HW5 STAT5376

Dynamic programming with SRSF

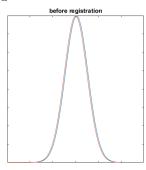
Li Sun

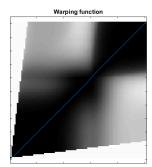
November 22, 2016

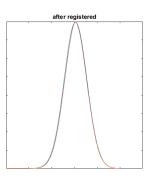
PART I: Smooth function registration

To demonstrate the dynamic programming with SRSF, I simulated several pairs of functions and try to register them.

1. First to register two identical function.

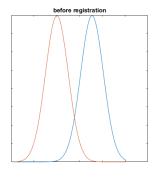


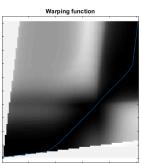


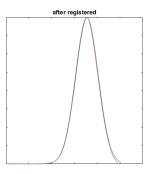


da=0 dp=0

2.Register 2 functions with different locations but exact same shapes

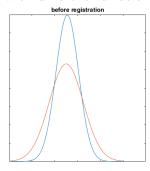


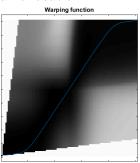


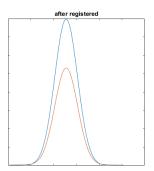


da=0.0466dp=0.8591

3. Functions with different variation but same location.



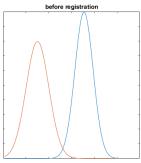


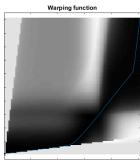


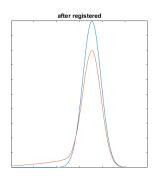
da = 0.2688

dp = 1.2325

4. Functions with different center and different variations.



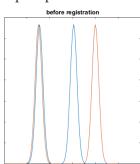


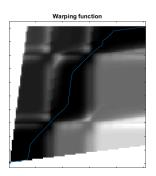


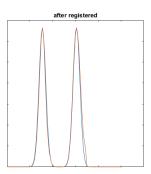
da = 0.3638

dp = 1.0277

5.Let's try warp bi-peak function.

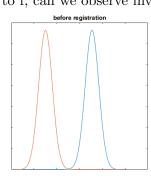


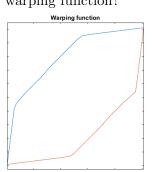


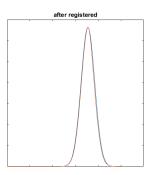


da=0.0014dp=0.3911

6. If warp g to f, can we observe inverted warping function?



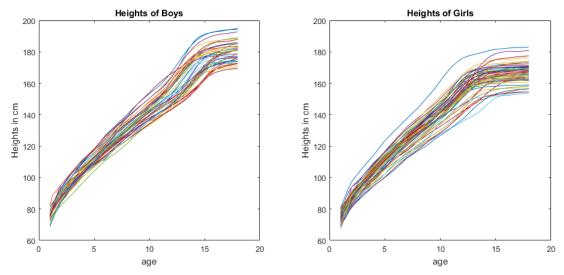




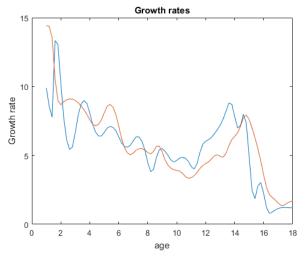
Above all, the algorithm searches 43 points as neighbors with 43 different slopes. It calculate fast and works well under most situations. Indeed, if we change the order of 2 functions to be warped, the warping function is inverse to each other.

However, I do observed some distortion when I tried to register a curve with larger magnitude to another curve with lower magnitude. The magnitude is well reserved which is an improvement comparing to L2-norm registration.

