

$$Z_{2} = \left[ \frac{1}{j\omega L + R_{L}} - \frac{\omega C}{j} \right]^{-1} = j \left[ \frac{1 - \omega C (\omega L - jR_{L})}{\omega L - jR_{L}} \right]^{-1}$$

$$= j \frac{\omega L - jR_{L}}{1 - (\omega^{2}LC - j\omega R_{L}C)} = \frac{R_{L} - j\omega L}{(1 - \omega^{2}LC) - j\omega R_{L}C}$$

Since Z, is real, let's go ahead and put Z2 m A+jB form.

$$Z_{2} = \frac{(R_{L} - j\omega L)[1 - \omega^{2}LC + j\omega R_{L}C]}{(1 - \omega^{2}LC)^{2} + (\omega R_{L}C)^{2}} 
= \frac{R_{L}(1 - \omega^{2}CC) + \omega^{2}KCR_{L} - j\omega R_{L}^{2}C - j\omega L (1 - \omega^{2}LC)}{(1 - \omega^{2}LC)^{2} + (\omega R_{L}C)^{2}} 
= \frac{R_{L} - j[\omega CR_{L}^{2} + \omega L (1 - \omega^{2}LC)]}{(1 - \omega^{2}LC)^{2} + (\omega CR_{L})^{2}}$$

$$A = \frac{R_L}{(1-\omega^2LC)^2 + (\omega CR_L)^2}$$

$$B = -\frac{[\omega CR_L^2 + \omega L(1-\omega^2LC)]}{(1-\omega^2LC)^2 + (\omega CR_L)^2}$$

$$Z_1 + Z_2 = \frac{A + jB}{R + A + jB}$$

$$A_{V} = \sqrt{\frac{A^2 + B^2}{(R+A)^2 + B^2}}$$

Now, we need to do the trick we use to find the phase angle:

$$\frac{Z_2}{Z_1 + Z_2} = \frac{A + jB}{R + A + jB} = \frac{(A + jB)(R + A - jB)}{\text{whatever}}$$

$$= \frac{A(R + A) + B^2 + j[B(R + A) - AB]}{\text{whatever}}$$

$$+an \phi = \frac{\operatorname{Im}\left\{\frac{z_{s}}{z_{1}+z_{s}}\right\}}{\operatorname{Re}\left\{\frac{z_{s}}{z_{1}+z_{s}}\right\}}$$

The trick here is that we only need the imaginary and real parts of the numerator. The whatever concels out.

$$+an \beta = \frac{BR}{A(R+A)+B^2}$$

$$\left(\begin{array}{c}
\text{If } R_{L}=0, A=0, R=\frac{\omega L}{1-\omega^{2}LC} \\
+\omega G=\frac{RR}{B^{2}}=\frac{R}{B}=\frac{R}{\omega L}\left(1-\omega^{2}LC\right)
\right)$$

Defore A, B, Av, and phi Python functions to facilitate plotting.

Find wo and the 3dB points numerically, with a cursor on an interactive plot.