

Macm 203 Assignment 6

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Part A: Denoising smooth images

Consider the following smooth grayscale image of size $n \times n$:

$$I = (1 + \cos(2\pi * (1:n)/n) * \sin(2\pi * (1:n)/n)) / 2;$$

Add Gaussian noise. Now apply mean filtering and median filtering to your noisy image. Which gives better results? Explain visually and using `immse()`. Apply a suitable structuring element and boundary conditions.

Add Salt & Pepper noise. Now apply mean filtering and median filtering to your noisy image. Which gives better results? Explain visually and using `immse()`. Apply a suitable structuring element and boundary conditions.

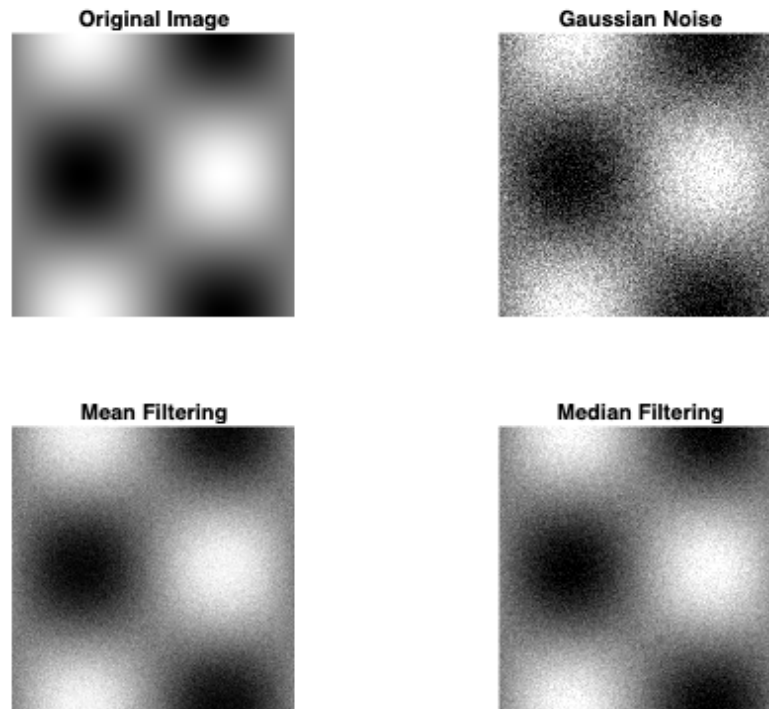
```
clc,clf,clearvars;
n = 1000;
I = (1+cos(2*pi*(1:n)/n)*sin(2*pi*(1:n)/n))/2;

% Add Gaussian noise
sigma = 1e-1;
G = imnoise(I,'gaussian',0,sigma^2);

% Apply mean filtering to G with mirror boundary conditions
filterSize = 3;
Gmeanfilter = imfilter(G,fspecial('average', filterSize), 'symmetric');

% Apply median filtering to G with mirror boundary conditions
Gmedfilter = medfilt2(G,'symmetric');

% Display the images
clf;
subplot(2,2,1)
imshow(I)
title('Original Image')
subplot(2,2,2)
imshow(G)
title('Gaussian Noise')
subplot(2,2,3)
imshow(Gmeanfilter)
title('Mean Filtering')
subplot(2,2,4)
imshow(Gmedfilter)
title('Median Filtering')
```



```
% Mean vs Median Filtering
```

```
immse(I,Gmeanfilter)
```

```
ans = 0.0011
```

```
immse(I,Gmedfilter)
```

```
ans = 0.0016
```

