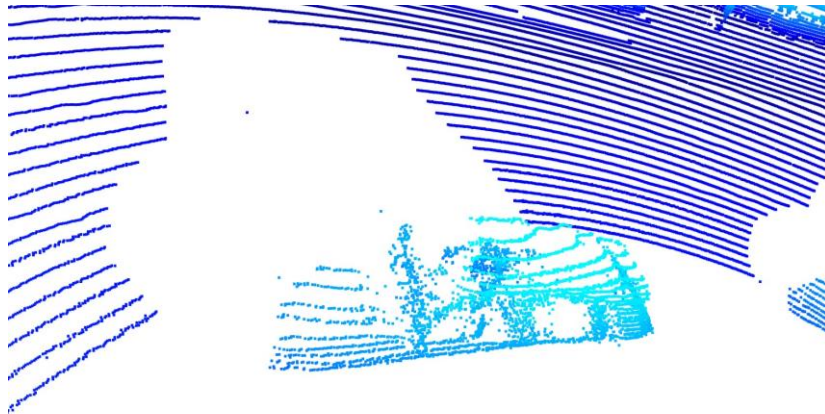
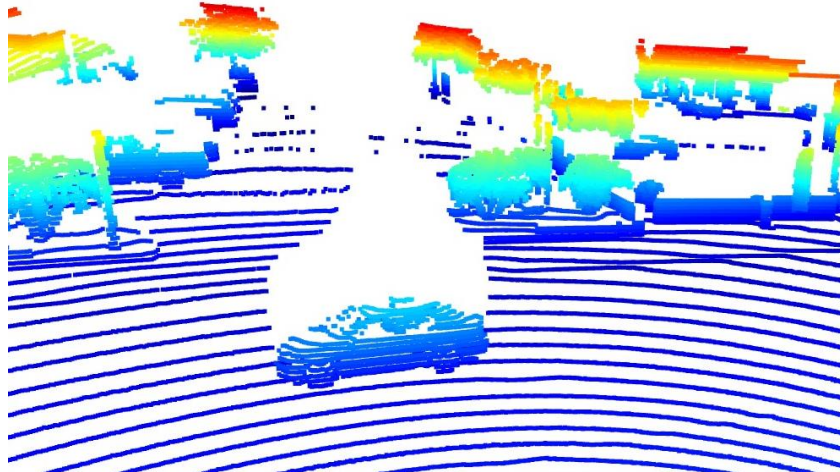


10 examples of vehicles with varying degrees of visibility in the point-cloud:

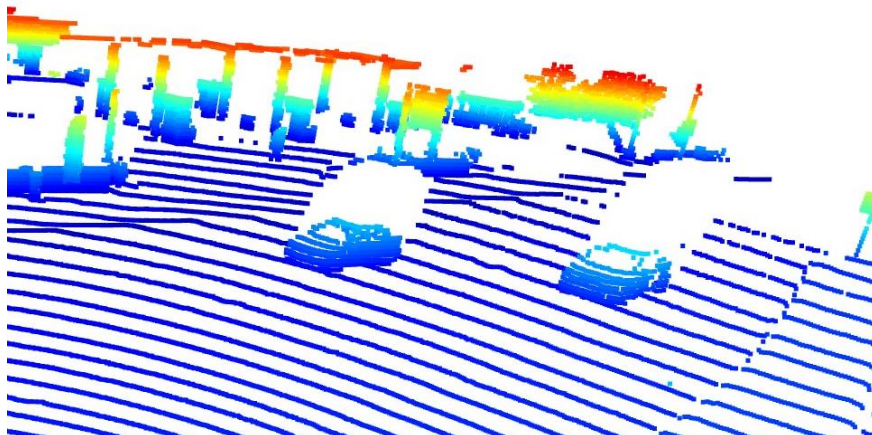
1. Close distance to lidar, blind spot



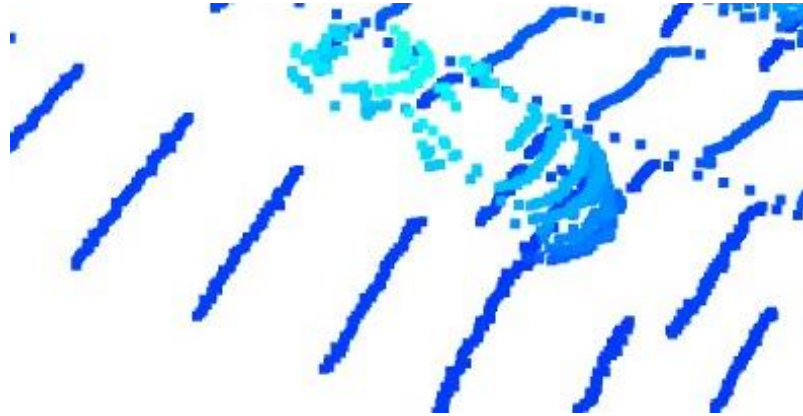
2. Close distance to lidar, visible area