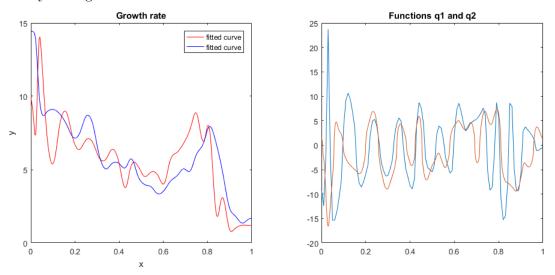
PART II: smooth and register growth data. Data from R package fda as in following figure:



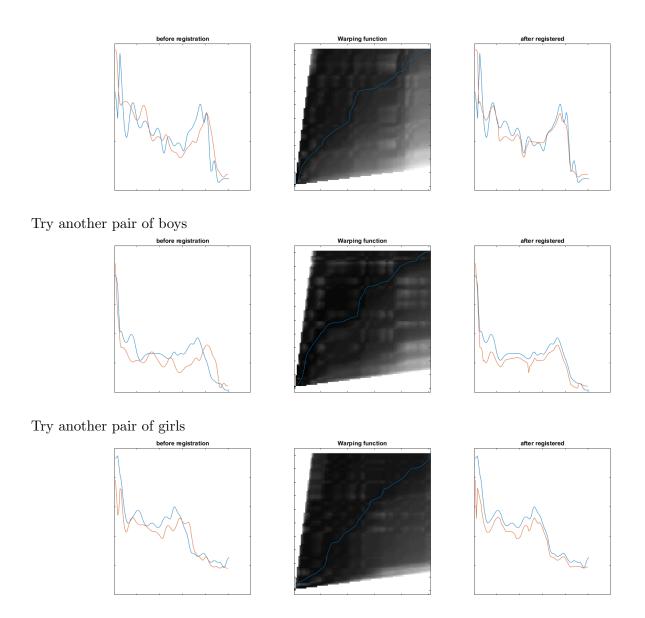
Because we are interested in the growth rates instead of absolute heights, so I first smooth the data and get a growth rate function of 2 random curves.



Next, I smoothed the growth rates curve and converted them to SRSF functions q1 and q2 which are ready for registration.



Now I applied dynamic programming with SRSF representations



Above all, the algorithm seem to work well for growth data. All code please see https://github.com/rikku1983/STAT5376

Thanks!