Visually, the mean filtering looks less noisy than the median filtering, when comparing it to the original image. Calculating the mean-squared error with `immse()`, we also see that the difference between the original image and the mean filtered image, is smaller than the difference between the original image and the median filtered image ($0.0012 < 0.0016$). So the original image and the mean filtered image are more similar than the median filtered image.

```
clc,clf;

n = 1000;
I = (1+cos(2*pi*(1:n)/n))*sin(2*pi*(1:n)/n))/2;

% Add Salt & Pepper noise to the original image
density = 0.05;
SP = imnoise(I,'salt & pepper', density);

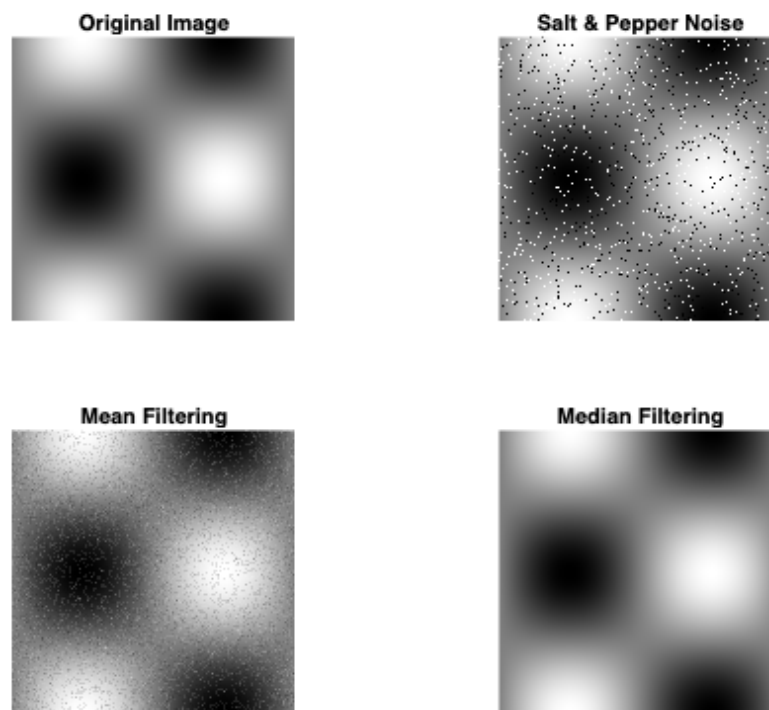
% Apply mean filtering to SP with mirror boundary conditions
filterSize = 3;
SPmeanfilter = imfilter(SP,fspecial('average', filterSize),'symmetric');

% Apply median filtering to SP with mirror boundary conditions
```

```
SPmedfilter = medfilt2(SP,'symmetric');
```

```
% Display the images
```

```
clf;  
subplot(2,2,1)  
imshow(I)  
title('Original Image')  
subplot(2,2,2)  
imshow(SP)  
title('Salt & Pepper Noise')  
subplot(2,2,3)  
imshow(SPmeanfilter)  
title('Mean Filtering')  
subplot(2,2,4)  
imshow(SPmedfilter)  
title('Median Filtering')
```



```
% Mean vs Median Filtering  
immse(I,SPmeanfilter)
```

```
ans = 0.0019
```

```
immse(I,SPmedfilter)
```

```
ans = 6.9014e-07
```

Visually, the median filtering gives better results, with the median filtered image looking more similar to the original image than the mean filtering does. This is confirmed by the `immse()` of median being smaller than of mean, so the mean-squared error of the original and median is smaller than that of the original and the mean.

Part B: Denoising nonsmooth images

```
clc,clf,clearvars;
textImage = im2double(imread('text.png'));

% Add gaussian noise
sigma = 1e-1;
tIGaussian = imnoise(textImage,'gaussian',0,sigma^2);

% Apply mean filtering
filterSize = 3;
tIMeanFilter = imfilter(tIGaussian,fspecial('average',filterSize),'symmetric');

% Apply median filtering
tIMedFilter = medfilt2(tIGaussian,'symmetric');

% Mean vs median filtering
immse(textImage,tIMeanFilter)
```

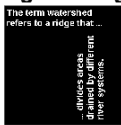
ans = 0.0168

```
immse(textImage,tIMedFilter)
```