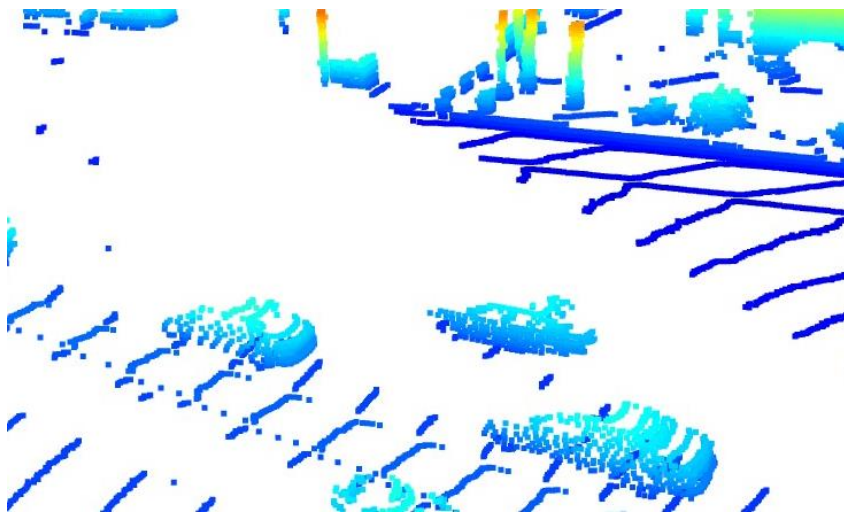
3. Average distance from lidar, cars moving towards (about 45 degrees)



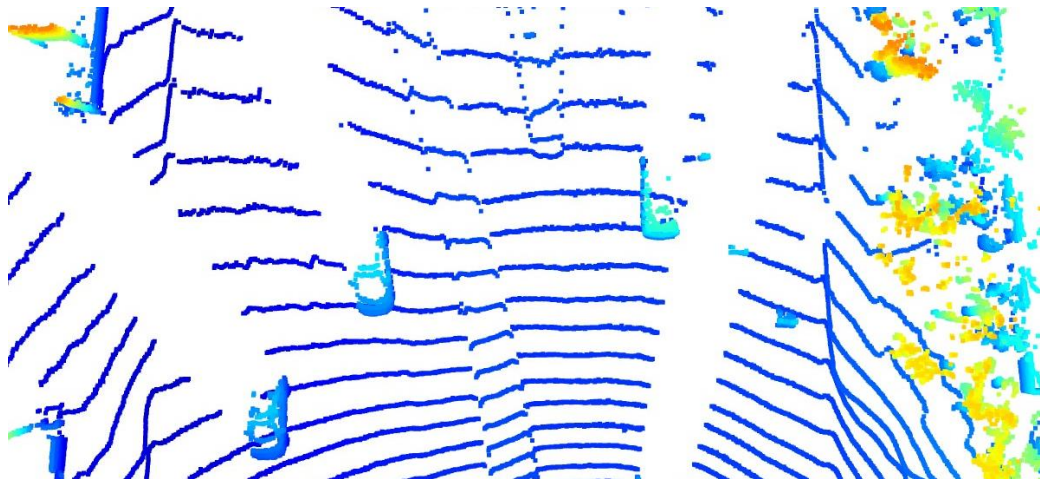
4. Average distance from lidar, cars behind, moving in the same direction



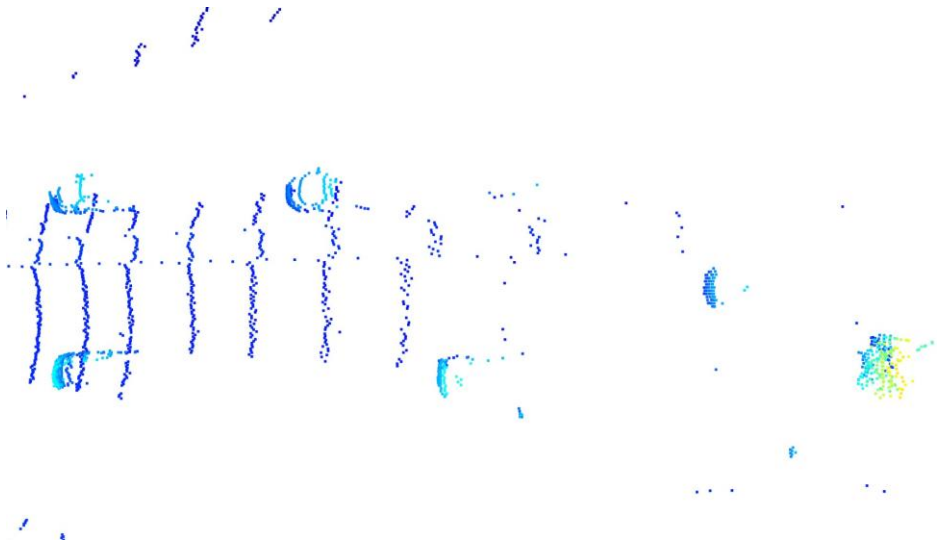
5. Average distance from lidar, cars behind, traveling in opposite direction