11/29/2016 hw52.m

```
%Part I
             clear all;
  3
             close all;
  4
             %define functions
             n=100;
  5
  6
             m = 100
             xx1=(0:n)/n;
             xx2=(0:m)/m;
  9
             f=normpdf(xx1,0.3,0.02)+normpdf(xx1,0.5,0.02);
             g=normpdf(xx2,0.3,0.02)+normpdf(xx2,0.6,0.02);
10
11
12
             %Smooth x1 and x2 by splines
             smthpara=1;
fs=fit(xx1',
            fs=fit(xx1', f', 'smoothingspline', 'SmoothingParam', smthpara);
gs=fit(xx2', g', 'smoothingspline', 'SmoothingParam', smthpara);
%Generate q1 from f and q2 from g
14
15
16
17
             %x2=0:1/m:1;
19
             for i = 1:length(xx1)
20
                        q1(i) = sign((\hat{f}s(xx1(i) + 0.0001) - fs(xx1(i) - 0.0001))/(2*0.0001)). *sqrt(abs((fs(xx1(i) + 0.0001) - fs(xx1(i) - 0.0001))/(2*0.0001)));
21
22
             end
             for i=1:length(xx2)
                        q2(i) = sign((gs(xx2(i) + 0.0001) - gs(xx2(i) - 0.0001))/(2*0.0001)). \\ *sqrt(abs((gs(xx2(i) + 0.0001) - gs(xx2(i) - 0.0001))/(2*0.0001)));
24
25
26
27
             [path, E]=sldpSRSF2(q1,q2);
             close all;
           close all;
fig=figure();
set(fig,'Position', [200 200 1600 450]);
subplot(131);plot(f);hold on;plot(g((1:n)*m/n));title('before registration');
set(gca,'XTickLabel',[],'YTickLabel',[]);
subplot(132);imagesc(E');colormap(gray);hold on;plot(path(:,1),path(:,2));axis xy;
axis equal;set(gca,'XTickLabel',[],'YTickLabel',[]);
title('Warping function');
subplot(133);plot(f);hold on;
plot((1:n).g(round(interp1(path(:,1),path(:,2),1:n)*(m+1)/(n+1))));title('after registration');
29
30
31
32
35
36
            37
38
40
             %Calculate da and dp
41
             %da is E
             da=E(n+1, n+1)
42
            %plot(path(:,1),path(:,2));
pathd=slderi(path,1,1);
%plot(pathd(:,1),pathd(:,2))
43
45
46
             dp=acos(sum(sqrt(pathd(:,2)))/n)
47
48
            %%Part2, Growth data.
close all, clear all;
dat=csvread('bgd.csv',1,0);
51
            age=dat(:,1);
boy=dat(:,2:40);
girl=dat(:,41:length(dat));
52
53
             %Visualization of data
            rigil=figure();
set(fig1,'Position', [200 200 1100 450]);
subplot(121);plot(age,boy);title('Heights of Boys');xlabel('age');ylabel('Heights in cm');
subplot(122);plot(age,girl);title('Heights of Girls');xlabel('age');ylabel('Heights in cm');
%Derivatives(Growth rates)
56
57
58
59
             %Smooth function and find growth rates.
62
             %Pick two curve.
            c1=girl(:,29);
c2=girl(:,28);
63
             smthpara=1;
            cls=fit(age,c1, 'smoothingspline', 'SmoothingParam', smthpara);
c2s=fit(age,c2, 'smoothingspline', 'SmoothingParam', smthpara);
67
             %Generate new functions gr1 and gr2 for derivative
68
             x=1:0.2:18;
69
             for i = 1:length(x)
71
                        gr1(i)=(c1s(x(i)+0.02)-c1s(x(i)-0.02))/(2*0.02);
72
             end
73
             for i=1:length(x)
                        gr2(i)=(c2s(x(i)+0.02)-c2s(x(i)-0.02))/(2*0.02);
74
75
76
             %plot the functions of growth rate to be registered
77
             close all;
78
             plot(x,gr1);hold on;plot(x,gr2);title('Growth rates');xlabel('age');ylabel('Growth rate');
79
             %Now lets calculate Q
             %Smooth x1 and x2 by splines and scale the curve to between 0 and 1
82
             fs=fit(((x-1)/max(x-1))', gr1', 'smoothingspline', 'SmoothingParam', smthpara); gs=fit(((x-1)/max(x-1))', gr2', 'smoothingspline', 'SmoothingParam', smthpara); 
83
84
             člose àll;
             fig1=figure();
            set(fig1, 'Position', [200 200 1100 450]);
subplot(121);plot(fs);hold on; plot(gs, 'b');title('Growth rate');
%Generate q1 from f and q2 from g
87
88
89
             %x2=0:1/m:1;
90
            n=100;
             m=1000;
93
            xx1=(0:n)/n;
94
             xx2=(0:m)/m;
95
96
             for i = 1:length(xx1)
                        \mathtt{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))). \\ *\mathbf{sqrt}(abs((f\text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001))/(2*0.0001))); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001)); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}((\dot{\mathsf{f}} \text{s}(xx1(i) + 0.0001) - f\text{s}(xx1(i) - 0.0001)))/(2*0.0001); \\ *\mathbf{q1(i)} = \text{sign}(
```

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```
for i=1:length(xx2)
100
                     q2(i) = sign((gs(xx2(i) + 0.0001) - gs(xx2(i) - 0.0001)) / (2*0.0001)) . *sqrt(abs((gs(xx2(i) + 0.0001) - gs(xx2(i) - 0.0001)) / (2*0.0001))); \\
101
            subplot(122);plot(xx1,q1);hold on; plot(xx2,q2);title('Functions q1 and q2');
102
103
           % Ready to register
[path, E]=sldpSRSF2(q1,q2);
104
105
          close all;
f=fs(xx1);
g=gs(xx2);
fig=figure();
set(fig,'Position', [200 200 1600 450]);
subplot(131);plot(f);hold on;plot(g((1:n)*m/n));title('before registration');
set(gca,'XTickLabel',[],'YTickLabel',[]);
subplot(132);imagesc(E');colormap(gray);hold on;plot(path(:,1),path(:,2));axis xy;
axis equal;set(gca,'XTickLabel',[],'YTickLabel',[]);
title('Warping function');
subplot(133);plot(f);hold on;
plot((1:n),g(round(interp1(path(:,1),path(:,2),1:n)*(m+1)/(n+1))));title('after registered');
set(gca,'XTickLabel',[],'YTickLabel',[]);
106
107
108
109
110
111
112
113
114
115
116
117
118
119
120
121
            da=E(n+1, n+1)
            pathd=slderi(path,1,1);
dp=acos(sum(sqrt(pathd(:,2)))/n)
122
123
```

