## Floating-point subtract single

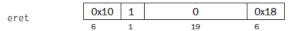
Compute the difference of the floating-point doubles (singles) in registers fs and ft and put it in register fd.

# Floating-point truncate to word

Truncate the floating-point double (single) value in register fs, convert to a 32-bit fixed-point value, and put the resulting word in register fd.

# **Exception and Interrupt Instructions**

#### **Exception return**



Set the EXL bit in coprocessor 0's Status register to 0 and return to the instruction pointed to by coprocessor 0's EPC register.

## System call



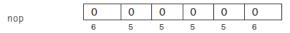
Register \$v0 contains the number of the system call (see Figure A.9.1) provided by SPIM.

#### Break



Cause exception code. Exception 1 is reserved for the debugger.

# No operation



Do nothing.