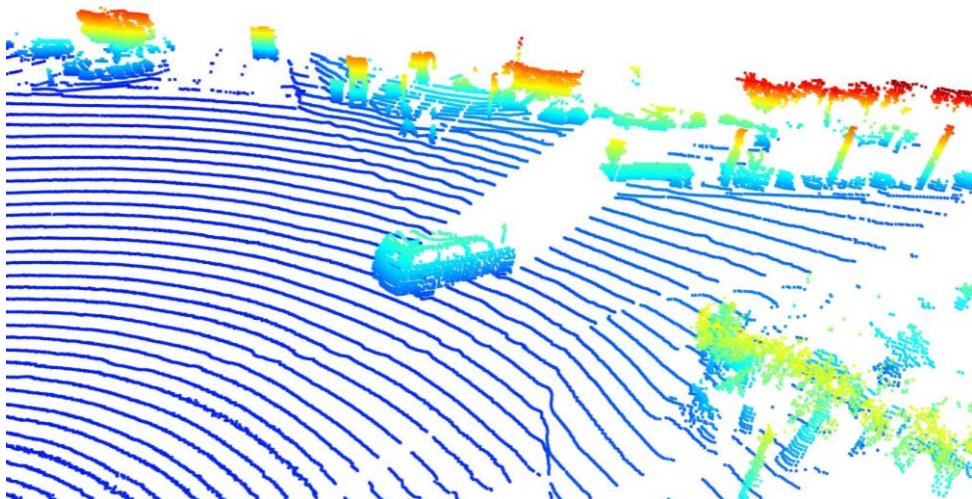
6. Far from the lidar, in front.



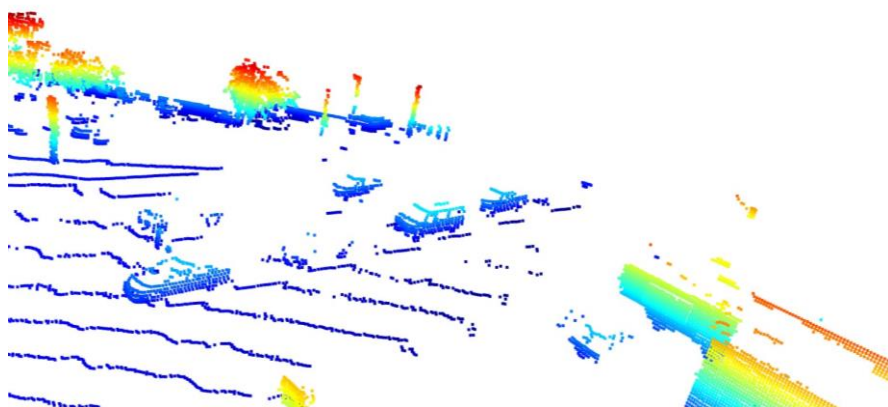
7. Very far away (rear hull)



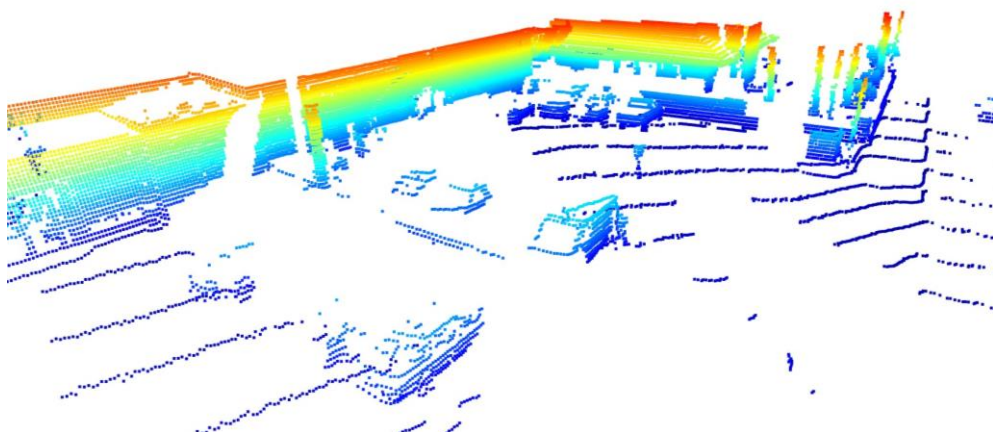
8. Front, perpendicular to traffic, side by side.



