm{tr}} \ll n_{\mathrm{te}}$$

Unsupervised Transfer Learning

Key idea: We assume

- It does not need to have test label
- Need some assumption

Standard approaches

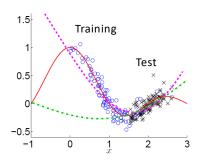
- Importance weighted method (e.g., Covariate shift adaptation)
- Subspace based method.

Unsupervised Transfer Learning: Covariate shift adaptation

Problem setup:

- $\{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y),$
- $\{x_i^{\text{te}}\}_{i=1}^{n_{\text{te}}} \overset{\text{i.i.d.}}{\sim} p_{\text{te}}(x)$, $n_{\text{tr}} \ll n_{\text{te}}$

Key idea: Learning a function so that error in test data is minimized under the assumption $p_{tr}(y|\mathbf{x}) = p_{te}(y|\mathbf{x})$



Unsupervised Transfer Learning

The risk can be written as

$$J(\mathbf{w}) = \iint L(y, f(\mathbf{x})) \rho_{\text{te}}(\mathbf{x}, y) d\mathbf{x} dy$$

$$= \iint L(y, f(\mathbf{x})) \frac{\rho_{\text{te}}(\mathbf{x}, y)}{\rho_{\text{tr}}(\mathbf{x}, y)} \rho_{\text{tr}}(\mathbf{x}, y) d\mathbf{x} dy$$

$$= \iint L(y, f(\mathbf{x})) \frac{\rho_{\text{te}}(y|\mathbf{x}) \rho_{\text{te}}(\mathbf{x})}{\rho_{\text{tr}}(y|\mathbf{x}) \rho_{\text{tr}}(\mathbf{x})} \rho_{\text{tr}}(y, \mathbf{x}) d\mathbf{x} dy$$

$$= \iint L(y, f(\mathbf{x})) \frac{\rho_{\text{te}}(\mathbf{x})}{\rho_{\text{tr}}(\mathbf{x})} \rho_{\text{tr}}(y, \mathbf{x}) d\mathbf{x} dy$$

$$\approx \frac{1}{n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} L(y_i^{\text{tr}}, f(\mathbf{x}_i^{\text{tr}})) \frac{\rho_{\text{te}}(\mathbf{x}_i^{\text{tr}})}{\rho_{\text{tr}}(\mathbf{x}_i^{\text{tr}})}$$

Actually, it is a weighted maximum likelihood problem. Note $\frac{p_{\rm te}(\mathbf{x}_i^{\rm tr})}{p_{\rm tr}(\mathbf{x}_i^{\rm tr})}$ is a ratio of probability densities (density-ratio)

Unsupervised Transfer Learning: Covariate shift adaptation

Exponentially-flattened Importance weighted empirical risk minimization (IW-ERM):

$$\min_{f \in \mathcal{F}} \frac{1}{n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} L(y_i^{\text{tr}}, f(\boldsymbol{x}_i^{\text{tr}})) \left(\frac{p_{\text{te}}(\boldsymbol{x}_i^{\text{tr}})}{p_{\text{tr}}(\boldsymbol{x}_i^{\text{tr}})}\right)^{\tau}$$

where $0 \le \tau \le 1$ is a tuning parameter for stabilizing the covariate shift adaptation.

- $\tau = 0 \rightarrow \mathsf{ERM}$
- $0 < \tau < 1 \rightarrow Intermediate$
- $\tau = 1$ IW-ERM

Setting τ to $0 < \tau < 1$ is practically useful.

Unsupervised Transfer Learning: Covariate shift adaptation

Relative Importance weighted empirical risk minimization (RIW-ERM):

$$\min_{f \in \mathcal{F}} \frac{1}{n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} L(y_i^{\text{tr}}, f(\boldsymbol{x}_i^{\text{tr}})) \frac{p_{\text{te}}(\boldsymbol{x}_i^{\text{tr}})}{(1-\alpha)p_{\text{tr}}(\boldsymbol{x}_i^{\text{tr}}) + \alpha p_{\text{tr}}(\boldsymbol{x}_i^{\text{tr}})}$$

where $0 \le \tau \le 1$ is a tuning parameter for stabilizing the covariate shift adaptation.

