Lab 3 - Joseph Riley Guest - MAT 275 Lab

Table of Contents

| Exercise 1 | 1 |
|-------------------|------|
| Exercise 2 | 2 |
| Essay Question | 5 |
| Exercise 3 | 6 |
| Exercise 4 | |
| Part (b) | 9 |
| Exercise 5 | 9 |
| Comparing results | . 10 |
| | |

Introduction to Numerical Methods for Solving ODEs

Exercise 1

Part (a) clc % clearing command window f=@(t,y) 3*y; % Defining ODE function f for this lab t=linspace(0,0.6,100); % Defining vector t of time values y=exp(3*t); % Solution of the the function f Nsmall = 6; Nmed = 60; Nlarge = 600; Nhuge = 6000; % declaring the different step increments [t6, y6]=euler(f,[0,0.6],1,Nsmall); %solve the ODE using Euler w/6[t60,y60]=euler(f,[0,0.6],1,Nmed); %solve the ODE using Euler w/ 60 steps [t600,y600]=euler(f,[0,0.6],1,Nlarge); %solve the ODE using Euler w/ 600 steps [t6000,y6000]=euler(f,[0,0.6],1,Nhuge); %solve the ODE using Euler w/ 6000 steps e6 = y(end) - y6(end)% error when N = 6e60 = y(end) - y60(end)% error when N = 60 e6000 = y(end) - y6000(end) % error when N = 6000 ratio60 = e6/e60; % ratio of Nsmall/Nmed ratio600 = e60/e600; % ratio of Nmed/Nlarge ratio6000 = e600/e6000; % ratio of Nlarge/Nhuge % Giving the approximations of Nsmall thorugh Nhuge. Nsmall(end);Nmed(end);Nlarge(end);Nhuge(end); disp('----disp(' approximation disp(' --disp(' 6 4.8268 N/A ') 1.2228 5.8916 0.1580 | 7.7373 | ') disp(' 60

```
disp(' 600
              6.0334
                       0.0163 | 9.7082 | ')
                     0.0016 | 9.9699 | ')
disp(' 6000
              6.0480
disp('----
e6 =
  1.2228
e60 =
  0.1580
e600 =
  0.0163
e6000 =
  0.0016
  N | approximation | error | ratio |
|----|
   | 6
```

Part b.) If you look at the column titled error, the ratio is roughly ten. So as the number of N steps increases by a factor of 10, the error decreases by a factor of ten.

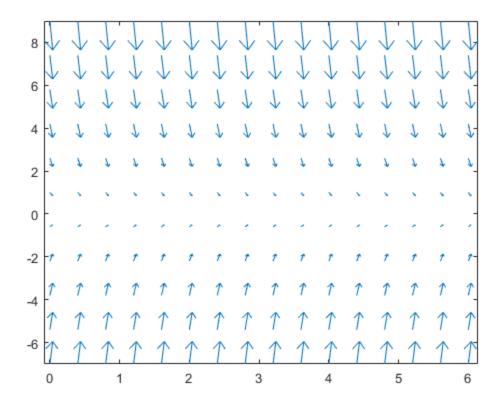
Part c.) The tangent line falls below the curve, so this means it is underestimating the answer for Euler's method

Exercise 2

```
Part (a)
```

60 600 6000

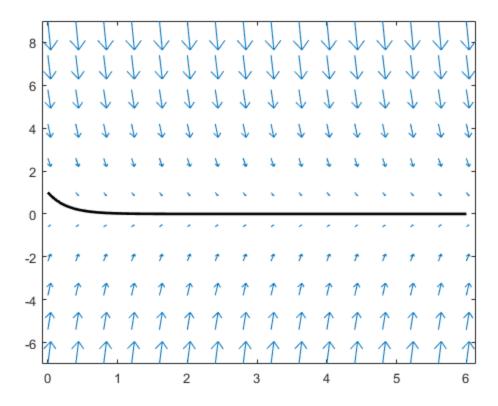
```
clc % clearing command window
t = 0:0.4:6; y = -7:1.6:9; % define a grid in t & y directions
[T,Y] = meshgrid (t,y); % create 2d matrices of points in ty - plane
dT = ones ( size (T)); %dt =1 for all points
dY = -3.7*Y; %dy = -3.7*y; this is the ODE
quiver (T,Y,dT,dY) % draw arrows (t,y)\rightarrow(t+dt,t+dy)
axis tight % adjust look
hold on % holding all plots on this figure until holding off
```



Part (b)