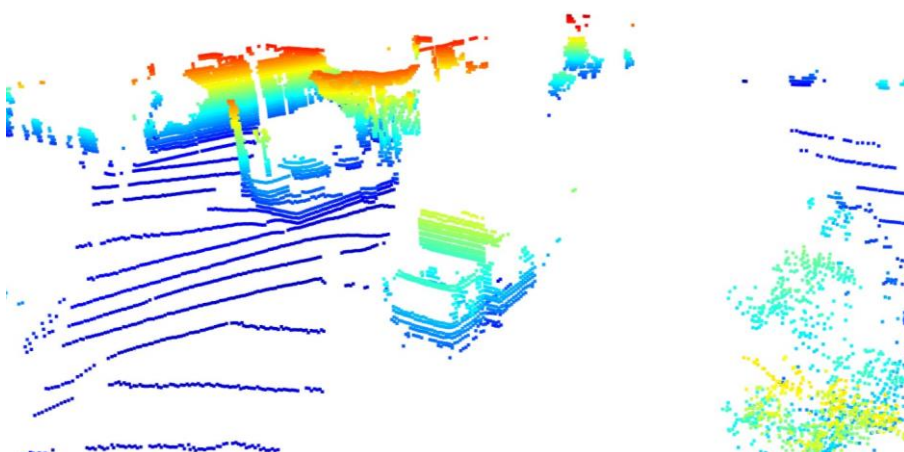
9. From behind, perpendicular to traffic, far left.



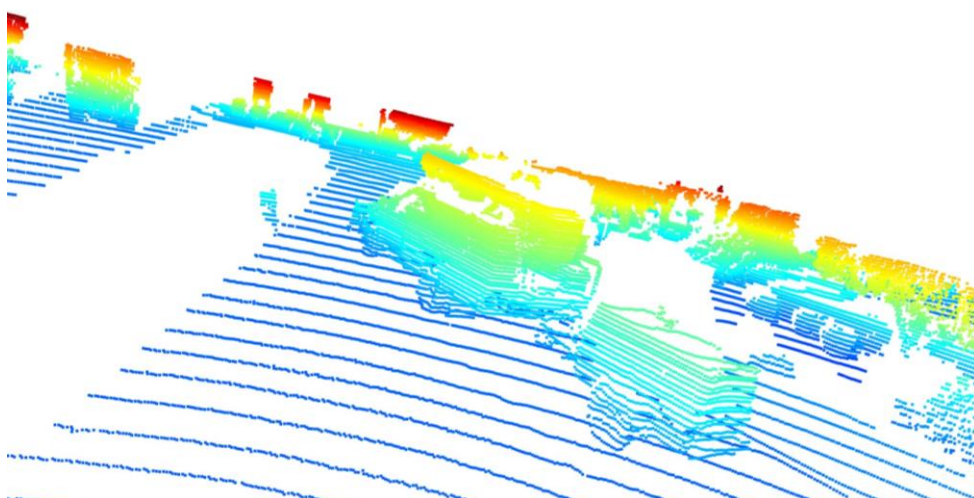
10. Cars in the parking lot, front



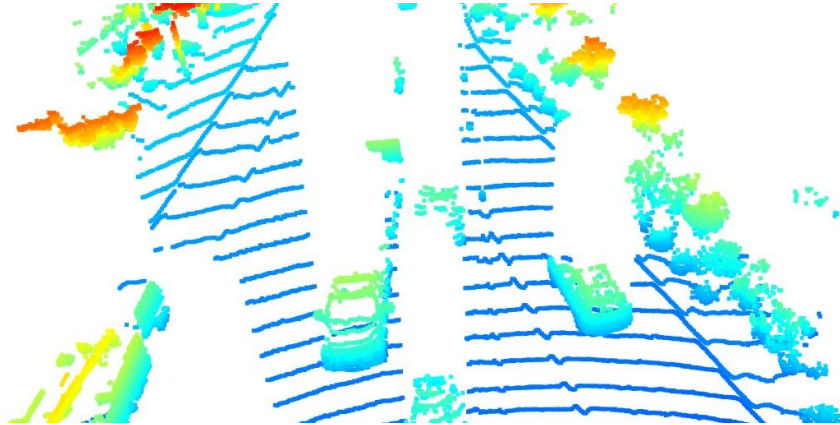
11. The truck is far away through the trees



12. Car with a trailer, close, in front.



13. Overlapping with another machine



Vehicle features

1. Window shape - no cloud of dots due to lack of reflectivity of glass
2. Front and rear bumper - clear shape in BEV
3. Wheel - clearly visible in side view at 45-90 degrees
4. Rearview mirror - highlighted when driving towards you
5. Numbers - high reflectivity (high intensity)
6. Headlights - high reflectivity (high intensity)