- $\alpha = 0 \rightarrow ERM$
- $0 < \alpha < 1 \rightarrow Intermediate$
- $\alpha = 1$ IW-ERM

$$r_{\alpha}(\mathbf{x}) = \frac{p_{\text{te}}(\mathbf{x})}{(1-\alpha)p_{\text{tr}}(\mathbf{x}) + \alpha p_{\text{tr}}(\mathbf{x})} < \frac{1}{1-\alpha}$$

The density ratio is bounded above by $1/(1-\alpha)$. Next lecture, I will introduce how to estimate the density ratio.

Unsupervised Transfer Learning: Importance Weighted Least Squares

The importance weighted least squares problem can be written as

$$\min_{\mathbf{w}} J(\mathbf{w}) = \frac{1}{n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} r(\mathbf{x}_i^{\text{tr}}) \| y_i^{\text{tr}} - \mathbf{w}^{\top} \mathbf{x}_i^{\text{tr}} \|_2^2,$$

where r(x) is a weight function (e.g., density-ratio).

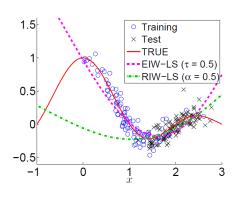
Take the derivative w.r.t. \mathbf{w} and equating it to zero.

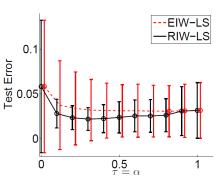
$$\frac{\partial J(\boldsymbol{w})}{\partial \boldsymbol{w}} = -\frac{2}{n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} r(\boldsymbol{x}_{i}^{\text{tr}}) (y_{i}^{\text{tr}} - \boldsymbol{w}^{\top} \boldsymbol{x}_{i}^{\text{tr}}) \boldsymbol{x}_{i}^{\text{tr}} = \boldsymbol{0}$$

$$\widehat{\boldsymbol{w}} = \left(\sum_{i=1}^{n_{\text{tr}}} r(\boldsymbol{x}_{i}^{\text{tr}}) \boldsymbol{x}_{i}^{\text{tr}} \boldsymbol{x}_{i}^{\text{tr}}^{\top} \right)^{-1} \sum_{i=1}^{n_{\text{tr}}} r(\boldsymbol{x}_{i}^{\text{tr}}) y_{i}^{\text{tr}} \boldsymbol{x}_{i}^{\text{tr}}$$

Covariate Shift Adaptation: Synthetic Example

Comparison of EIW-LS and RIW-LS:





Supervised Transfer Learning

Problem formulation:

$$\bullet \{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y)$$

•
$$\{(x_j^{\text{te}}, y_j^{\text{te}})\}_{j=1}^{n_{\text{te}}} \overset{\text{i.i.d.}}{\sim} p_{\text{te}}(x, y), n_{\text{te}} \ll n_{\text{tr}}$$

We assume to have a large number of training samples and a small number of paired target labeled samples.

- Frustratingly easy domain adaptation
- Multi-task Learning
- Fine-tuning (Deep Learning)

Supervised Transfer Learning: Importance Weight

Naive approach: Pooling training and test samples

$$J(\mathbf{w}) = \iint \mathsf{loss}(y, f(\mathbf{x}; \mathbf{w})) p_{te}(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y}$$

$$= \alpha \iint \mathsf{loss}(y, f(\mathbf{x}; \mathbf{w})) p_{tr}(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y}$$

$$+ (1 - \alpha) \iint \mathsf{loss}(y, f(\mathbf{x}; \mathbf{w})) p_{te}(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y}$$

$$\simeq \frac{\alpha}{n_{tr}} \sum_{i=1}^{n_{tr}} \mathsf{loss}(y_i^{tr}, f(\mathbf{x}_i^{tr}; \mathbf{w})) + \frac{(1 - \alpha)}{n_{te}} \sum_{j=1}^{n_{te}} \mathsf{loss}(y_j^{te}, f(\mathbf{x}_j^{te}; \mathbf{w})),$$

where $0 \le \alpha \le 1$ is a tuning parameter to control trade off between source and target errors. Let us define the pooled input matrix and the pooled output vector:

Problem formulation:

- Task1: $\{(x_i^{(1)}, y_i^{(1)})\}_{i=1}^{n_1} \stackrel{\text{i.i.d.}}{\sim} p(x, y)$
- Task2: $\{(\mathbf{x}_{j}^{(2)}, y_{j}^{(2)})\}_{j=1}^{n_{2}} \overset{\text{i.i.d.}}{\sim} p'(\mathbf{x}, y)$
- ..
- TaskM: $\{(\boldsymbol{x}_{j}^{(M)}, y_{j}^{(M)})\}_{j=1}^{n_{M}} \overset{\text{i.i.d.}}{\sim} p'(\boldsymbol{x}, y)$
- Linear Models:

$$f_1(\mathbf{x}^{(1)}) = \mathbf{w}_1^{\top} \mathbf{x}^{(1)}, f_2(\mathbf{x}^{(2)}) = \mathbf{w}_2^{\top} \mathbf{x}^{(2)}, \dots, f_M(\mathbf{x}^{(M)}) = \mathbf{w}_M^{\top} \mathbf{x}^{(M)}$$

$$\min_{\mathbf{w}_{1},...,\mathbf{w}_{M}} \sum_{m=1}^{M} \frac{1}{n_{m}} \sum_{i=1}^{n_{m}} loss(y_{i}^{(m)}, f_{m}(\mathbf{x}^{(m)})) + \lambda R(\mathbf{w}_{1},...,\mathbf{w}_{M}).$$

where $R(\mathbf{w}_1, \dots, \mathbf{w}_M)$ is a regularizer.

- $\lambda = 0$: Independently optimize **w**s
- $\lambda > 0$: We share some information among models.

Multi-task learning optimization (Graph-Laplacian).

$$\min_{\boldsymbol{w}_{1},...,\boldsymbol{w}_{M}} \sum_{m=1}^{M} \frac{1}{n_{m}} \sum_{i=1}^{n_{m}} loss(y_{i}^{(m)}, f_{m}(\boldsymbol{x}_{i}^{(m)})) + \lambda \sum_{m=1}^{M} \sum_{m'=1}^{M} r_{m,m'} \|\boldsymbol{w}_{m} - \boldsymbol{w}_{m'}\|_{2}^{2}.$$

where $r_{m,m'} \ge 0$ is a model parameter (similarity between models). If $r_{m,m'} > 0$, we make \mathbf{w}_m and $\mathbf{w}_{m'}$ close.

Other approach: Explicitly including shared parameter. We decompose

$$\mathbf{w}_m = \mathbf{w}_0 + \mathbf{v}_m$$

That is

$$\bullet f_1(\mathbf{x}^{(1)}) = (\mathbf{w}_0 + \mathbf{v}_1)^{\top} \mathbf{x}^{(1)},$$

•
$$f_2(\mathbf{x}^{(2)}) = (\mathbf{w}_0 + \mathbf{v}_2)^{\top} \mathbf{x}^{(2)}$$
,

• . . .

$$\bullet \ f_M(\mathbf{x}^{(M)}) = (\mathbf{w}_0 + \mathbf{v}_M)^\top \mathbf{x}^{(M)}$$

where \mathbf{w}_0 is a common factor for all models.

For squared-loss, we can write the problem as

$$\min_{\boldsymbol{w}_{1},...,\boldsymbol{w}_{M}} \frac{1}{2} \sum_{m=1}^{M} \frac{1}{n_{m}} \sum_{i=1}^{n_{m}} \left(y_{i}^{(m)} - (\boldsymbol{w}_{0} + \boldsymbol{v}_{m})^{\top} \boldsymbol{x}_{i}^{(m)} \right)^{2} + \lambda (\|\boldsymbol{w}_{0}\|_{2}^{2} + \sum_{m=1}^{M} \|\boldsymbol{v}_{m}\|_{2}^{2})$$