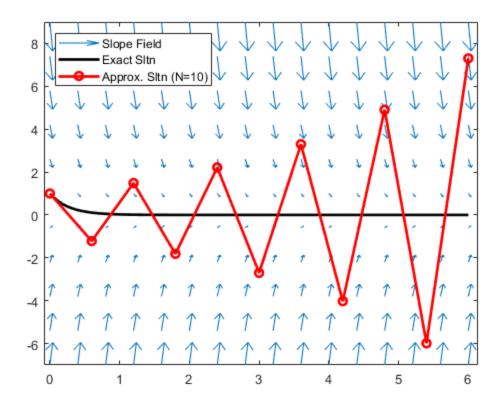
t = linspace(0, 6, 100); % defining vector t of given interval for
 exact solution

 $y = \exp(-3.7.*t)$; % defining the exact solution to dydt plot(t, y, 'k', "Linewidth", 2) % plotting analytical solution vector with slopefield



Part (c)

f = @(t,y) -3.7*y; % defining the ODE as an anonymous function [t10, y10] = euler(f, [0,6], 1, 10); % Solving ODE with Euler's method using 10 steps plot(t10, y10, 'ro-', 'linewidth', 2) % Plotting the approx solution N=10 legend('Slope Field', 'Exact Sltn', 'Approx. Sltn (N=10)', 'location', 'northwest') hold off; % end plotting in this figure window



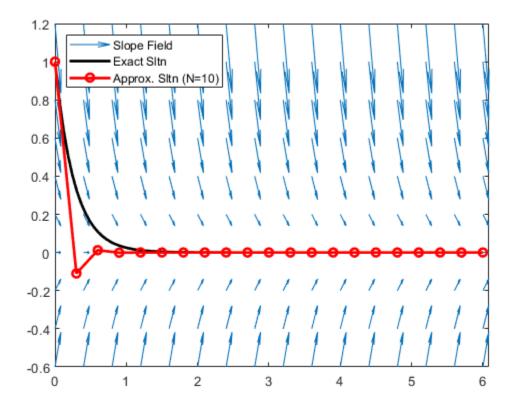
Essay Question

It's obvious that the more steps you have, the better the approximation. What makes this so inaccurate is that the coefficient of the solution is negative. Which in turn makes the solution unstable.

Part (d)

```
figure; % calling a new figure
t = 0:0.4:6; % defining the t vector (time values)
y = -0.6:0.2:1.3; % defining the y vector
[T,Y] = meshgrid (t,y); % defining new grid of t and y values for
 plotting
dT = ones ( size (T)); % dt = 1 for all points
dY = -3.7*Y; % dy = -3.7*y; this is the ODE
quiver (T,Y,dT,dY) % draw arrows (t,y) \rightarrow (t+dt,t+dy)
axis tight % adjust look
hold on; %holding all plots on this figure
t = linspace(0, 6, 100); % defining t vector for exact solution
y = \exp(-3.7.*t); % defining the exact solution to dydt
plot(t, y, 'k', "Linewidth",2) % plotting solution vector
f = @(t,y) -3.7*y; % defining the ODE as an anonymous function
[t20, y20] = euler(f, [0,6], 1, 20); % Solving ODE with Euler's using
plot(t20, y20, 'ro-', 'linewidth', 2) % Plotting the approx solution
 N = 10
```

```
legend('Slope Field','Exact Sltn','Approx. Sltn
  (N=10)','location','northwest')
hold off; % end plotting in this figure window
```



With the stepsize at N = 20, it would make this solution stable.

Exercise 3

```
% tspan = [t0, tf] where t0 = initial time value and tf = final
   time value
            % y0 = initial value of the dependent variable. If solving a
   system,
                                                 initial conditions must be given as a vector.
            % N
                               = number of steps used.
            % Output:
            % t = vector of time values where the solution was computed
            % y = vector of computed solution values.
            m = length(y0);
            t0 = tspan(1);
            tf = tspan(2);
            h = (tf-t0)/N;
                                                                                                % evaluate the time step size
            t = linspace(t0, tf, N+1); % create the vector of t values
            y = zeros(m,N+1); % allocate memory for the output y
            y(:,1) = y0';
                                                                                                % set initial condition
            for n=1:N
                        f1 = f(t(n), y(:,n)); % declaring f1 = (t_n,y_n)
                        f2 = f(t(n) + h, y(:,n) + h*f1); % declaring f2 = (f(t_n+h), f2) = f(t(n) + h, f3) = f(t(n) + h, f3)
  y n+hf 1)
                       y(:,n+1) = y(:,n) + (h/2)*(f1+f2); % implement Improved
  Euler's method
            end
            t = t'; y = y'; % change t and y from row to column vectors
end
ans =
                                        1.0000
                           0
                                        1.3450
            0.1000
            0.2000
                                        1.8090
            0.3000
                                        2.4331
            0.4000
                                        3.2726
            0.5000
                                         4.4016
            0.6000
                                        5.9202
```

My output matches the output of the protocol.