```
1
                %f,g: 2 functions
   2
                %n: points of f
   3
                %m: points of g
   4
                %This function search neiborghood v
   5
                function [path, E] = sldp(f, g)
   6
                c=inf;
                n=length(f);
   7
   8
                m=length(g);
                xx1=(0:n-1)/(n-1);
   9
10
                xx2=(0:m-1)/(m-1);
11
                E=zeros(n,n);
                E(1,:)=\dot{c};
12
13
                E(:,1)=c;
14
                E(1,1)=0;
                v = [1, 1; 2, 1; 3, 1; 4, 1; 5, 1; 6, 1; 1, 2; 1, 3; 1, 4; 1, 5; 1, 6; 2, 3; 3, 2; 3, 4; 4, 3; 2, 5; 3, 5; 4, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 2, 5, 4; 4, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 2; 5, 3; 5, 4; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 5, 6; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5; 6, 5;
15
16
                             1,7;2,7;3,7;4,7;5,7;6,7;7,1;7,2;7,3;7,4;7,5;7,6;1,8;3,8;5,8;7,8;8,7;8,5;8,3;8,1];
                for i=2:n;
17
18
                             for j=2:n;
                                           for r=1:size(v,1);
19
                                                        k=i-v(r,1);
20
                                                        1=j-v(r,2);
21
22
                                                        if (k>0 && 1>0)
23
                                                                     CandE(r) = E(k,l) + energySRSF2(f,g,k,l,i,j);
24
25
                                                                     CandE(r)=c;
                                                        end
26
27
                                           end
28
                                           [E(i,j),idx] =min(CandE);
                                           path(i,j,1) = i-v(idx,1);
29
30
                                           path(i,j,2) = j-v(idx,2);
                             end
31
32
                end
33
                %reconstruct gamma
34
                x(1) = n;
                y(1) = n;
35
36
                cnt = 1;
37
                while x(cnt)>1;
38
                             x(cnt+1) = path(x(cnt), y(cnt), 1);
39
                             y(cnt+1) = path(x(cnt), y(cnt), 2);
40
                             cnt = cnt+1;
41
                end
42
                path=[x',y'];
```

```
function cost=energy(f,g,k,l,i,j)
function cost=energy(f,g,k,l,i,i,j)
function cost=energy(f,g,k,l,i,i,j)
function cost=energy(f,g,k,l,i,i,j)
function cost=energy(f,g,k,l,i,i,i,j)
function cost=energy(f,g,k,l,i,i,i,j)
function cost=energy(f,g,k,l,i,i,i,i,j)
function cost=e
```

11/29/2016 slderi.m

```
%function to calculate derivative based on inpute discrete data in f as a 2 \%column matrix, x is col1 and y is col2. d is order of derivative from 0 and above. smthpara is smooth parameter from
  3
        %0 to 1.
 4
5
6
        function q=slderi(f,d,smthpara)
        if d==0
               q=f;
 7
        else
               ftemp=slderi(f,d-1,smthpara);
               x=ftemp(:,1);
y=ftemp(:,2);
tempx=(x-min(x))/range(x);
 9
10
11
               tempx=(\tau_init(x)) / range(x),
q(:,1)=x;
fs=fit(tempx, y, 'smoothingspline', 'SmoothingParam', smthpara);
for i = 1:length(tempx)
    q(i,2)=(fs(tempx(i)+0.00001)-fs(tempx(i)-0.00001))/(0.00002)/range(x);
12
13
14
15
16
```