Supervised Transfer Learning: Frustratingly easy domain adaptation

A frustratingly easy feature augmentation approach:

$$\begin{split} & \boldsymbol{z}^{\text{tr}} = [\boldsymbol{x}^{\text{tr}^{\top}} & \boldsymbol{x}^{\text{tr}^{\top}} & \boldsymbol{0}_{\text{d}}^{\top}]^{\top}, \\ & \boldsymbol{z}^{\text{te}} = [\boldsymbol{x}^{\text{te}^{\top}} & \boldsymbol{0}_{\text{d}}^{\top} & \boldsymbol{x}^{\text{te}^{\top}}]^{\top}, \end{split}$$

The inner product of z in the same domain is give as

$$egin{aligned} oldsymbol{z^{ ext{tr}}}^{ op} oldsymbol{z^{ ext{tr}}}^{ op} oldsymbol{x^{ ext{tr}}}^{ op} oldsymbol{x^{ ext{tr}}}^{ op} oldsymbol{x^{ ext{tr}}}^{ op} oldsymbol{x^{ ext{te}}}^{ op} oldsymbol{x^{ ext{te}}}^{ op} oldsymbol{x^{ ext{te}}}^{ op}. \end{aligned}$$

while we have

$$\mathbf{z}^{\mathrm{tr}}^{\top}\mathbf{z}^{\mathrm{te}} = \mathbf{x}^{\mathrm{tr}}^{\top}\mathbf{x}^{\mathrm{tr}},.$$

Then, we train a supervised learning method with the transformed vectors

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Actually, supervised transfer learning can be regarded as a two-task learning problem. First task is for training and second task is for test. Let us denote the transformed vectors as

$$egin{aligned} oldsymbol{z}^{ ext{tr}} &= [oldsymbol{x}^{ ext{tr}}^{ op} & oldsymbol{x}^{ ext{tr}}^{ op} & oldsymbol{0}_{ ext{d}}^{ op}]^{ op}, \ oldsymbol{z}^{ ext{te}} &= [oldsymbol{x}^{ ext{te}}^{ op} & oldsymbol{0}_{ ext{d}}^{ op} & oldsymbol{x}^{ ext{te}}^{ op}]^{ op}. \end{aligned}$$

And, we consider a linear regression problem: The model parameter of the linear model can be written as

$$\mathbf{w} = [\mathbf{w}_0^{\top} \quad \mathbf{v}_1^{\top} \quad \mathbf{v}_2^{\top}]^{\top} \in \mathbb{R}^{3d}$$

$$J(\mathbf{w}) = \frac{1}{2n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} \|y_i^{\text{tr}} - \mathbf{z}_i^{\text{tr}}^{\top} \mathbf{w}\|_2^2 + \frac{1}{2n_{\text{te}}} \sum_{i=1}^{n_{\text{te}}} \|y_i^{\text{te}} - \mathbf{z}_i^{\text{te}}^{\top} \mathbf{w}\|_2^2 + \lambda \|\mathbf{w}\|_2^2$$
$$= \frac{1}{2} \sum_{m=1}^{M} \frac{1}{n_m} \sum_{i=1}^{n_m} \left(y_i^{(m)} - (\mathbf{w}_0 + \mathbf{v}_m)^{\top} \mathbf{x}_i^{(m)} \right)^2 + \lambda (\|\mathbf{w}_0\|_2^2 + \sum_{m=1}^{M} \|\mathbf{v}_m\|_2^2),$$

where we use

$$egin{aligned} m{w}^{ op} m{z}^{ ext{tr}} &= (m{w}_0 + m{v}_1)^{ op} m{x}^{ ext{tr}}, \quad m{w}^{ op} m{z}^{ ext{te}} &= (m{w}_0 + m{v}_2)^{ op} m{x}^{ ext{te}} \\ m{x}^{ ext{tr}} &= m{x}^{(1)}, \quad m{x}^{ ext{te}} &= m{x}^{(2)}, \\ \|m{w}\|_2^2 &= \|m{w}_0\|_2^2 + \sum_{m=1}^2 \|m{v}_m\|_2^2. \end{aligned}$$

Frustratingly easy domain adaptation is a multi-task learning.

Summary

- Semi-supervised learning. Use unlabeled samples and assume the data distribution of unlabeled data is same as training.
- Weighted Maximum Likelihood, Graph-based method.
- Transfer Learning. Use samples from test data. Training and test distributions are different.
- Covariate shift adaptation, frustratingly easy domain adaptation.