Exercise 4

```
Part (a)
```

```
[t600,y600]=impeuler(f,[0,0.6],1,600); % solve the ODE using impeuler
w/ 600 steps
[t6000,y6000] = impeuler(f,[0,0.6],1,6000); solve the ODE using
impeuler w/ 6000 steps
y6(end), y60(end), y600(end), y6000(end) % evaluating approximations @
6, 60, 600, 6000
ratio60 = e6 / e60
ratio600 = e60/e600
                        % ratio of Nsmall/Nmed
                        % ratio of Nmed/Nlarge
ratio6000 = e600/e6000
                        % ratio of Nlarge/Nhuge
disp(' N approximation error ratio ')
disp('|----
                -----
                                       |----|')
               5.9202
                                        N/A | ')
disp(' 6
                             0.1295
disp(' 60
                 6.0481
                             0.0016
                                       81.0854 | ')
disp(' 600
                 6.0496
                             1.6297e-5 | 97.9844|')
disp('| 6000
                 6.0496
                            | 1.6330e-7 | 99.7976 | ')
disp('----')
ans =
   5.9202
ans =
   6.0481
ans =
   6.0496
ans =
   6.0496
e6 =
   0.1295
e60 =
   0.0016
```

```
e600 =

1.6297e-05

e6000 =

1.6330e-07

ratio60 =

81.0854

ratio600 =

97.9844

ratio6000 =

99.7976
```

| N | approximation | error | ratio |
|--------------------------|---------------|---|-----------|
| 6 60 600 | - | 0.1295 0.0016 1.6297e-5 | N/A |
| 6000 | 6.0496 | 1.6330e-7 | 99.7976 |

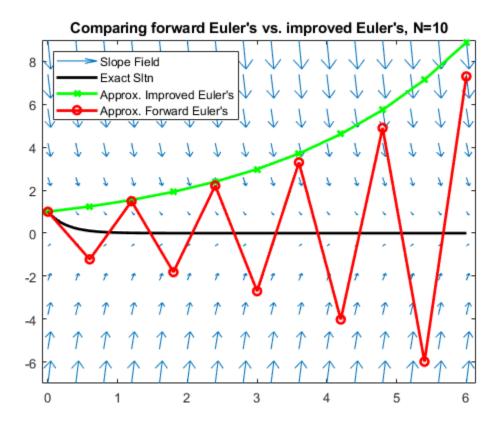
Part (b)

The ratio of errors is proportional to the number of N steps. The higher you go with the number of steps, the closer the ratio will get to 1. At N=60000, the ratio is 1.

Exercise 5

```
clc % clearing command window
t = 0:0.4:6; y = -7:1.6:9; % define a grid in t & y directions
[T,Y] = meshgrid (t,y); % create 2d matrices of points in ty - plane
dT = ones ( size (T)); %dt =1 for all points
dY = -3.7*Y; %dy = -3.7*y; this is the ODE
quiver (T,Y,dT ,dY) % draw arrows (t,y)->(t+dt , t+dy)
axis tight % adjust look
hold on % holding all plots on this figure until holding off
t = linspace(0, 6, 100); % defining vector t of given interval for
exact solution
y = exp(-3.7.*t); % defining the exact solution to dydt
plot(t, y, 'k', "Linewidth",2) % plotting analytical solution vector
with slopefield
```

```
f = @(t,y) -3.7*y; % defining the ODE as an anonymous function
[t10, y10] = impeuler(f, [0,6], 1, 10); % Solving ODE with Improved
Euler's method using 10 steps
plot(t10, y10, 'gx-', 'linewidth', 2) % Plotting the approx solution
N=10
[t10forward, y10forward] = euler(f, [0,6], 1, 10); % Solving ODE with
forward Euler's method using 10 steps
plot(t10forward, y10forward, 'ro-', 'linewidth', 2) % Plotting the
approx solution N=10
legend('Slope Field', 'Exact Sltn', "Approx. Improved Euler's", "Approx.
Forward Euler's", 'location', 'northwest')
title("Comparing forward Euler's vs. improved Euler's, N=10") % Adding
a title to the plot
```



Comparing results

If you compare the results of the forward euler's method to improved eulers method. The improved eulers approximation follows along the linear fit of the positive points of the forward eulers method.

Published with MATLAB® R2019b