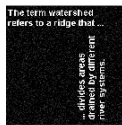
ans = 0.0089

```
clf;
subplot(2,2,1)
imshow(textImage)
title('Original Image')
subplot(2,2,2)
imshow(tIGaussian)
title('Gaussian Noise')
subplot(2,2,3)
imshow(tIMeanFilter)
title('Mean Filtering')
subplot(2,2,4)
imshow(tIMedFilter)
title('Median Filtering')
```

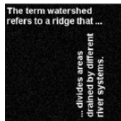
Original Image



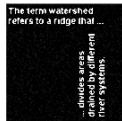
Gaussian Noise



Mean Filtering



Median Filtering



By running `immse()` on the median and mean filtered images, we see that median filtering has the smaller mean-squared value when comparing to the original image. We also see visually that the output of mean filtering has changed the text colour from a stark white to a more muted gray-white colour.

```
% Add salt & pepper noise
```

```

clc,clf;
textImage = im2double(imread('text.png'));
density = 0.05;
tISP = imnoise(textImage,'salt & pepper',density);

```

```

% Apply mean filtering
filterSize = 3'

```

```

filterSize = 3

```

```

tISPMeanFilter = imfilter(tISP,fspecial('average',filterSize),'symmetric');

```

```

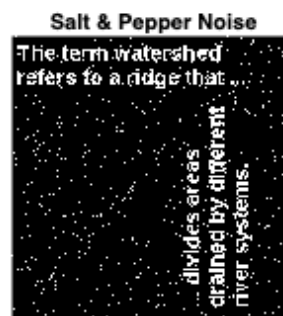
% Apply median filtering
tISPMedFilter = medfilt2(tISP,'symmetric');

```

```

clf;
subplot(2,2,1)
imshow(textImage)
title('Original Image')
subplot(2,2,2)
imshow(tISP)
title('Salt & Pepper Noise')
subplot(2,2,3)
imshow(tISPMeanFilter)
title('Mean Filtering')
subplot(2,2,4)
imshow(tISPMedFilter)
title('Median Filtering')

```



```

% Mean vs median filtering

```

```
immse(textImage,tISPMeanFilter)
```

```
ans = 0.0180
```

```
immse(textImage,tISPMedFilter)
```

```
ans = 0.0106
```

From `immse()`, median filtering produces better results as its mean-squared error of the original is smaller than the mean-squared error of mean and the original image. We also notice that the Mean Filtering appears to have left more of the white pixels compared to the median filtering.

Part C: Image enhancement via ordered filters

```
clearvars,clc,clf;
J = imread('letterj.jpg');

% Explore the use of ordered filters to make the letter wider and narrower
% You may wish to use the ordfilt2() command to simplify your coding task

% Makes j narrower
Jthin = J;
domainthin = ones(10,10);
orderthin = 1;
%for i=1:3
%    Jthin(:,:,i) = ordfilt2(Jthin(:,:,i),orderthin,domainthin);
%end
%imshow(Jthin)
Jthin = cat(3, ordfilt2(Jthin(:,:,1),orderthin,domainthin), ...
            ordfilt2(Jthin(:,:,2),orderthin,domainthin), ...
            ordfilt2(Jthin(:,:,3),orderthin,domainthin));

% Makes j wider
Jwide = J;
domainwide = ones(10,10);
orderwide = numel(domainwide);
%for i=1:3
%    Jwide(:,:,i) = ordfilt2(Jwide(:,:,i),orderwide,domainwide);
%end
Jwide = cat(3, ordfilt2(Jwide(:,:,1),orderwide,domainwide),...
            ordfilt2(Jwide(:,:,2),orderwide,domainwide),...
            ordfilt2(Jwide(:,:,3),orderwide,domainwide));

% Display the j's
montage({J,Jthin,Jwide})
title('original j (left), narrow j (middle), wide j (right) using ordered filters')
```

original j (left), narrow j (middle), wide j (right) using ordered filters

